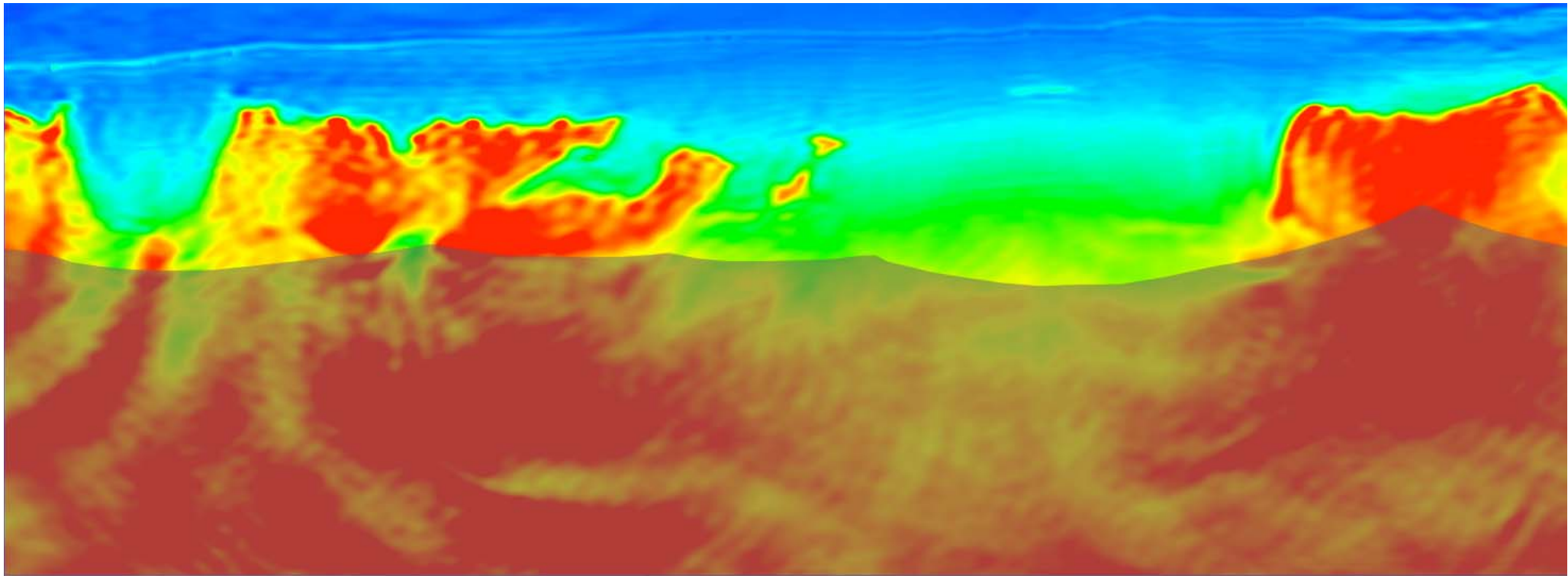




 **Husky Energy** *CREWES* 

4D seismic monitoring with
full-waveform tomography

Chad Hogan, Ken Hedlin, Gary
Margrave, & Michael Lamoureux



Waveform tomography in complex structure

from: Frequency Domain
Waveform Tomography Using
Refracted Arrivals. R.G. Pratt &
A. Brenders. EAGE 2004

Waveform tomography

- Lailly, Tarantola, and Mora started things off in the early 80s, Marta Woodward and others later.
- Gerhard Pratt et al. have advanced the method, and produced reference code that we are learning to use.
- Seiscope (Université Nice) is developing full-scale code.

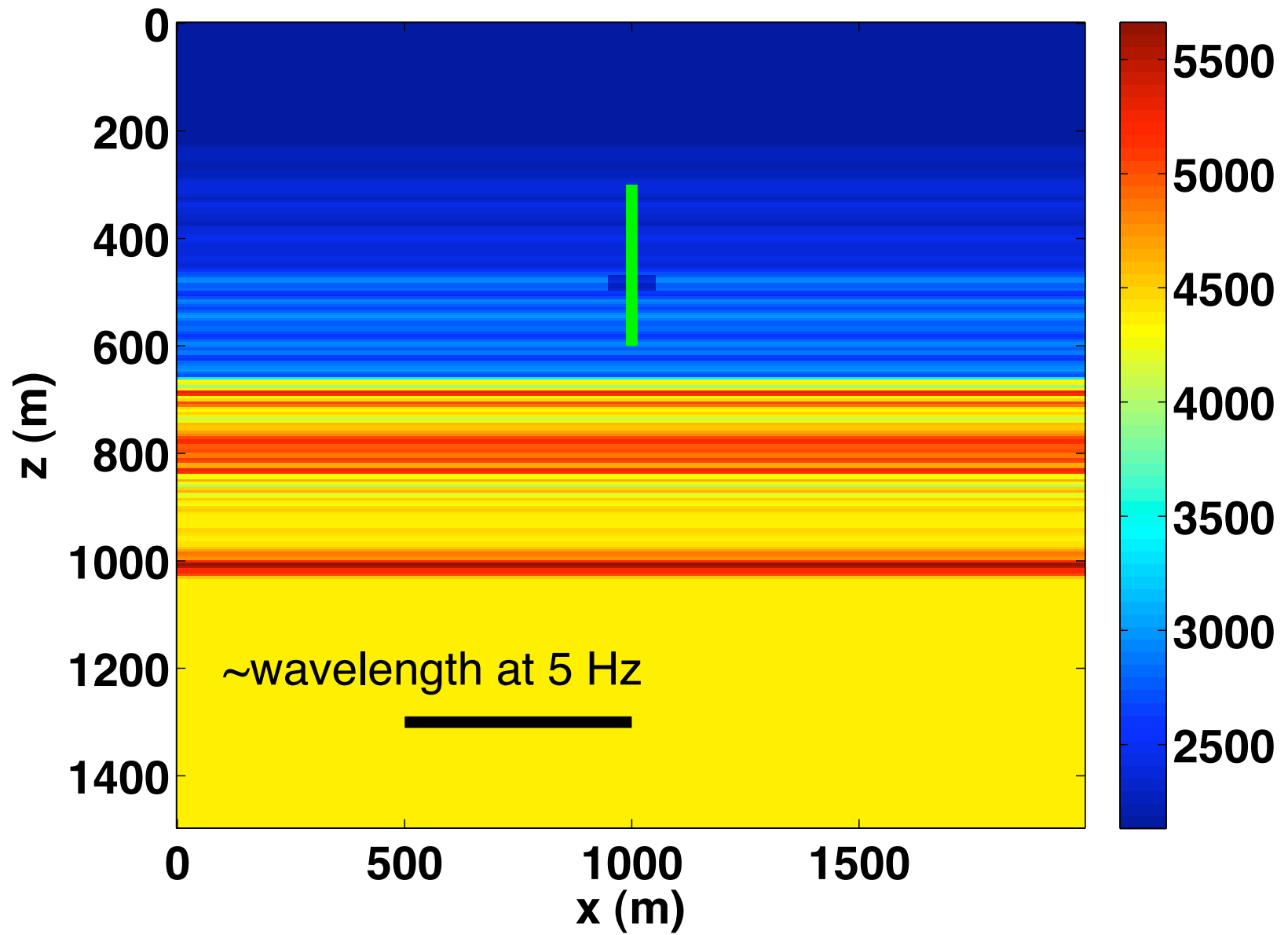


Waveform tomography

- The method finds perturbations to a “high quality” initial starting model, and to a source waveform.
- Traditional velocity analysis and/or travelttime tomography may be used to find a starting model.
- We need “long” offsets, “low frequency” data, and “good” starting models.
- Apply it to 4D problems!

