

# A framework for linear and nonlinear converted wave time-lapse difference AVO

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# Outline

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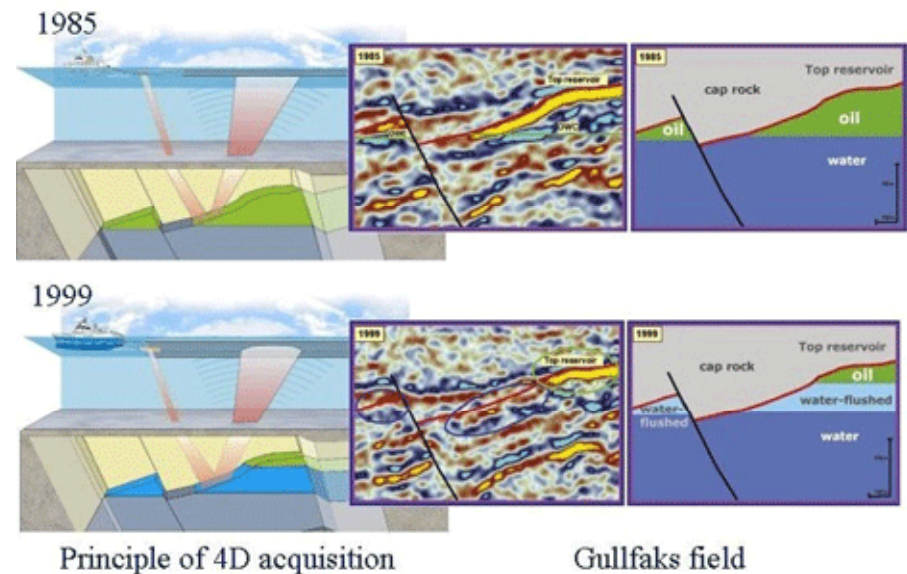
- Introduction and review
- A framework for converted wave time-lapse AVO
- Numerical example
- Conclusions
- Future work
- Acknowledgments

# Time-lapse seismic

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- Monitoring changes in reservoir: production, EOR
- Repeated seismic surveys over calendar time
- The baseline and monitor survey
- Changes in seismic parameters

Quantitative time-lapse (4D) seismic  
(Image courtesy of Statoil)



# AVO : Amplitude Versus Offset

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## Baseline and time-lapse changes

