Understanding the Evolving Seismic Wavelet

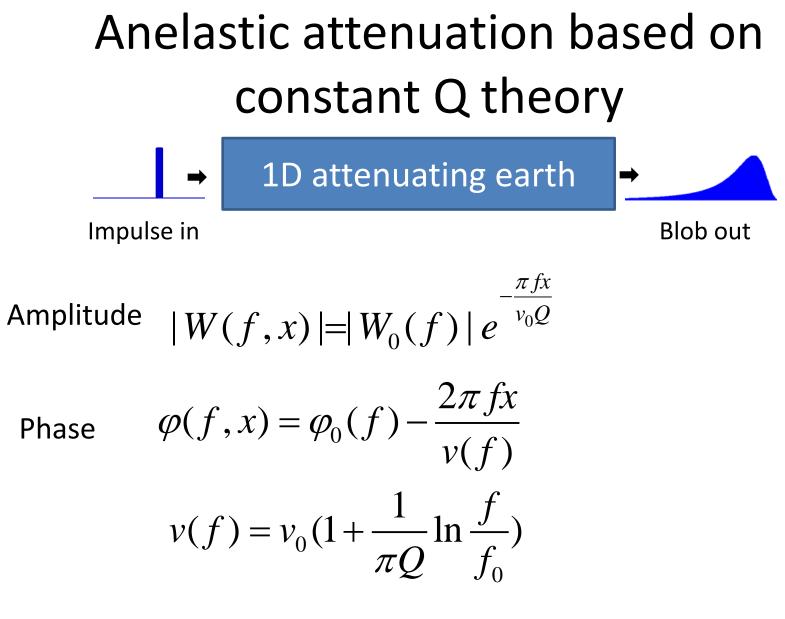
Tianci Cui Gary F. Margrave





Outline

- Anelastic attenuation based on constant Q theory
- Continuous and discrete minimum-phase wavelets
- Minimum phase and linear phase wavelets
- Conclusions



Kjartanssen (1979, Geophysics)

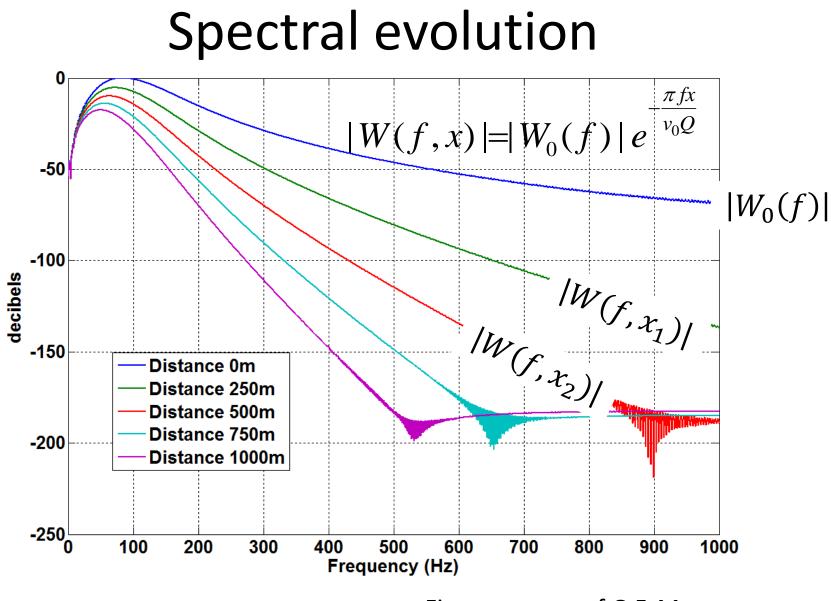
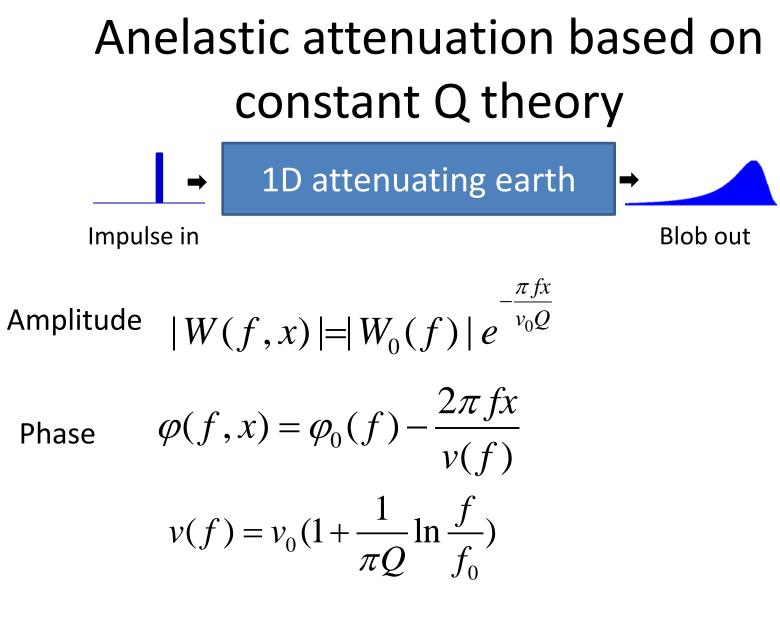


