

# Seismic-to-well ties by smooth dynamic time warping

Tianci Cui and Gary Margrave

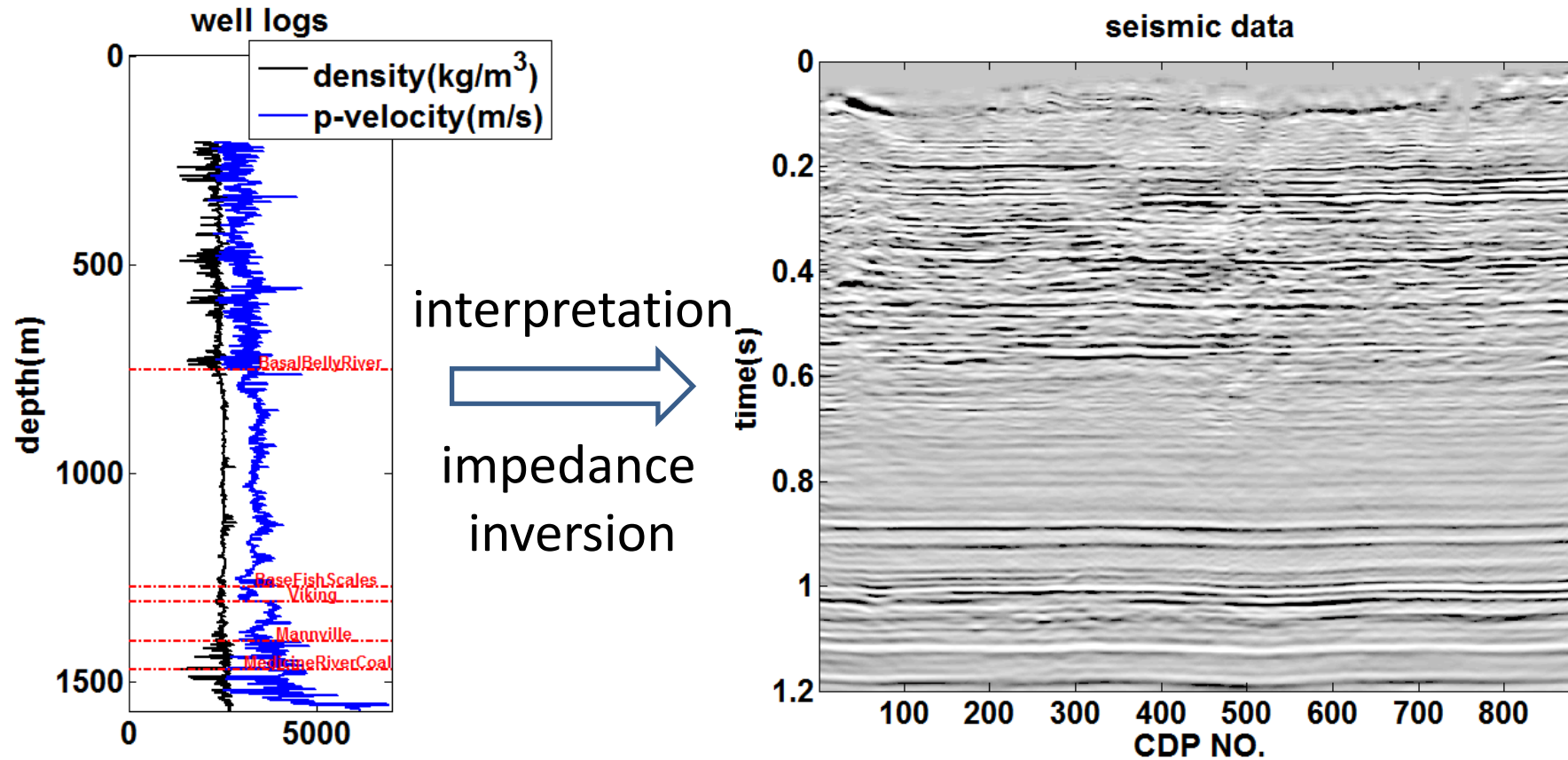
# Outline

- **Introduction**
- **Smooth dynamic time warping**
- **Seismic-to-well ties on Hussar field data**
- **Conclusions**
- **Acknowledgements**

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# Introduction

What are seismic-to-well ties for?



# Introduction

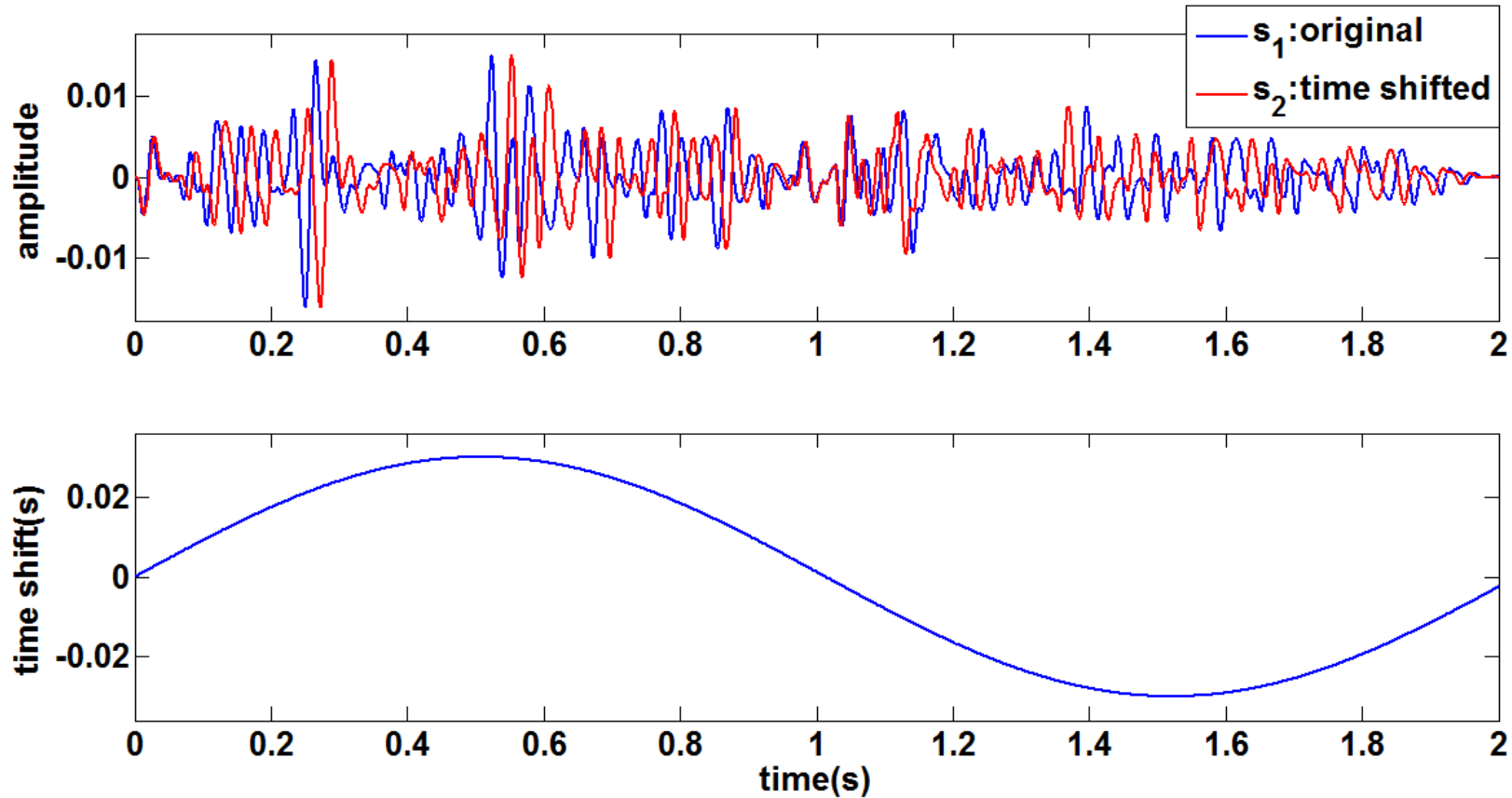
## How to tie wells to seismic?

1. Edit well logs and process seismic data
2. Calibrate sonic times to seismic times (**Anelastic attenuation**)
  - Q
  - Check-shot/VSP survey
  - Manually stretch and squeeze → **Smooth dynamic time warping**
3. Estimate wavelet and calculate reflectivity to create synthetic seismogram
4. Rotate the seismic trace by a single constant-phase  
→ **Time-variant constant-phase rotation**

# Outline

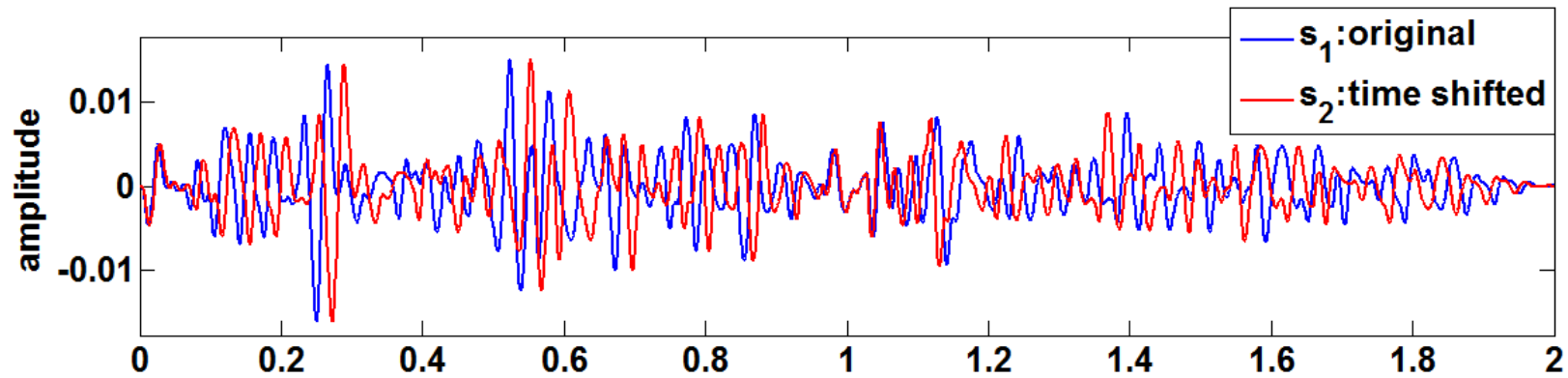
- **Introduction**
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- **Seismic-to-well ties on Hussar field data**
- **Conclusions**
- **Acknowledgements**

# Dynamic time warping



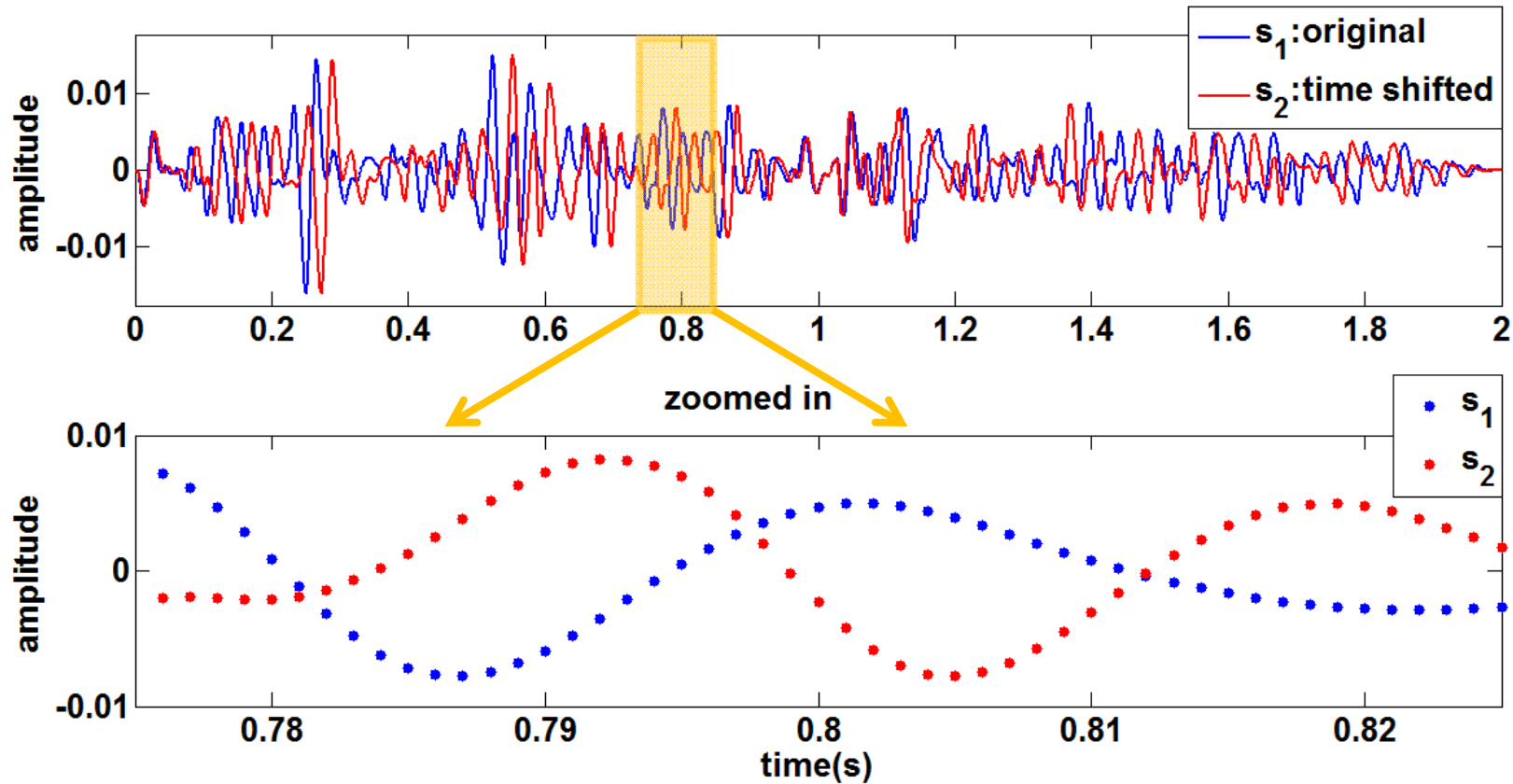
Hale, D., 2013, Dynamic warping of seismic images: Geophysics

