

Comparison of MEMS accelerometers and geophones at Spring Coulee, Alberta



Michael Hons and Rob Stewart

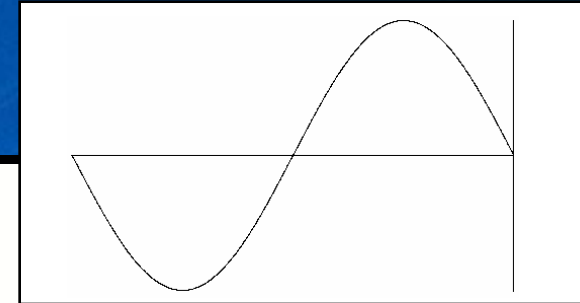
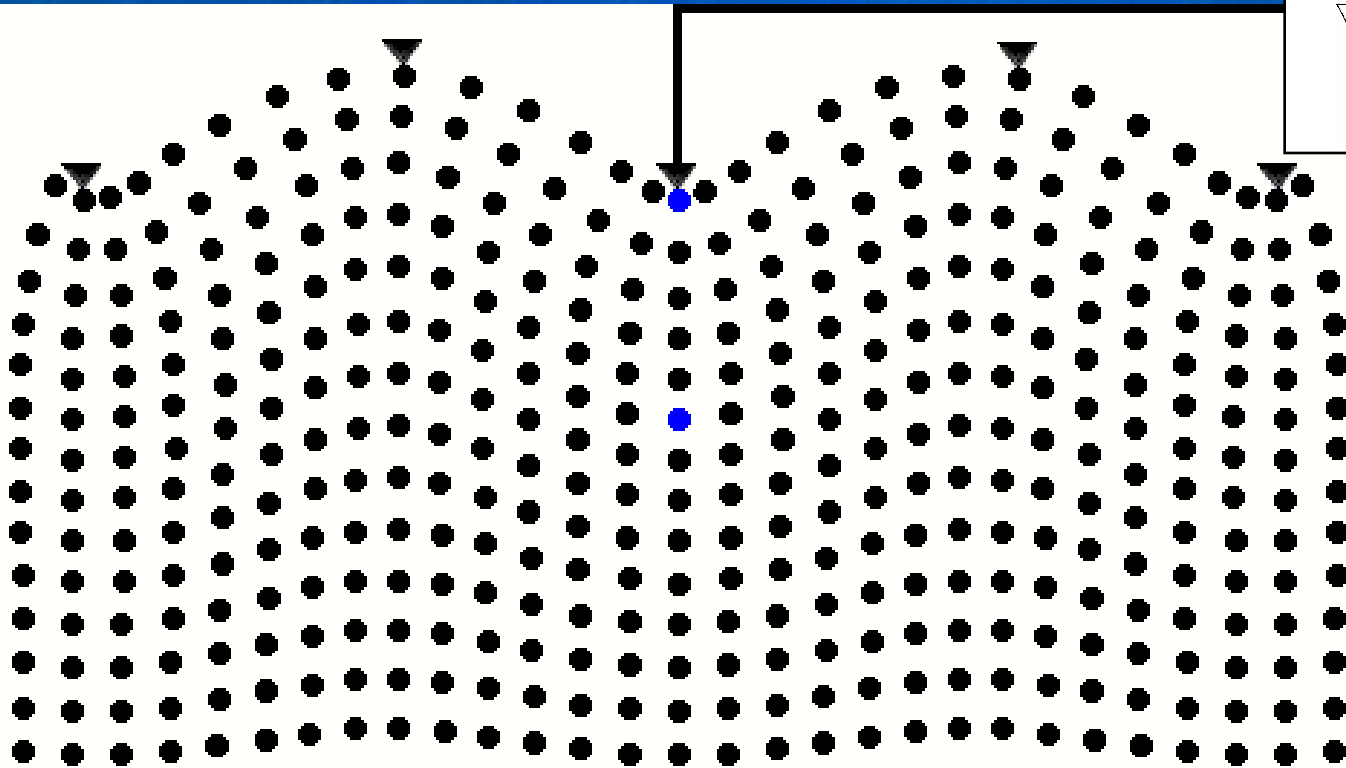
CREWES Sponsors Meeting 2008
Canmore, Alberta

Outline

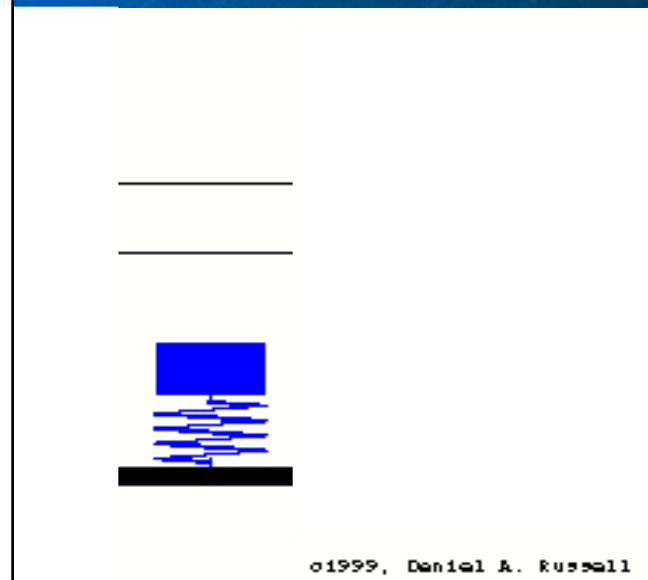
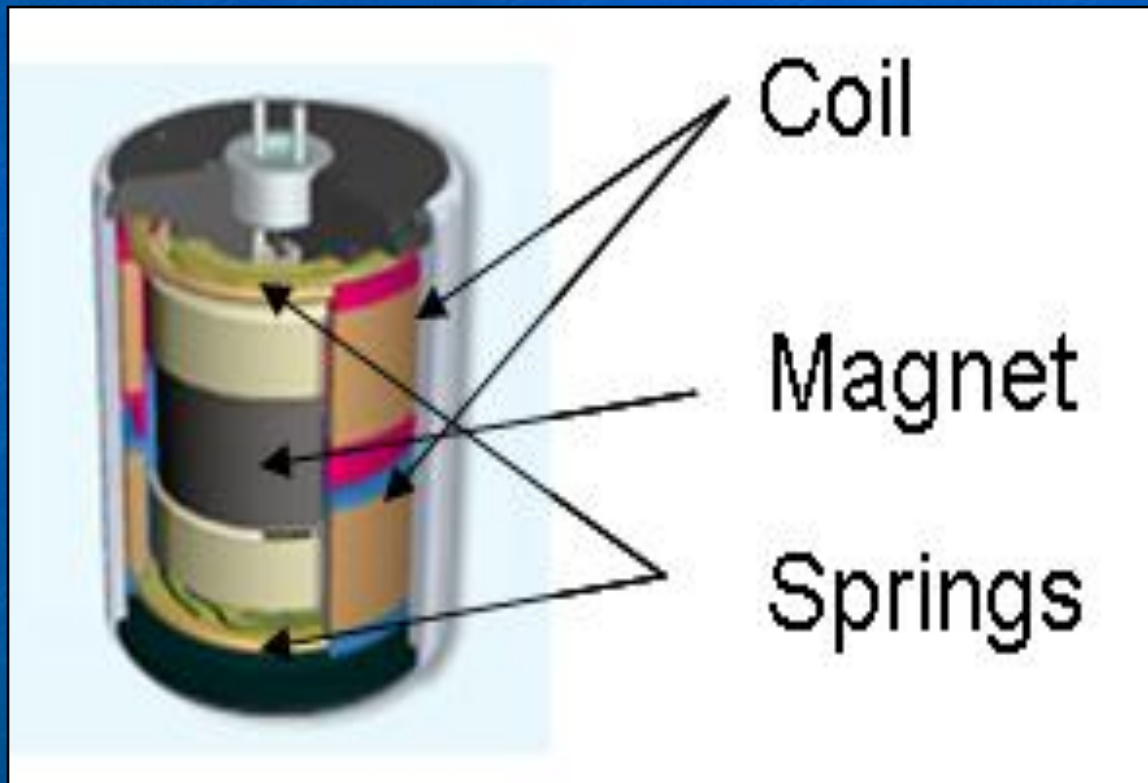
- Data correction
- Field Data
- Comparisons
 - Corrected data
 - Crosscorrelation
 - Noise window comparison
 - Trace coherence
- Conclusions