Figure curtesy of G.F. Margrave



Kjartanssen (1979, Geophysics)

Frequency dependence of velocity

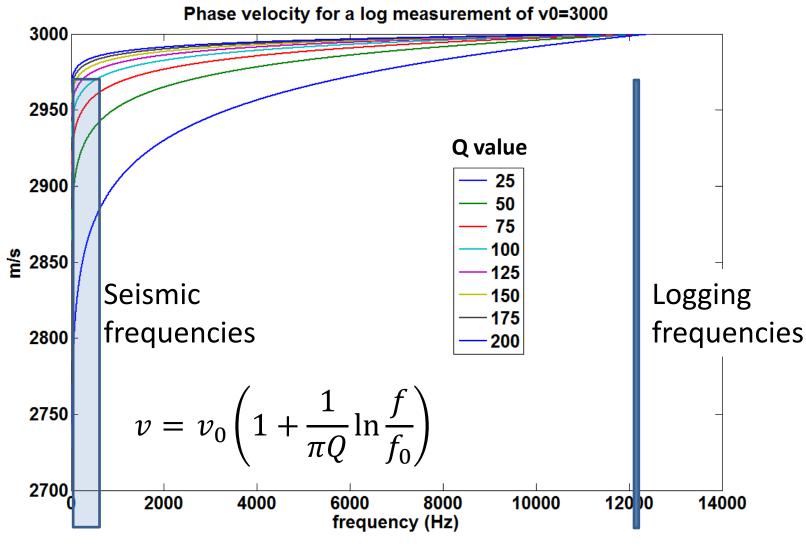
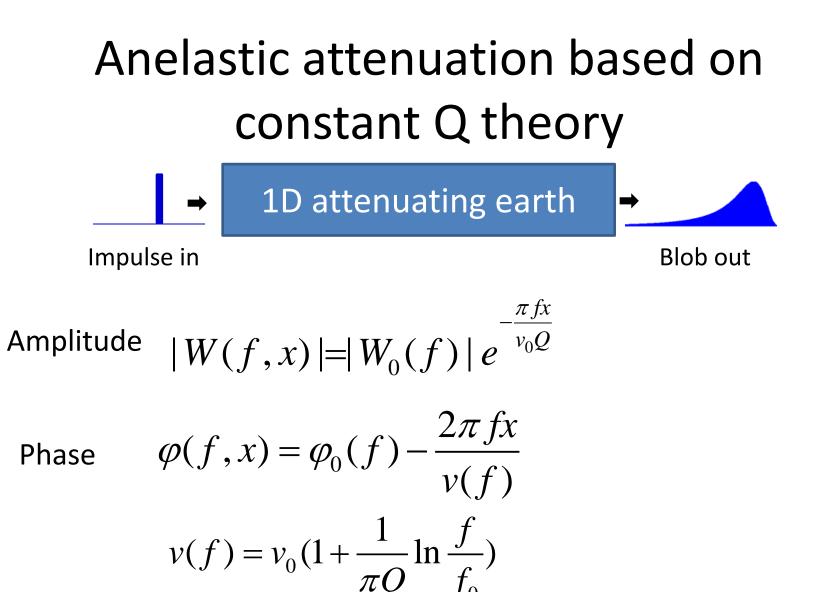
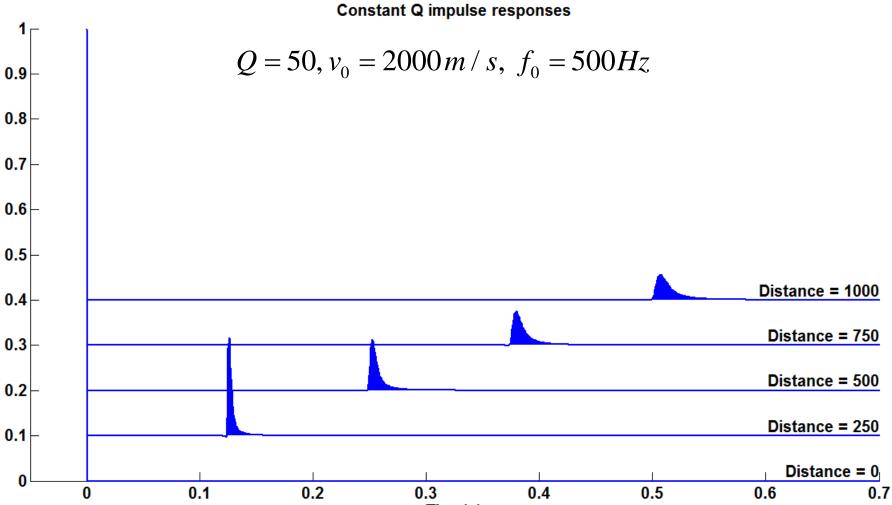