# Dynamic time warping

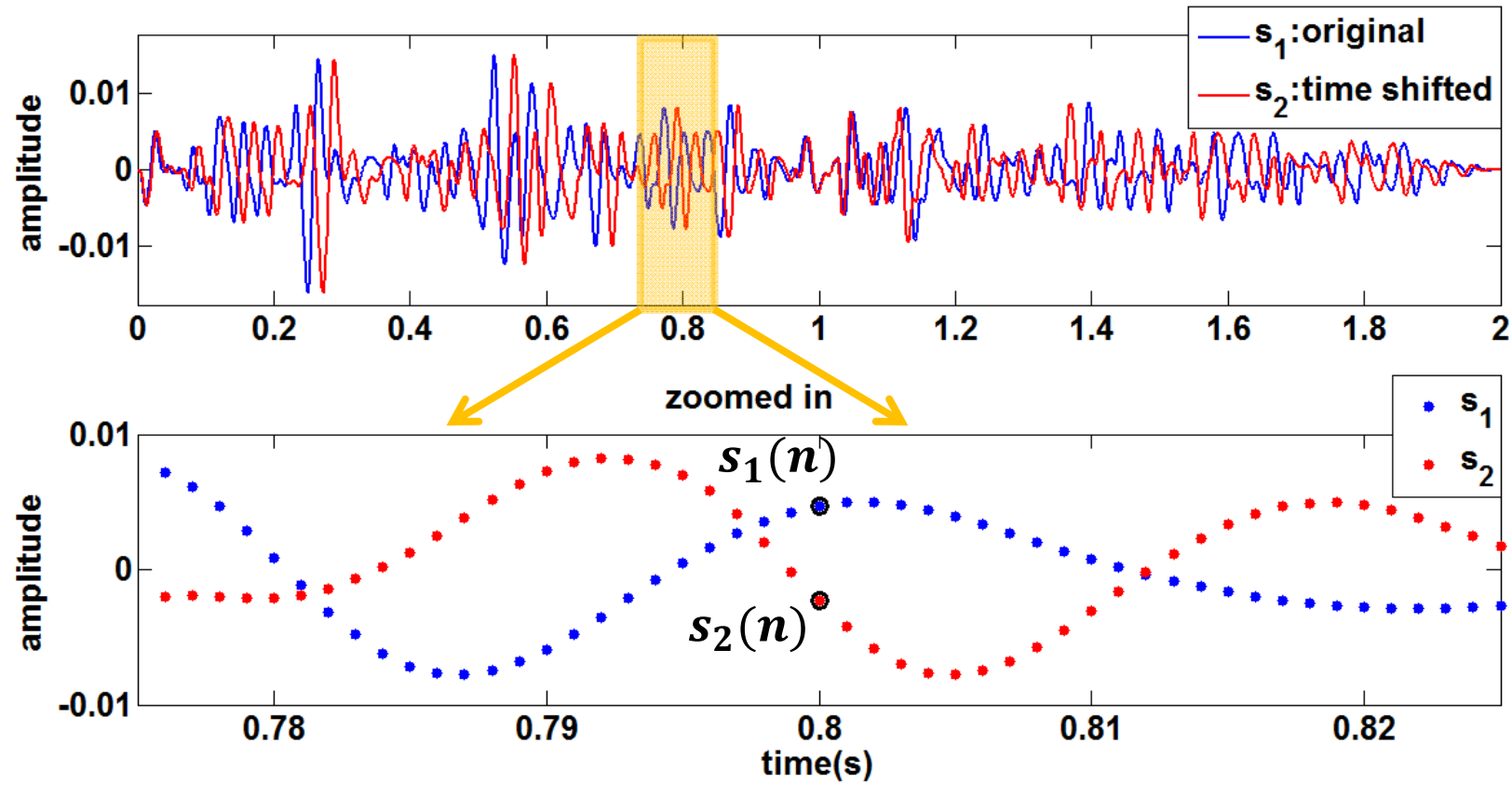




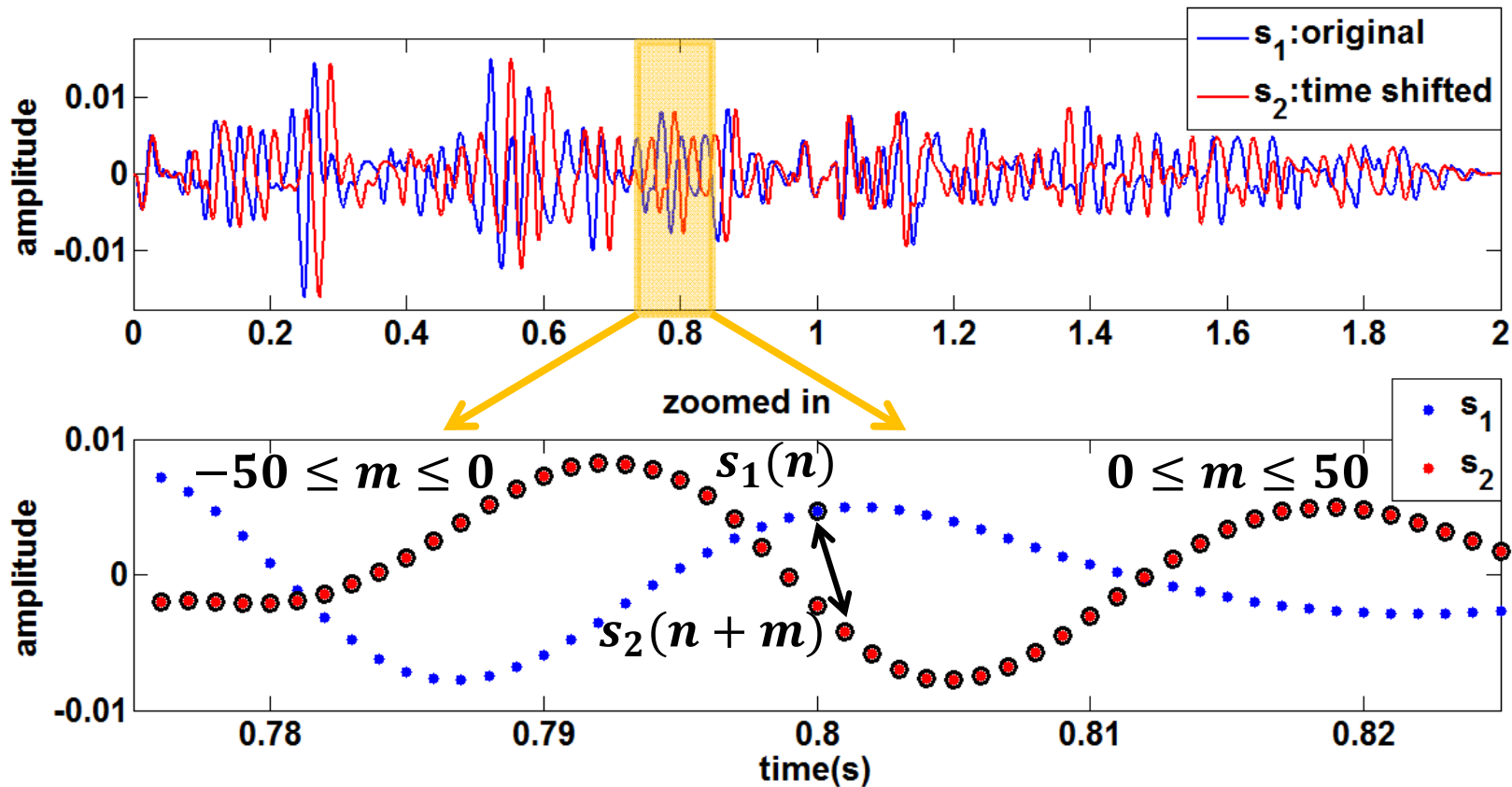
# Dynamic time warping



# Dynamic time warping

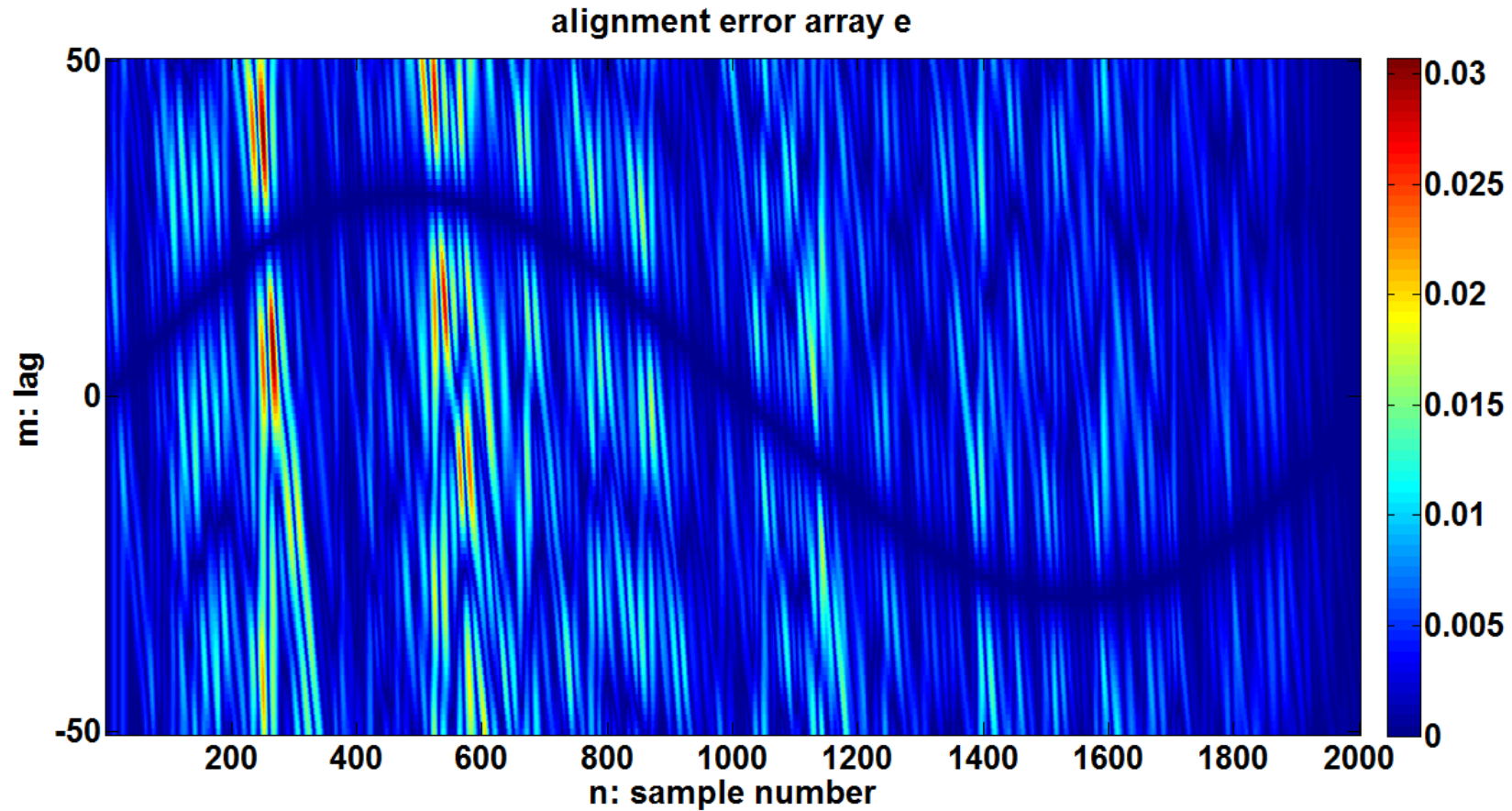


# Dynamic time warping



$$e(m, n) = [s_1(n) - s_2(n + m)]^2 \quad n = 1, 2, \dots, 2000$$

# Dynamic time warping

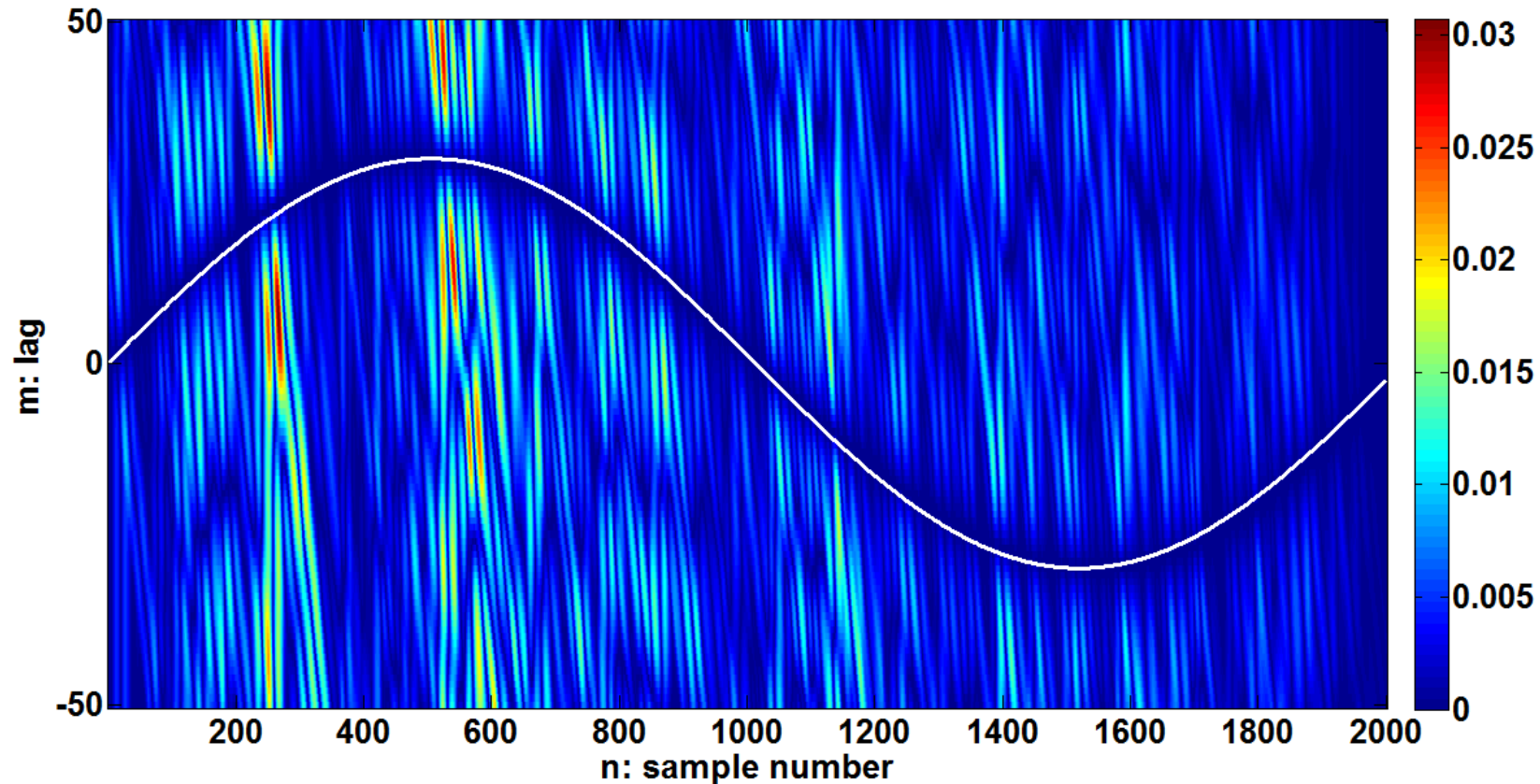


# Dynamic time warping

$101^{2000} \Rightarrow$  infinite

Constraint:  $|m(n) - m(n - 1)| \leq 1$

alignment error array e



# Dynamic programming

Alignment error array  $e$

2	<b>4</b>	<b>7</b>	<b>3</b>
1	<b>1</b>	<b>8</b>	<b>4</b>
0	<b>3</b>	<b>5</b>	<b>8</b>
-1	<b>6</b>	<b>5</b>	<b>9</b>
-2	<b>2</b>	<b>8</b>	<b>1</b>
	1	2	3
	n		

125 possible paths

# Dynamic programming: accumulation

Alignment error array e

		<b>4</b>	<b>7</b>	<b>3</b>	
2					
1		<b>1</b>	<b>8</b>	<b>4</b>	
0	<b>m</b>	<b>3</b>	<b>5</b>	<b>8</b>	
-1		<b>6</b>	<b>5</b>	<b>9</b>	
-2		<b>2</b>	<b>8</b>	<b>1</b>	
		<b>1</b>	<b>2</b>	<b>3</b>	<b>n</b>

Distance array d

		<b>4</b>	<b>?</b>		
2					
1		<b>1</b>			
0	<b>m</b>	<b>3</b>			
-1		<b>6</b>			
-2		<b>2</b>			
		<b>1</b>	<b>2</b>	<b>3</b>	<b>n</b>

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			n	

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1		1	9	
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1		1	9	
0	m	3	?	
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125 possible paths

Distance array d

		4	8	
2				
1		1	9	
0	m	3	6	
-1		6		
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1		1	8	4
0	m	3	5	8
-1		6	5	9
-2		2	8	1
		1	2	3
			n	

Distance array d

		4	8	
2				
1		1	9	
0	m	3	6	
-1		6	7	
-2		2	10	
		1	2	3
			n	

125 possible paths

$$\text{Constraint: } |m(n) - m(n - 1)| \leq 1$$



# Dynamic programming: accumulation

Alignment error array e

		4	7	3
2				
	1	1	8	4
m	0	3	5	8
	-1	6	5	9
	-2	2	8	1
		1	2	3
			n	

Distance array d

		4	8	11
2				
	1	1	9	10
m	0	3	6	14
	-1	6	7	15
	-2	2	10	8
		1	2	3
			n	

125 possible paths

Constraint:  $|m(n) - m(n - 1)| \leq 1$

# Dynamic programming: accumulation

Alignment error array e

		4	7	3
2		4	7	3
1		1	8	4
m 0		3	5	8
-1		6	5	9
-2		2	8	1
		1	2	3
			n	

125 possible paths

Distance array d

		4	8	11
2		4	8	11
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	1	1	9	10
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2		4	7	3
1		1	8	4
m 0		3	5	8
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-2		2	8	1
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			n	

125 possible paths

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		4	8	11
2		4	8	11
1		1	9	10
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1		1	8	4
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-2		2	8	1
		1	2	3
			n	

125 possible paths

Distance array d

		4	8	11
2				
1		1	9	10
0	m	3	6	14
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-2		2	10	8
		1	2	3
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		4	7	3
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	1	1	8	4
m	0	3	5	8
	-1	6	5	9
	-2	2	8	1
		1	2	3
			n	

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Distance array d

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	1	1	9	10
m	0	3	6	14
	-1	6	7	15
	-2	2	10	8
		1	2	3
			n	

5 possible paths

Constraint:  $|m(n) - m(n - 1)| \leq 1$

# Dynamic programming: backtracking

Alignment error array e

		4	7	3
2				
	1	1	8	4
m	0	3	5	8
	-1	6	5	9
	-2	2	8	1
		1	2	3
			n	

125 possible paths

Distance array d

		4	8	11
2				
	1	1	9	10
m	0	3	6	14
	-1	6	7	15
	-2	2	10	8
		1	2	3
			n	

5 possible paths

Constraint:  $|m(n) - m(n - 1)| \leq 1$

# Dynamic programming: backtracking

Alignment error array e

		1	2	3
2	4	7	3	
1	1	8	4	
m 0	3	5	8	
-1	6	5	9	
-2	2	8	1	
		1	2	3
			n	

125 possible paths

Distance array d

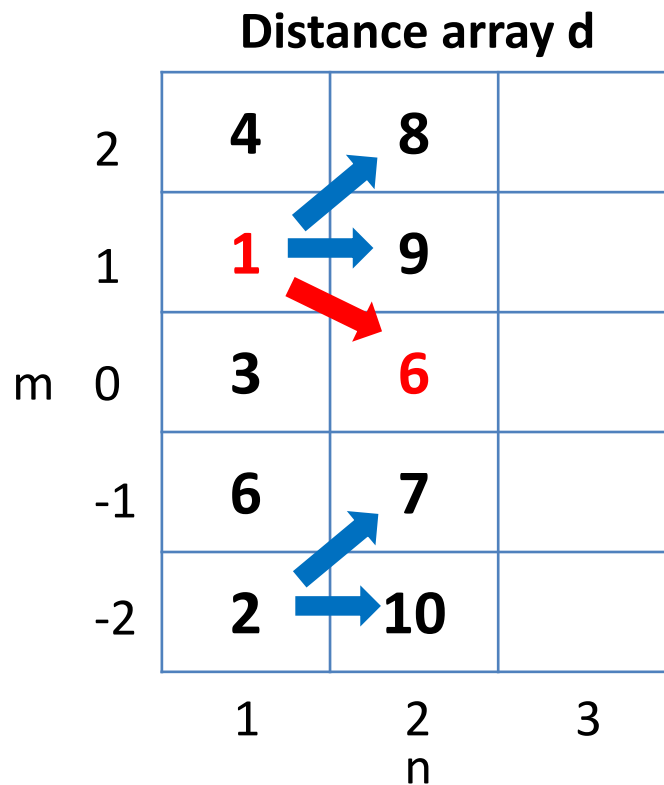
		1	2	3
2	4	8	11	
1	1	9	10	
m 0	3	6	14	
-1	6	7	15	
-2	2	10	8	
		1	2	3
			n	

