



Non-welded contact interface with media

Xiaoqin(Jean) Cui

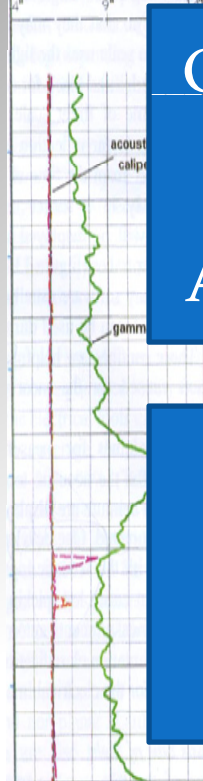
Larry R. Lines

Outline

- **Introduction**
- **Mechanism of the interface contacts**
- **Long wavelength assumption**
 - Estimate moduli for the linear slip interface**
- **Group theory**
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- **Conclusions**
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Introduction

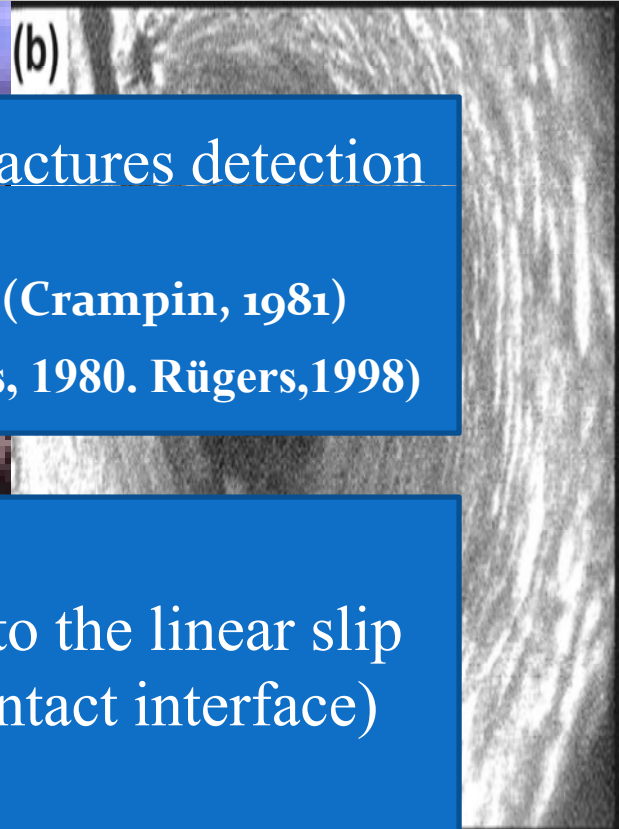
GAMMA RAY		ACOUSTIC SCANNER	
0	API	100	
ACOUSTIC CALIPERS		COMPENSATED AMPLITUDES	TIME OF FLIGHT



Geophysical methods for fractures detection

Shear wave splitting, (Crampin, 1981)
AVO, AVAZ (Aki and Richards, 1980. Rügers,1998)

Fracture can be simulated to the linear slip interface (Non-welded contact interface)