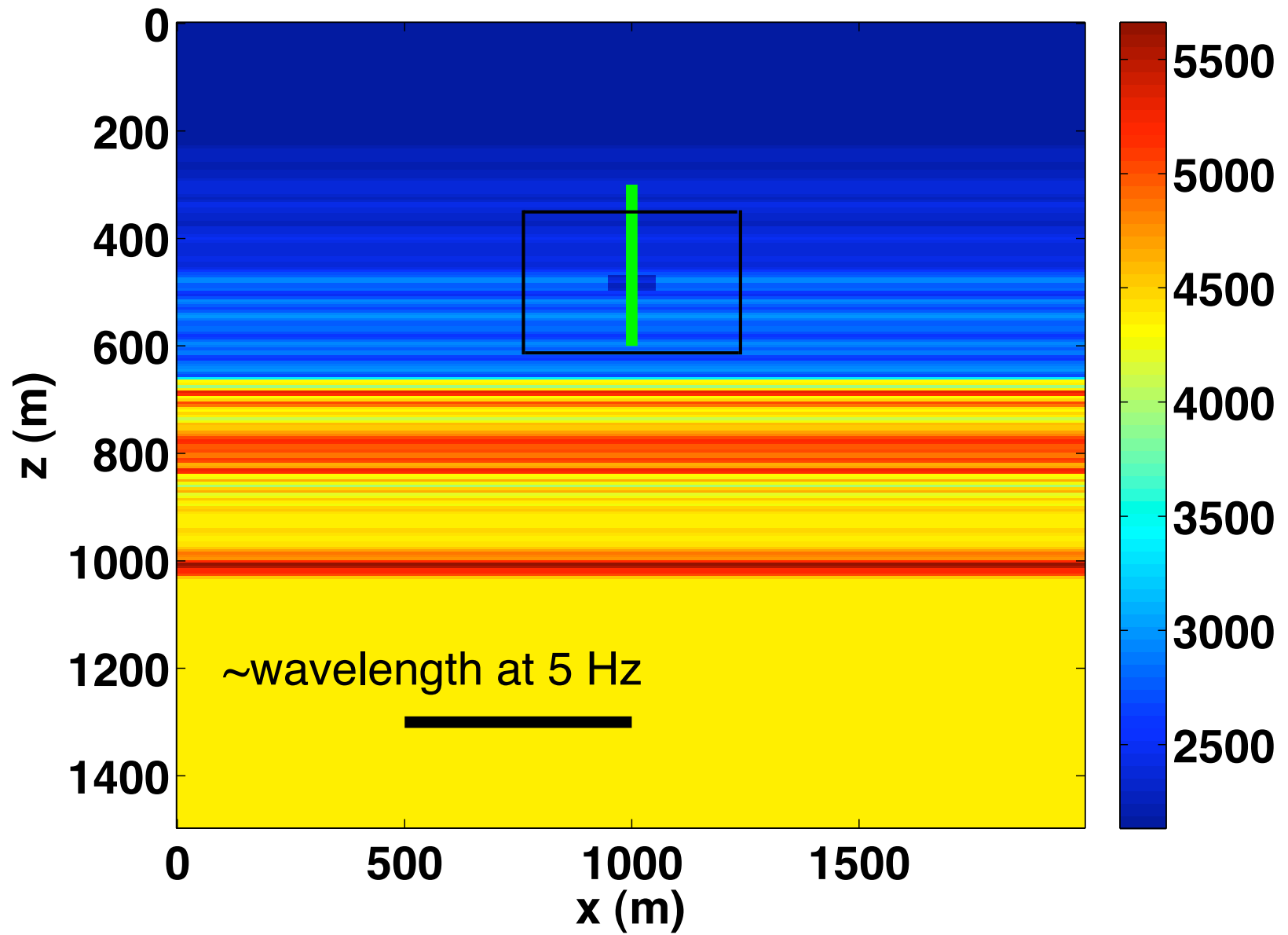


Velocity model (m/s)



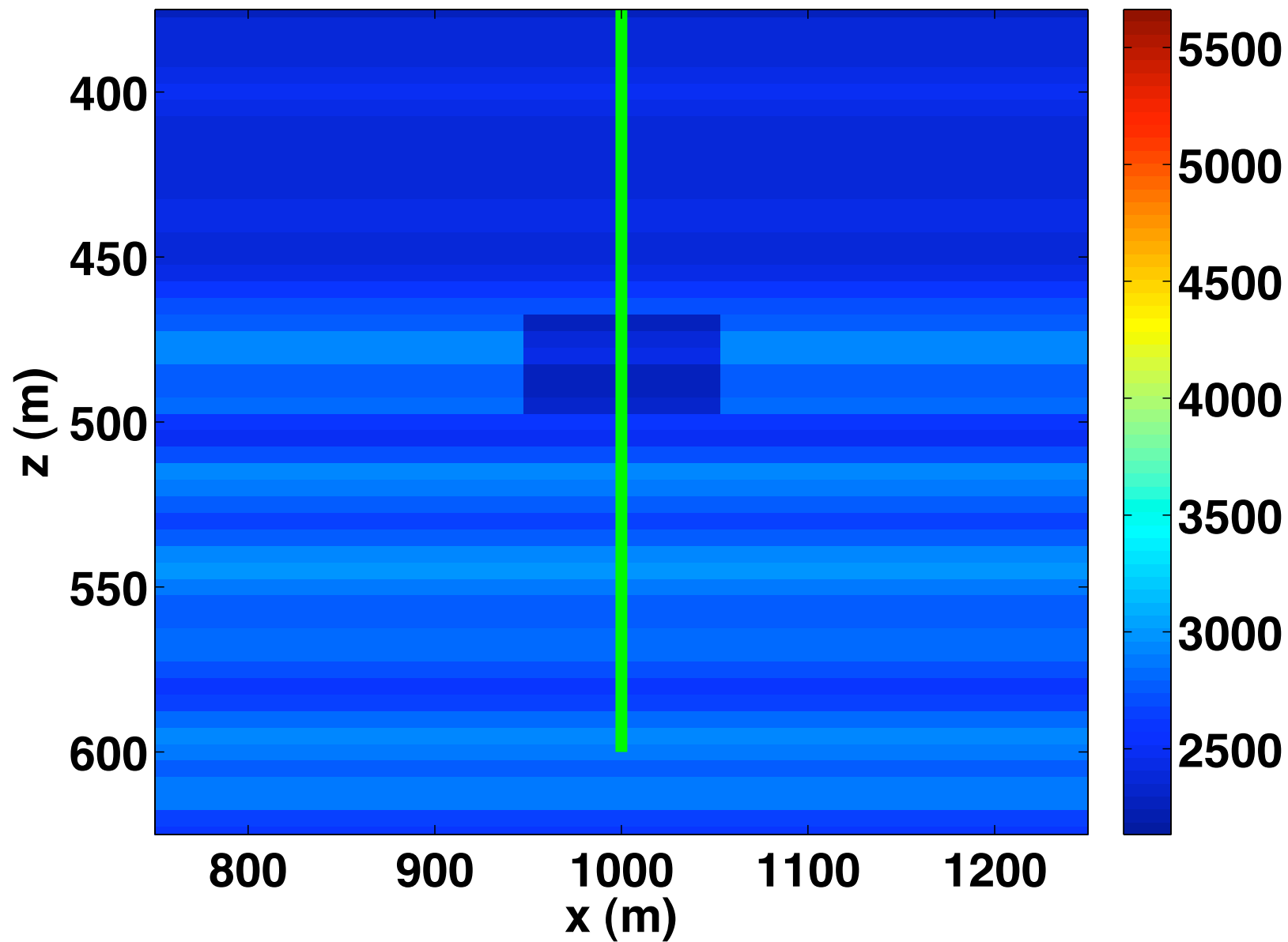
Green line marks the location of VSP receivers

Velocity model (m/s)