5 possible paths

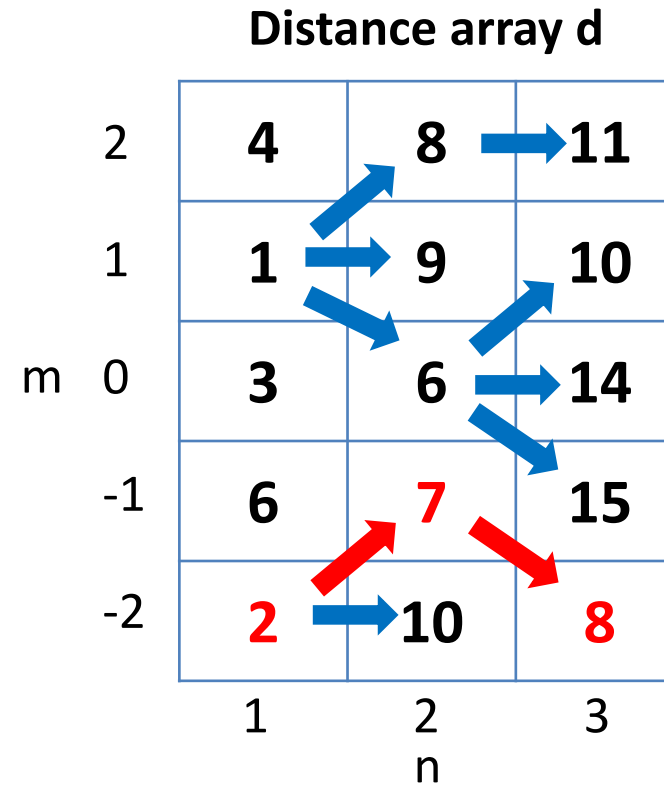
Constraint:  $|m(n) - m(n - 1)| \leq 1$   
 Estimated lag sequence:  $m(n) = [-2, -1, -2]$



# Dynamic time warping



$$m(n) = [1, 0]$$



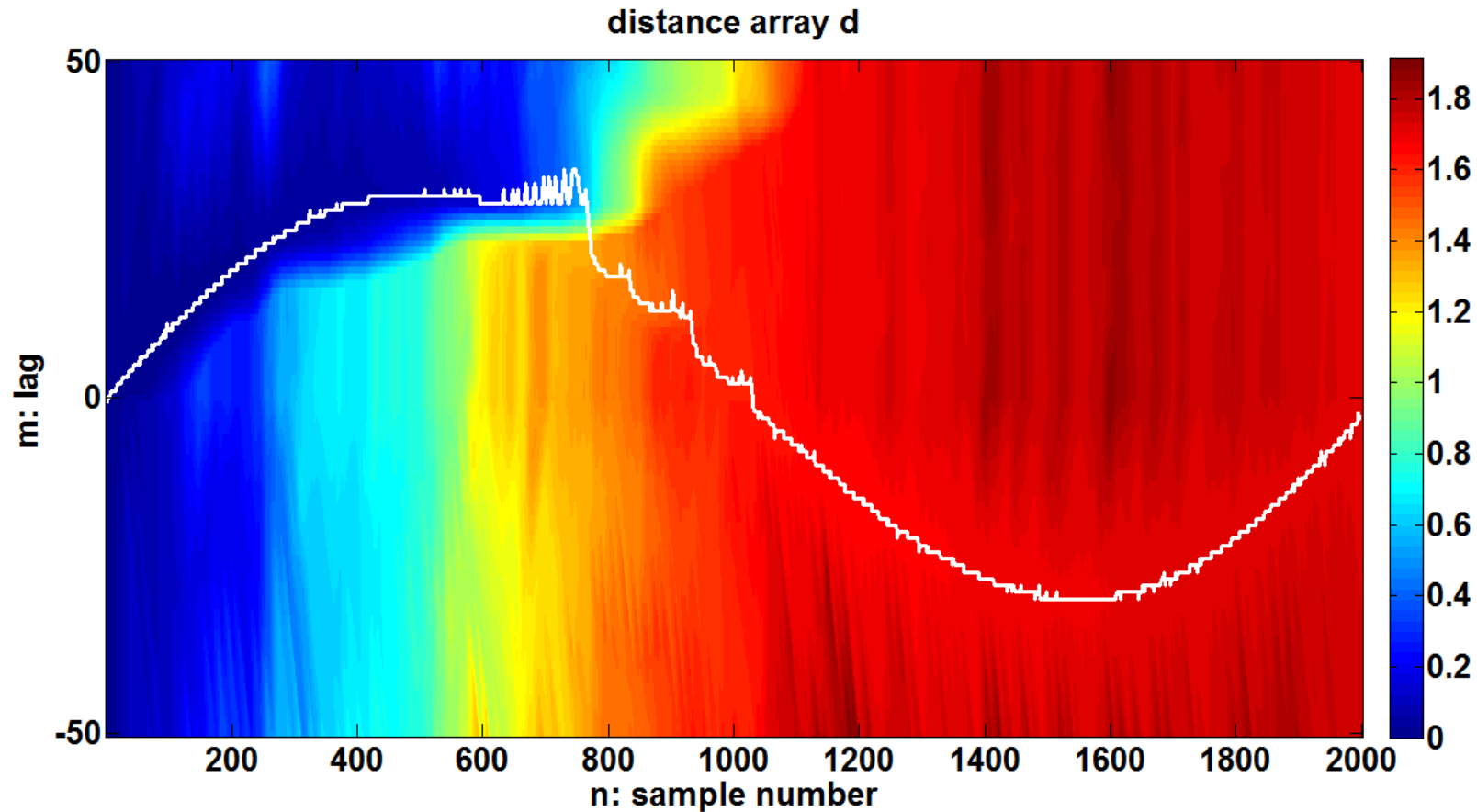
$$m(n) = [-2, -1, -2]$$

Dynamic: optimal path varies at different stages

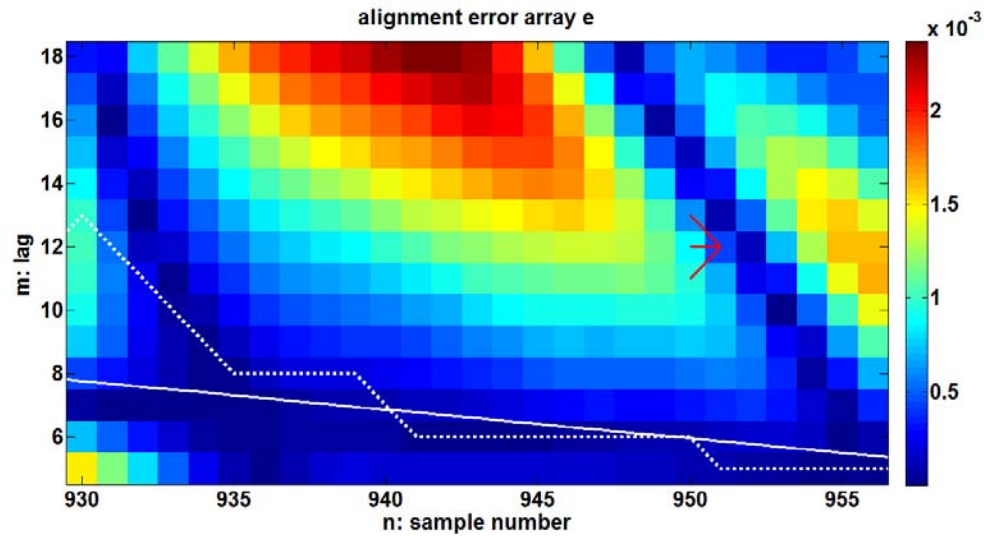
Warping path: lag sequence

# Dynamic time warping

CREWES Matlab toolbox function: *DTW*

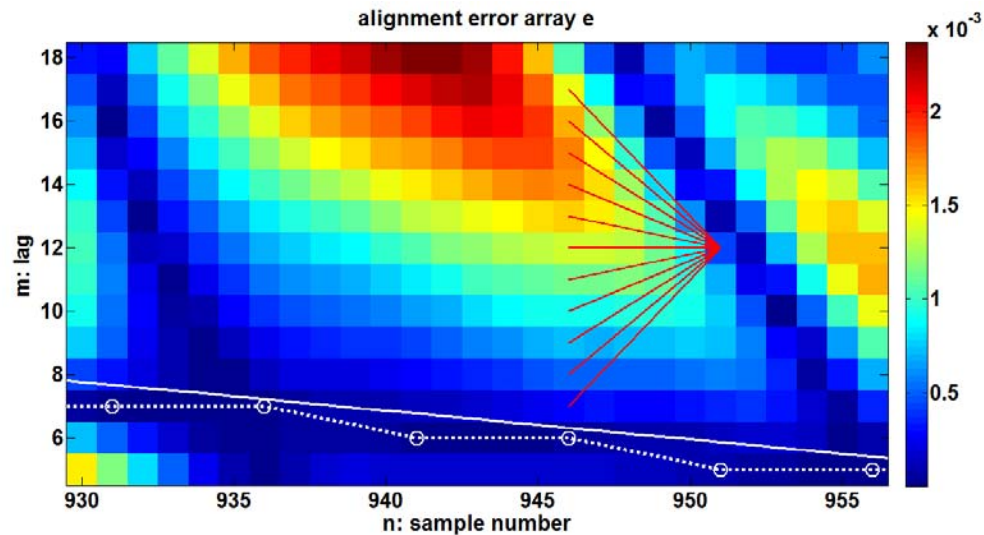


# Smooth dynamic time warping



Constraint:  $|m(n) - m(n - 1)| \leq 1$

**Dynamic time warping**  
 **$h = 1$**

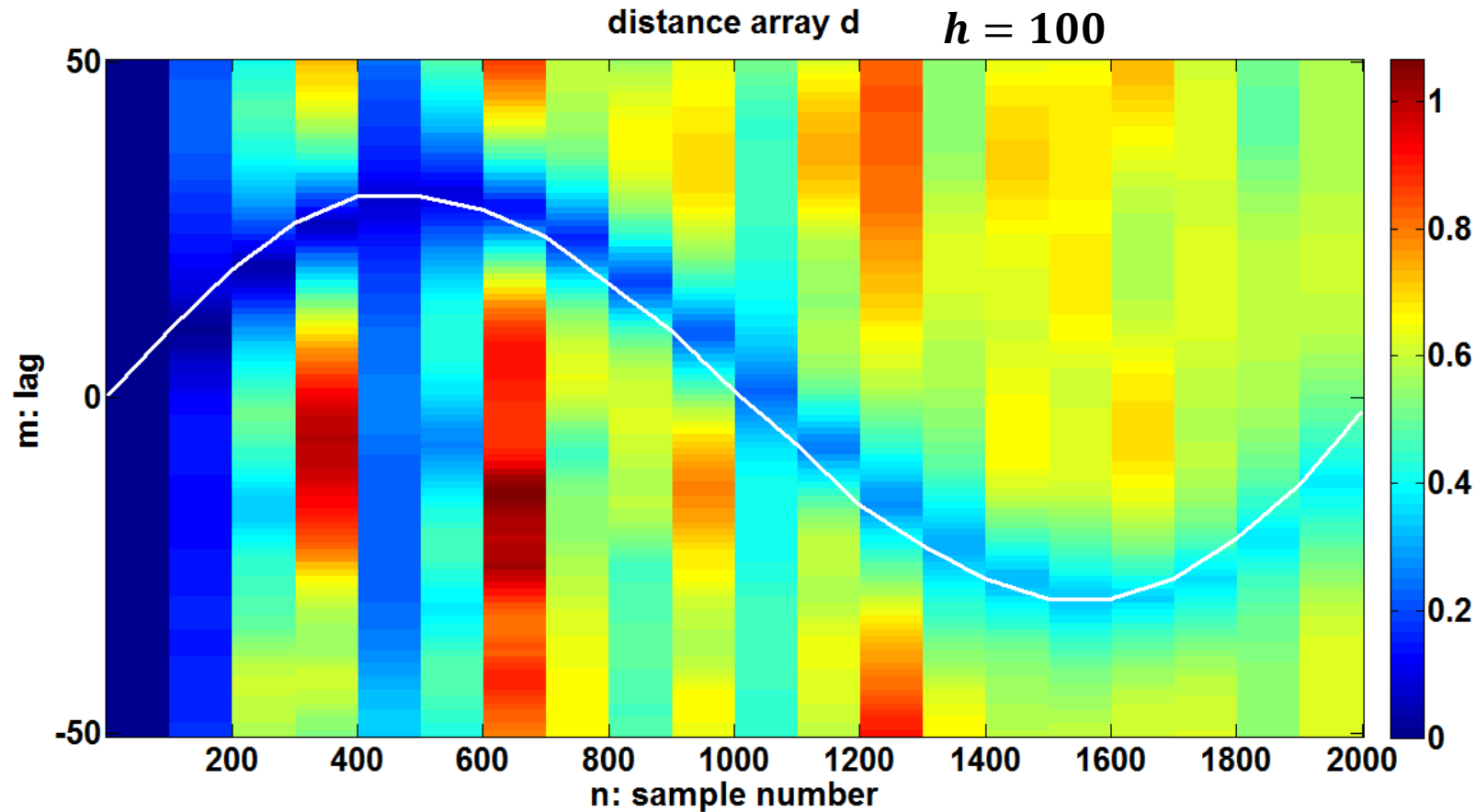


**Smooth dynamic time warping**  
**Coarse sampling interval  $h = 5$**

Compton, S., and Hale, D., 2014,  
Estimating V-P/V-S ratios using smooth  
dynamic image warping: Geophysics