Motion sensing

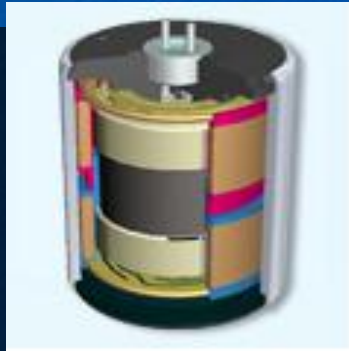
Rayleigh waves



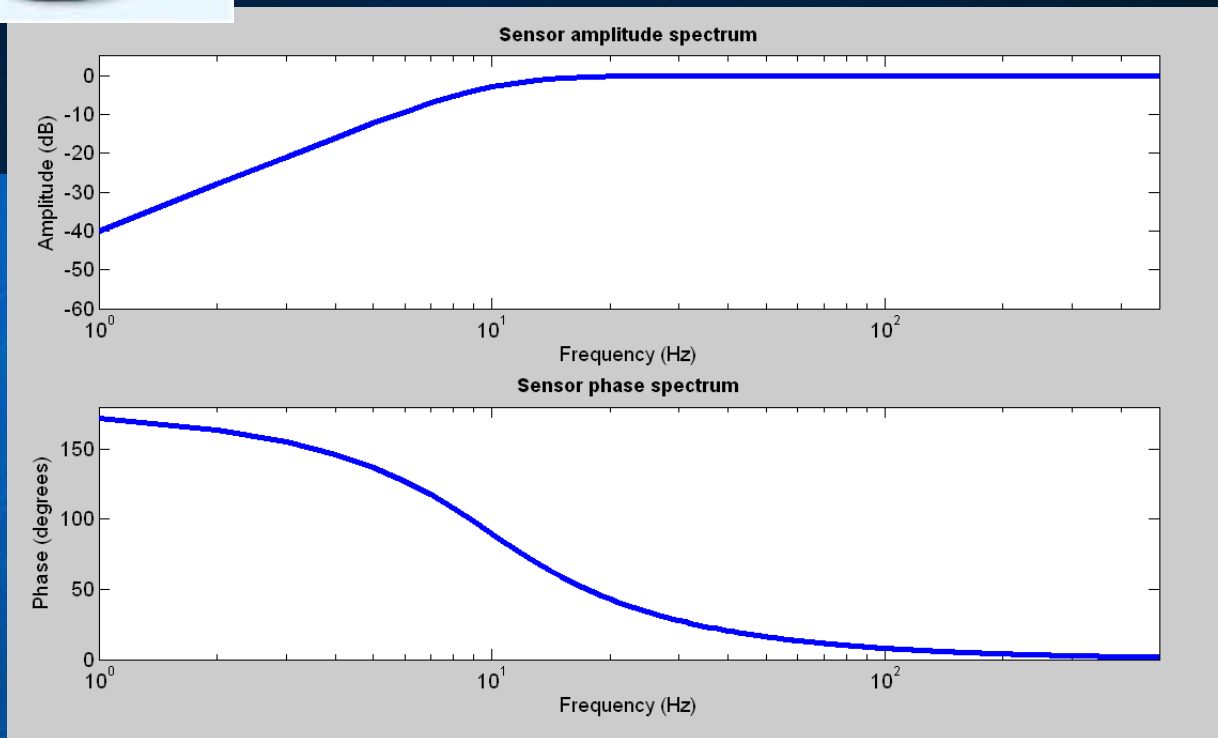
Geophones



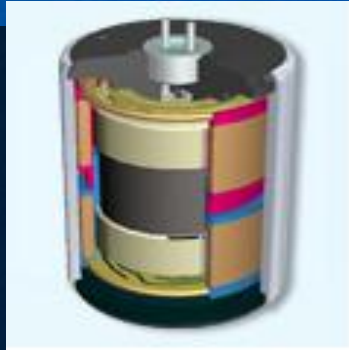
Geophone response



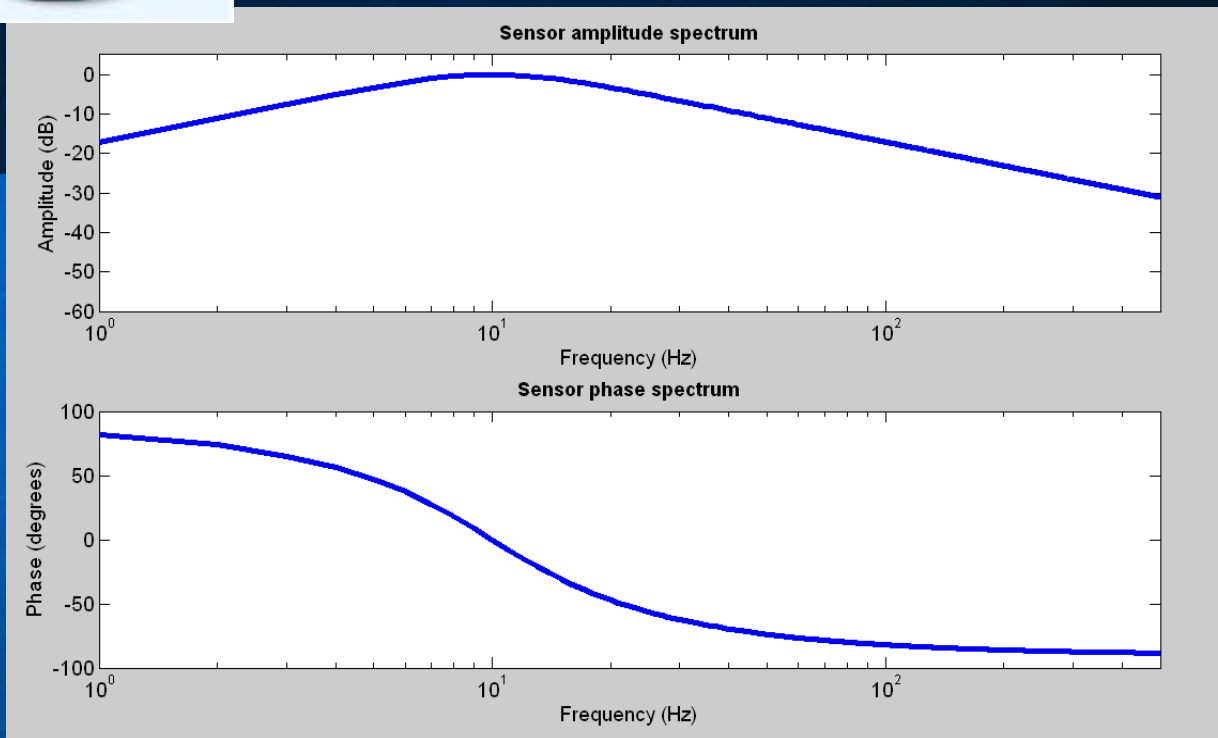
$$\frac{\partial X}{\partial t} = \frac{-\omega^2}{-\omega^2 + 2i\lambda\omega\omega_0 + \omega_0^2} \frac{\partial U}{\partial t}$$



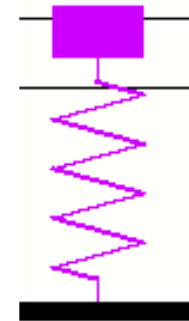
Geophone response



$$\frac{\partial X}{\partial t} = \frac{i\omega}{-\omega^2 + 2i\lambda\omega\omega_0 + \omega_0^2} \frac{\partial^2 U}{\partial t^2}$$



MEMS accelerometer

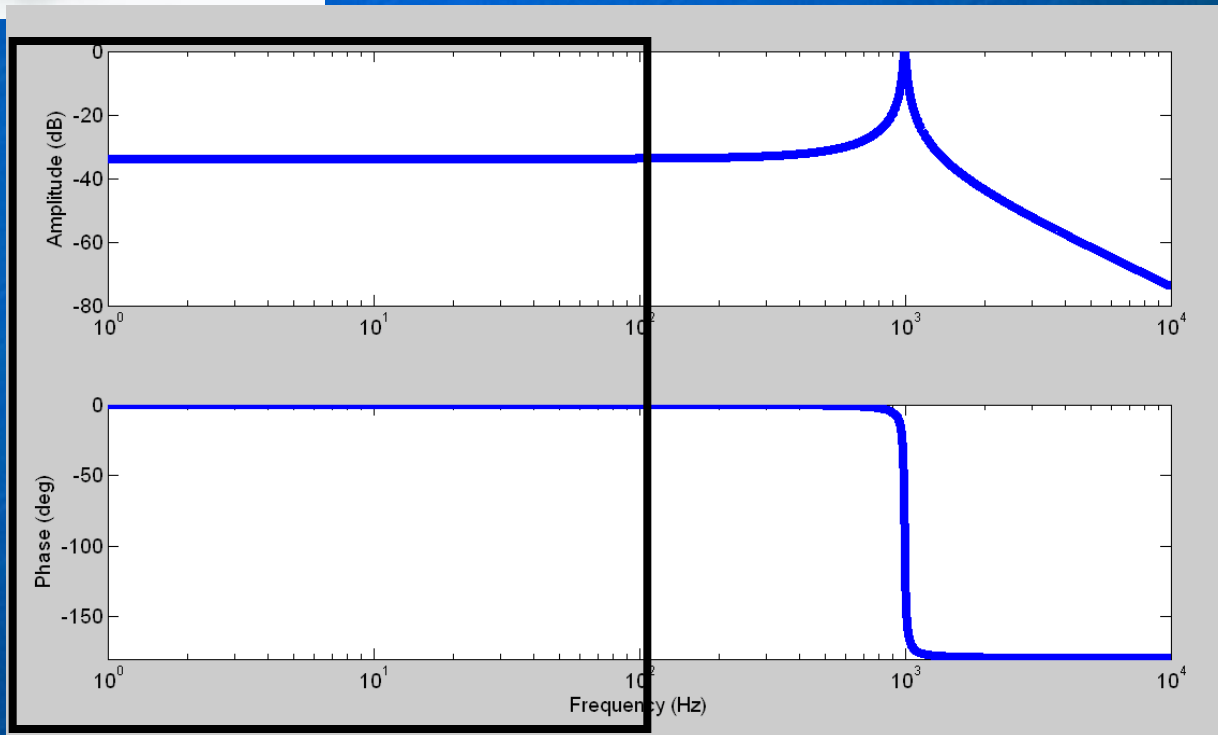


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MEMS accelerometer



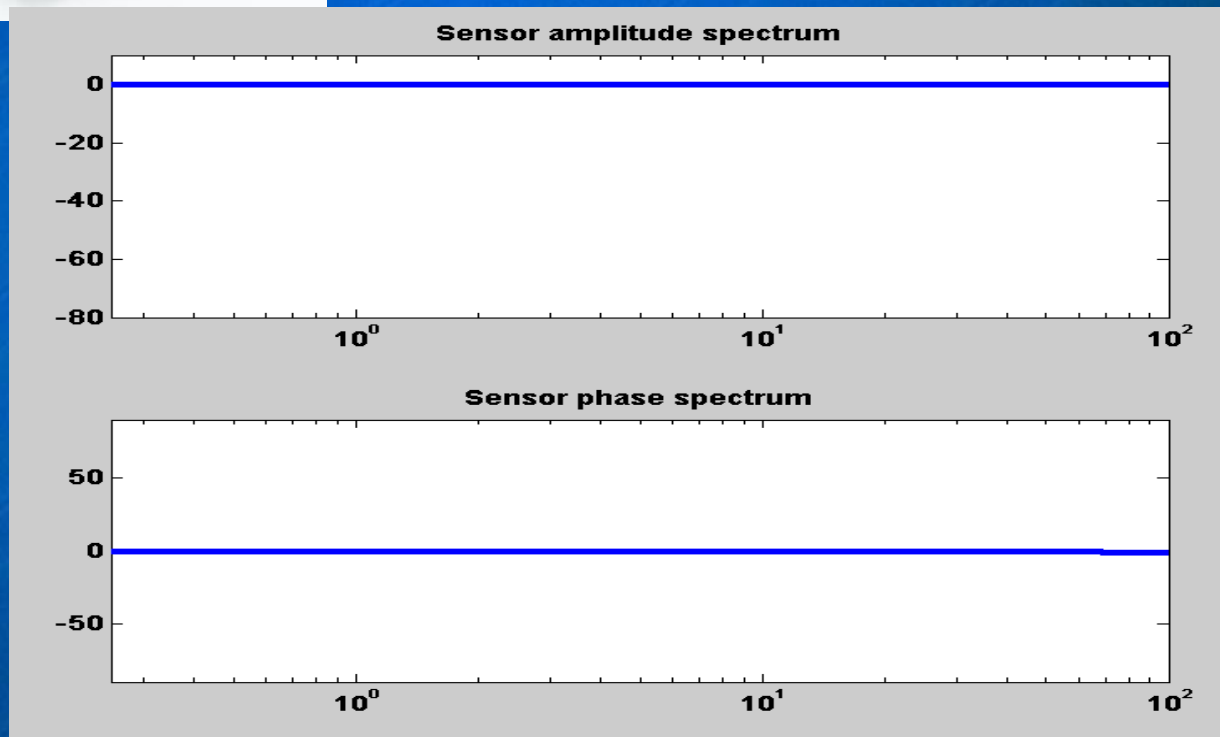
$$X = \frac{1}{-\omega^2 + 2i\lambda\omega_0\omega + \omega_0^2} \frac{\partial^2 U}{\partial t^2}$$