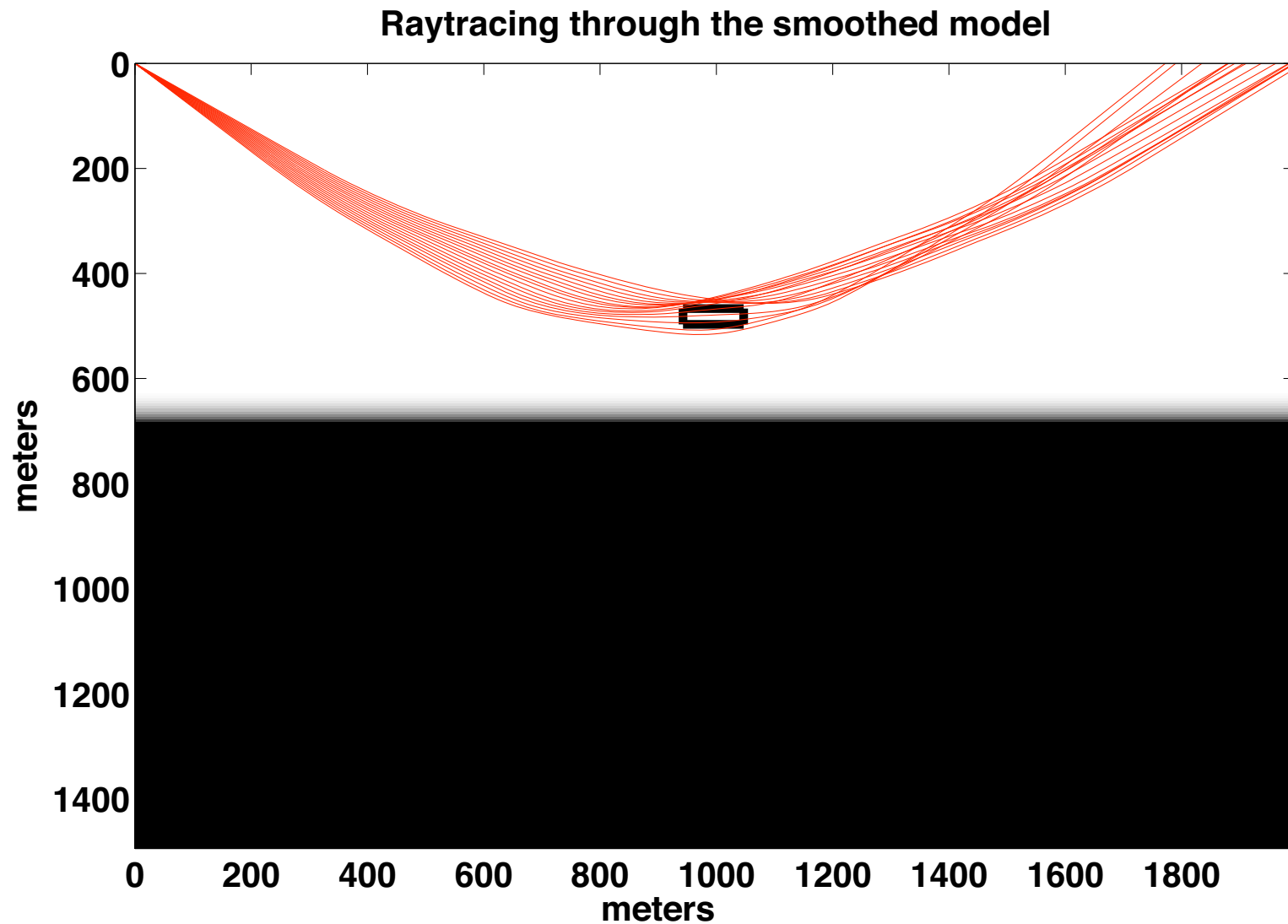


Green line marks the location of VSP receivers

Velocity model (m/s)