# Smooth dynamic time warping

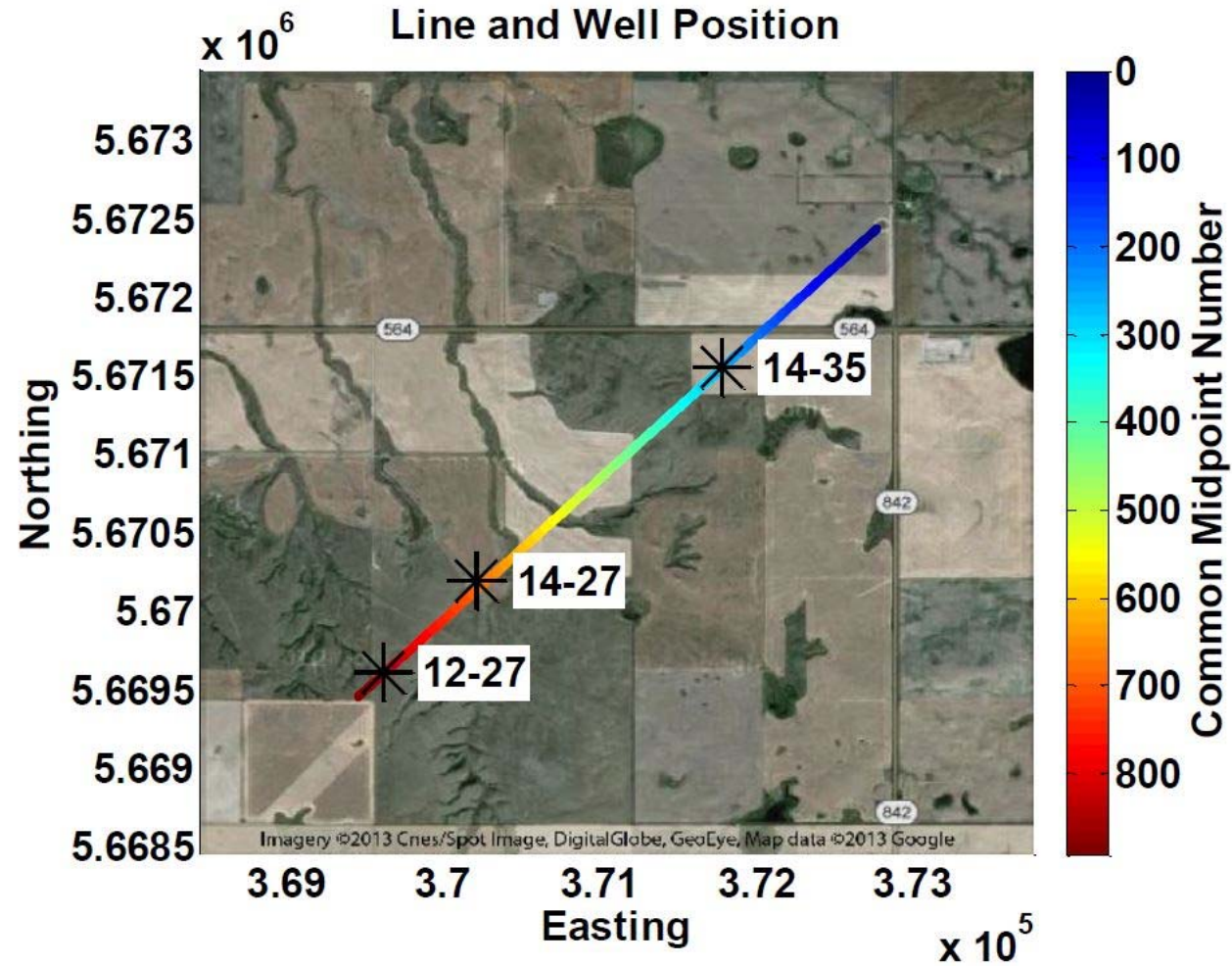
CREWES Matlab toolbox function: *DTWs*



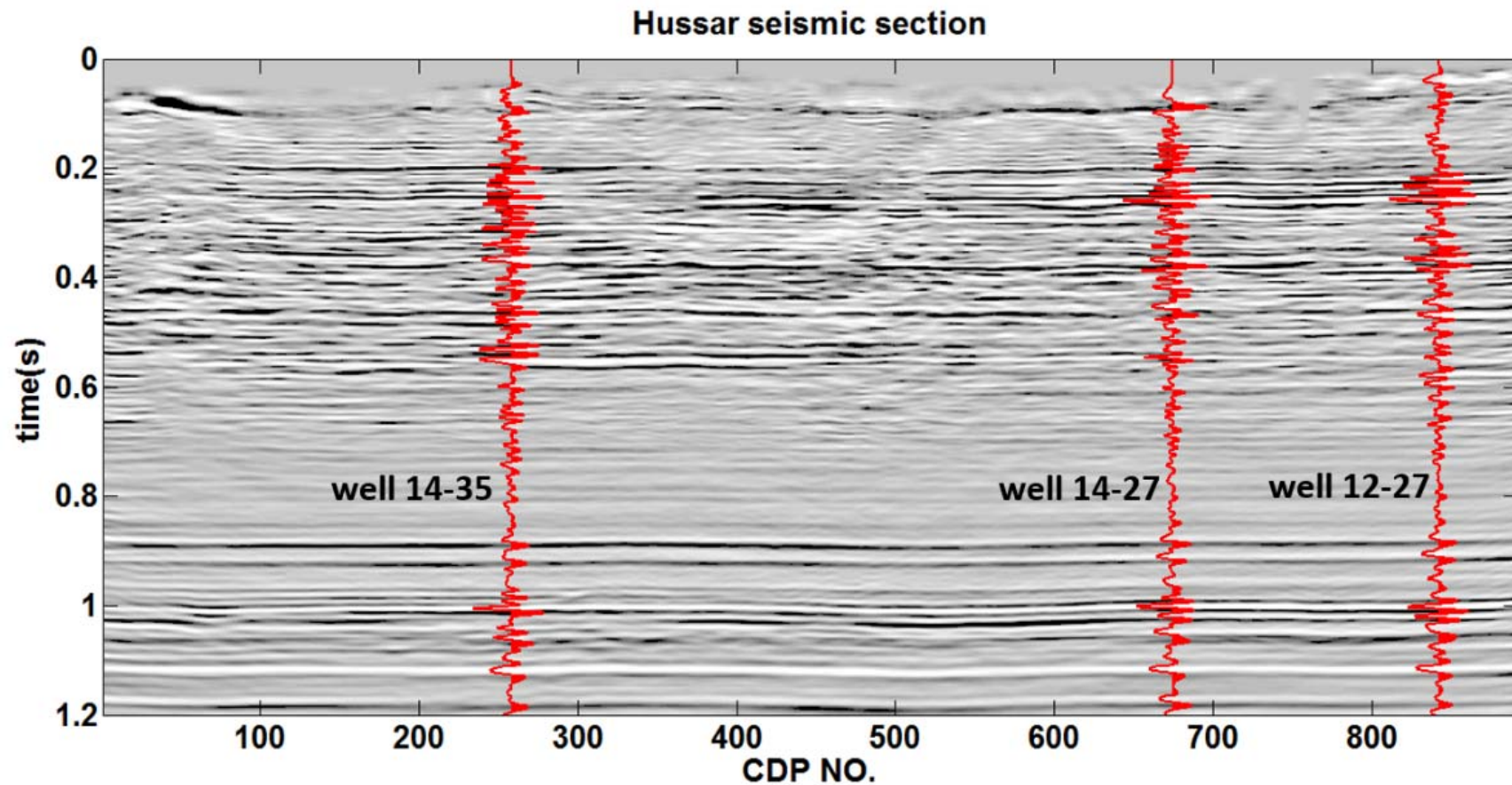
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- **Conclusions**
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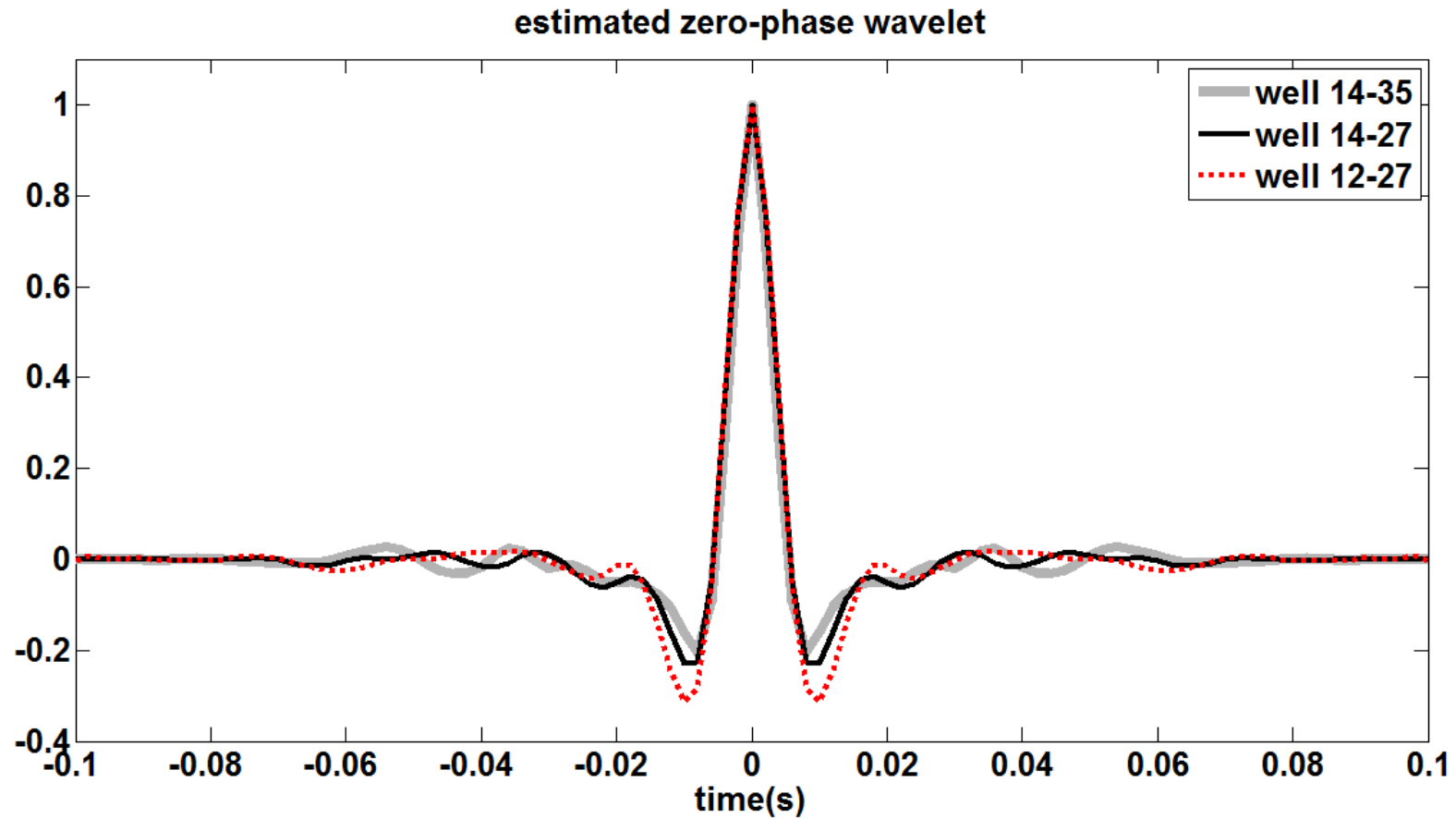
# Hussar experiment