Rider, 2002

**Fractured
media**

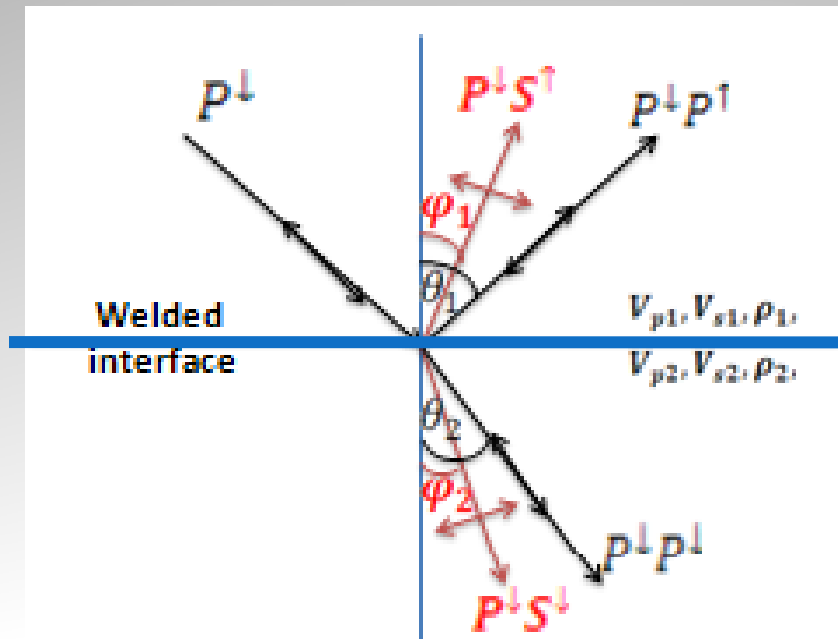
Asquith and Krygowski, 2004

Introduction

- Schoenberg developed the theory of non-welded contact interface. (1980)
- Pyrak-Nolte has confirmed non-welded contact interface theory by laboratory measurements (1990)
- Chaisri and Krebes obtained the solutions of the reflection and transmission coefficients for non-welded contact interface embedded in isotropic media. (2000)
- Slawinski and Krebes modeled SH wave propagation in non-welded contact media. (2002)
- Hood, 1989, 1991; Carcione, 1996; Hsu, 1993; Coates, 1995.

Mechanism of the interface contacts with media

A welded contact interface



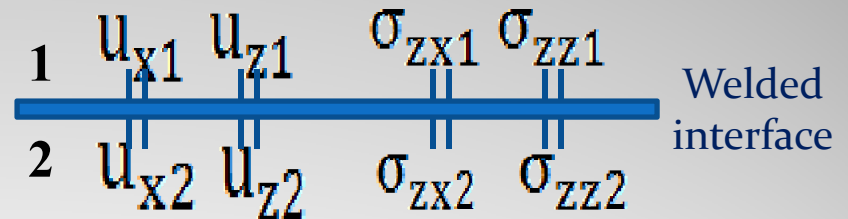
AVO and AVAZ detected fractures using amplitude variation versus offset and azimuth (Aki and Richards, 1980, Rügers, 1998)

Mechanism of the interface contacts with media

A welded contact interface boundary conditions (P-SV)

1) The continuity displacements

$$u_{x1} = u_{x2} \quad u_{z1} = u_{z2}$$



2) The continuity stresses

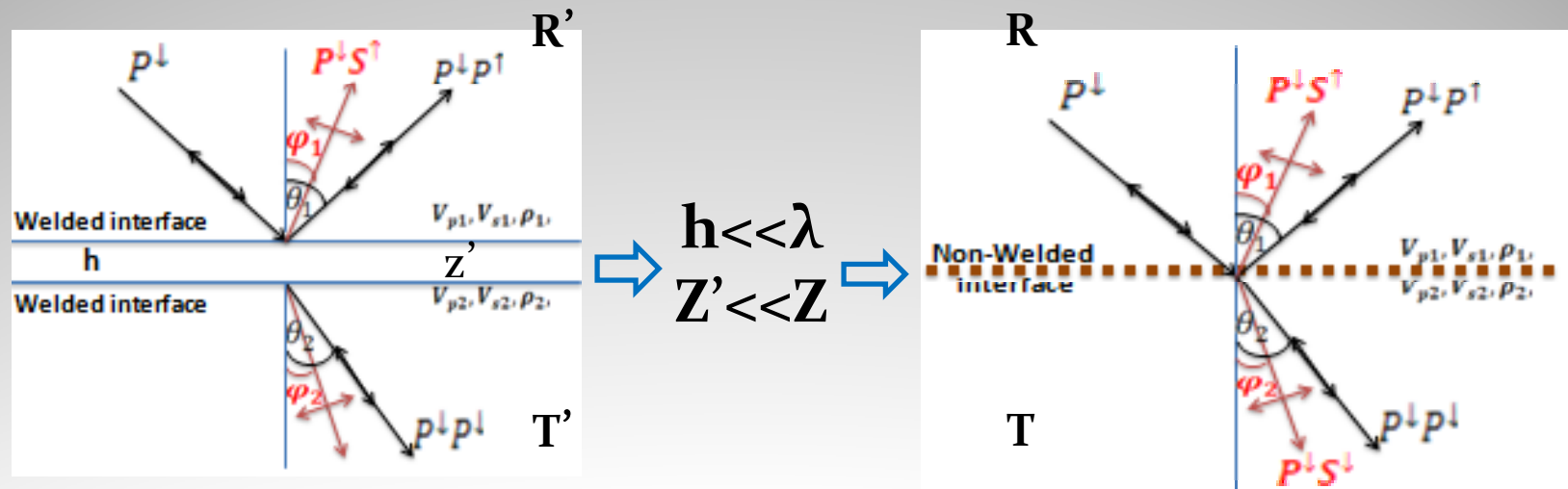
$$\sigma_{zx1} = \sigma_{zx2} \quad \sigma_{zz1} = \sigma_{zz2}$$