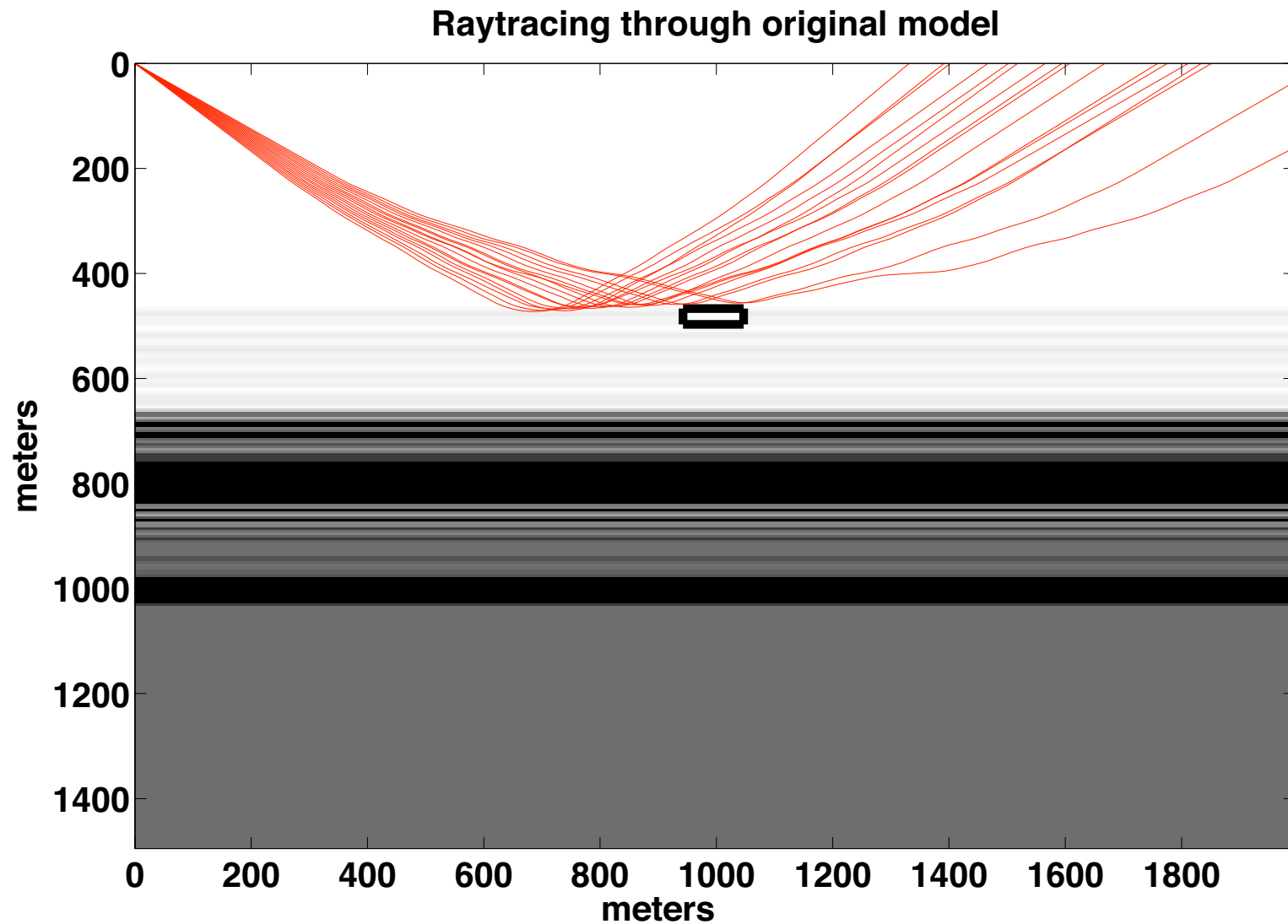


Green line marks the location of VSP receivers



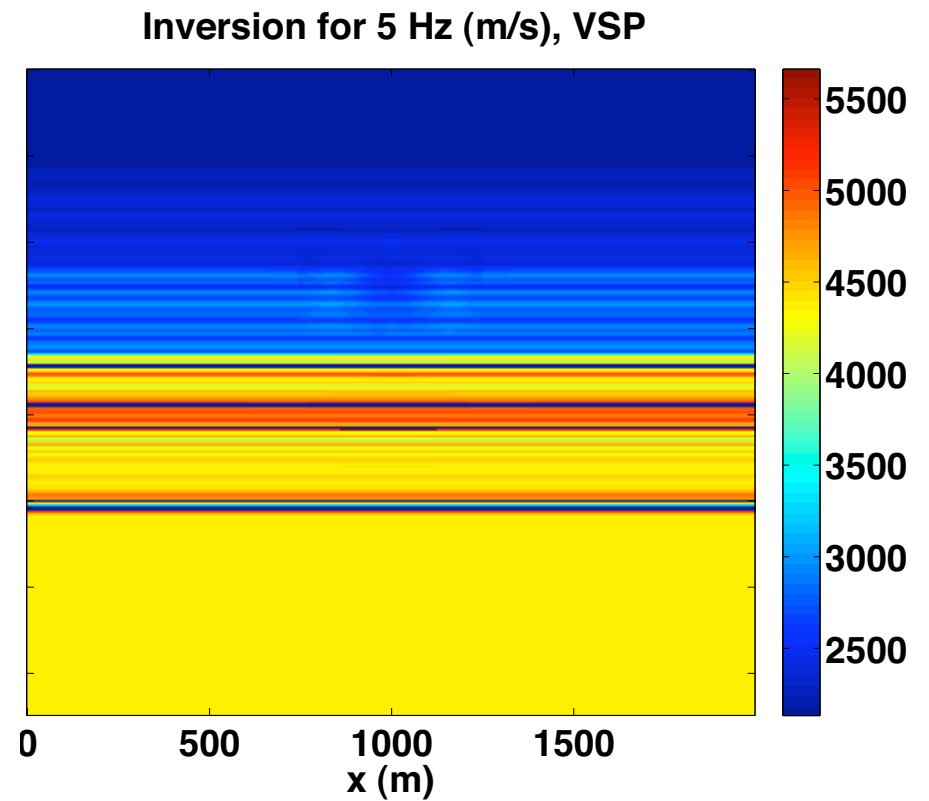
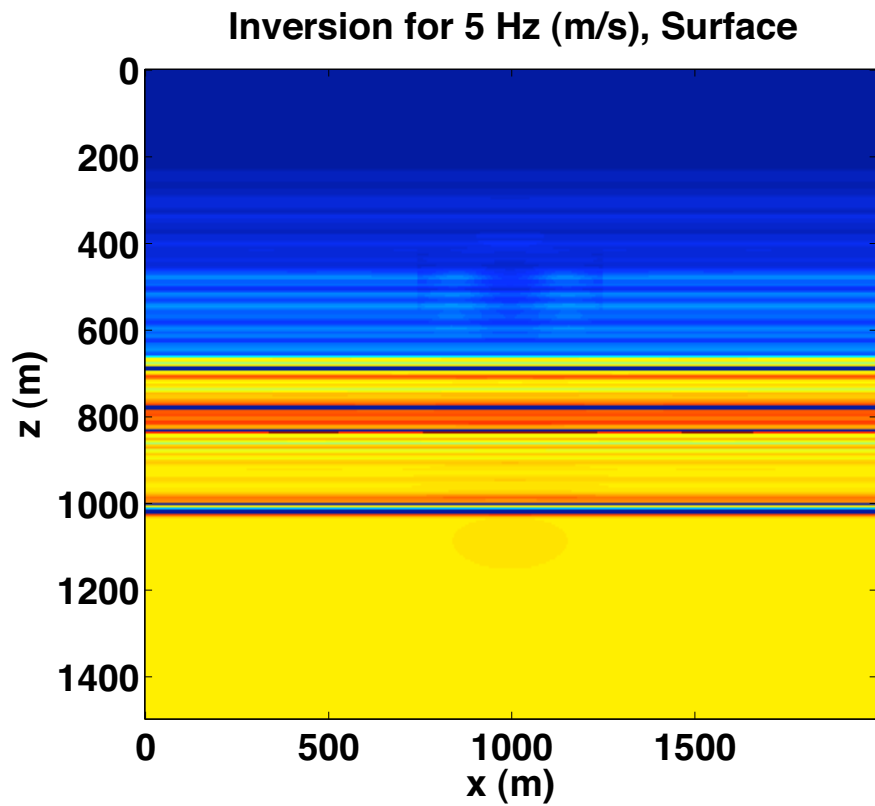
Long offsets give us tomographic data.

Smoothed with 20m Gaussian.



Long offsets give us tomographic data.

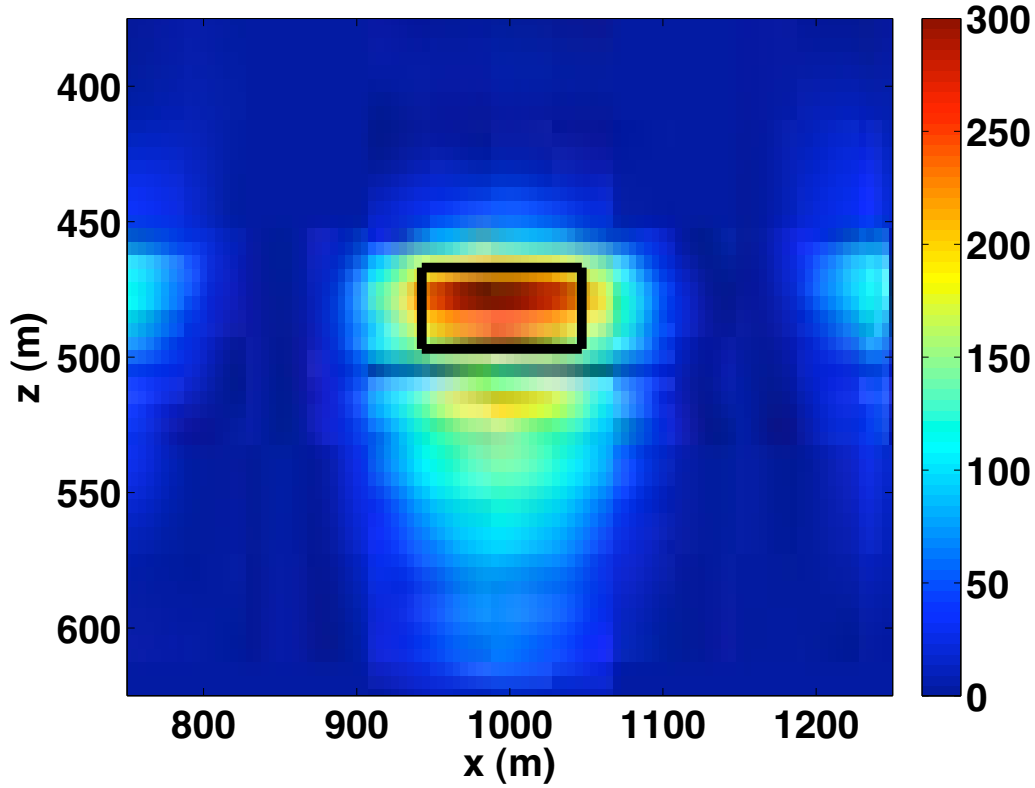
Smoothing implies low frequency?