MEMS accelerometer

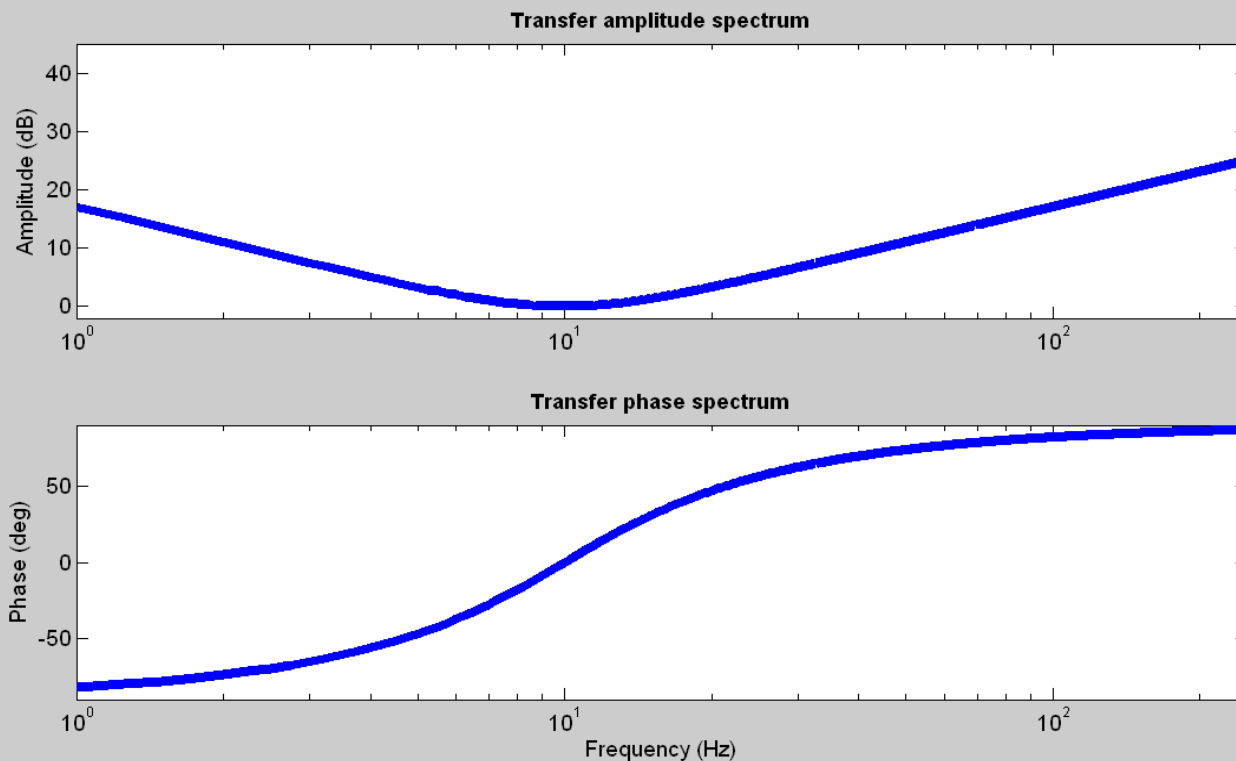


$$X = \frac{1}{\omega_0^2} \frac{\partial^2 U}{\partial t^2}$$



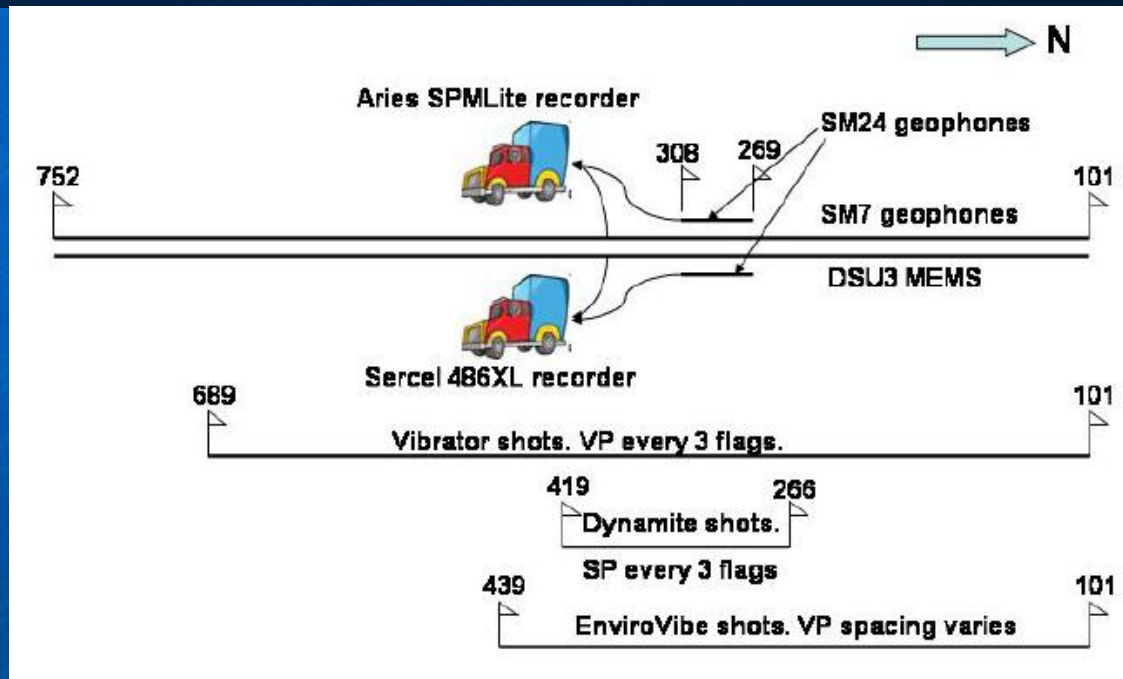
Geophone/Accelerometer transfer

$$\frac{\partial^2 U}{\partial t^2} = \frac{2\lambda\omega\omega_0 + i(\omega_0^2 - \omega^2)}{\omega} \frac{V_G}{S_G}$$



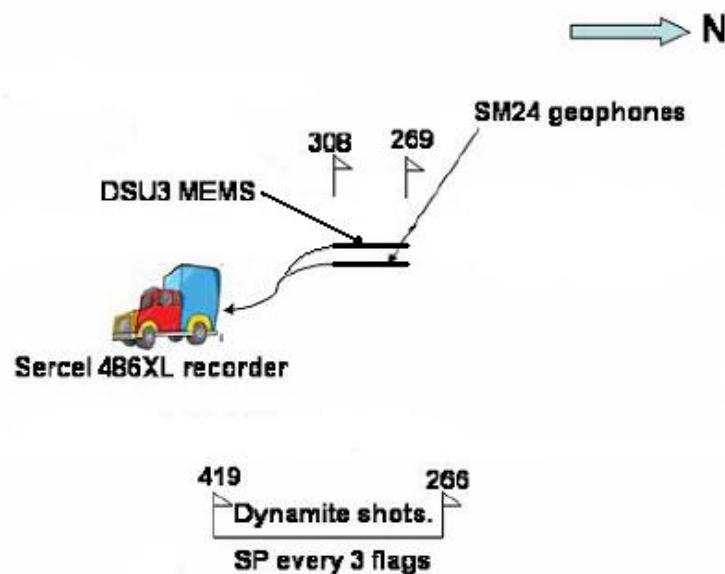
Field Data

- 54 dynamite shots, 40 receivers
- All receivers through Sercel system
- Receivers every 10 m, shots every 30 m
- Maximum offset: 1500 m