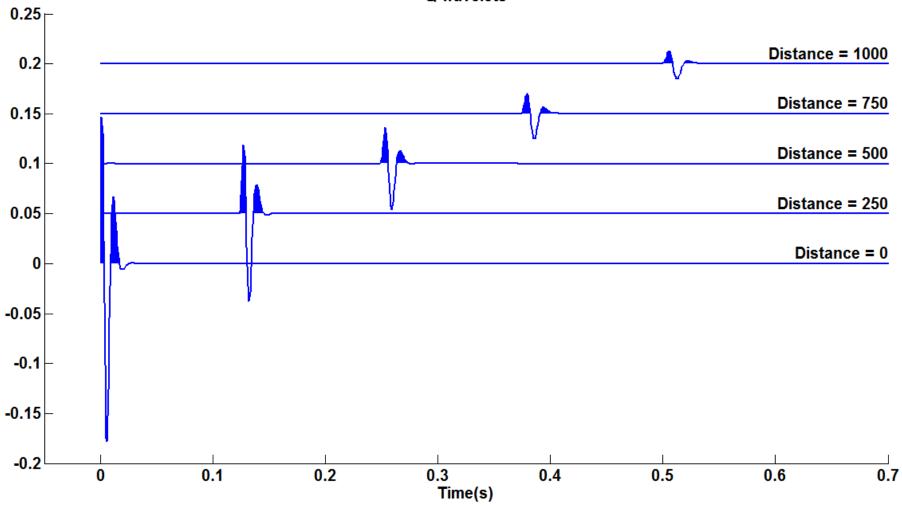
Figure curtesy of G.F. Margrave



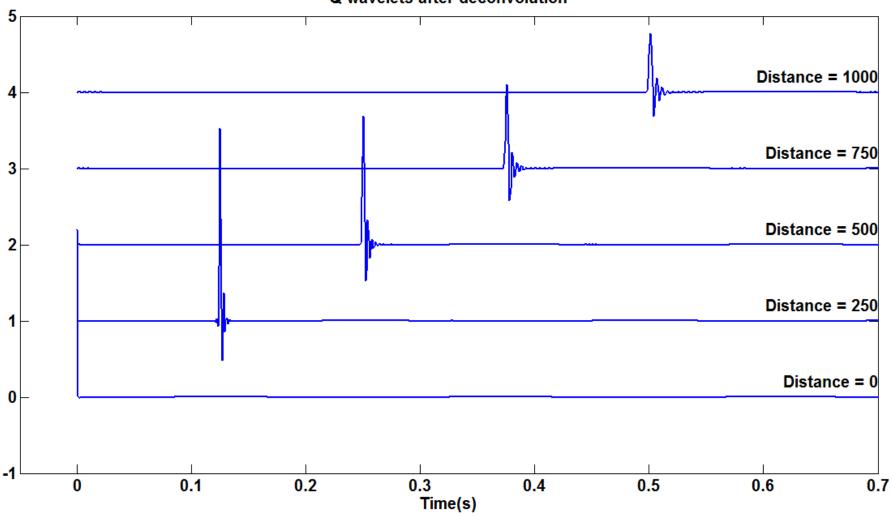
Kjartanssen (1979, Geophysics)