# Zero-offset seismic section

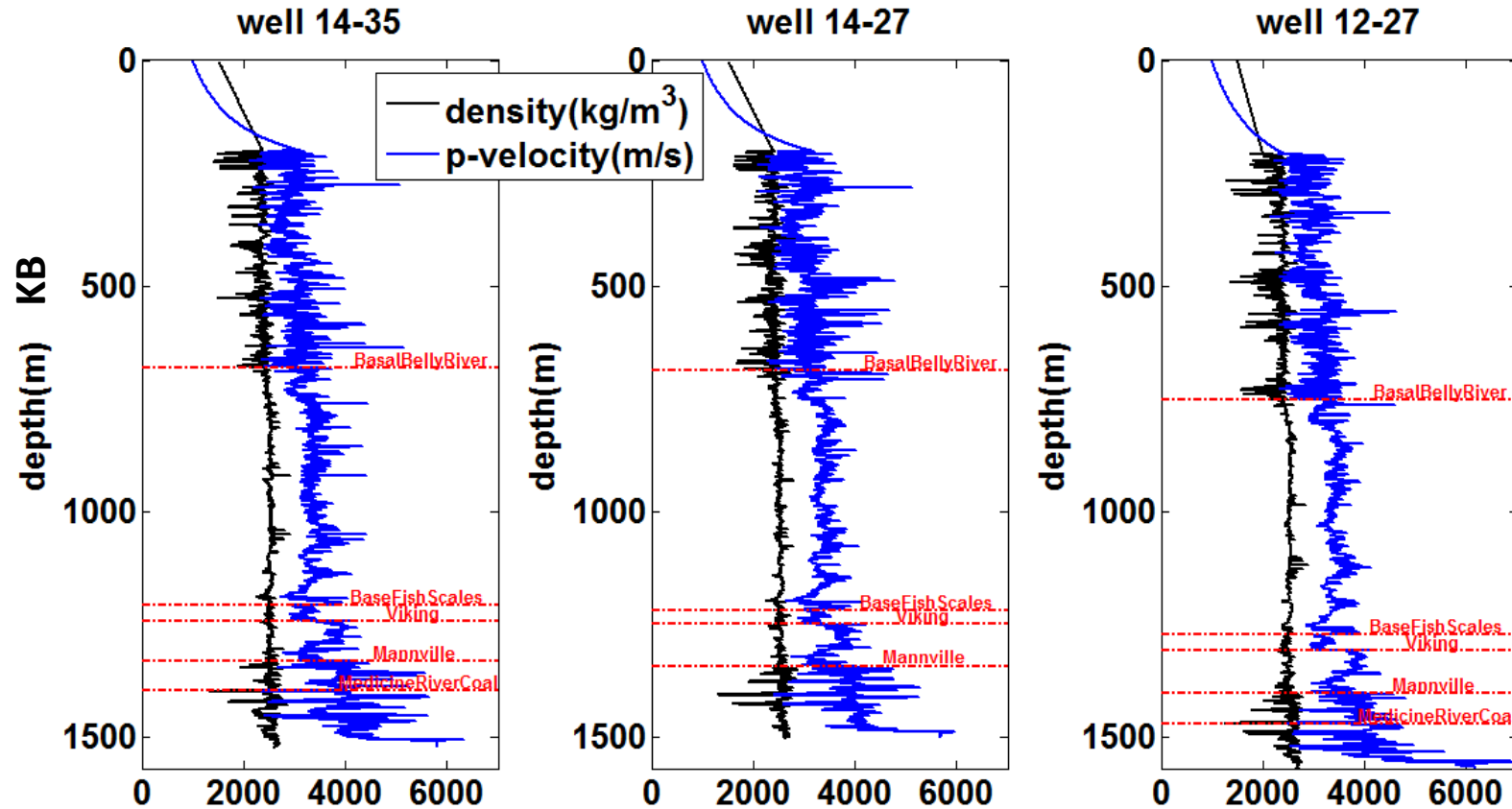


# Estimate seismic wavelet

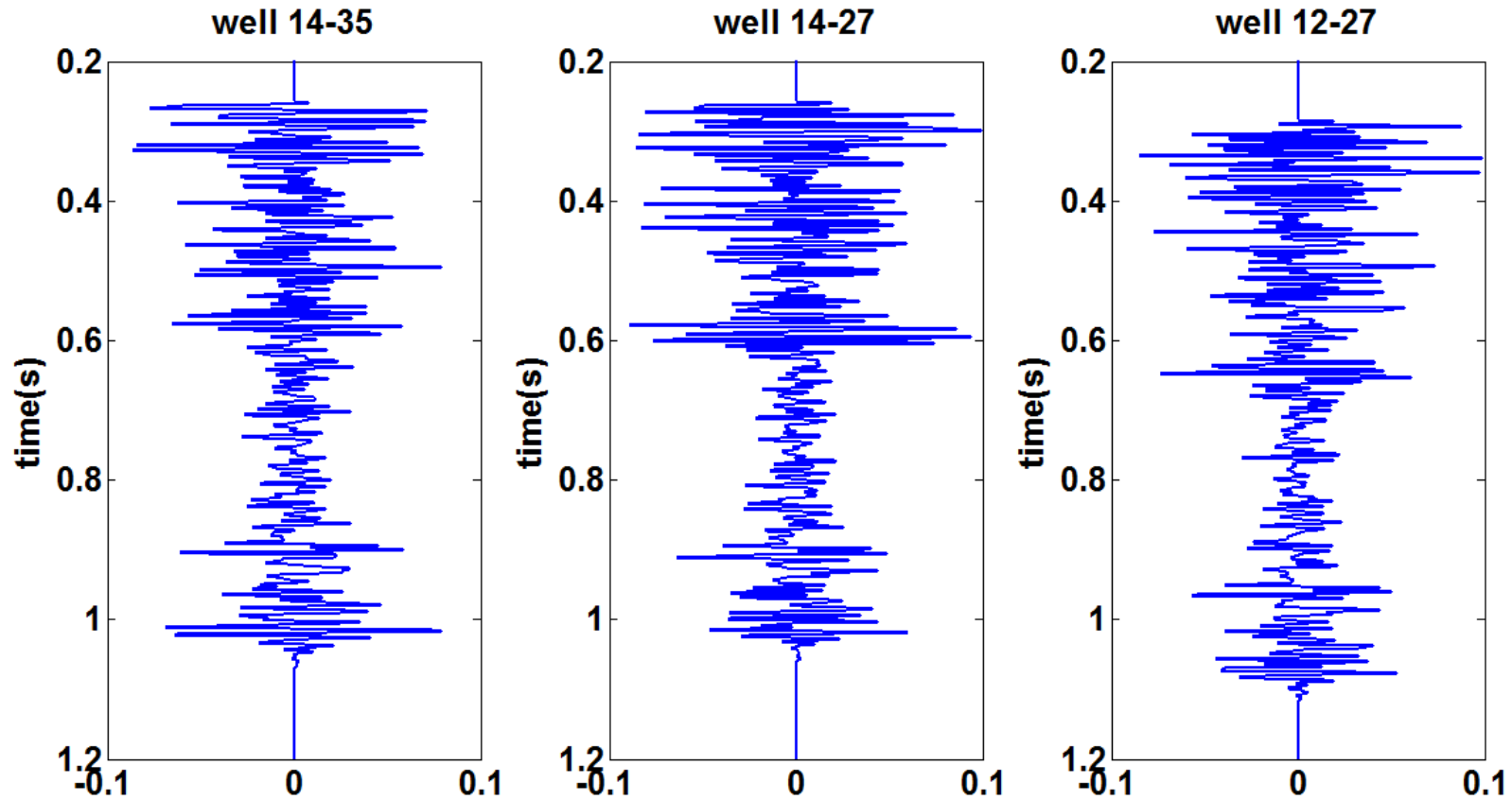




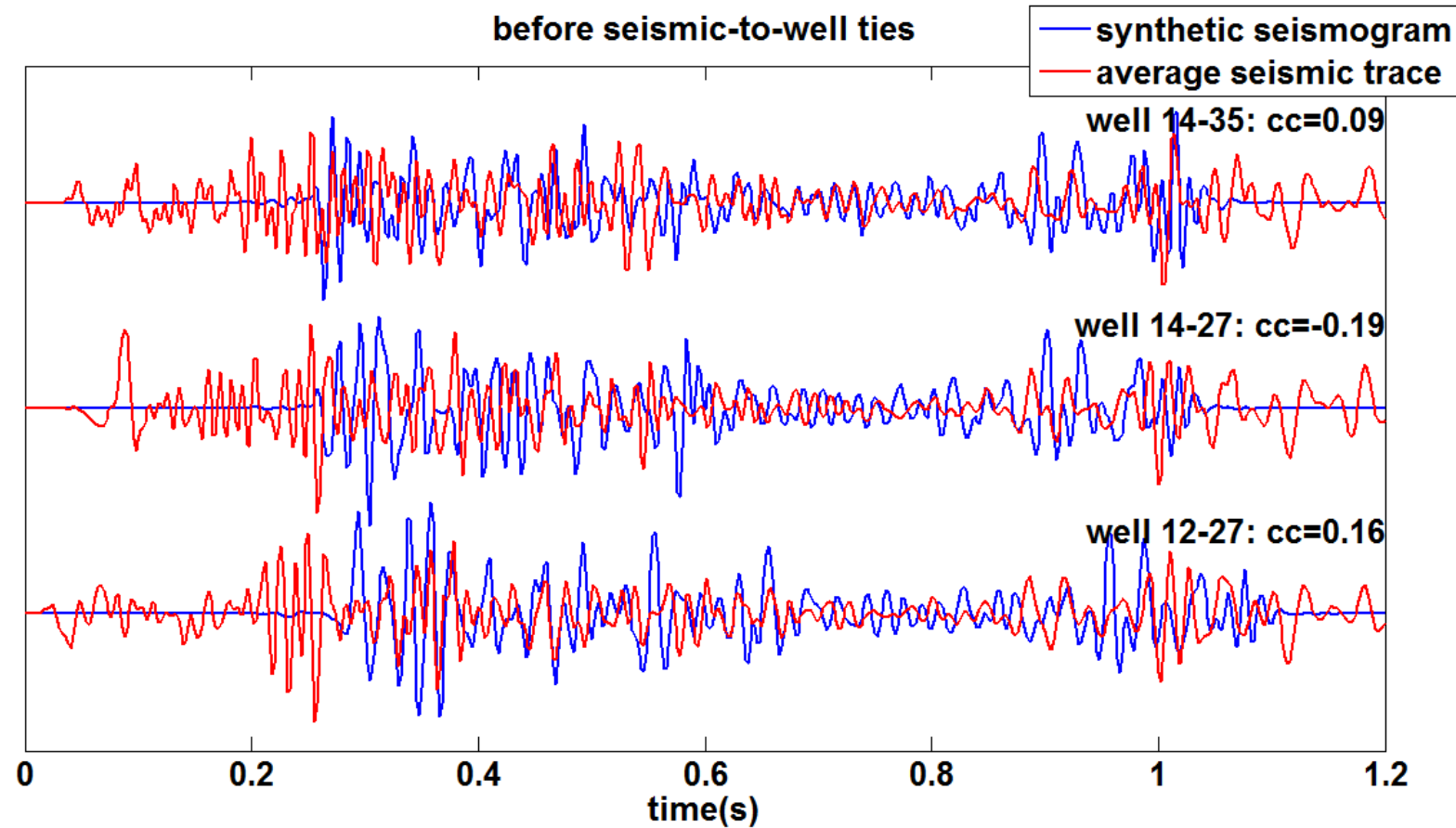
# Well logs after editing



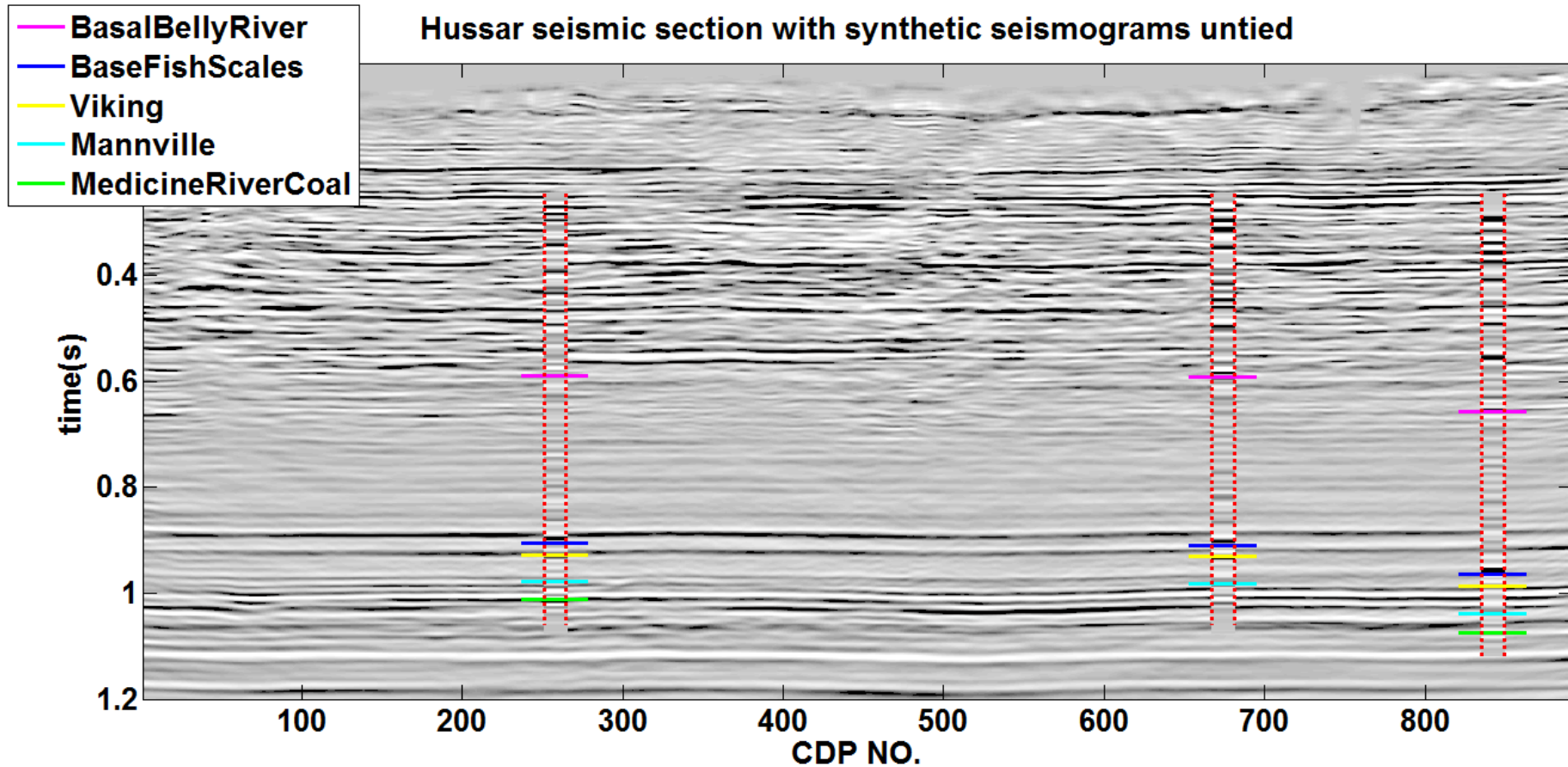
# Well reflectivity



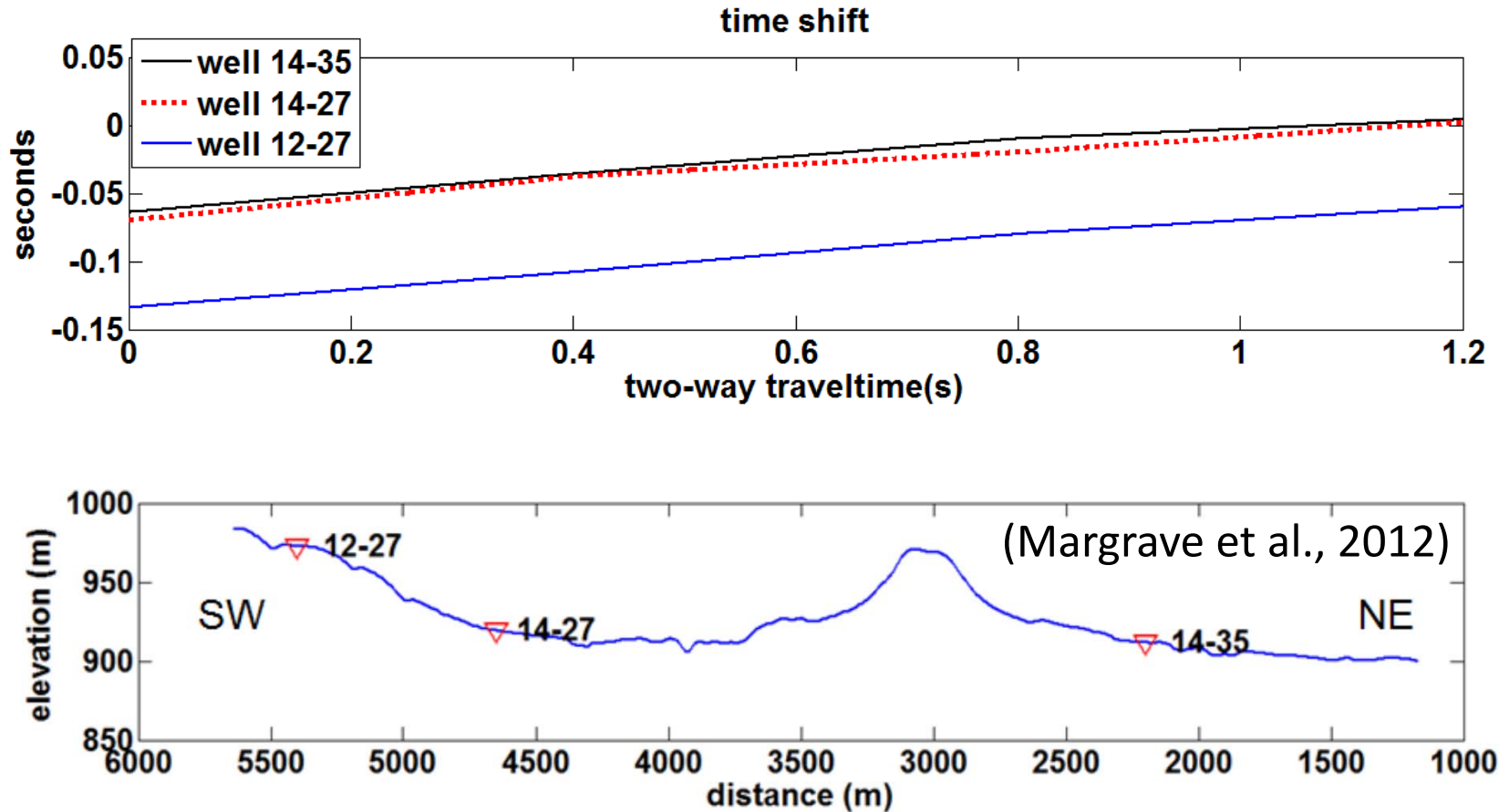
# Construct synthetic seismogram



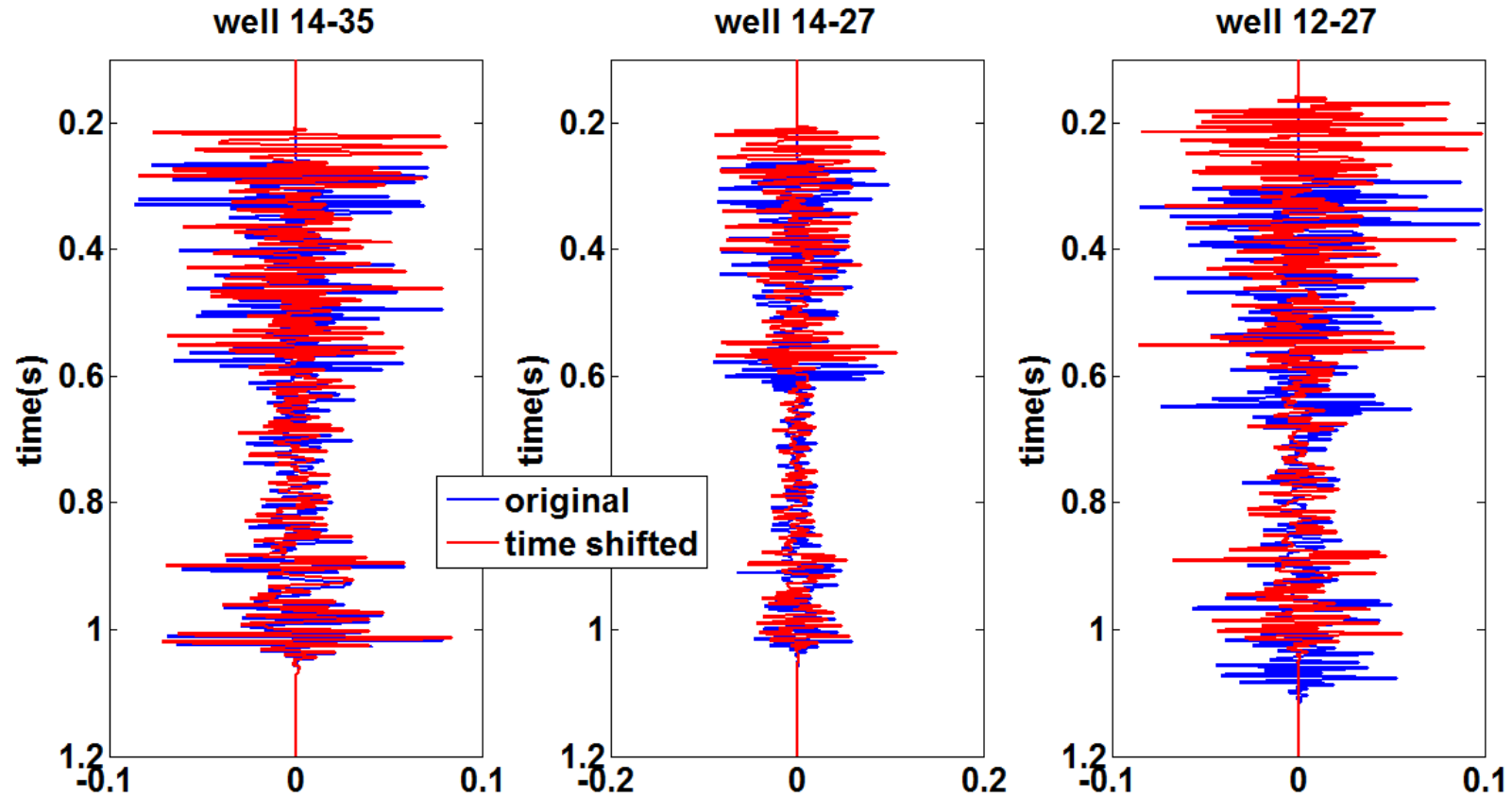
# Before seismic-to-well ties



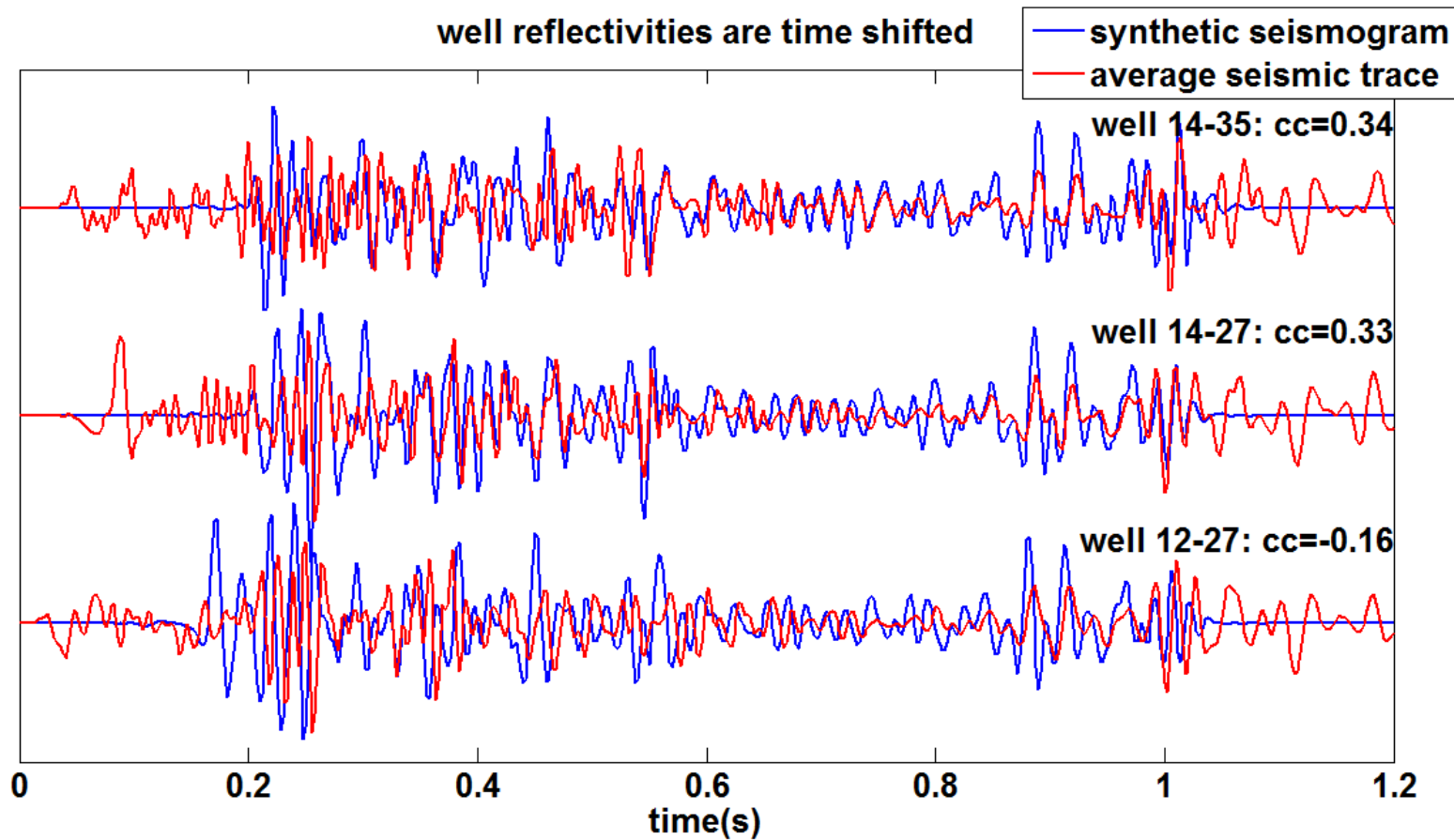