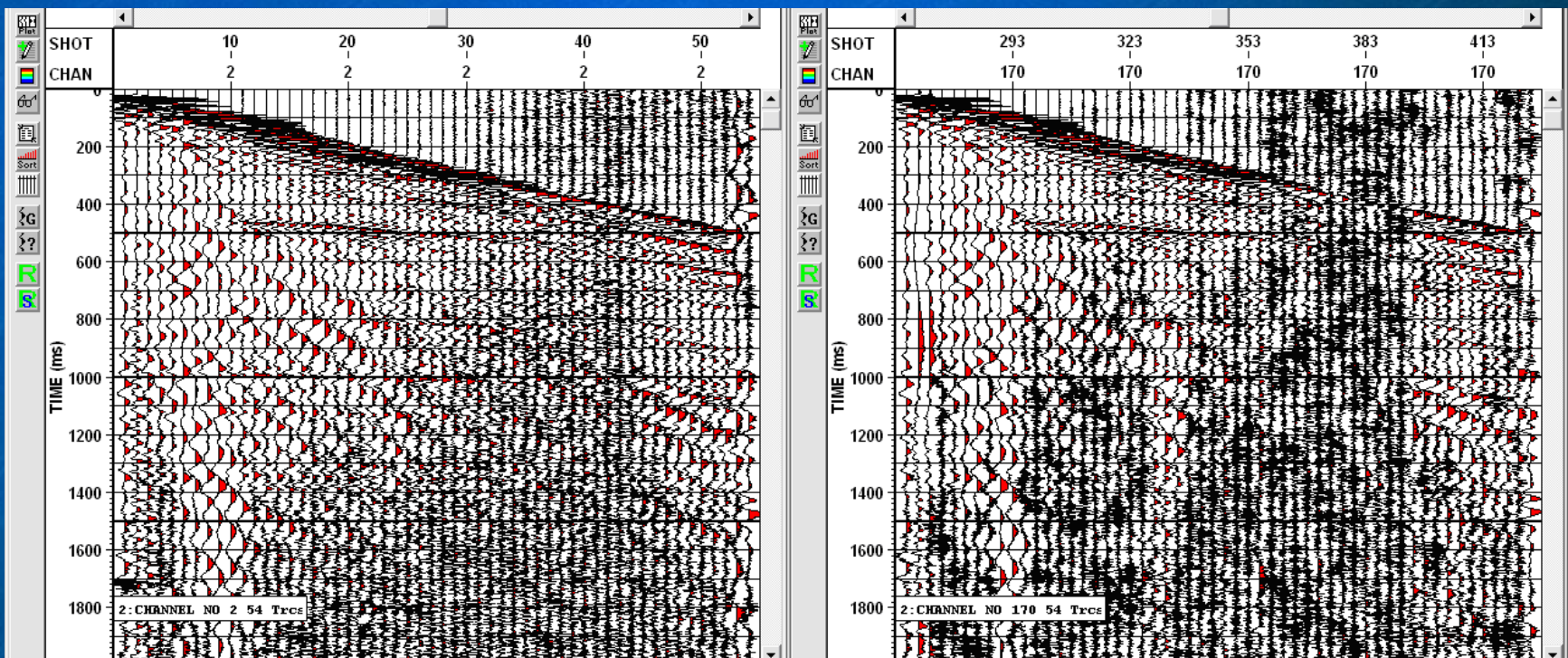
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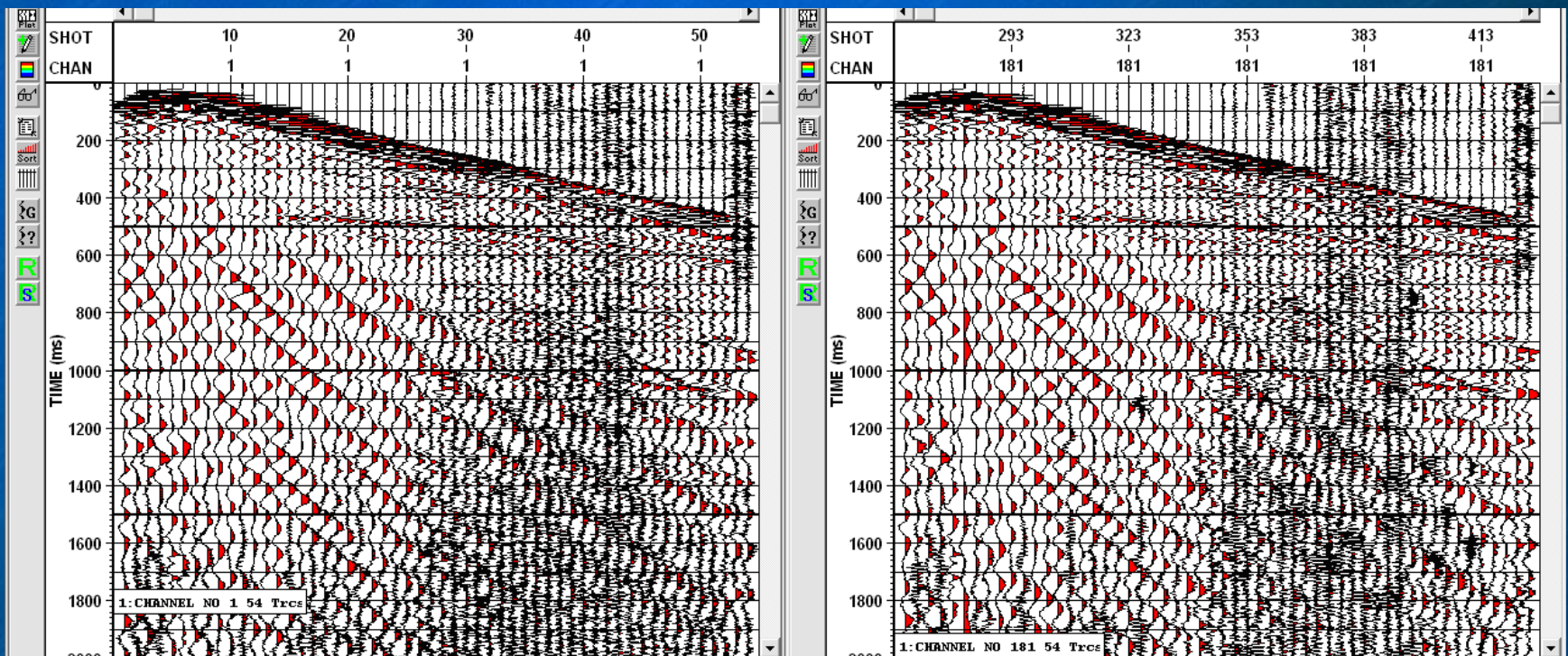
Acceleration receiver gathers