Time(s)



Q wavelets



Q wavelets after deconvolution

Continuous and discrete minimum-phase wavelets

Q wavelets are based on physical model. They are **continuous** minimum-phase wavelets

Deconvolution is designed for **discrete** minimumphase wavelets

Discrete minimum-phase wavelet

A causal wavelet with a stable causal inverse is a minimum phase wavelet

$$\begin{pmatrix} w(0) & 0 & 0 \\ w(1) & w(0) & 0 \\ w(2) & w(1) & w(0) \\ 0 & w(2) & w(1) \end{pmatrix} \begin{pmatrix} w_{inv}(0) \\ w_{inv}(1) \\ w_{inv}(2) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} w(0) & w(1) & w(2) \\ 0 & w(0) & w(1) \end{pmatrix} \begin{pmatrix} w(0) & 0 & 0 \\ w(1) & w(0) & 0 \\ w(2) & w(1) & w(0) \\ 0 & w(2) & w(1) \end{pmatrix} \begin{pmatrix} w_{inv}(0) \\ w_{inv}(1) \\ w_{inv}(2) \end{pmatrix} = \begin{pmatrix} w(0) & w(1) & w(2) & 0 \\ 0 & w(0) & w(1) & w(2) \\ 0 & 0 & w(0) & w(1) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

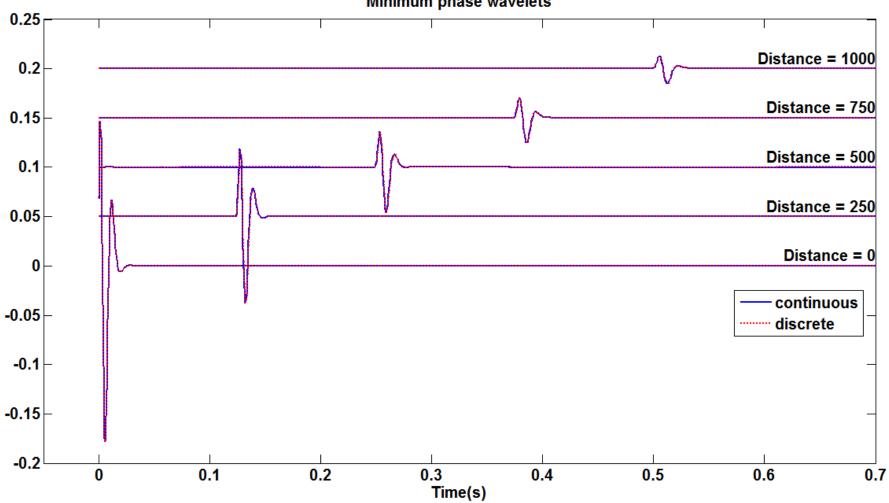
 $\begin{vmatrix} 0\\0 \end{vmatrix}$

Double deconvolution method

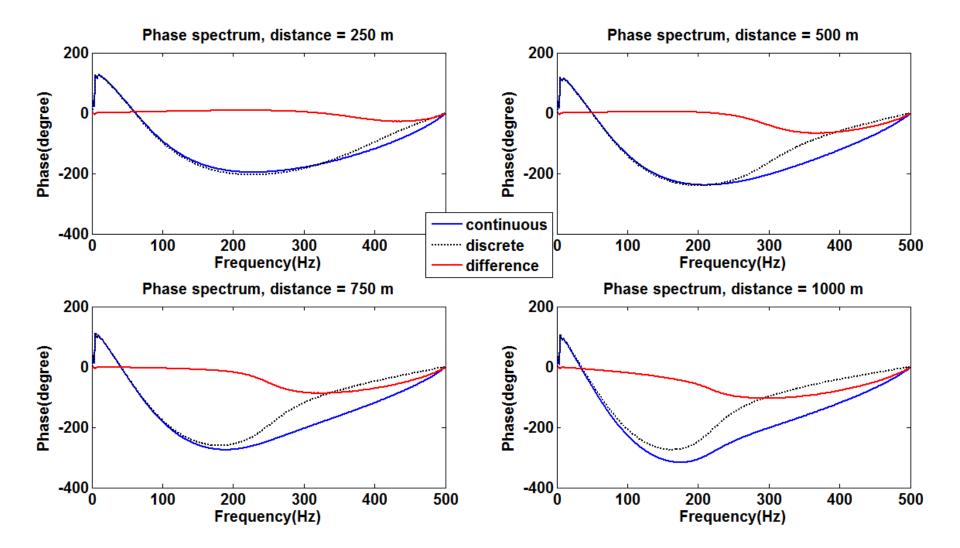
$$\begin{pmatrix} \phi_{w}(0) & \phi_{w}(1) & \phi_{w}(2) \\ \phi_{w}(1) & \phi_{w}(0) & \phi_{w}(1) \\ \phi_{w}(2) & \phi_{w}(1) & \phi_{w}(0) \end{pmatrix} \begin{pmatrix} w_{inv}(0) \\ w_{inv}(1) \\ w_{inv}(2) \end{pmatrix} = \begin{pmatrix} w(0) \\ 0 \\ 0 \end{pmatrix}$$