### Baseline

$$\Delta V_{Pb} = V_{Pb} - V_{P_0}$$

$$\Delta V_{Sb} = V_{Sb} - V_{S_0}$$

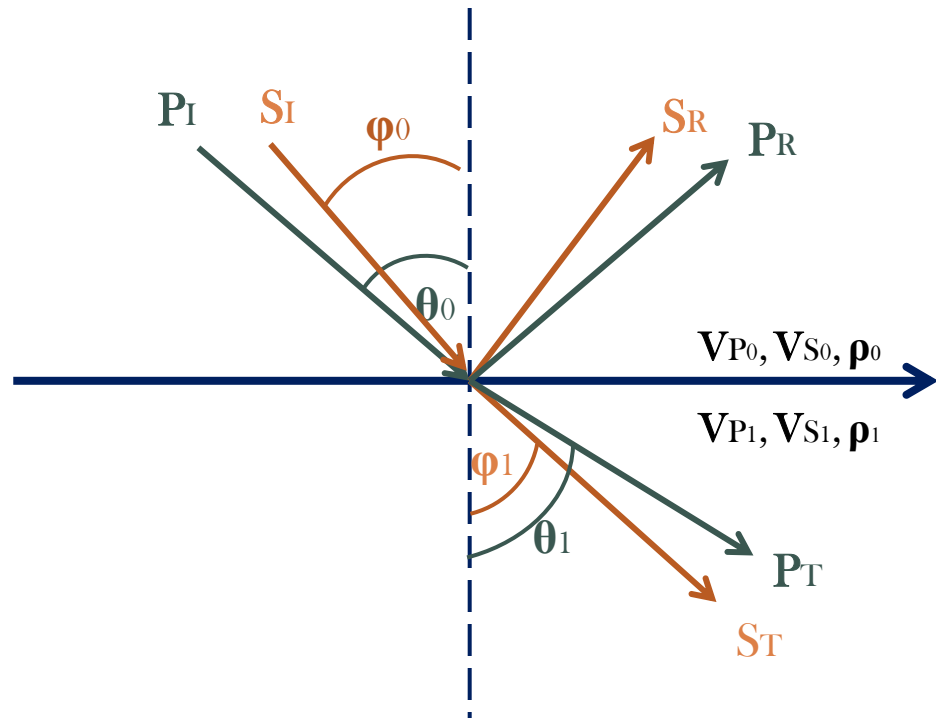
$$\Delta \rho_b = \rho_b - \rho_0$$

### Time lapse

$$\delta V_P = V_{Pm} - V_{Pb}$$

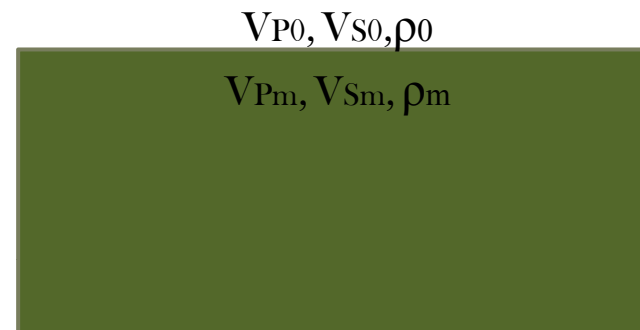
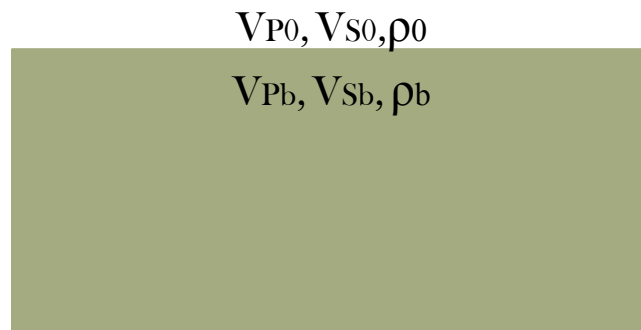
$$\delta V_S = V_{Sm} - V_{Sb}$$

$$\delta \rho = \rho_m - \rho_b$$



# Landrø et al. 2001

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- Landrø's linear equation for  $\Delta R_{PP}$

$$\Delta R_{PP}(\theta) = \frac{1}{2} \left( \frac{\delta \rho}{\rho} + \frac{\delta V_P}{V_P} \right) - 2 \frac{V_S^2}{V_P^2} \left( \frac{\delta \rho}{\rho} + 2 \frac{\delta V_S}{V_S} \right) \sin^2 \theta + \frac{\delta V_P}{2V_P} \tan^2 \theta$$

- Inaccurate for large time-lapse contrasts
- Independent of the contrast in the baseline survey

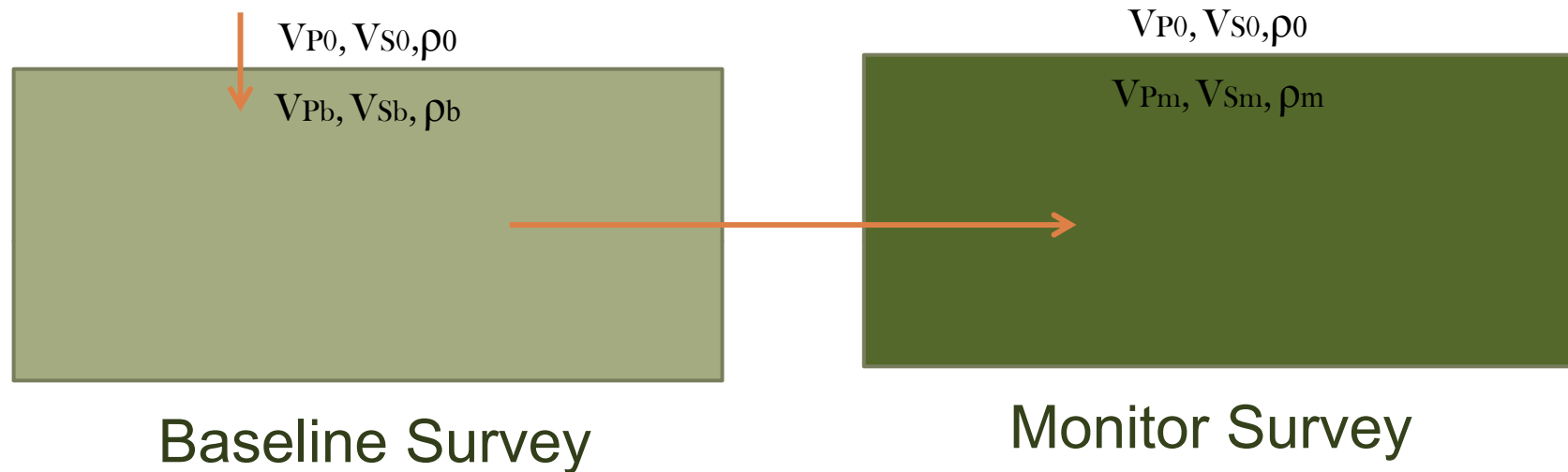
# Time lapse difference AVO for P-P section