- Acceleration domain, vertical component
- Coupling problems at some stations



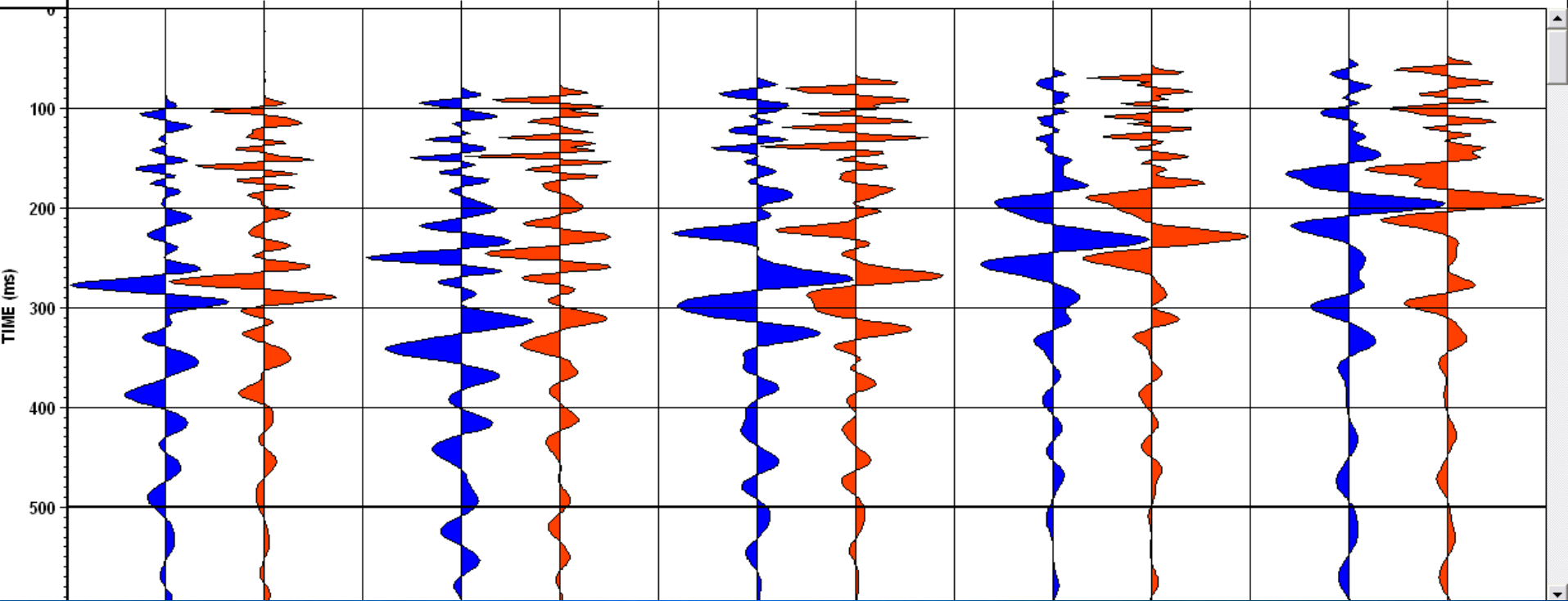
Acceleration receiver gathers

- Not everywhere
- Reflections very similar



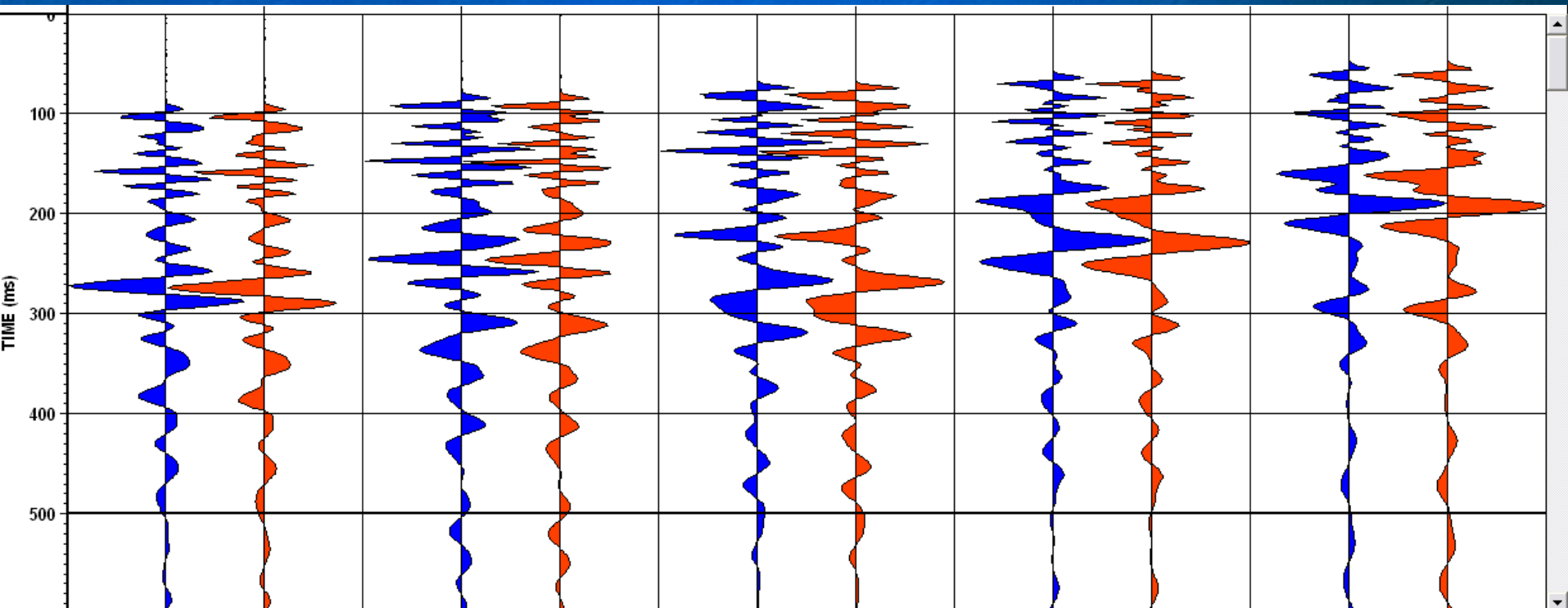
Acceleration traces

- Visually, very similar



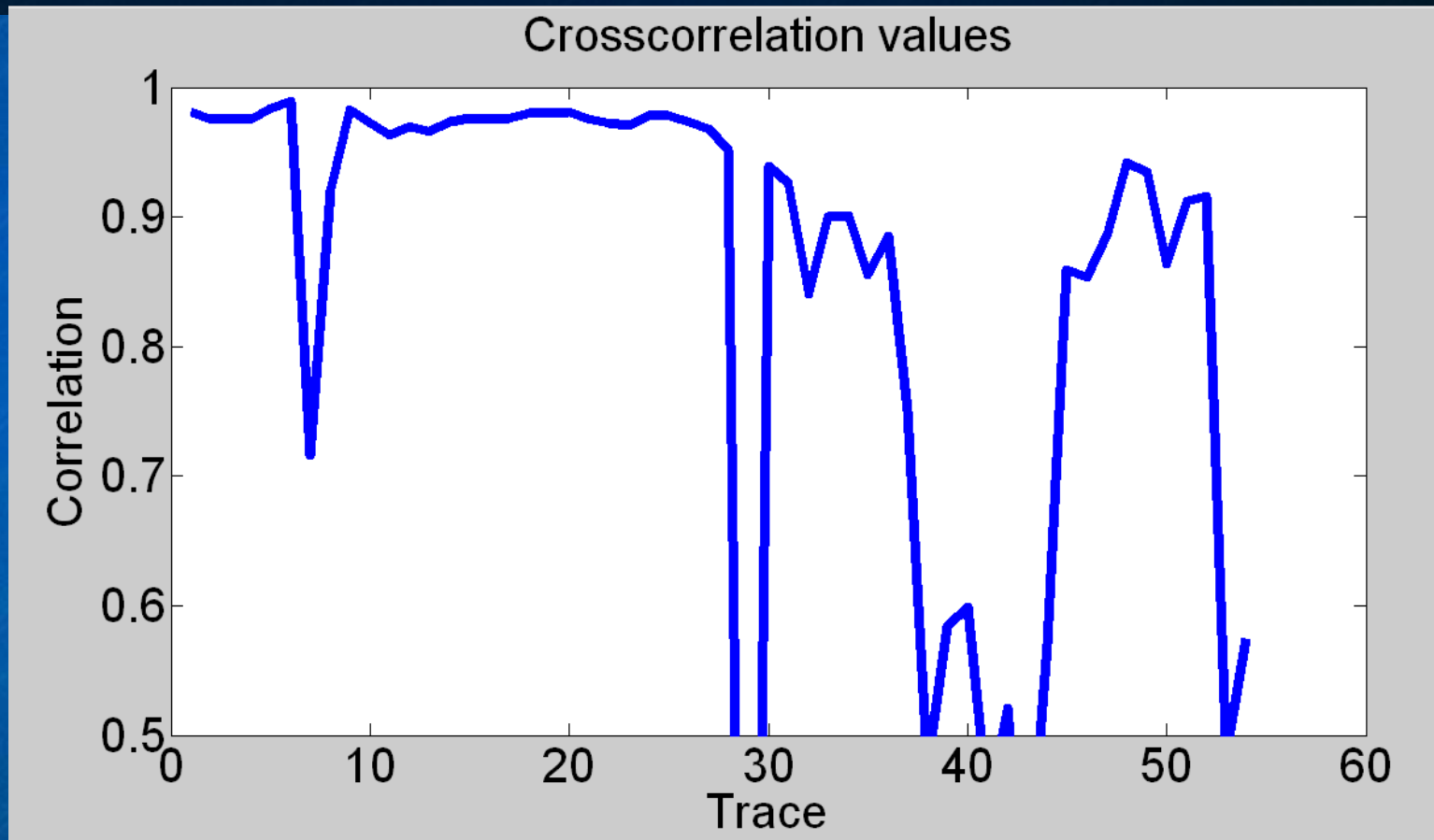
Acceleration traces

- Visually, very similar



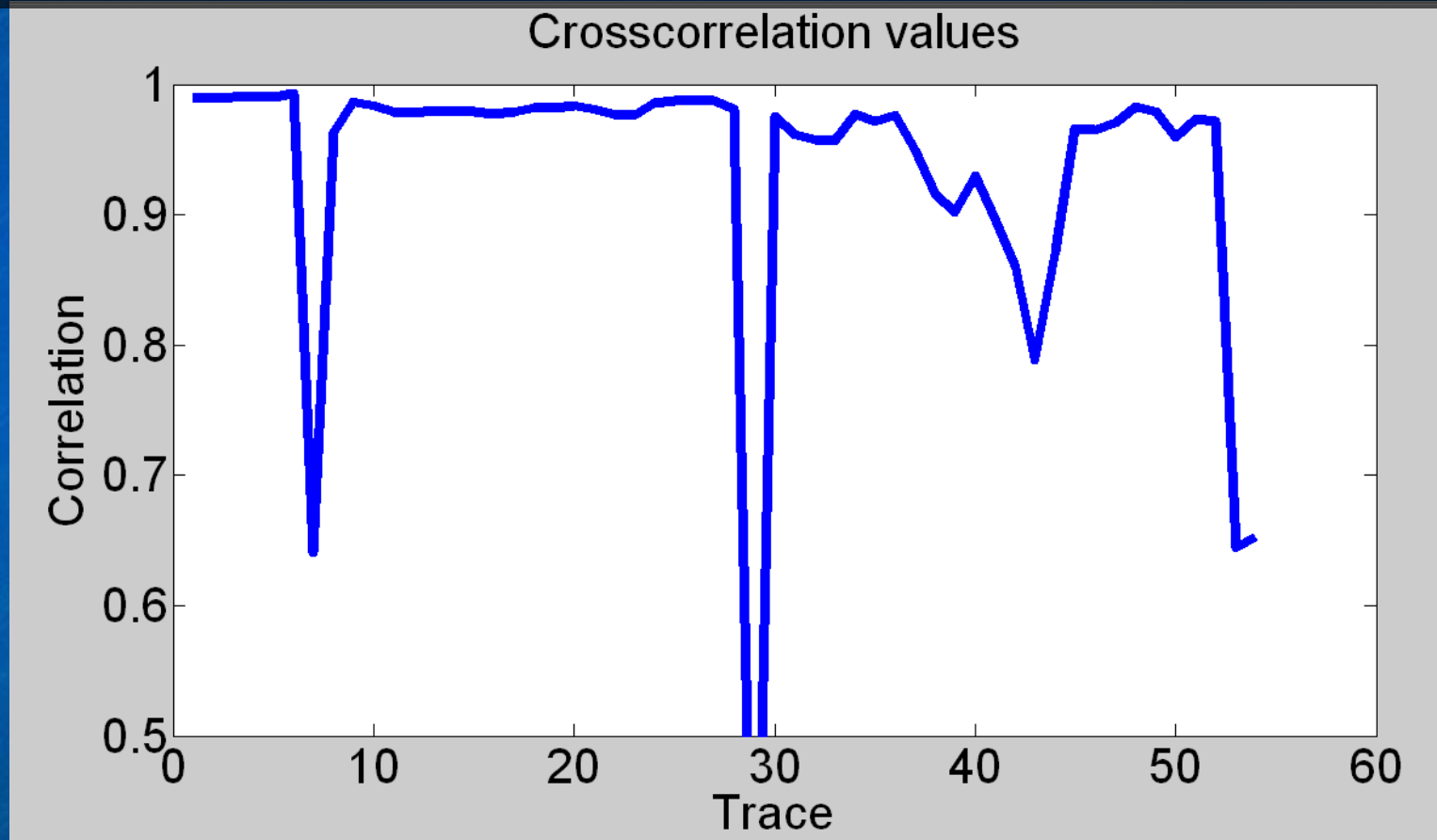
Crosscorrelations

- 3 Hz lowcut