$$\sigma_{zx} = \mu \left(\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right)$$

$$\sigma_{zz} = \lambda \frac{\partial u_x}{\partial x} + (\lambda + 2\mu) \frac{\partial u_z}{\partial z}$$

Mechanism of the interface contacts with media

A non-welded contact interface



Pyrak-Nolte (1990) has confirmed non-welded contact interface theory by laboratory measurements.

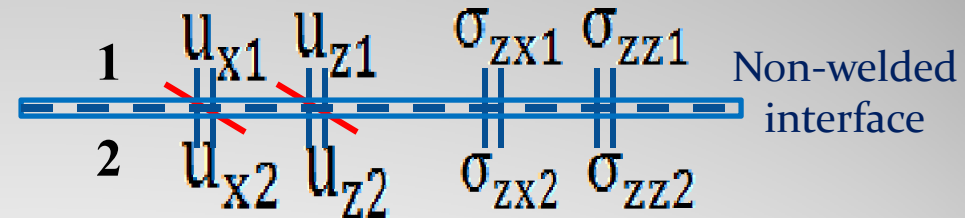
Mechanism of the interface contacts with media

An non-welded interface contact boundary conditions (P-SV)

1) The discontinuity displacements

$$u_{x1} - u_{x2} = S_x \sigma_{zx}$$

$$u_{z1} - u_{z2} = S_z \sigma_{zz}$$



2) The continuity stresses

$$\sigma_{zx1} = \sigma_{zx2}$$

$$\sigma_{zz1} = \sigma_{zz2}$$

$$\sigma_{zx} = \mu \left(\frac{\partial u_z}{\partial x} + \frac{\partial u_x}{\partial z} \right)$$

$$\sigma_{zz} = \lambda \frac{\partial u_x}{\partial x} + (\lambda + 2\mu) \frac{\partial u_z}{\partial z}$$