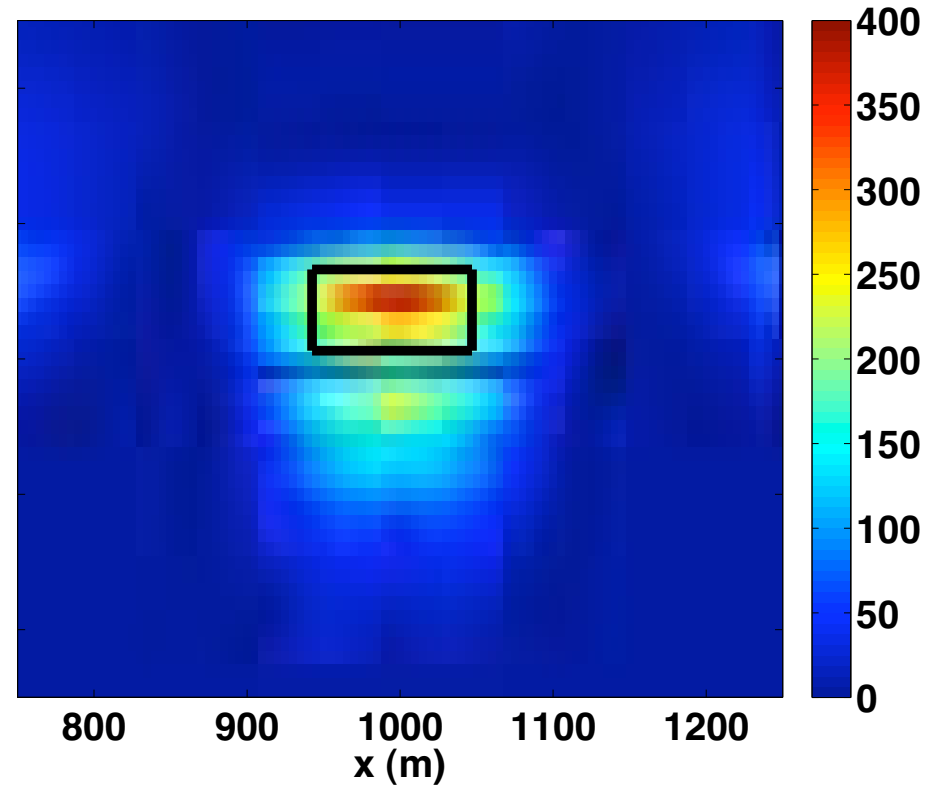
Inversion for 5 Hz

Constrained to target area

Inversion difference (m/s), 5 Hz Surface



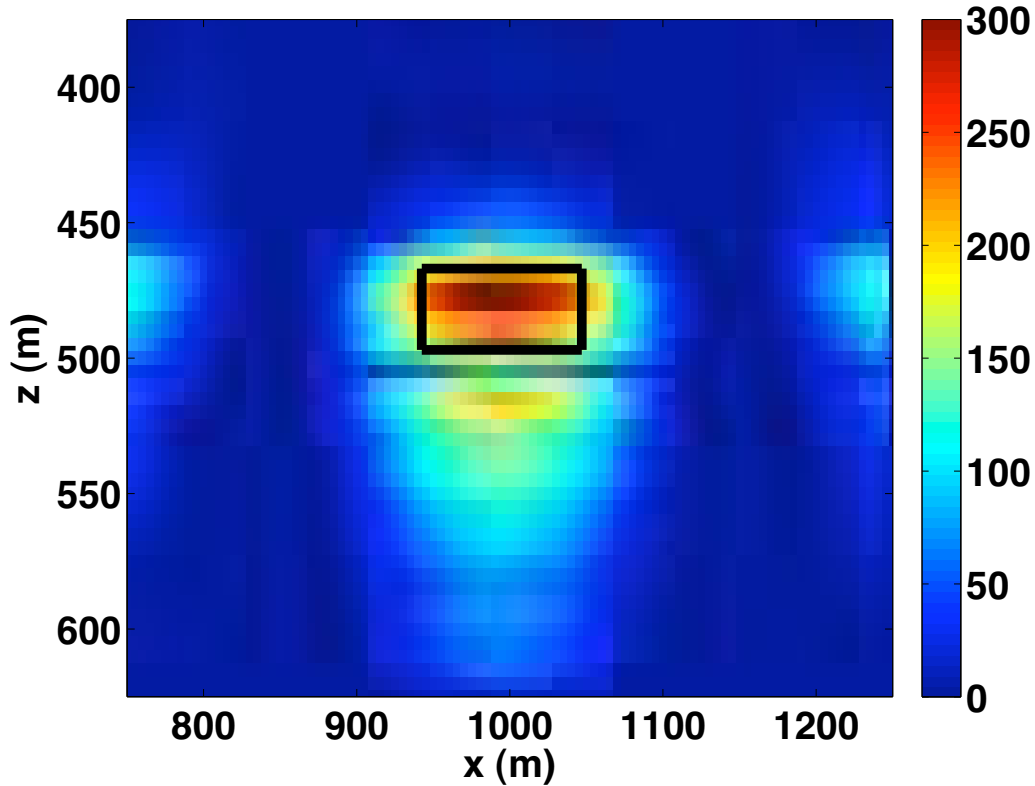
Inversion difference (m/s), 5 Hz VSP



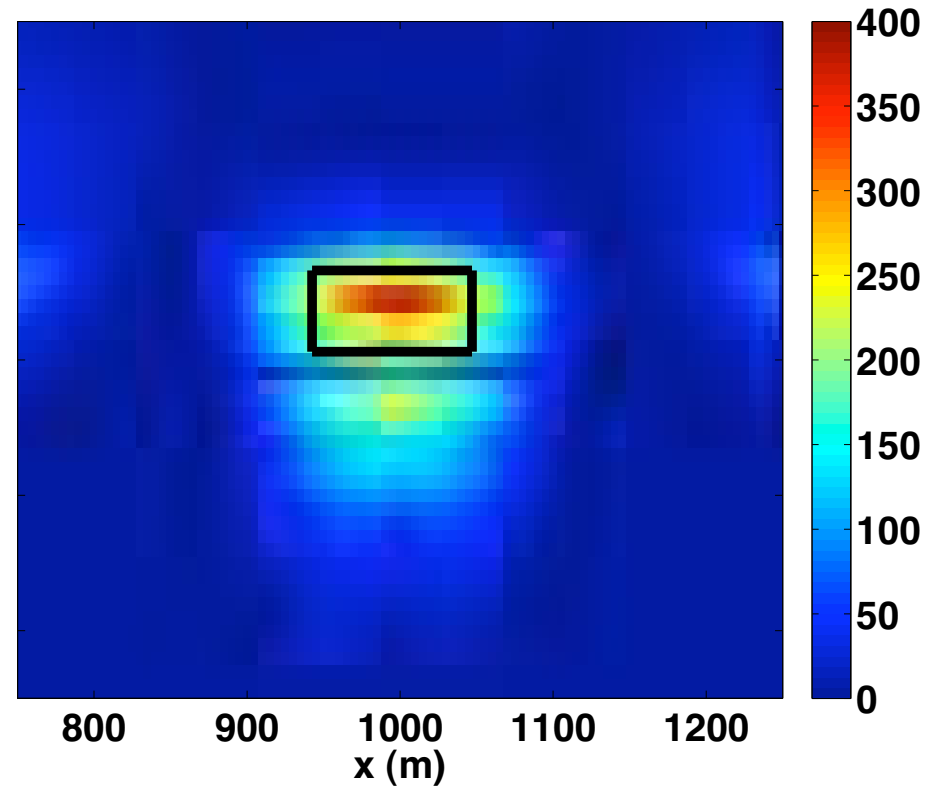