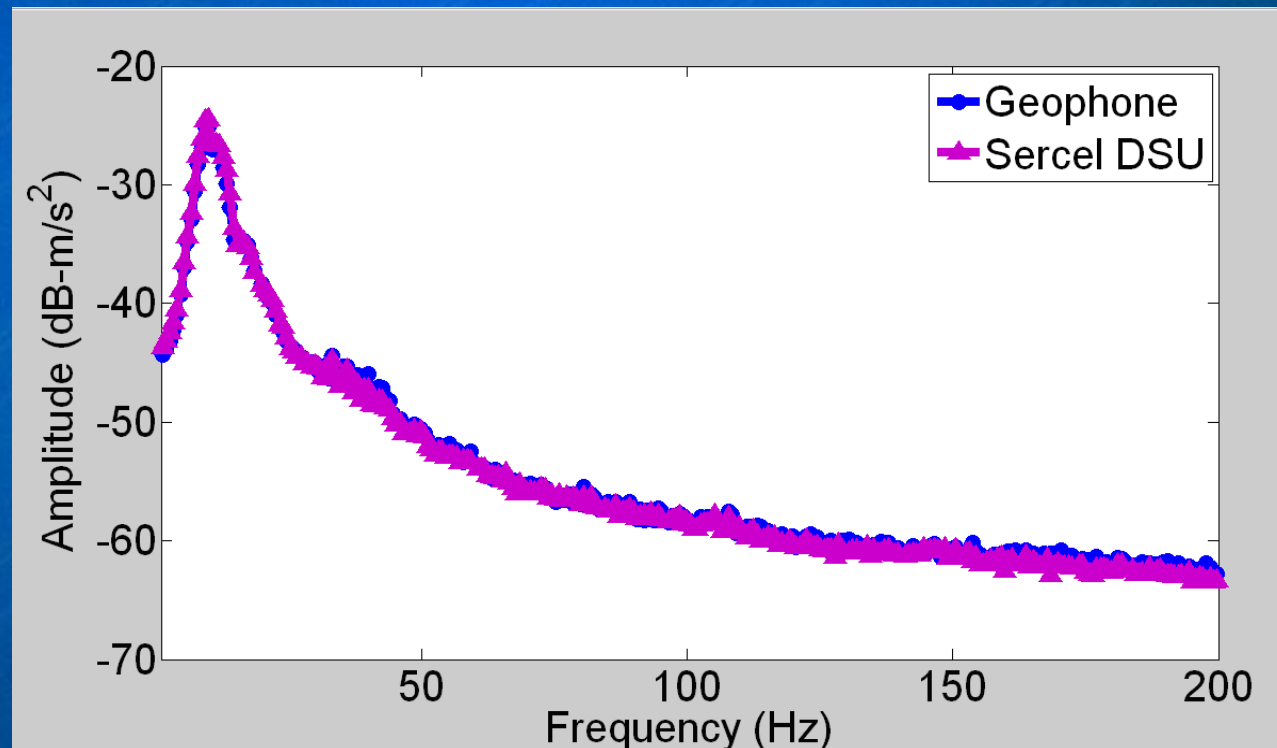
Crosscorrelations

- 3 Hz lowcut + 60 Hz highcut



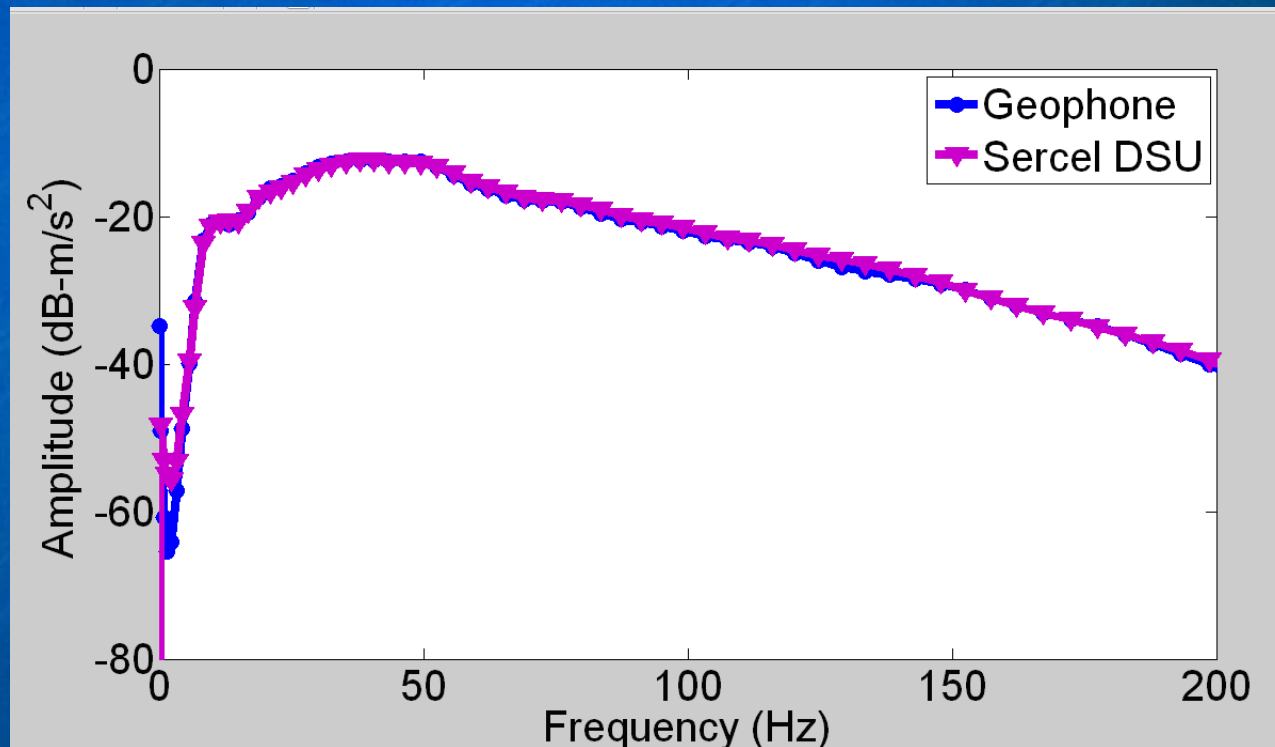
Amplitude spectra

- Very similar at well-planted stations
- Similar overall, larger low-f in DSUs



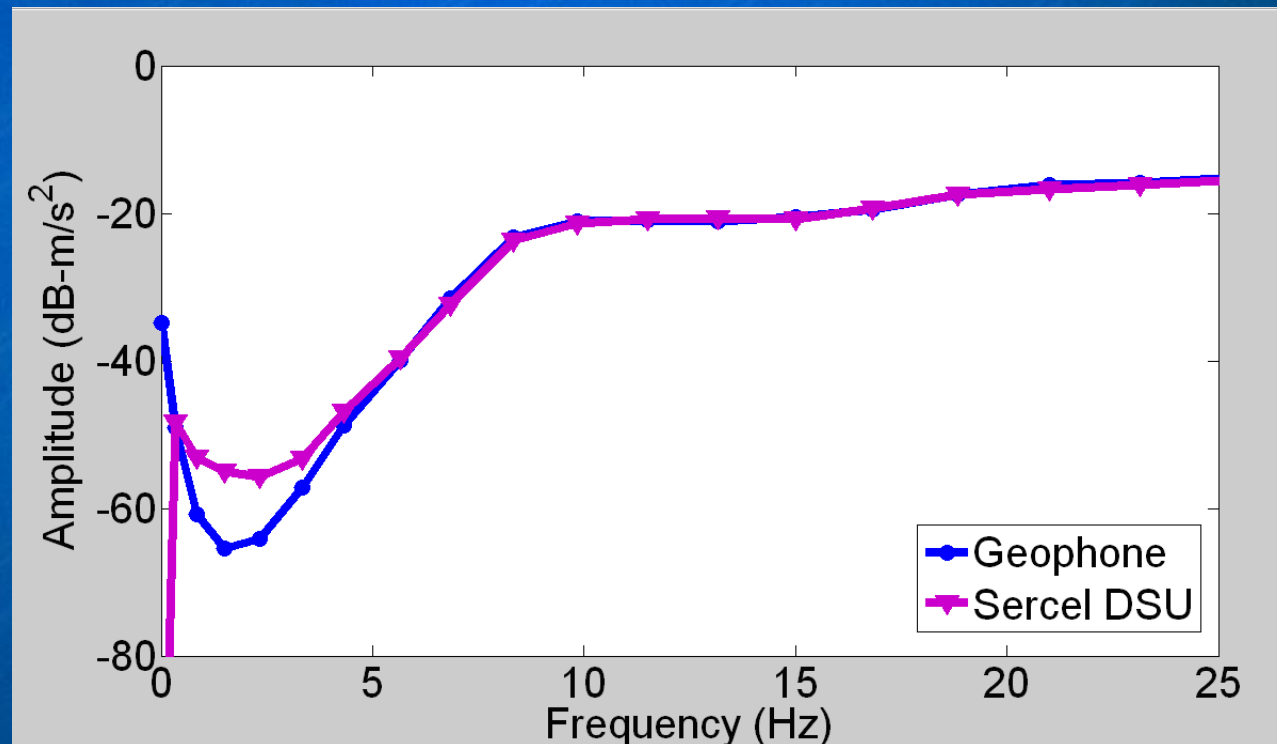
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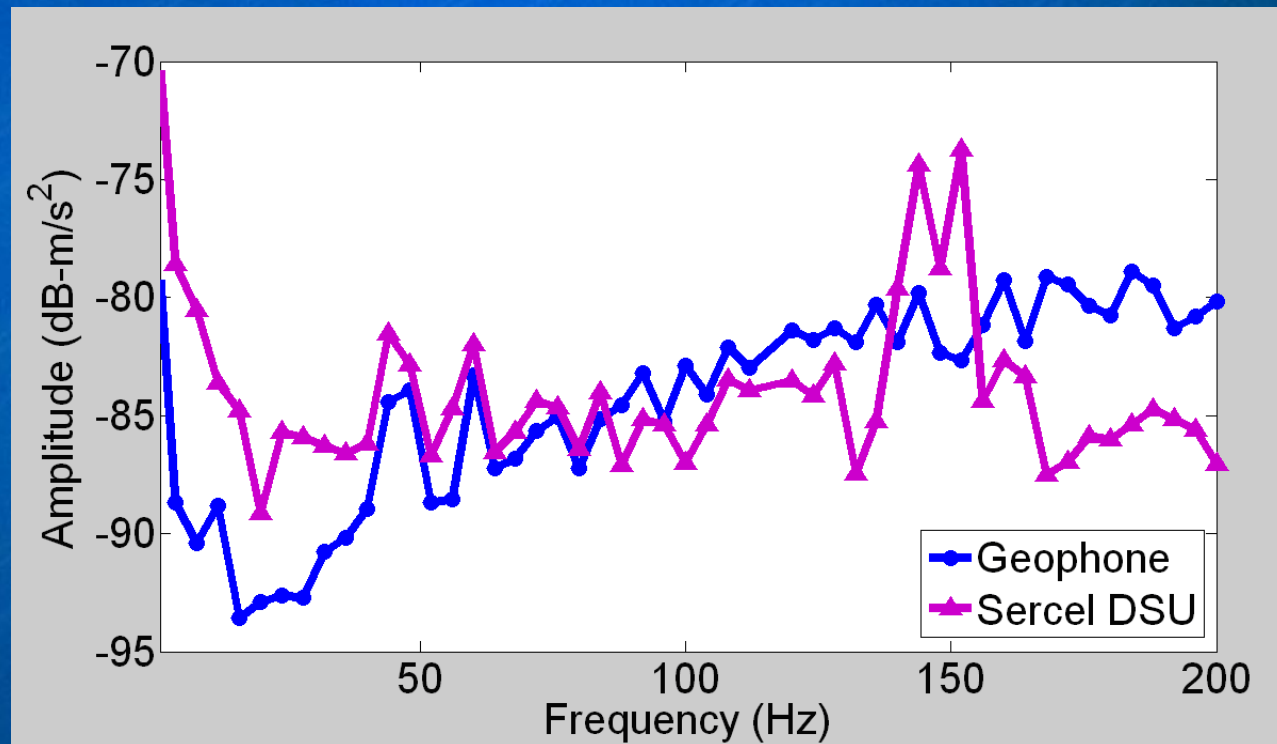
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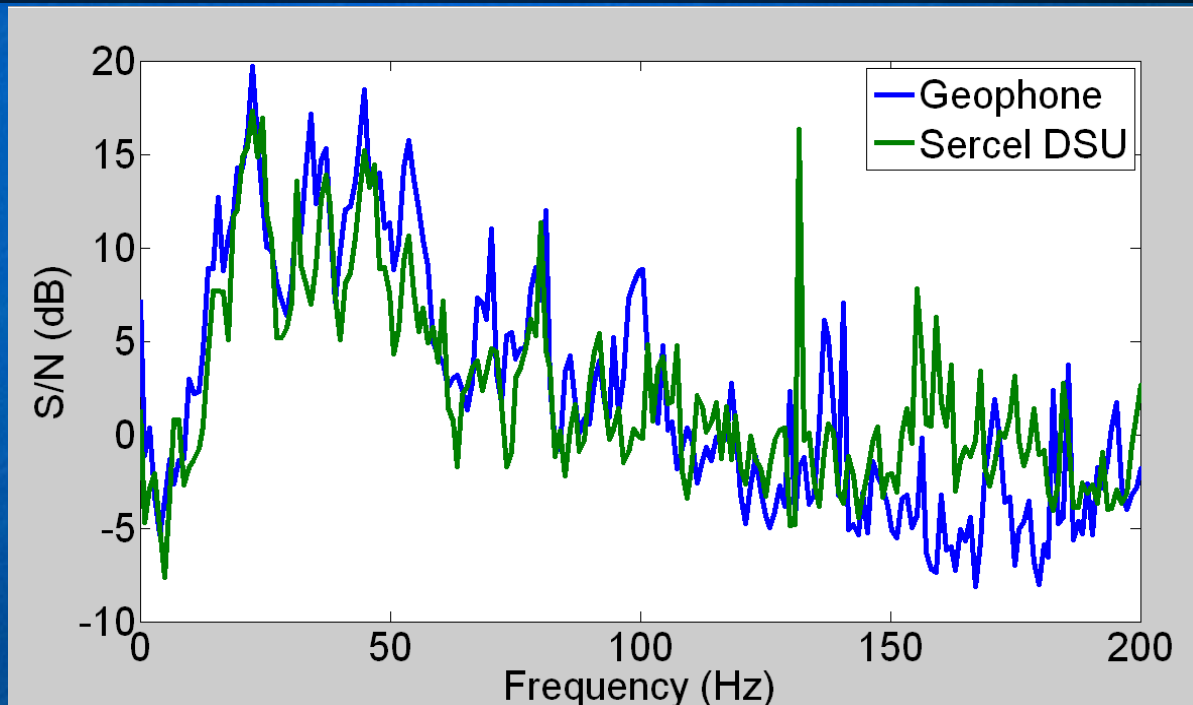
Noise-only spectra