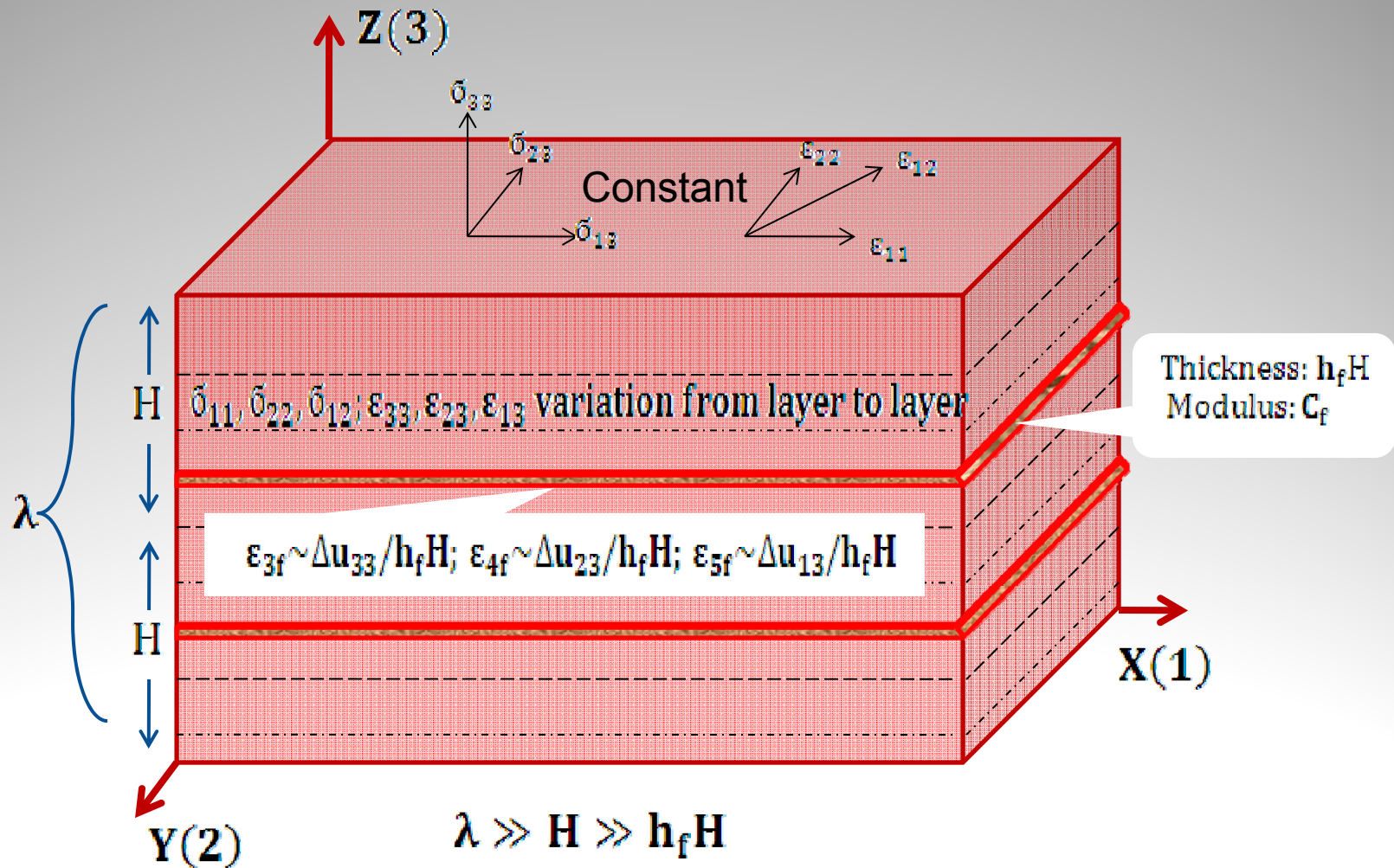
Long wavelength assumption

Estimate elastic moduli for the linear slip interface

- Finely layered medium behaves approximately as TI medium
- Some Strains of fine layer can be expressed in terms of thickness-weighted average
- An equivalent TI media can replace the fractured media (the linear slip interface embedded in background medium)

Long wavelength assumption

Estimate elastic moduli for the linear slip interface

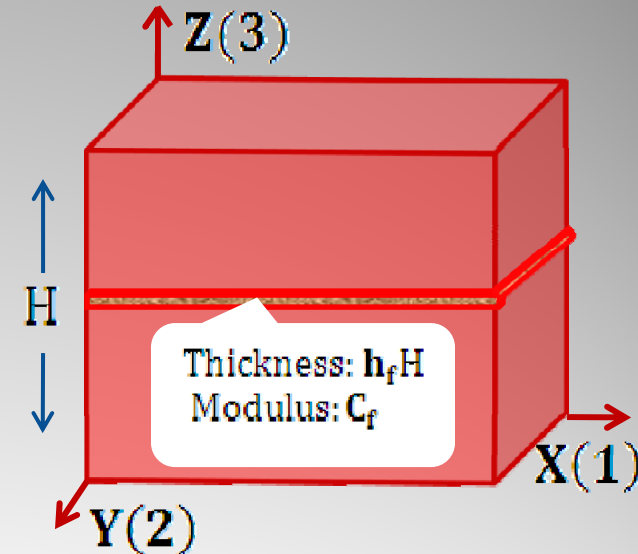


Long wavelength assumption

Estimate elastic moduli for the linear slip interface

Elastic moduli:

$$\begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \sigma_4 \\ \sigma_5 \\ \sigma_6 \end{bmatrix} = \begin{bmatrix} C11 & C12 & C13 & C14 & C15 & C16 \\ C21 & C22 & C23 & C24 & C25 & C26 \\ C31 & C32 & C33 & C34 & C35 & C36 \\ C41 & C42 & C43 & C44 & C45 & C46 \\ C51 & C52 & C53 & C54 & C55 & C56 \\ C61 & C62 & C63 & C64 & C65 & C66 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_4 \\ \epsilon_5 \\ \epsilon_6 \end{bmatrix}$$