# Estimate time shift by SDTW



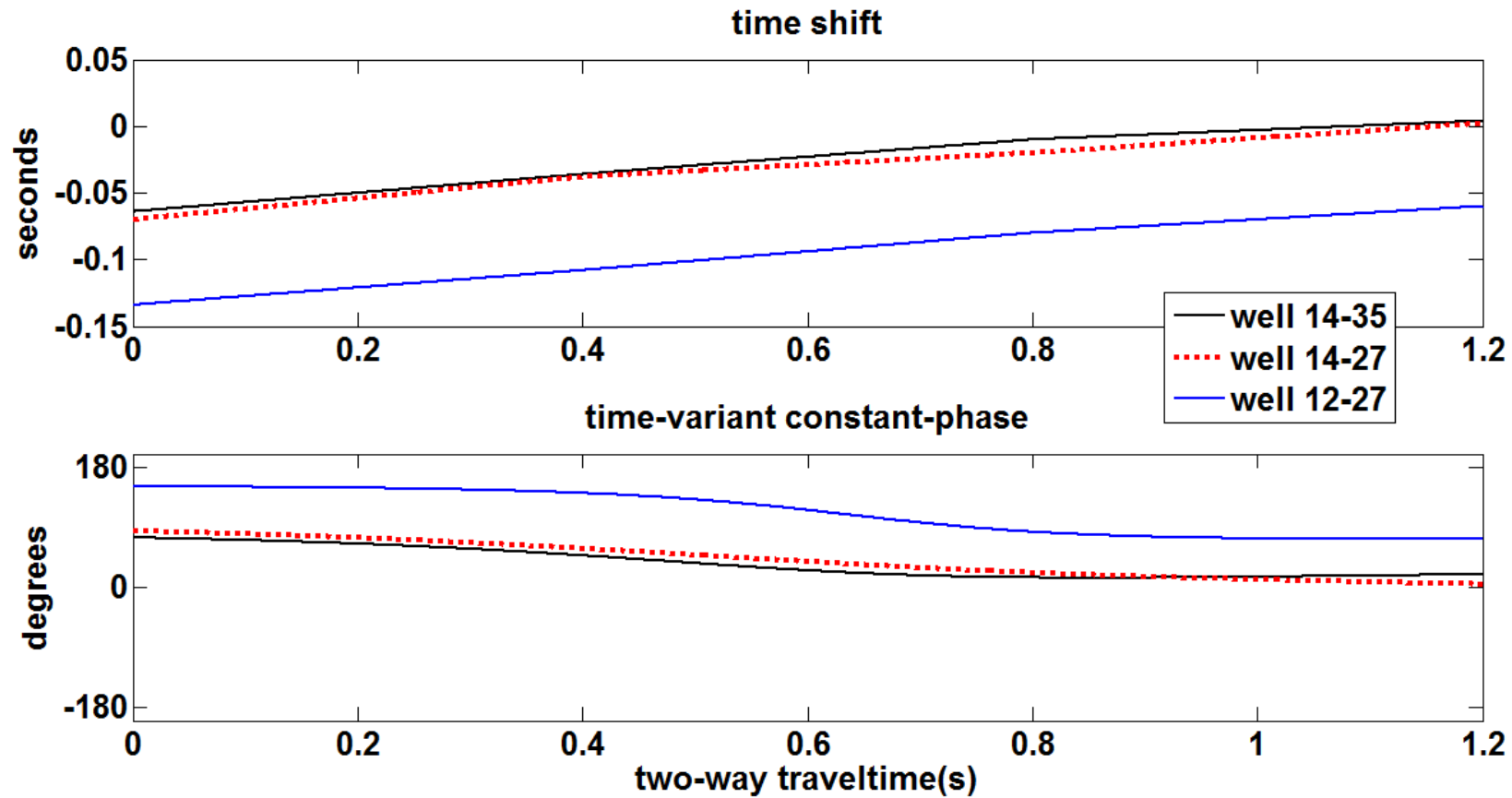
# Time calibration of reflectivity



# Reconstruct synthetic seismogram

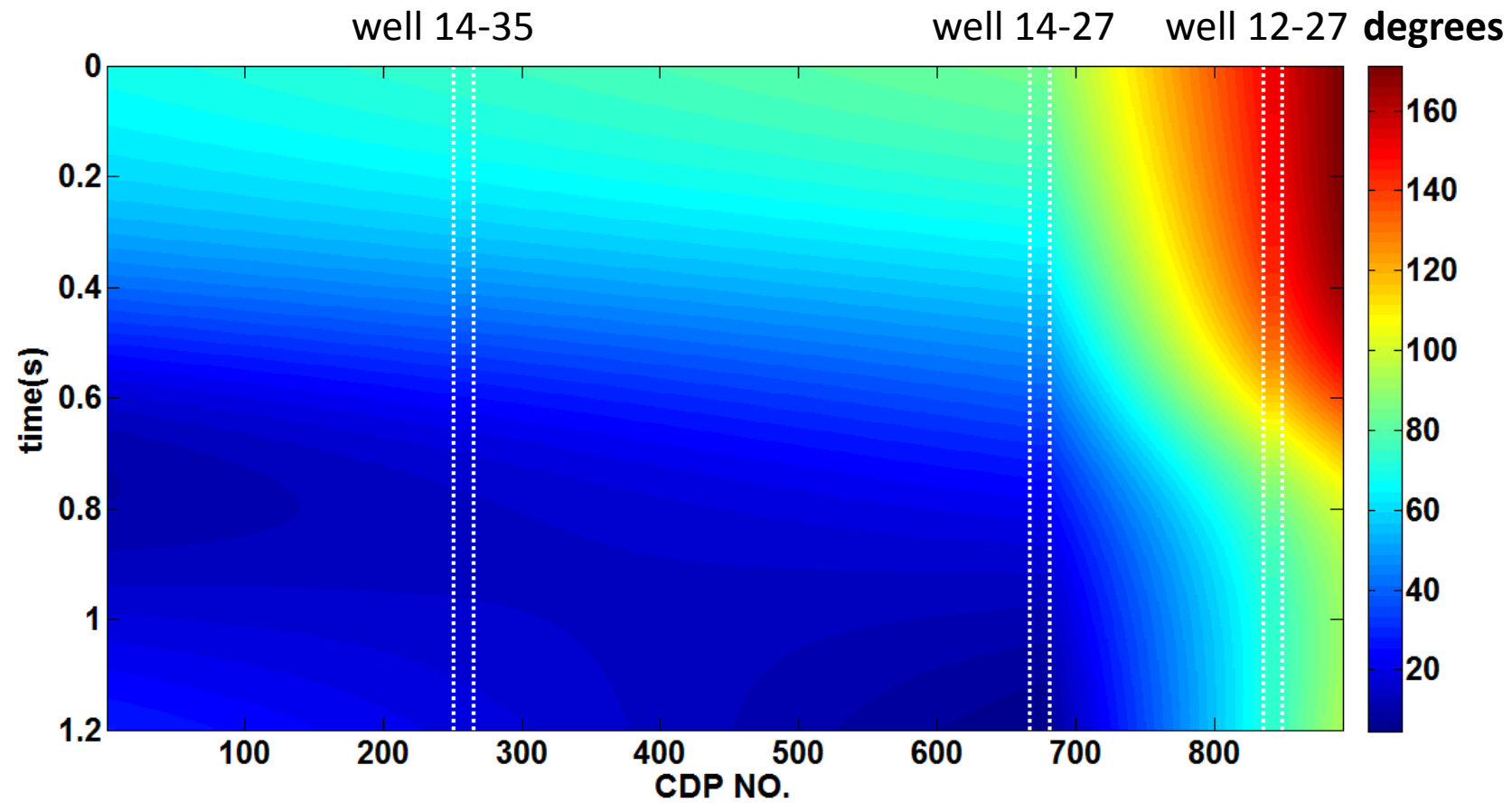


# Estimate time-variant constant-phase



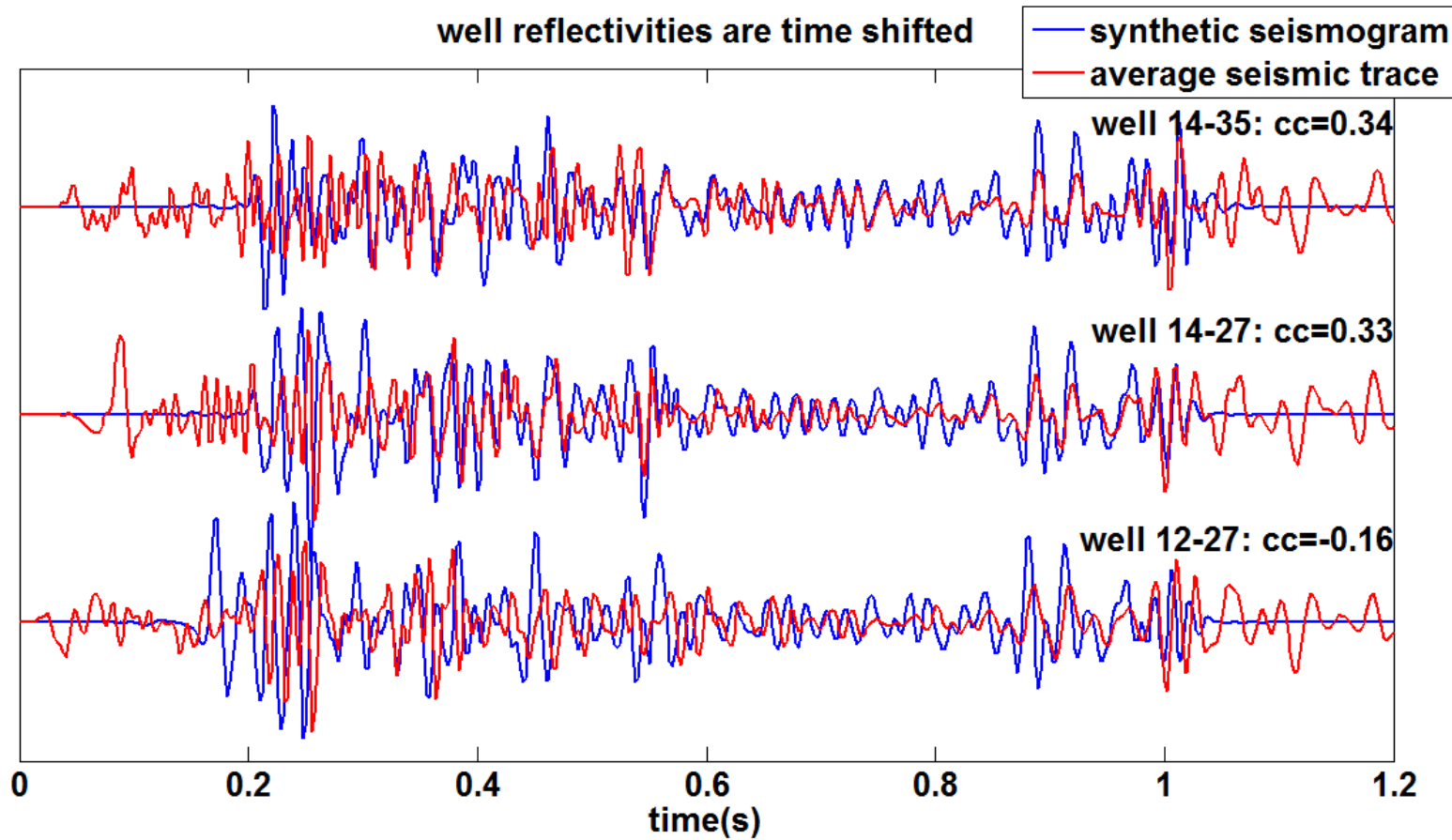


# 2-D time-variant constant-phase

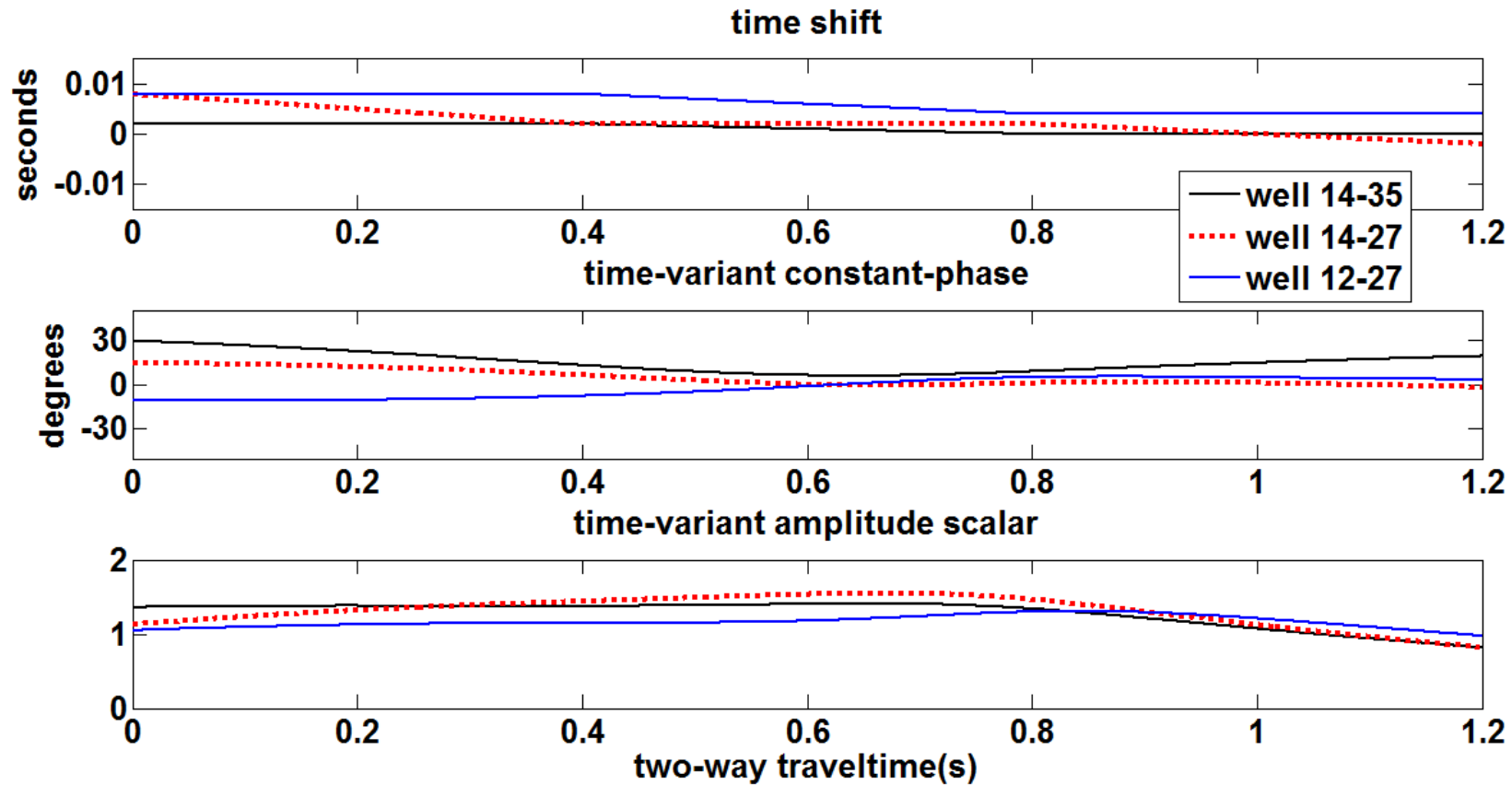


# Second iteration of time calibration

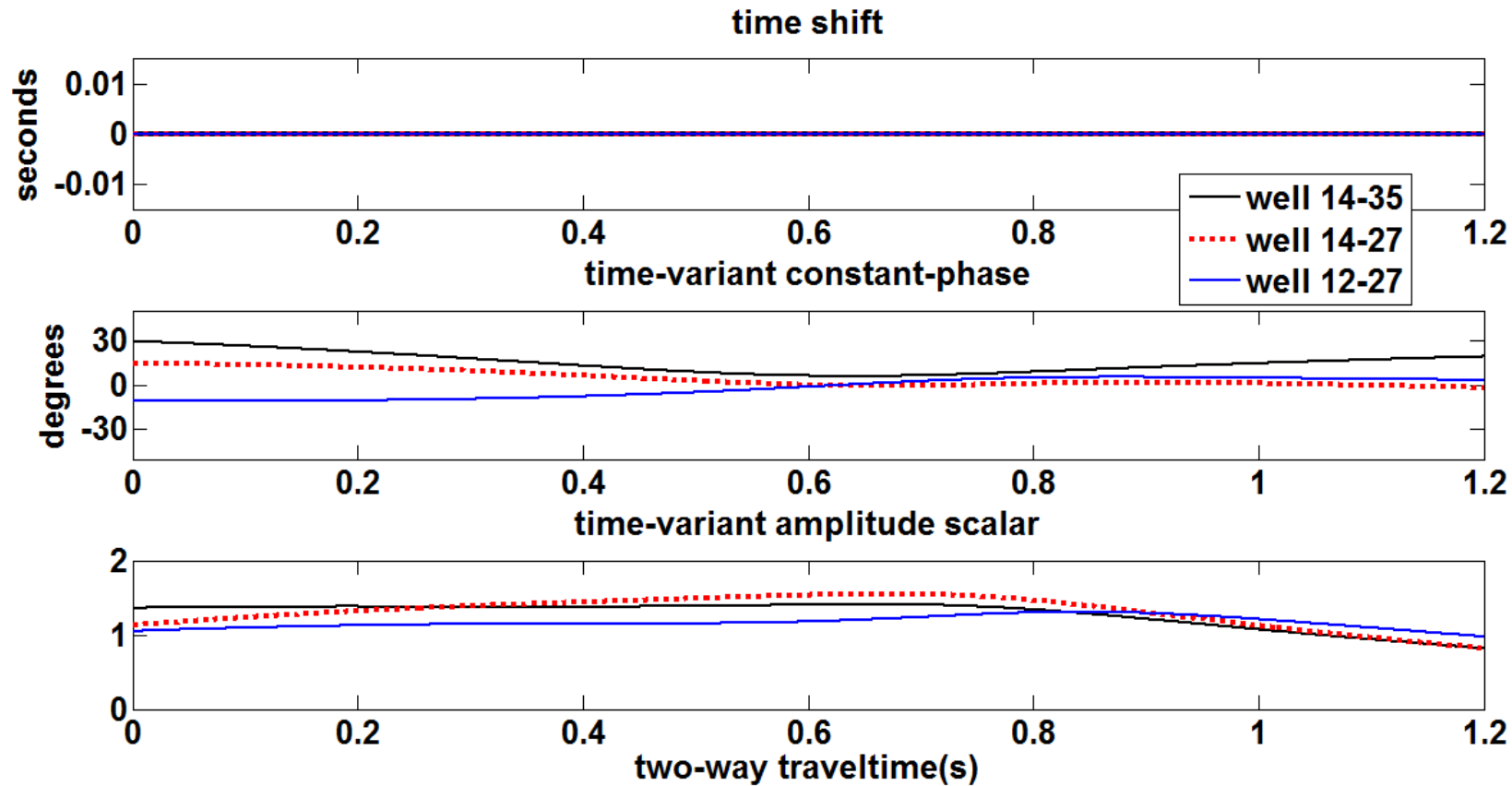
## Synthetic seismogram after time calibration once