- Before first break arrivals
- Cross-over around 70-80 Hz



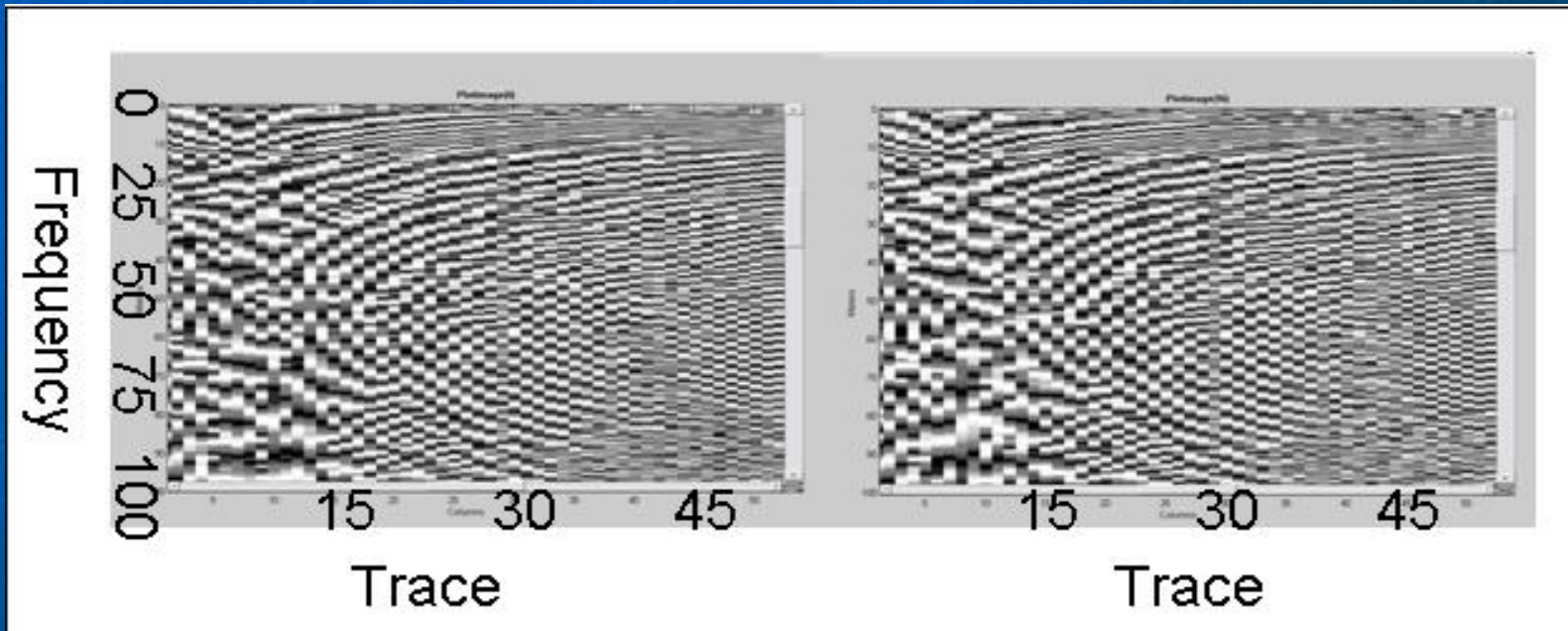
Far-offset SNR

- From traces with >450 ms noise record
- Spectrum from reflection window divided by spectrum from noise window



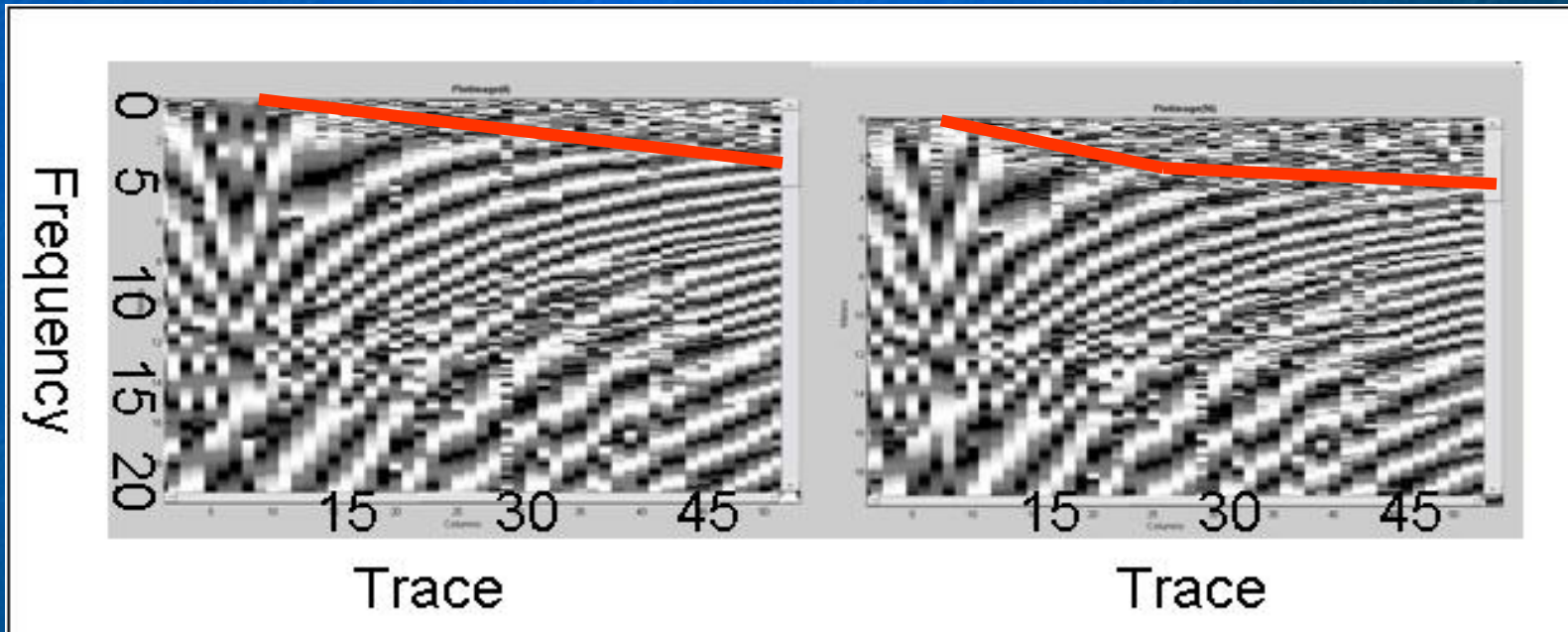
F-X coherency plot

- No major differences evident
- Geophone more coherent at low-f?



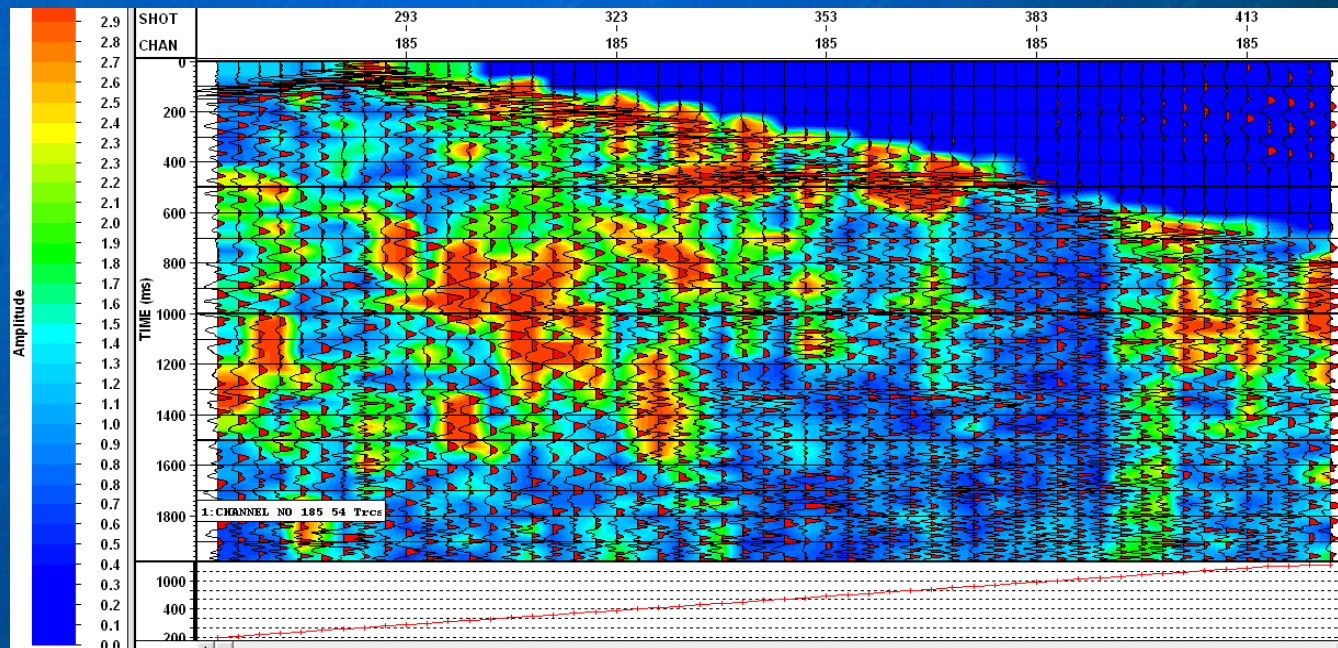
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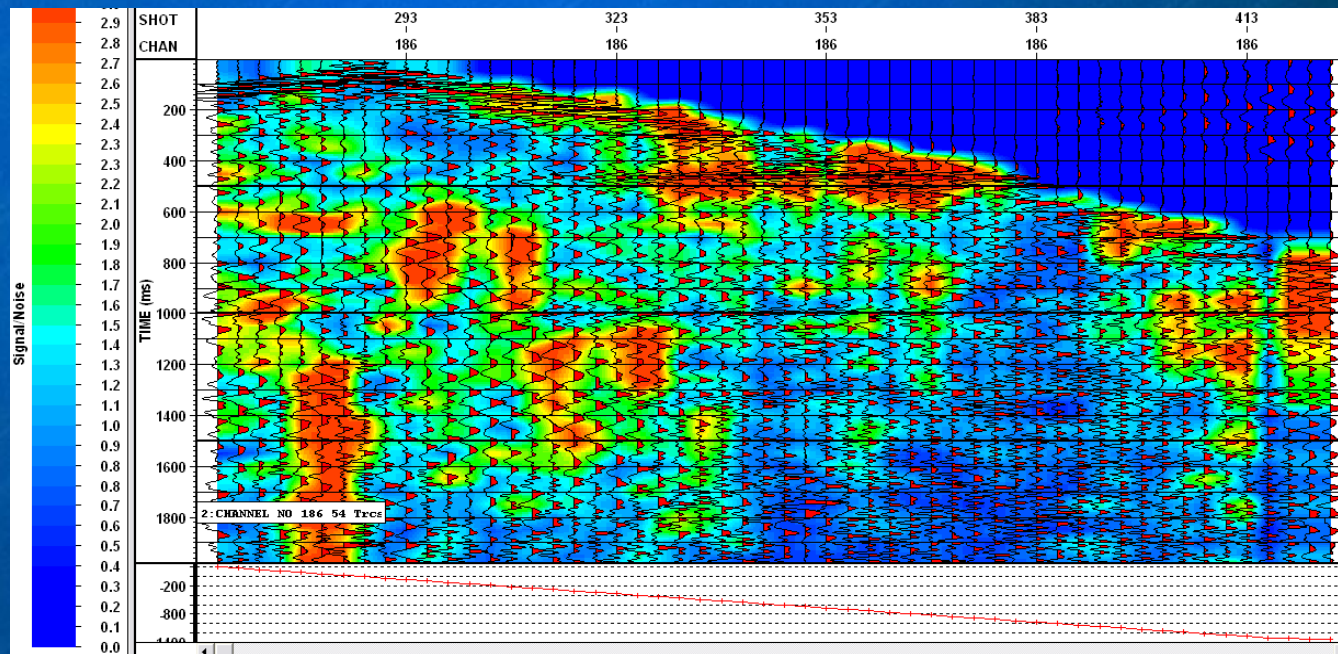
S/N estimate