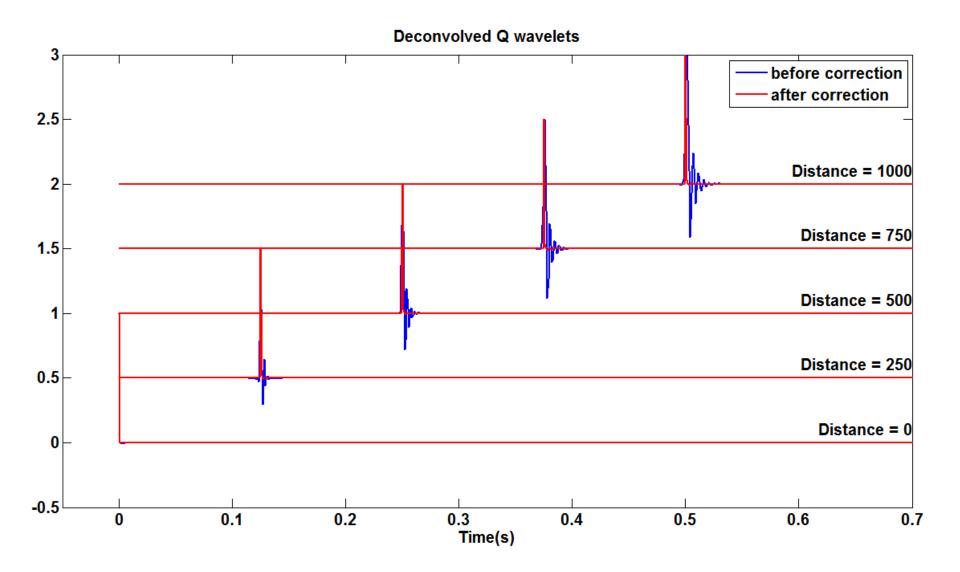
$$FT(\phi_w) = |\tilde{W}(f)|^2$$

$$\begin{pmatrix} w(0) \\ w(1) \\ w(2) \end{pmatrix} = inv \begin{pmatrix} w_{inv}(0) \\ w_{inv}(1) \\ w_{inv}(2) \end{pmatrix}$$