Inversion for 5 Hz

update constrained to target region

Inversion difference (m/s), 5 Hz Surface



Inversion difference (m/s), 5 Hz VSP

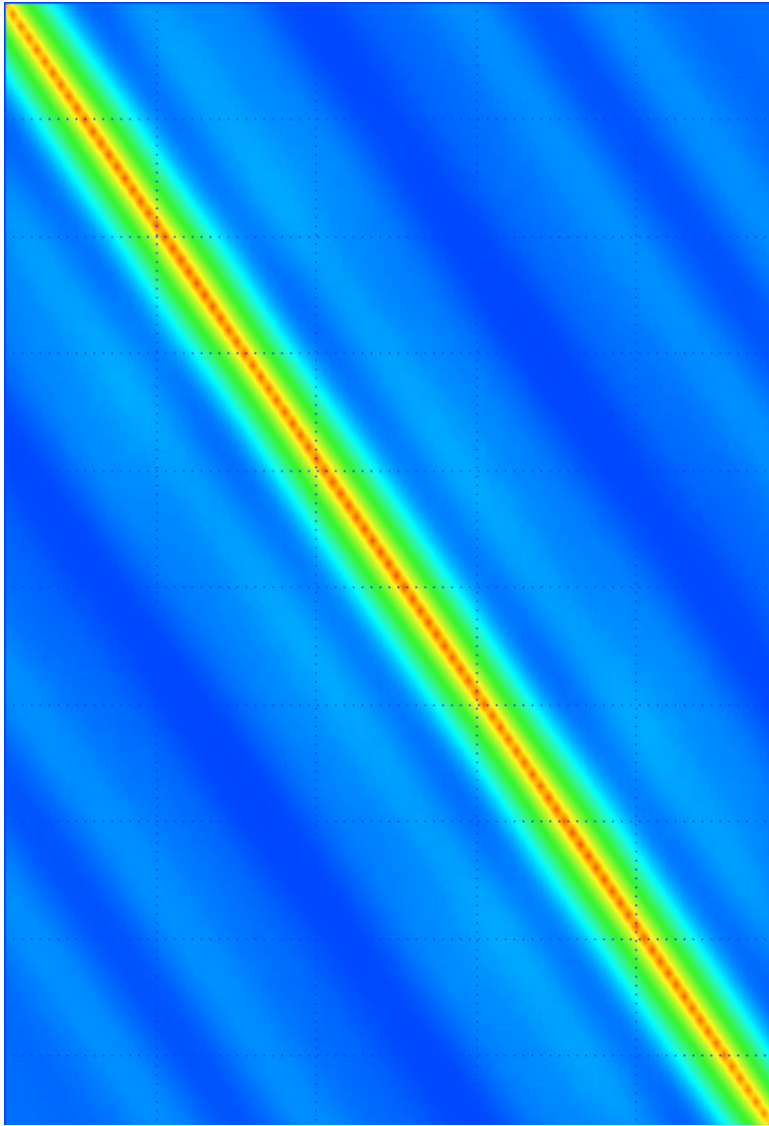


wavelength

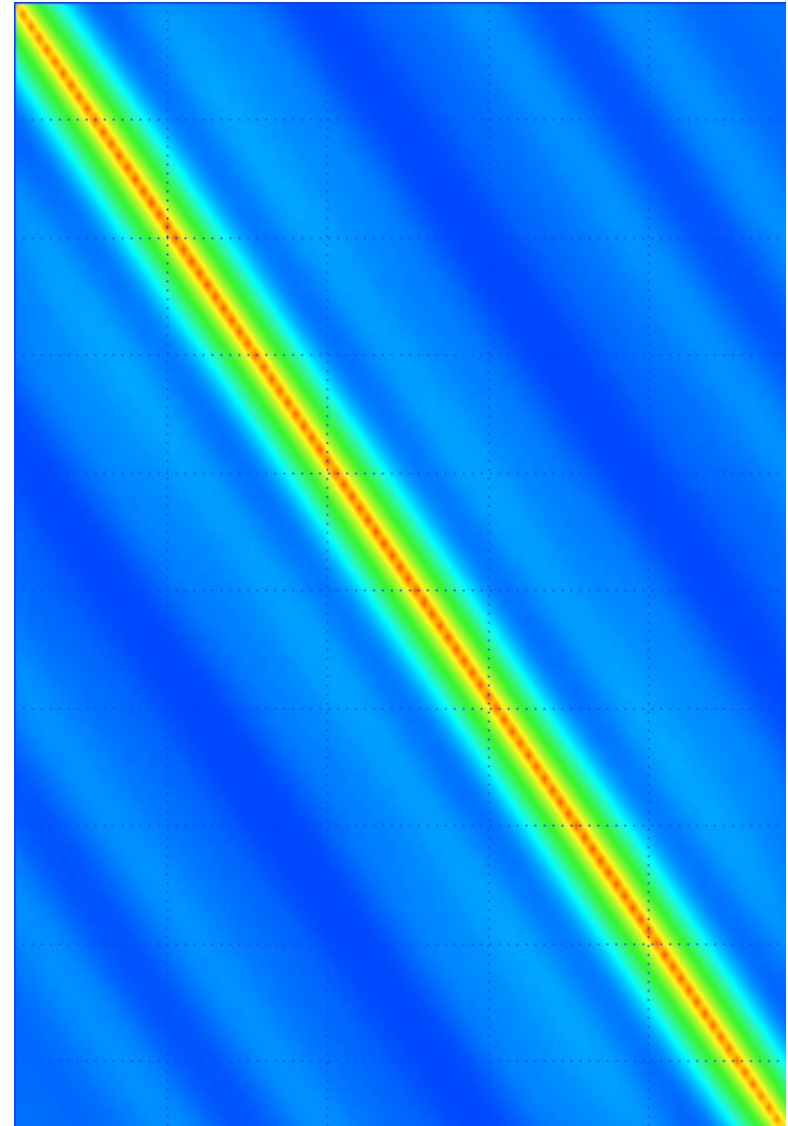
Inversion for 5 Hz