- Window 6 traces wide, 500 ms long
- Value plotted at centre of window
- DSU advantage near, geophone advantage far



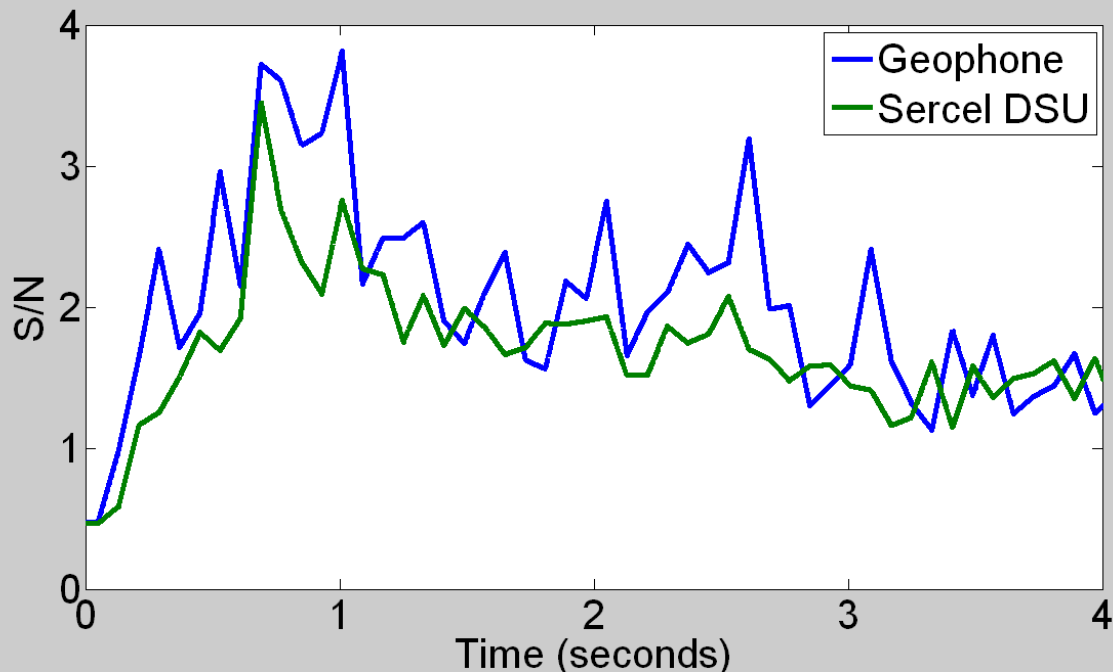
S/N estimate

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Time/frequency analysis

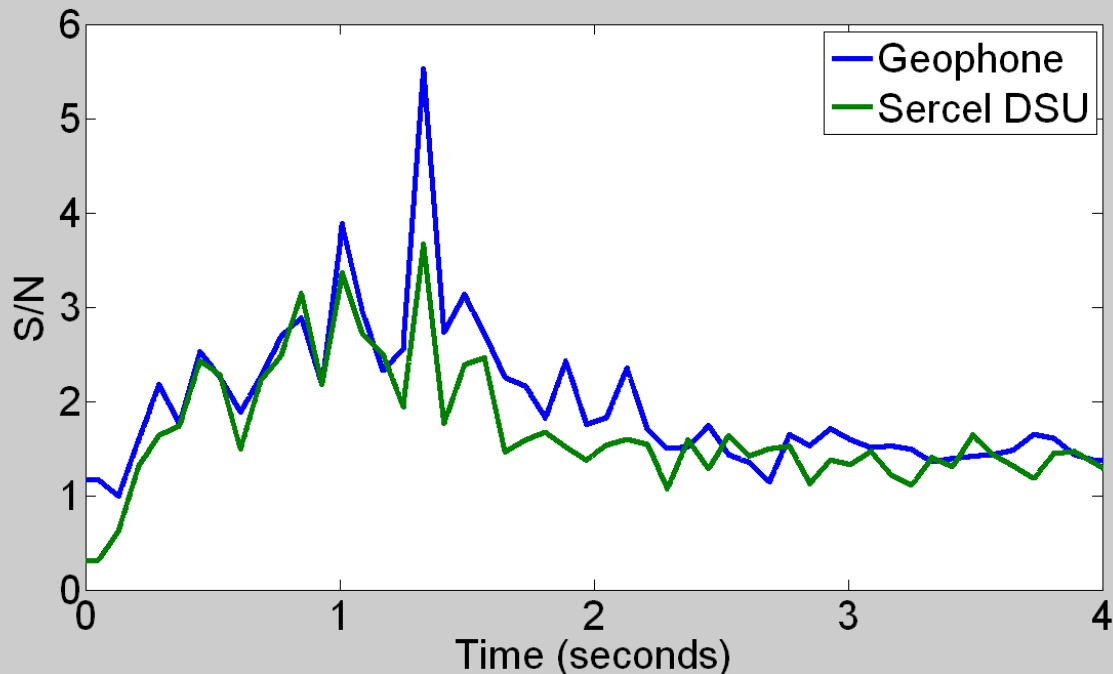
- Geophones more coherent at low-f
- Fairly even over dominant frequencies
- Higher S/N at high-f in DSU, 1-2.5 sec



• 5-20 Hz

Time/frequency analysis

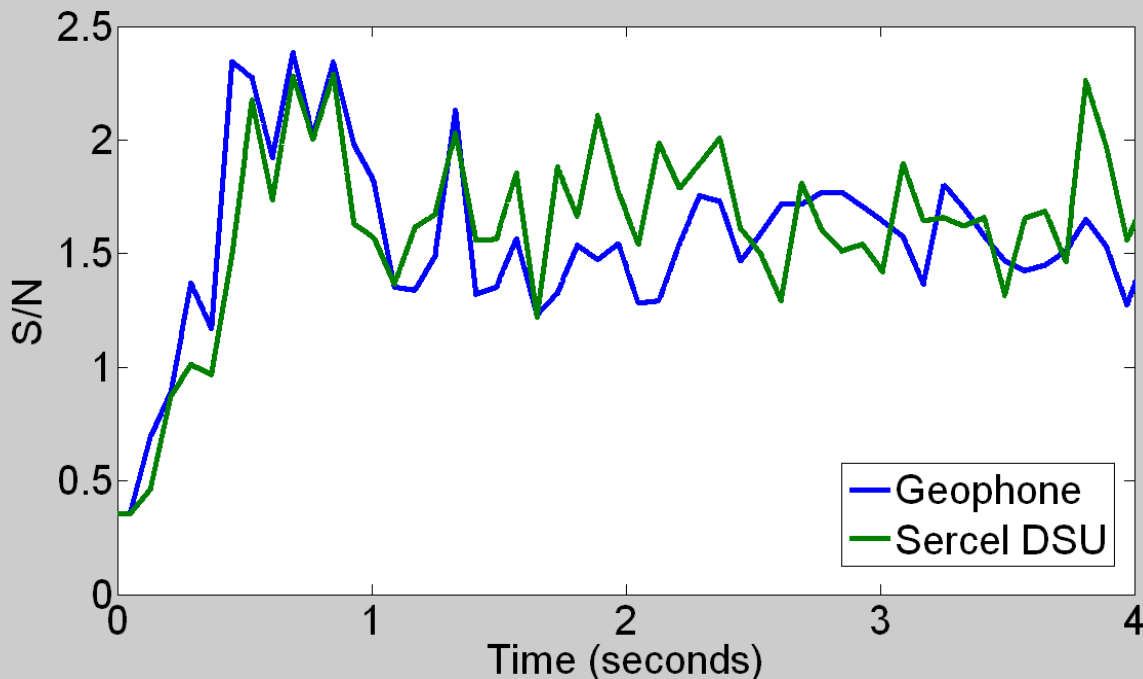
- Geophones more coherent at low-f
- Fairly even over dominant frequencies
- Higher S/N at high-f in DSU, 1-2.5 sec



• 20-35 Hz

Time/frequency analysis

- Geophones more coherent at low-f
- Fairly even over dominant frequencies
- Higher S/N at high-f in DSU, 1-2.5 sec



•50-65 Hz

Conclusions

- Some coupling problems evident for DSUs
- Where well-coupled, data is similar
- Where reliable noise record available, cross-over exists ~70-80 Hz
 - Similar crossover in S/N
- No evidence of better signal at very low-frequencies in vertical component
- Early suggestions:
 - geophones may be better for lower frequency far-offset or late arrivals
 - DSUs may be better for higher frequency near-offset or shallow arrivals

Acknowledgements

- All those who contributed to the Spring Coulee experiment
- Glenn Hauer and Malcolm Bertram
- All the CREWES sponsors