The stress tractions across the fracture:

$$\sigma = \begin{bmatrix} \sigma_3 \\ \sigma_4 \\ \sigma_5 \end{bmatrix} = \left(h_f \begin{bmatrix} C13 & C23 & C36 \\ C14 & C24 & C46 \\ C15 & C25 & C56 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_6 \end{bmatrix} + \begin{bmatrix} C33 & C34 & C35 \\ C34 & C44 & C45 \\ C35 & C54 & C55 \end{bmatrix} \begin{bmatrix} \epsilon_{3f} \\ \epsilon_{4f} \\ \epsilon_{5f} \end{bmatrix} \right) \quad h_f \rightarrow 0 \quad \begin{bmatrix} \epsilon_{3f} \\ \epsilon_{4f} \\ \epsilon_{5f} \end{bmatrix} = \begin{bmatrix} \Delta U_{3f}/H \\ \Delta U_{4f}/H \\ \Delta U_{5f}/H \end{bmatrix}$$

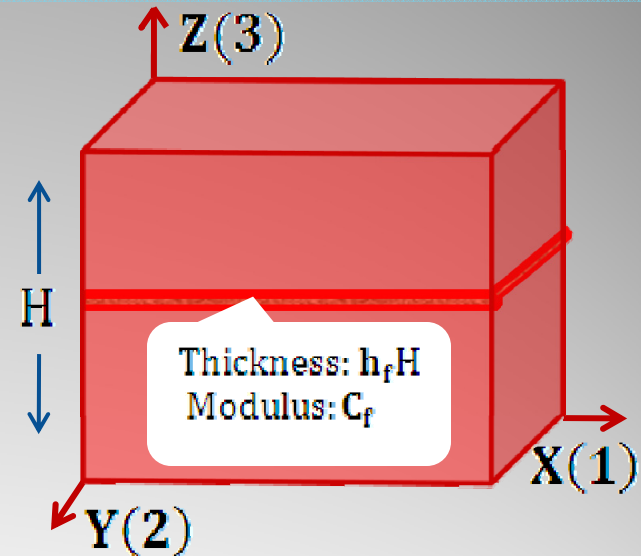
Long wavelength assumption
Strains are same as background

Long wavelength assumption

Estimate elastic moduli for the linear slip interface

The relationship of stresses and strains in fracture system (linear slip interface)

$$\begin{bmatrix} \Delta U_{3f}/H \\ \Delta U_{4f}/H \\ \Delta U_{5f}/H \end{bmatrix} = Z \begin{bmatrix} \sigma_3 \\ \sigma_4 \\ \sigma_5 \end{bmatrix}$$



The transverse isotropic fracture system (linear slip interface) compliance matrix

$$Z = \begin{bmatrix} Z_N & 0 & 0 \\ 0 & Z_T & 0 \\ 0 & 0 & Z_T \end{bmatrix}$$

Group theory

Fractured media decomposed into fracture medium and background medium

- elastic moduli be mapped to the elements of group
- fractured media are originated by fracture sum background media
- fractured media can decomposed into background medium and fracture.