update constrained to target region

“real” data



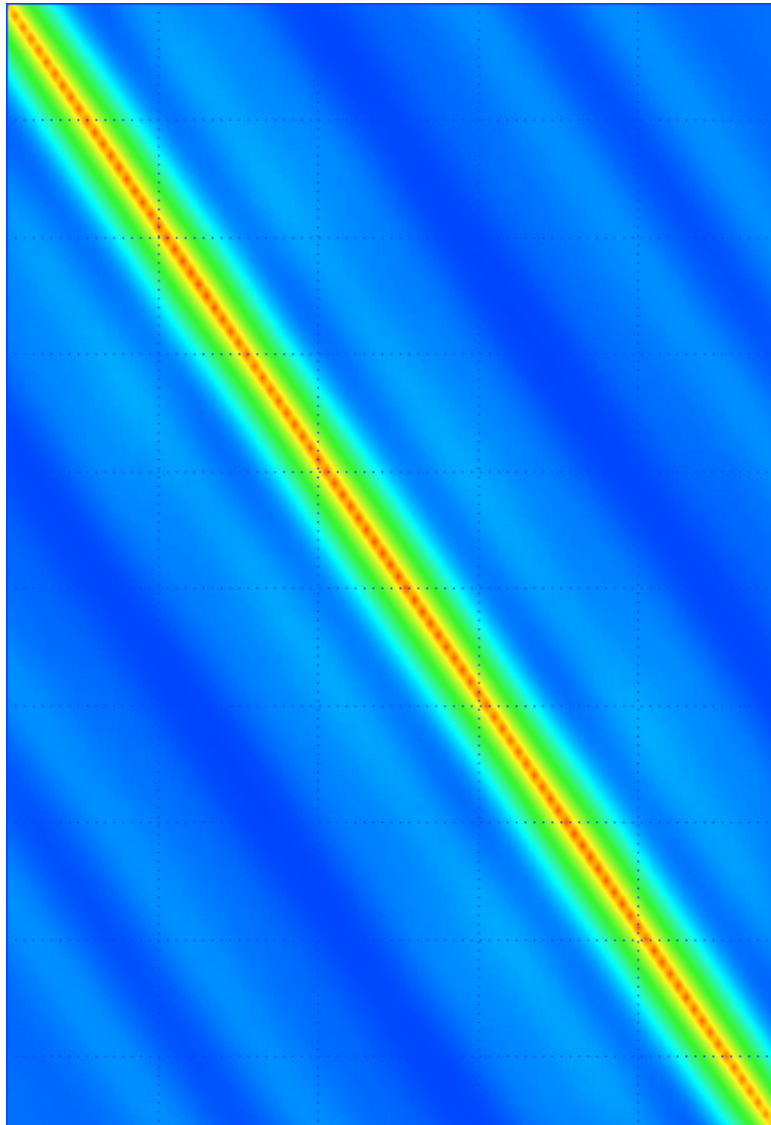
estimated data



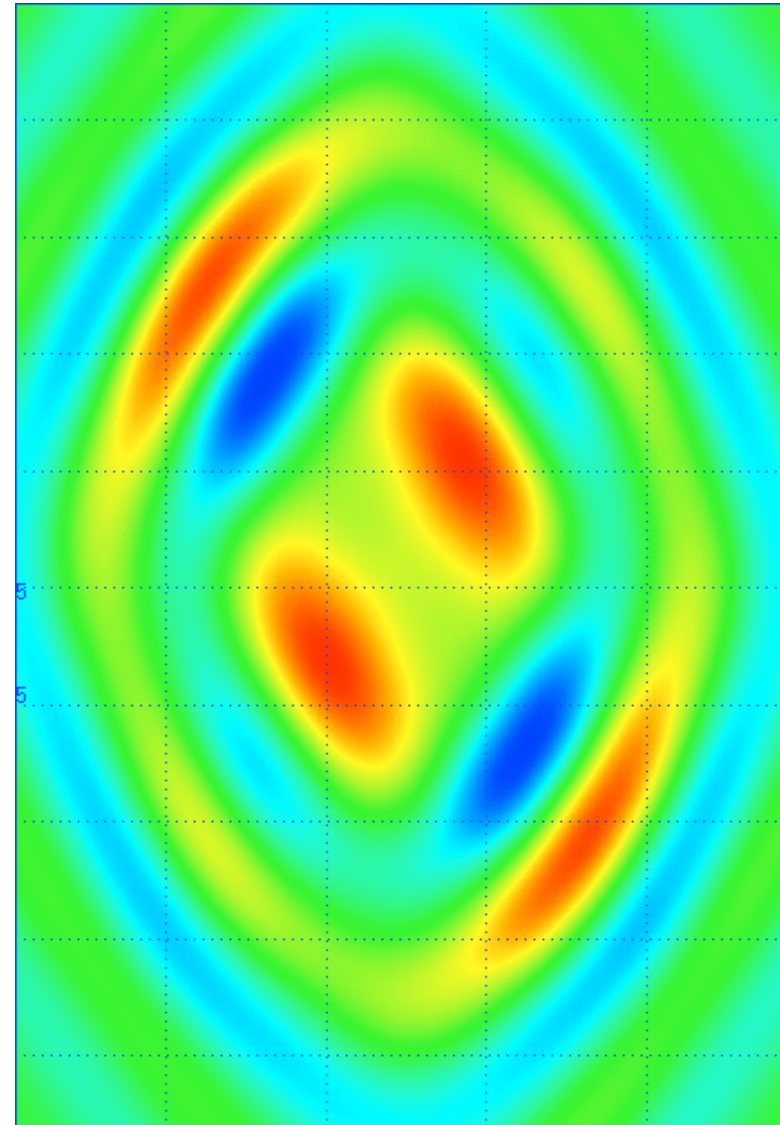
Inversion in FK

We want these to be the same

“real” data



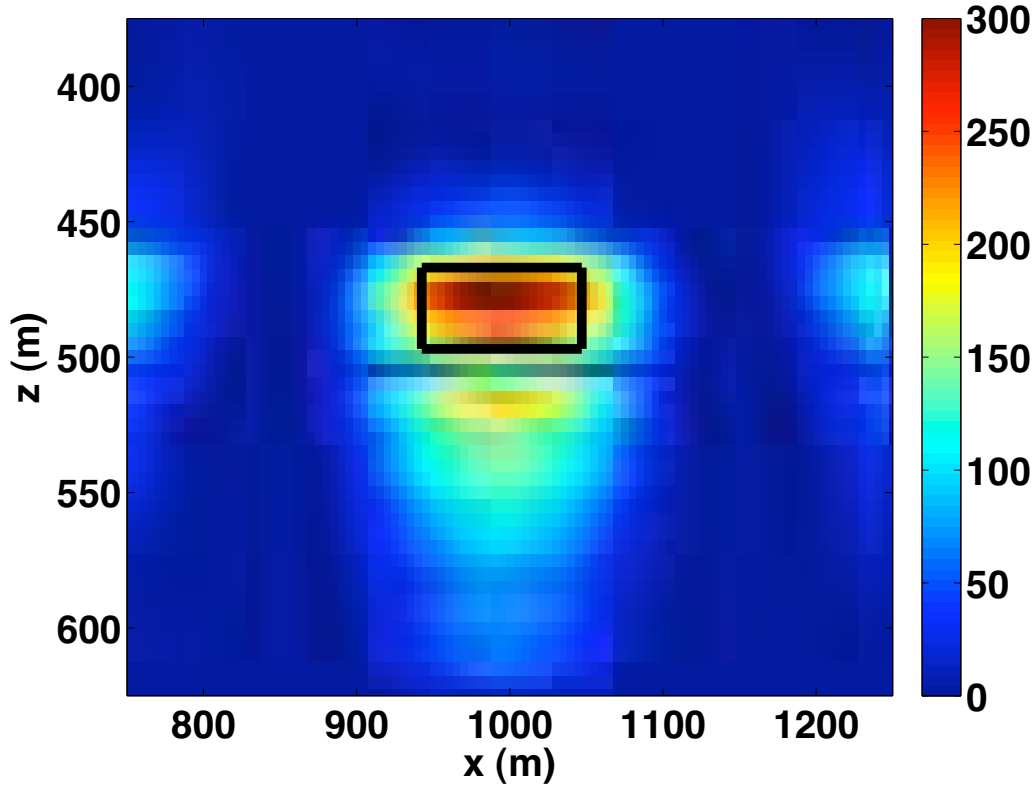
difference (x100)