# Second iteration of time calibration

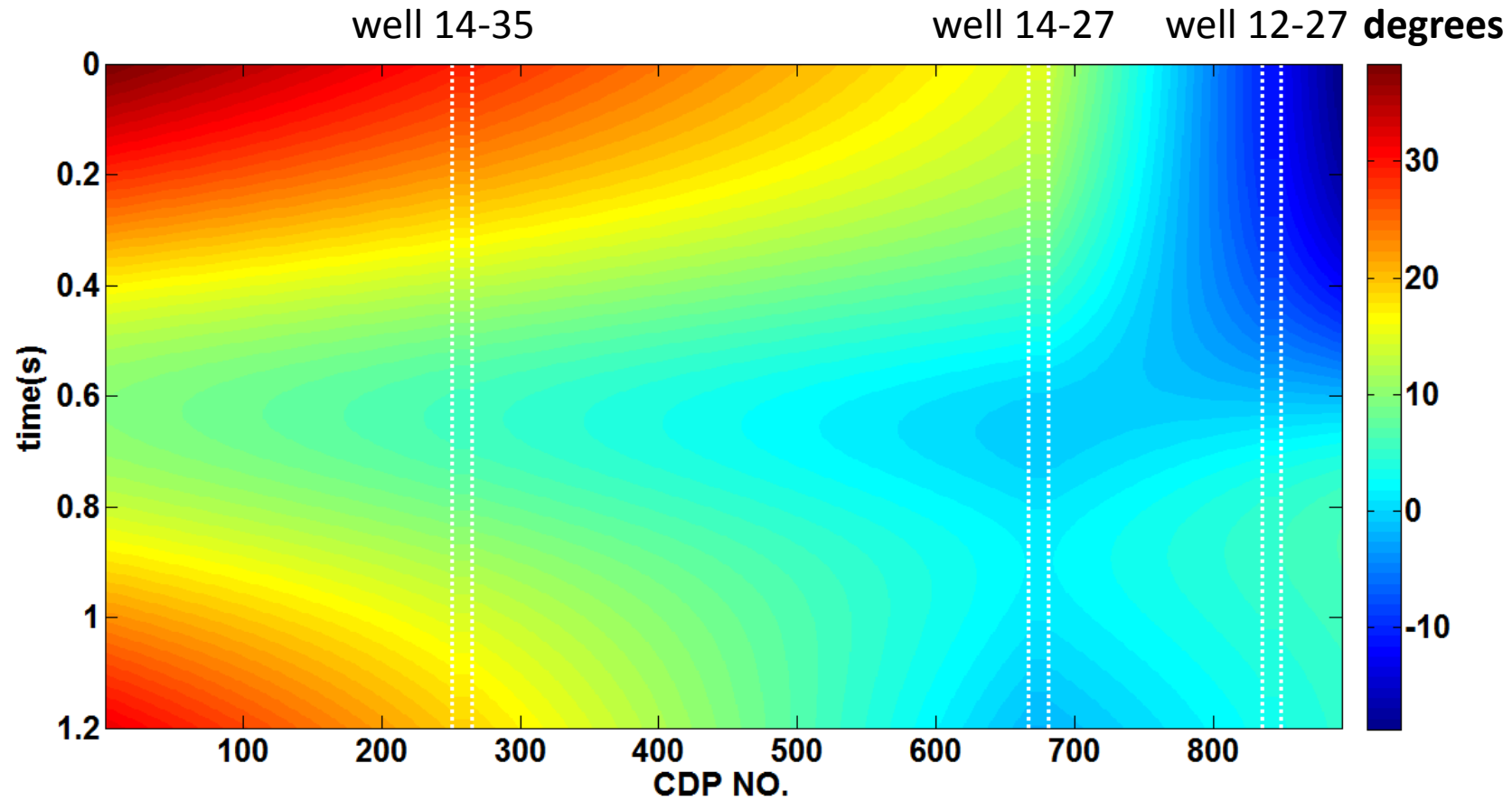


# Third iteration of time calibration

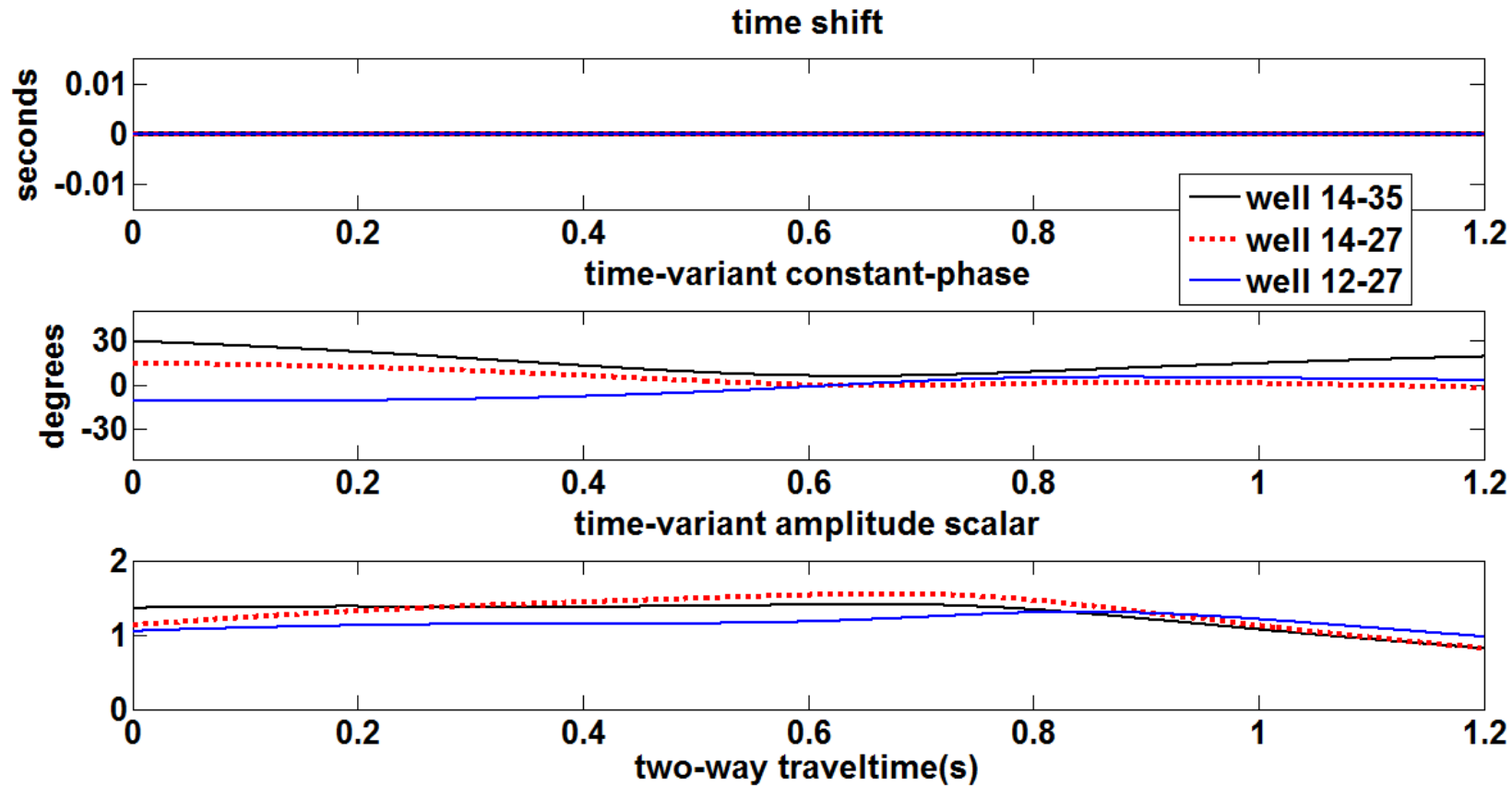


# 2-D time-variant constant-phase

## Two iterations of time calibration

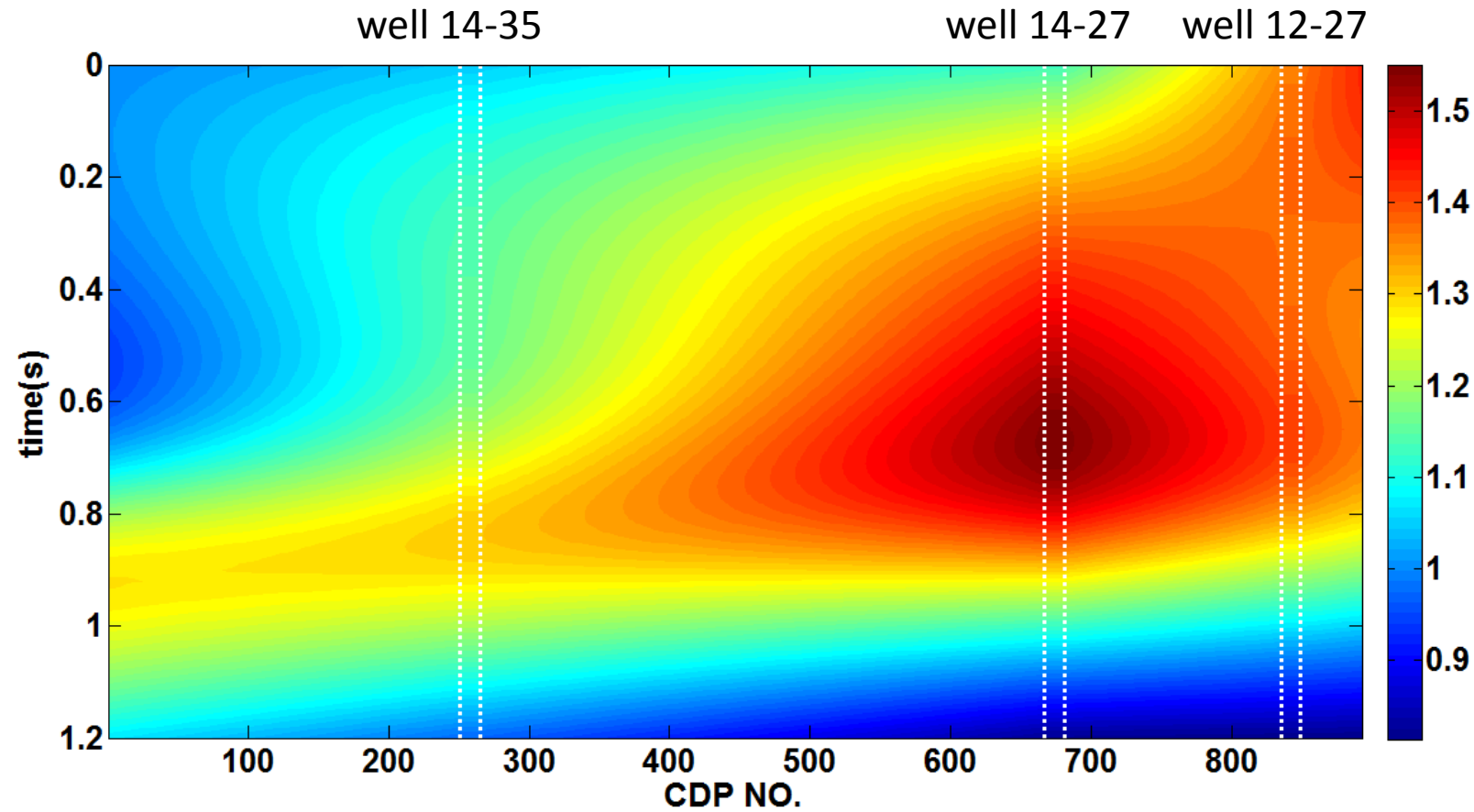


# Third iteration of time calibration

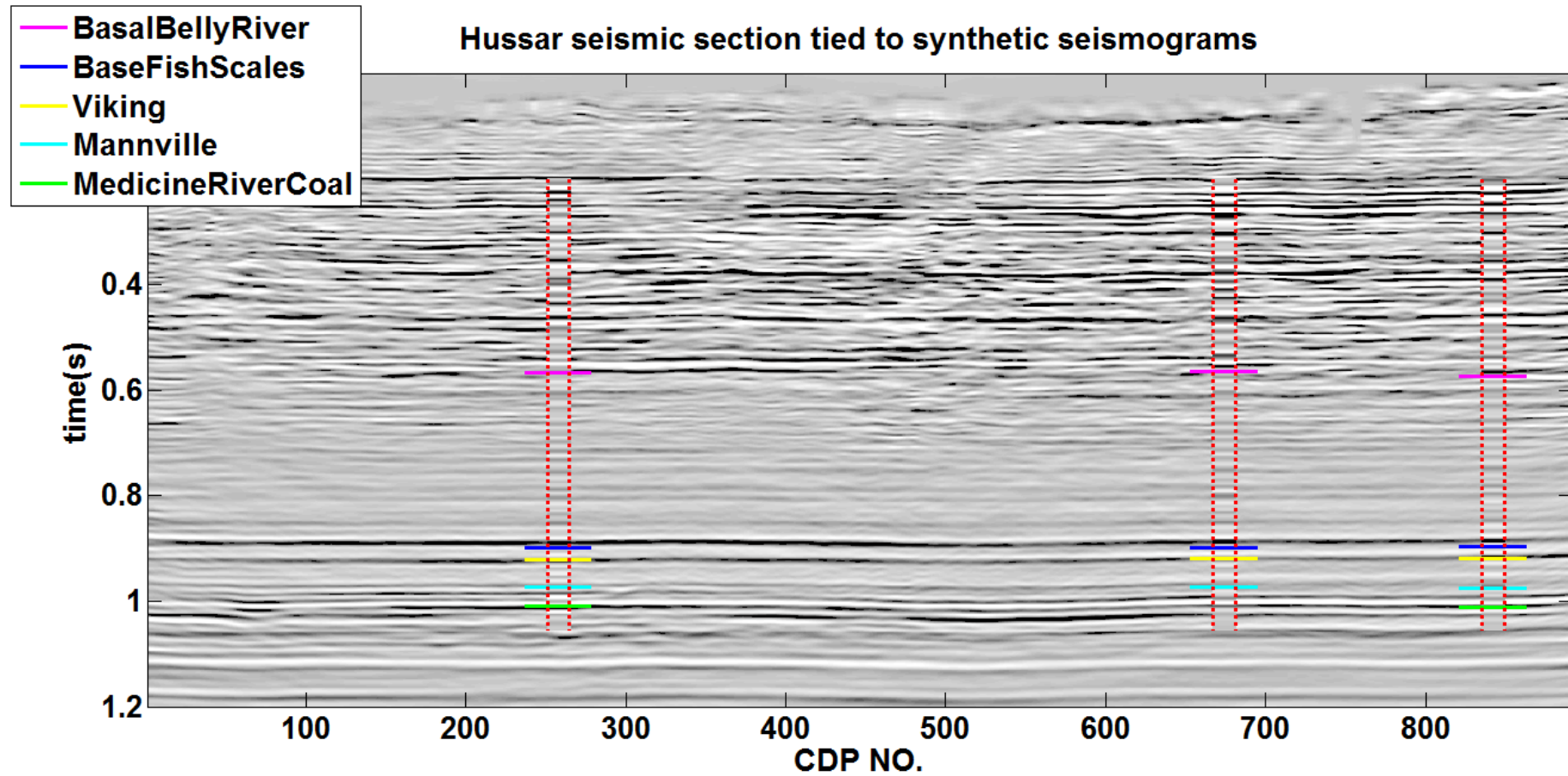


# 2-D time-variant amplitude scalar

## Two iterations of time calibration

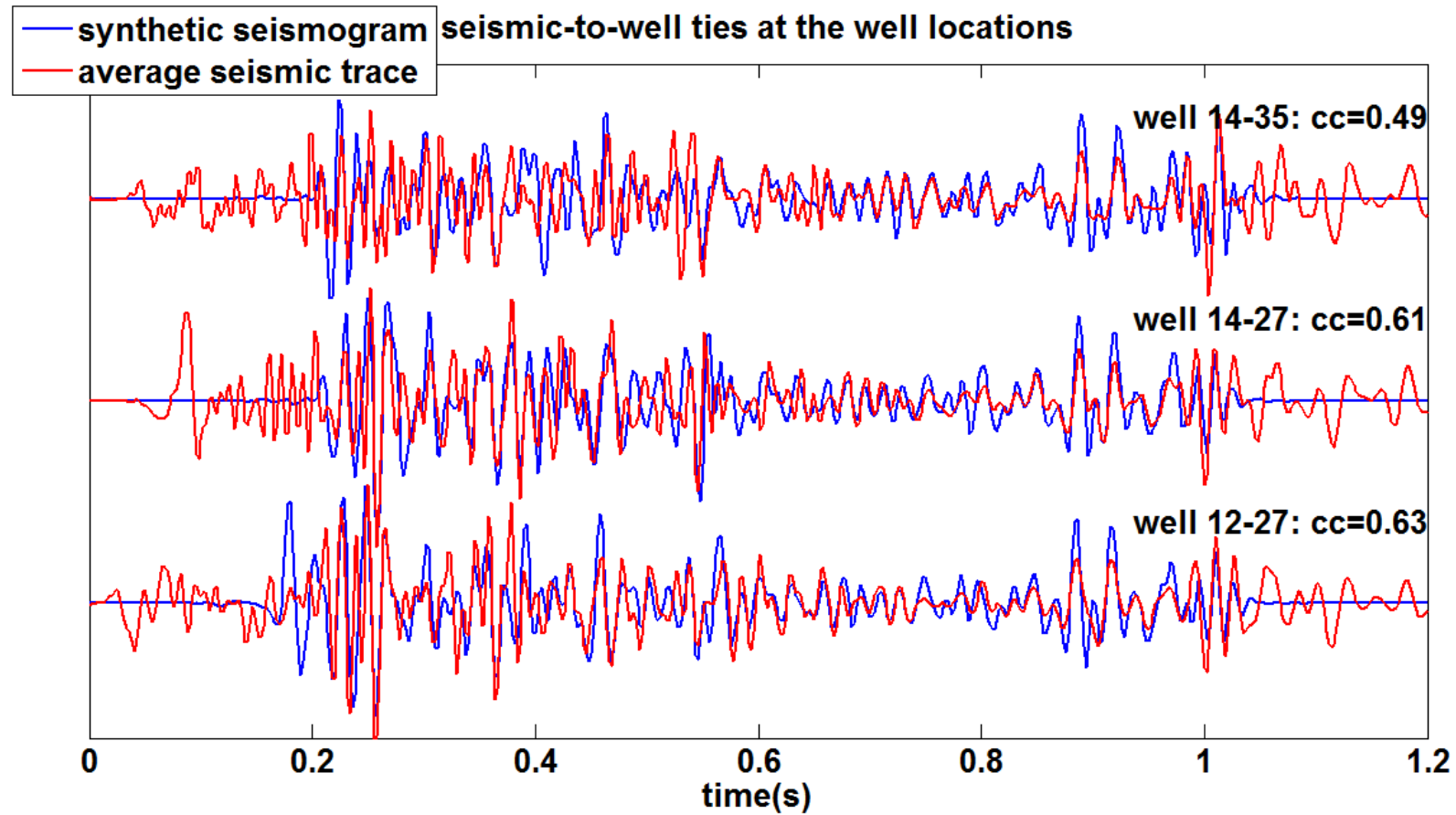


# After seismic-to-well ties

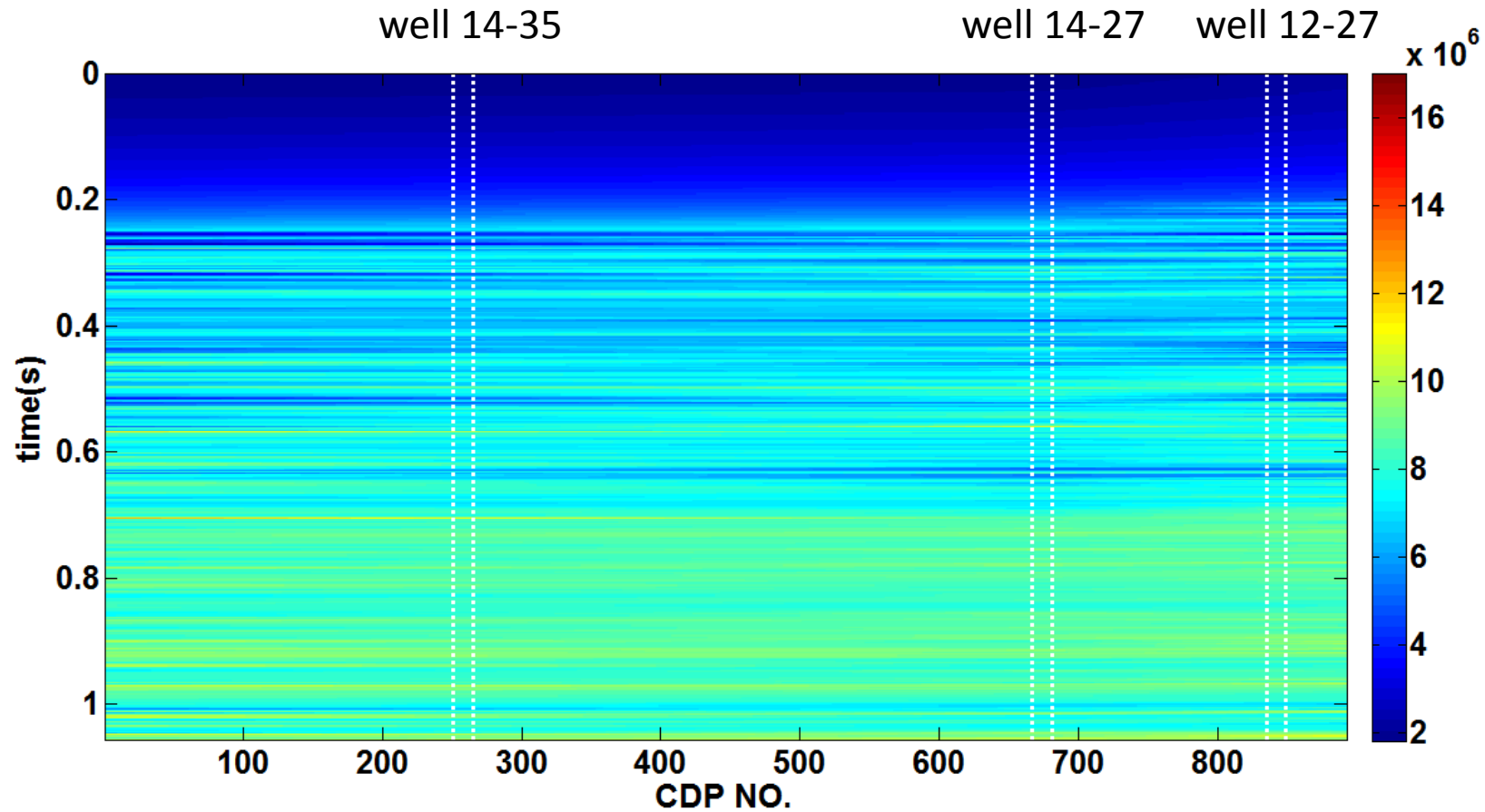




# After seismic-to-well ties



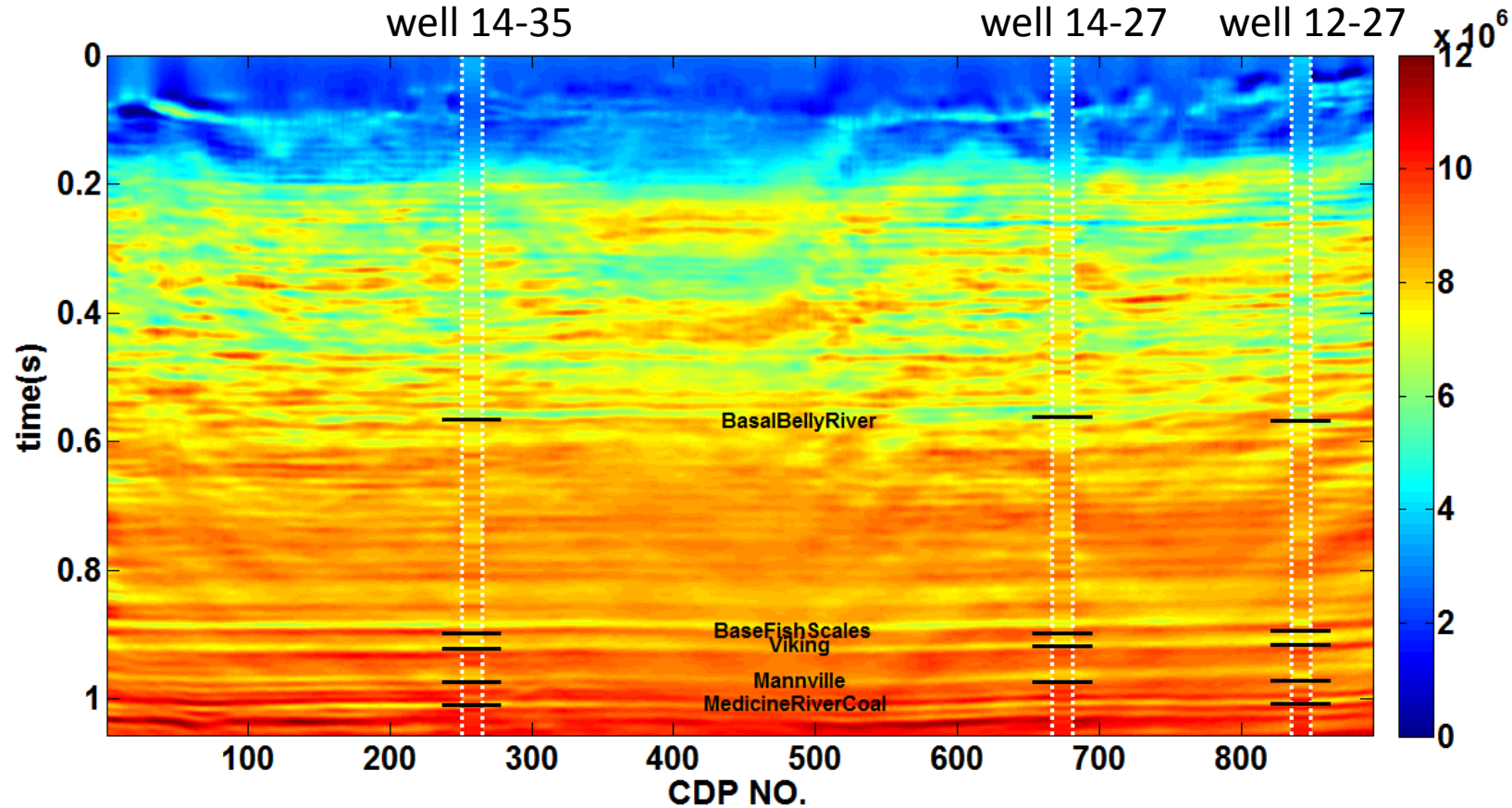
# Interpolated well impedance



# Bandlimited impedance inversion

One iteration of time calibration