Group theory

Fractured media decomposed into fracture medium and background medium

Fractured medium moduli transform to a commutative group

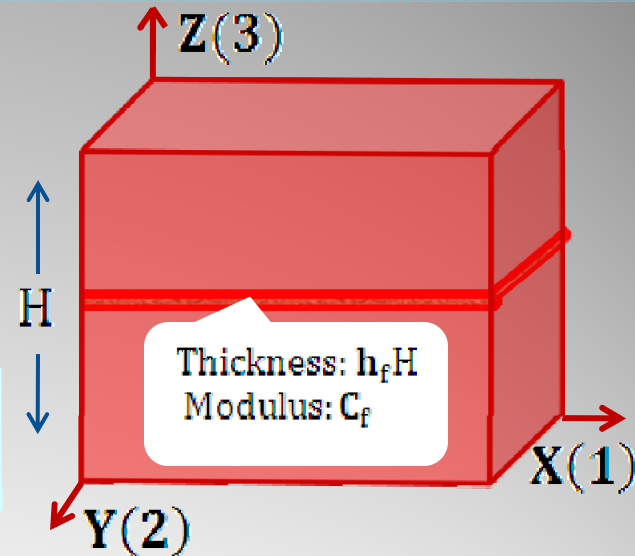
$$[H, H\rho, g(3), g(4), g(5),]$$

$$g(3) = H \begin{bmatrix} 1/C33 & 0 & 0 \\ 0 & 1/C44 & 0 \\ 0 & 0 & 1/C44 \end{bmatrix} \quad g(4) = H \frac{C13}{C33} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$g(5) = H \left\{ \begin{bmatrix} C11 & C11 - 2C66 & 0 \\ C11 - 2C66 & C11 & 0 \\ 0 & 0 & C66 \end{bmatrix} \right\} - \frac{C13}{C33} \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Subtracting group element of fracture $g_f(3)$, from the fractured medium group

$$[H, H\rho, g(3) - g_f(3), g(4), g(5),]$$



$$g_f(3) = \begin{bmatrix} Z_N & 0 & 0 \\ 0 & Z_T & 0 \\ 0 & 0 & Z_T \end{bmatrix}$$

Group theory

Fractured media decomposed into fracture medium and background medium

The background medium stiffness moduli 6x6 matrix

$$\begin{bmatrix} C_{11} + \frac{C_{13}^2 Z_N}{1 - C_{33} Z_N} & C_{11} + 2C_{66} \frac{C_{13}^2 Z_N}{1 - C_{33} Z_N} & \frac{C_{13}}{1 - C_{33} Z_N} & 0 & 0 & 0 \\ C_{11} + 2C_{66} \frac{C_{13}^2 Z_N}{1 - C_{33} Z_N} & C_{11} + \frac{C_{13}^2 Z_N}{1 - C_{33} Z_N} & \frac{C_{13}}{1 - C_{33} Z_N} & 0 & 0 & 0 \\ \frac{C_{13}}{1 - C_{33} Z_N} & \frac{C_{13}}{1 - C_{33} Z_N} & \frac{C_{13}}{1 - C_{33} Z_N} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{C_{44}}{1 - C_{44} Z_T} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{C_{44}}{1 - C_{44} Z_T} & 0 \\ 0 & 0 & 0 & 0 & C_{65} & C_{66} \end{bmatrix}$$

Fractured media ← Fracture + background

Fractured media – Fracture → background

Group theory

Fractured media decomposed into fracture and background medium

Fracture compliances with a isotropic background medium:

$$Z_T = \frac{1}{C_{44}} - \frac{1}{C_{66}} \quad Z_N = \frac{1}{C_{33}} \left[1 - \frac{C_{33} - C_{13}}{2C_{66}} \right]$$

$$E_T = \mu Z_T = \frac{C_{66}}{C_{44}} - 1 \quad E_N = (2\mu + \lambda) Z_N = \frac{2C_{66}}{C_{33} - C_{13}} - 1$$

$$S_T = \frac{E_T H}{\mu} \quad S_N = \frac{E_N H}{2\mu + \lambda}$$

Conclusion

- The linear slip interface (non-welded contact) exhibits displacement discontinuity and stress continuity inherent in the boundary conditions.
- In the long wavelength assumption, the linear slip interface can simulate the fracture and moduli can be derived so that fractured medium can be described with four parameters μ , λ , E_N and E_T .
- Group theory can decompose fractured media into a fracture medium and a background medium.

Future work

- Model horizontal and vertical fractures (linear slip interface) embedded in isotropic or anisotropic background media.
- Study a medium moduli of the non-linear slip interface by considering the viscosity parameter.
- Study a case of fractured media-wormholes caused by cold heavy oil production.

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Acknowledgements

- Thanks to CREWES and CHORUS sponsors.
- Thanks to Dr. E.S Krebes.
- Thanks to Zaiming Jiang for discussion.

Thank you!