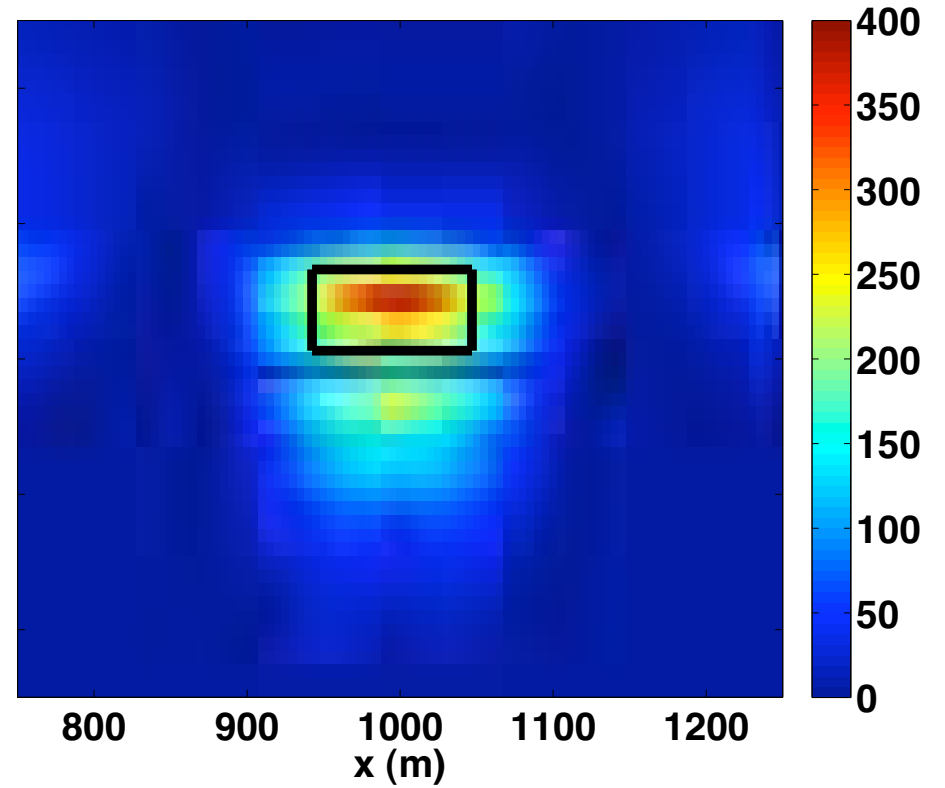
Inversion in FK

back-propagating the difference gives hints about the perturbation

Inversion difference (m/s), 5 Hz Surface



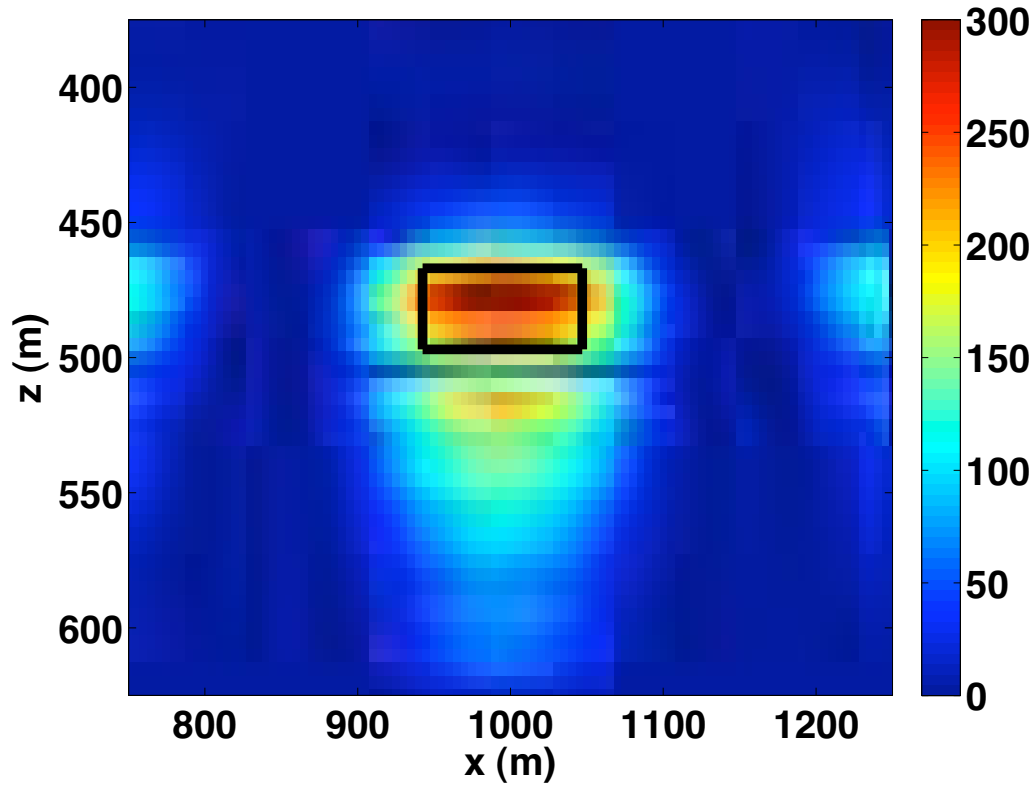
Inversion difference (m/s), 5 Hz VSP



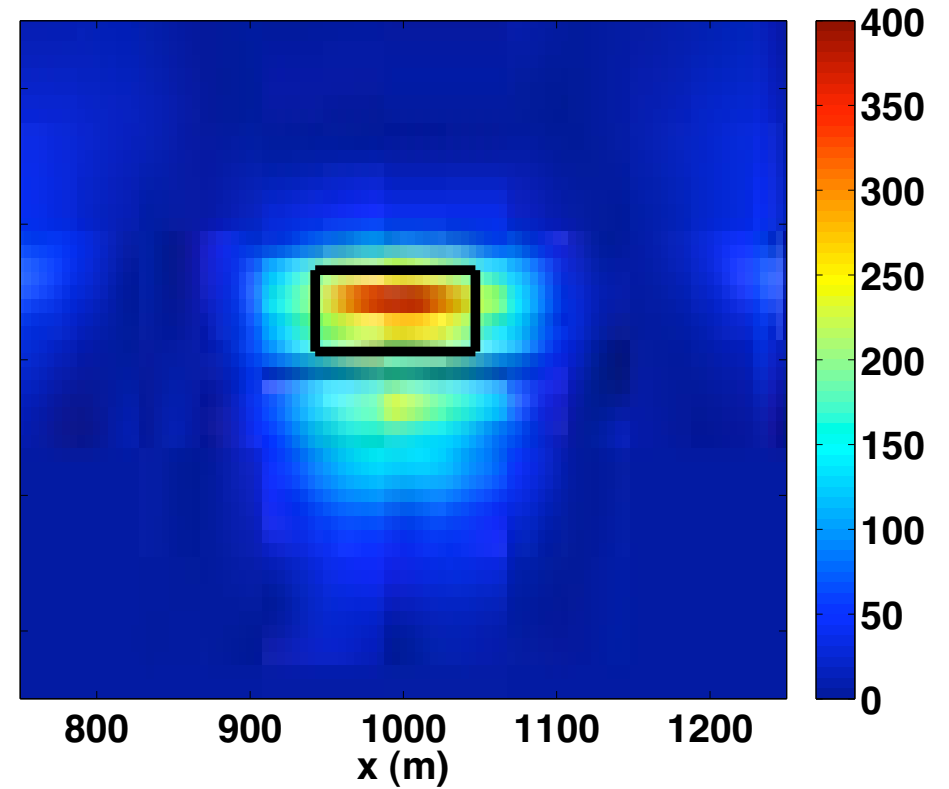
Inversion for 5 Hz

update constrained to target region

Inversion difference (m/s), 5,6 Hz Surface



Inversion difference (m/s), 5,6 Hz VSP



Inversion for 5 & 6 Hz

update constrained to target region

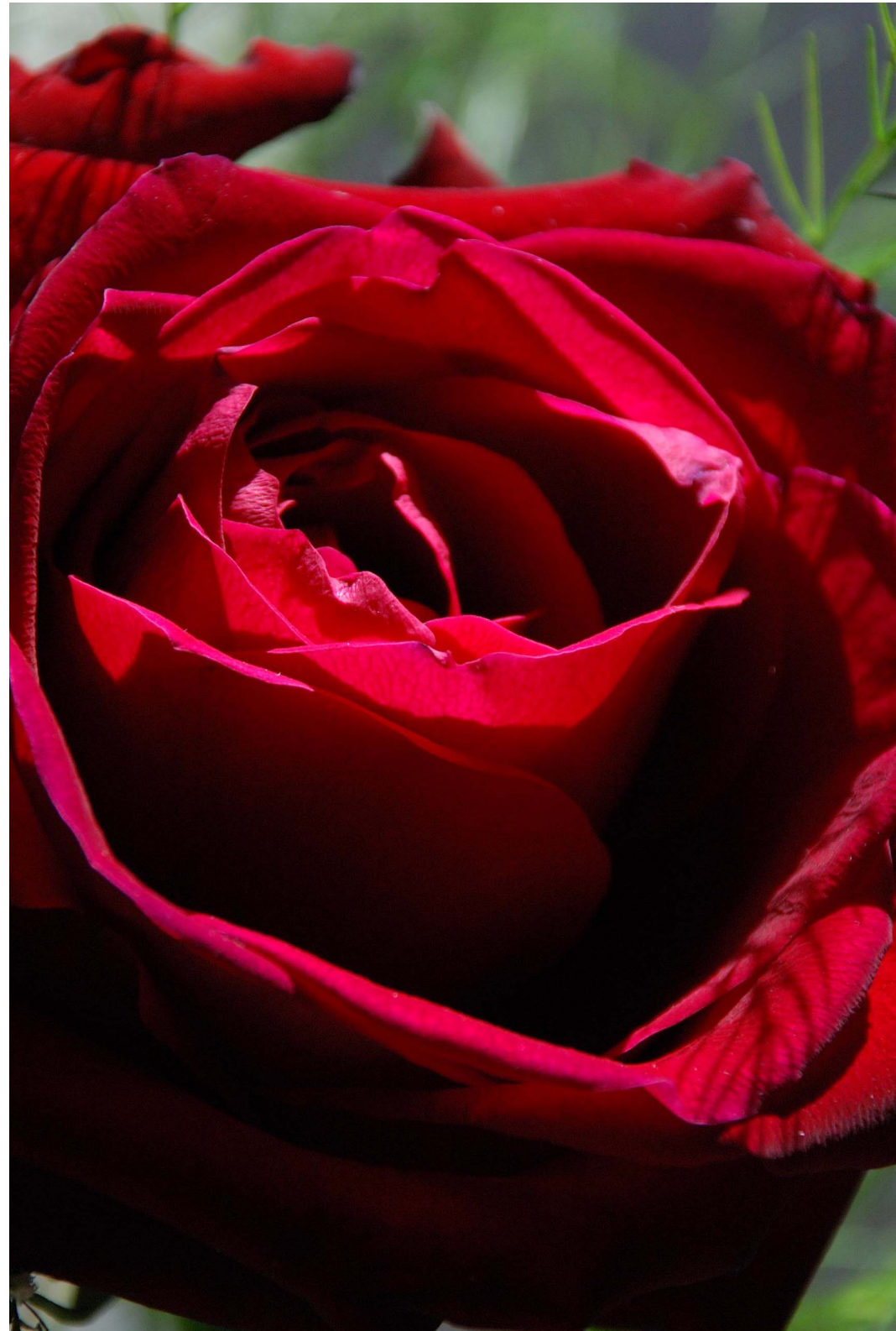
Inversion results

- Lower than 5 Hz? Not required, and probably not feasible anyhow. But we need a good model!
- Higher than 6 Hz? Very little update in the target region due to very low energy penetration, and therefore highly unstable.
- Modelling and geometry seems crucial to success.



The good news

- 5 Hz could be “low frequency” with “good” starting models.
- 2:1 or 3:1 offset:depth ratios might be reasonable.
- Raytracing & modelling can help with survey design.
- Small perturbations (much below a typical wavelength) may be imaged, with some reasonable magnitude information.



The challenges

- What about random and coherent noise? Elastic effects?
- What about smoothed (or incorrect!) velocity models?
- What about unknown source waveforms?
- What about perturbation size and magnitude?
- ...and many more.



Acknowledgements