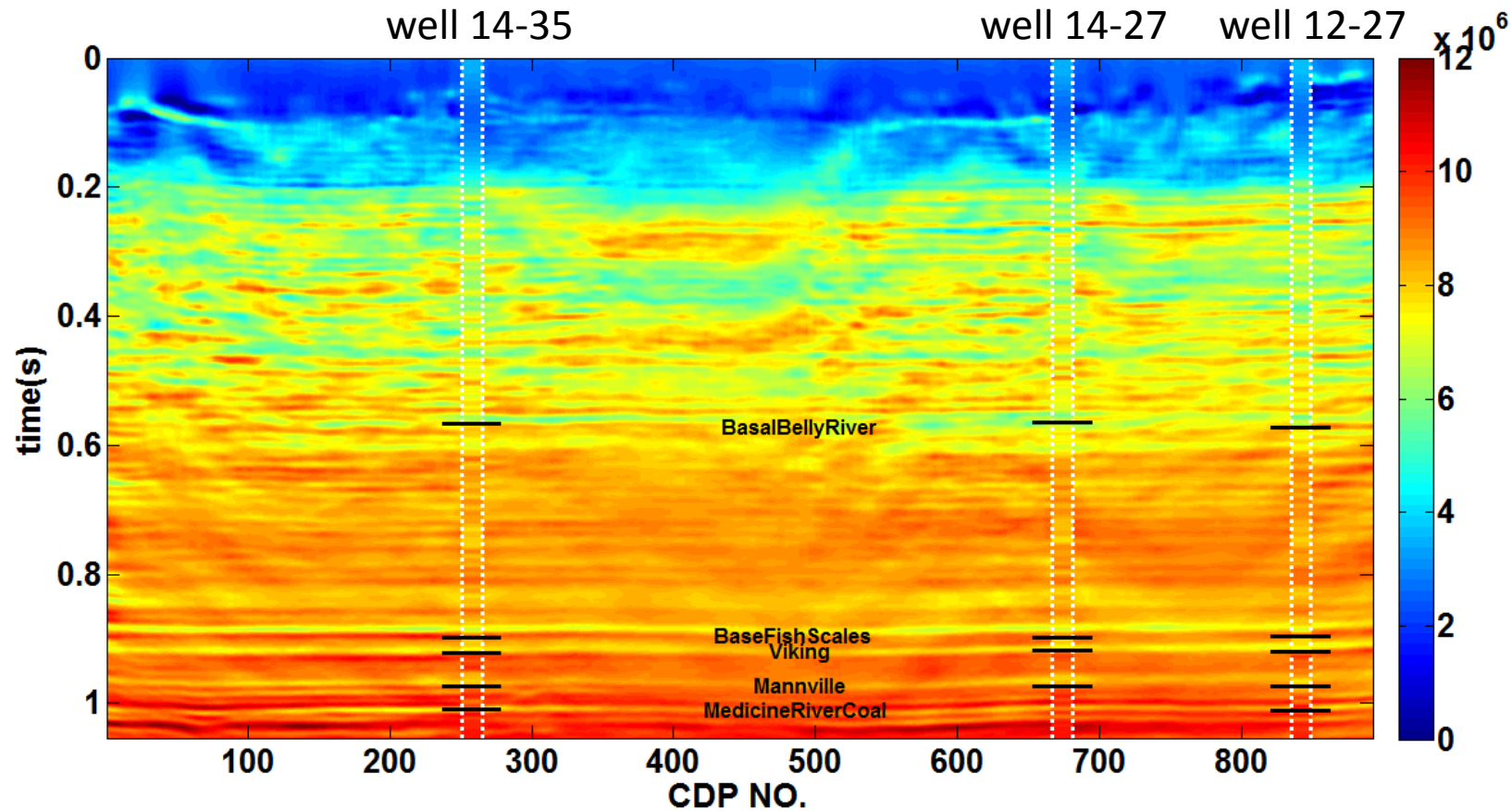
Well: 0-3 Hz  
Seismic: 3-75 Hz



# Bandlimited impedance inversion

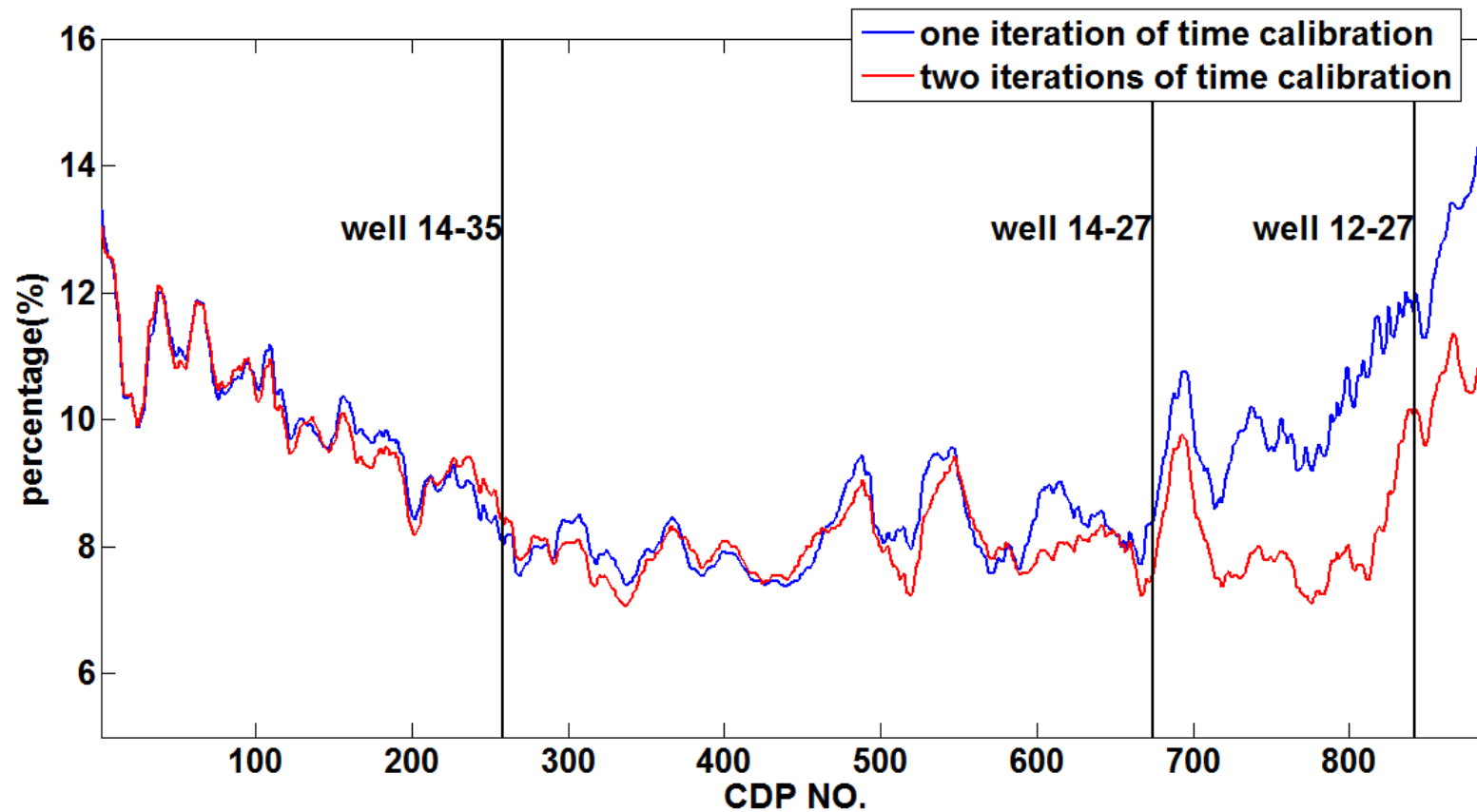
Two iterations of time calibration

Well: 0-3 Hz  
Seismic: 3-75 Hz



# Errors between seismic and well impedance

impedance: 0-75 Hz



# Conclusions

- Smooth dynamic time warping can accurately estimate the smooth time shift between two traces.
- Smooth dynamic time warping takes the place of the manual stretch-squeeze process in the Hussar well tying.
- The second iteration of time calibration reduces inversion errors around the well 12-27, verifying better seismic-to-well ties.

# Acknowledgements

- **CREWES sponsors**
- **NSERC: grant CRDPJ 379744-08**
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