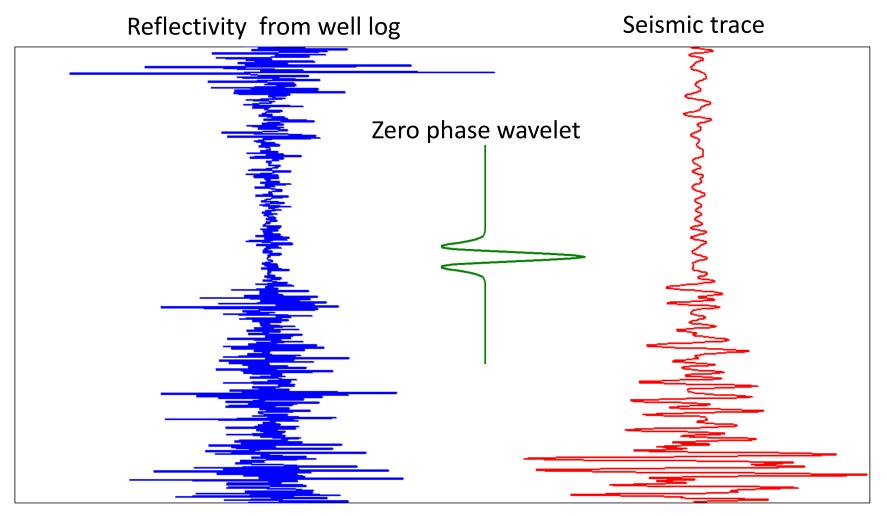


Minimum phase wavelets



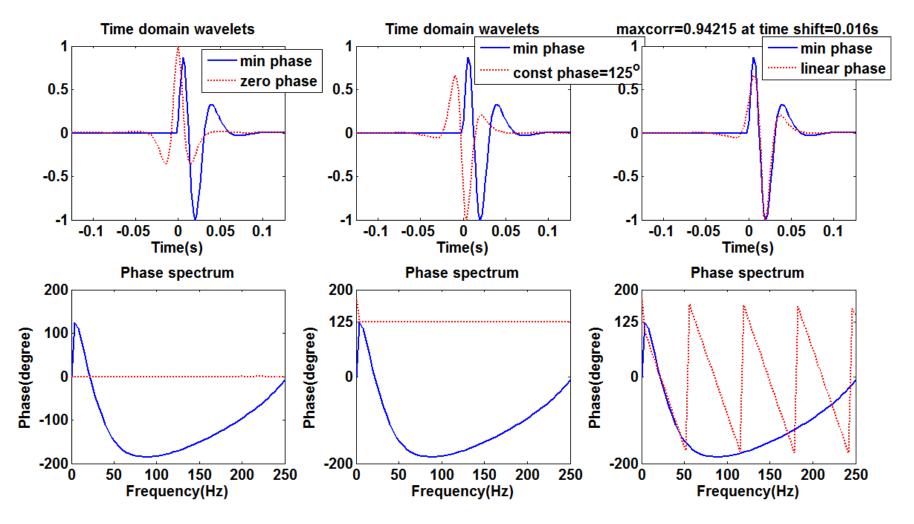


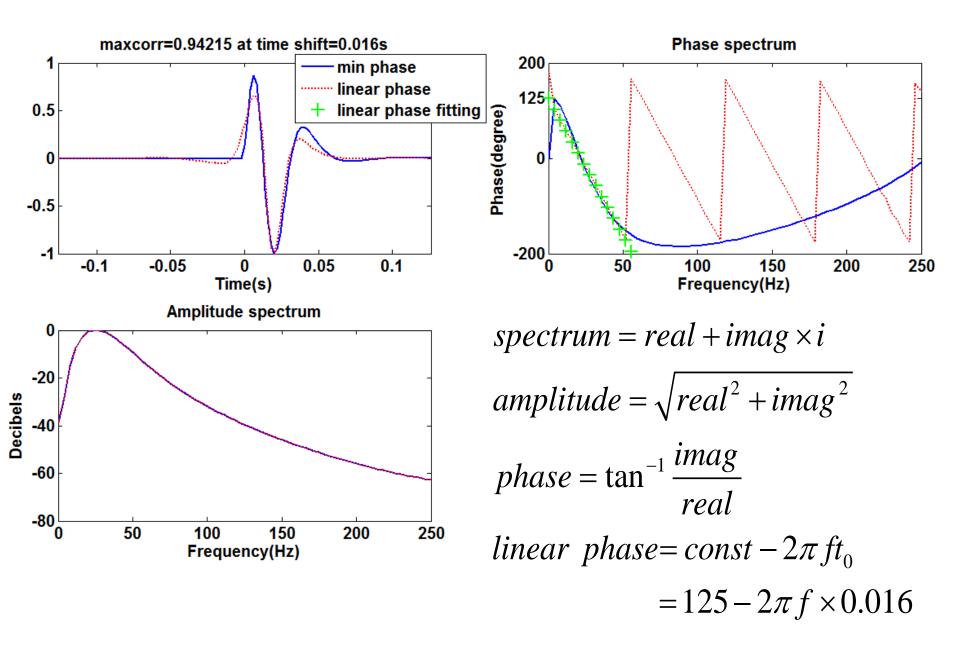
Minimum phase wavelet and linear phase wavelet



Stretch and squeeze - time shift Constant phase rotation - constant phase

Finding the most similar linear phase wavelet to a minimum phase wavelet





Conclusions

- Continuous and discrete minimum-phase wavelets are different. After correcting continuous minimum-phase wavelets to discrete ones, deconvolution can get nice spikes.
- Some minimum phase wavelets can be modeled by constant phase rotation plus time shift.

Future work

- Design a time-variant operator to correct continuous minimum-phase wavelets to discrete ones
- Conduct stationary and nonstationary deconvolution on nonstationary trace; model the residual wavelets by constant phase rotation plus time shift

Acknowledgements

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Questions and Comments