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- In plausible large contrast time-lapse scenarios Landrø's approximation requires correction.
- A framework for linear and non linear time-lapse AVO analysis is formulated.
- Agreement of linear term in  $\Delta R_{PP}$  with Landrø's work.
- Higher order approximations made corrections in  $\Delta R_{PP}$ .
- Physical model validated the importance of low order interpretable nonlinear corrections.

# A time-lapse problem

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$$b_{VP} = 1 - \frac{V_{P0}^2}{V_{PBL}^2}, \quad b_{VS} = 1 - \frac{V_{S0}^2}{V_{SBL}^2}, \quad b_{\rho} = 1 - \frac{\rho_0}{\rho_{BL}},$$

$$a_{VP} = 1 - \frac{V_{PBL}^2}{V_{PM}^2}, \quad a_{VS} = 1 - \frac{V_{SBL}^2}{V_{SM}^2}, \quad a_{\rho} = 1 - \frac{\rho_{BL}}{\rho_M},$$

# A general framework for time-lapse AVO

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- Zoeppritz equations for baseline and monitoring targets:

$$P_{BL} \begin{bmatrix} R_{PP} \\ R_{PS} \\ T_{PP} \\ T_{PS} \end{bmatrix} = b_{BL} \quad R_{PS}^{BL}(\theta) = \frac{\det(P_P)}{\det(P)}$$

$$P_M \begin{bmatrix} R_{PP} \\ R_{PS} \\ T_{PP} \\ T_{PS} \end{bmatrix} = b_M \quad R_{PS}^M(\theta) = \frac{\det(P_P)}{\det(P)}$$

$$S_{BL} \begin{bmatrix} R_{SS} \\ R_{SP} \\ T_{SS} \\ T_{SP} \end{bmatrix} = c_{BL} \quad R_{SP}^{BL}(\varphi) = \frac{\det(S_S)}{\det(S)}$$

$$S_M \begin{bmatrix} R_{SS} \\ R_{SP} \\ T_{SS} \\ T_{SP} \end{bmatrix} = c_M \quad R_{SP}^M(\varphi) = \frac{\det(S_S)}{\det(S)}$$



# Time-lapse AVO

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- Deriving  $\Delta R_{PS}(\theta)$  and  $\Delta R_{SP}(\varphi)$  from Zoeppritz equations

$$\Delta R_{PS}(\theta) = R_{PS}^{(M)}(\theta) - R_{PS}^{(BL)}(\theta) \quad \Delta R_{SP}(\varphi) = R_{SP}^{(M)}(\varphi) - R_{SP}^{(BL)}(\varphi)$$

- Expand  $\Delta R_{PP}(\theta)$  in orders of perturbation parameters

$$\Delta R_{PS}(\theta) = \Delta R_{PS}^{(1)}(\theta) + \Delta R_{PS}^{(2)}(\theta) + \Delta R_{PS}^{(3)}(\theta) + \dots$$

$$\Delta R_{SP}(\varphi) = \Delta R_{SP}^{(1)}(\varphi) + \Delta R_{SP}^{(2)}(\varphi) + \Delta R_{SP}^{(3)}(\varphi) + \dots$$

# Numerical example

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## □ Baseline survey

$$V_{P0}=2000 \text{ m/s}$$

$$V_{S0}=1500 \text{ m/s}$$

$$\rho_0=2000 \text{ kg/m}^3$$

$$V_{Pbl}=3000 \text{ m/s}$$

$$V_{Sbl}=1700 \text{ m/s}$$

$$\rho_{bl}=2100 \text{ kg/m}^3$$

## □ Monitor survey

$$V_{P0}=2000 \text{ m/s}$$

$$V_{S0}=1500 \text{ m/s}$$

$$\rho_0=2000 \text{ kg/m}^3$$

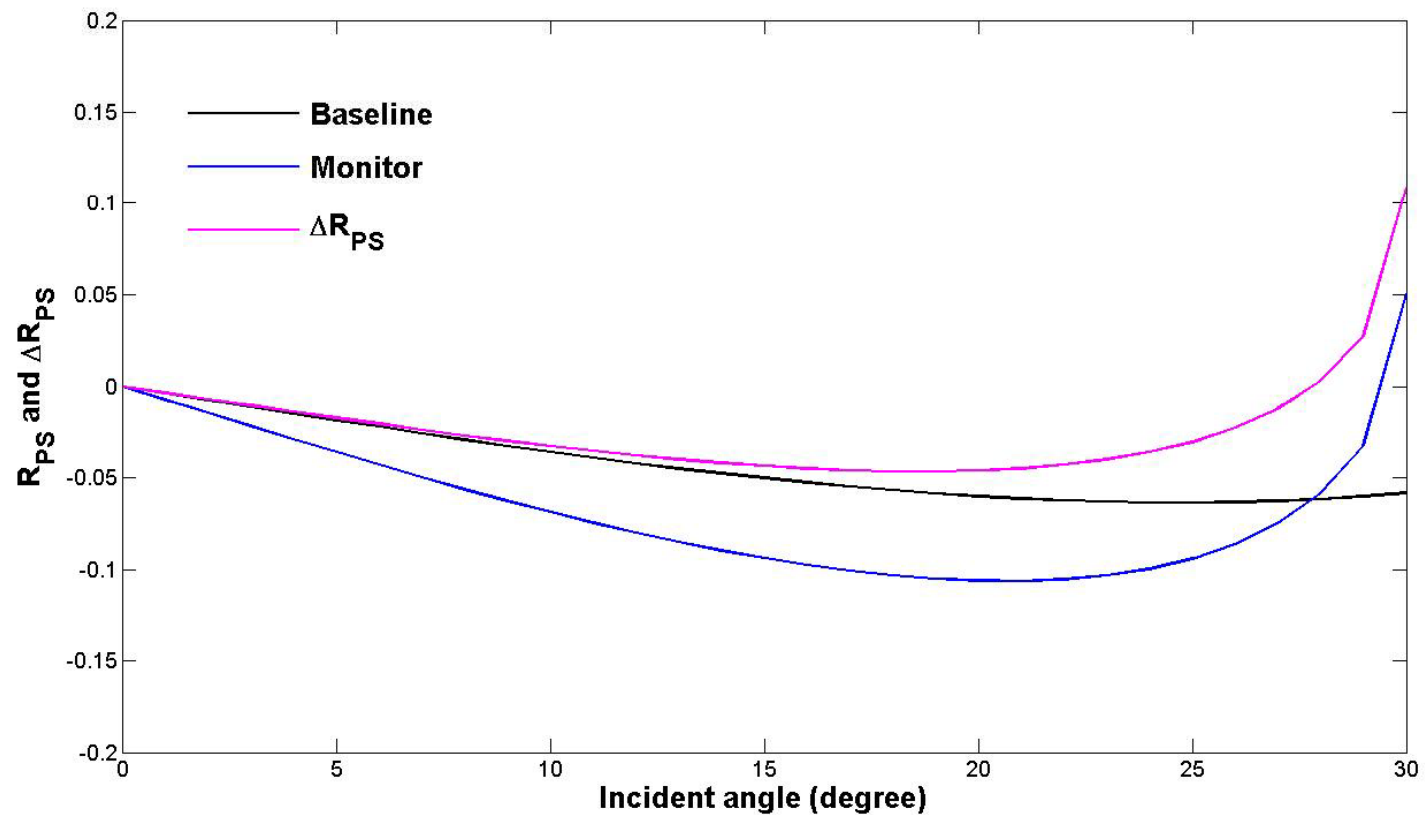
$$V_{Pm}=4000 \text{ m/s}$$

$$V_{Sm}=1900 \text{ m/s}$$

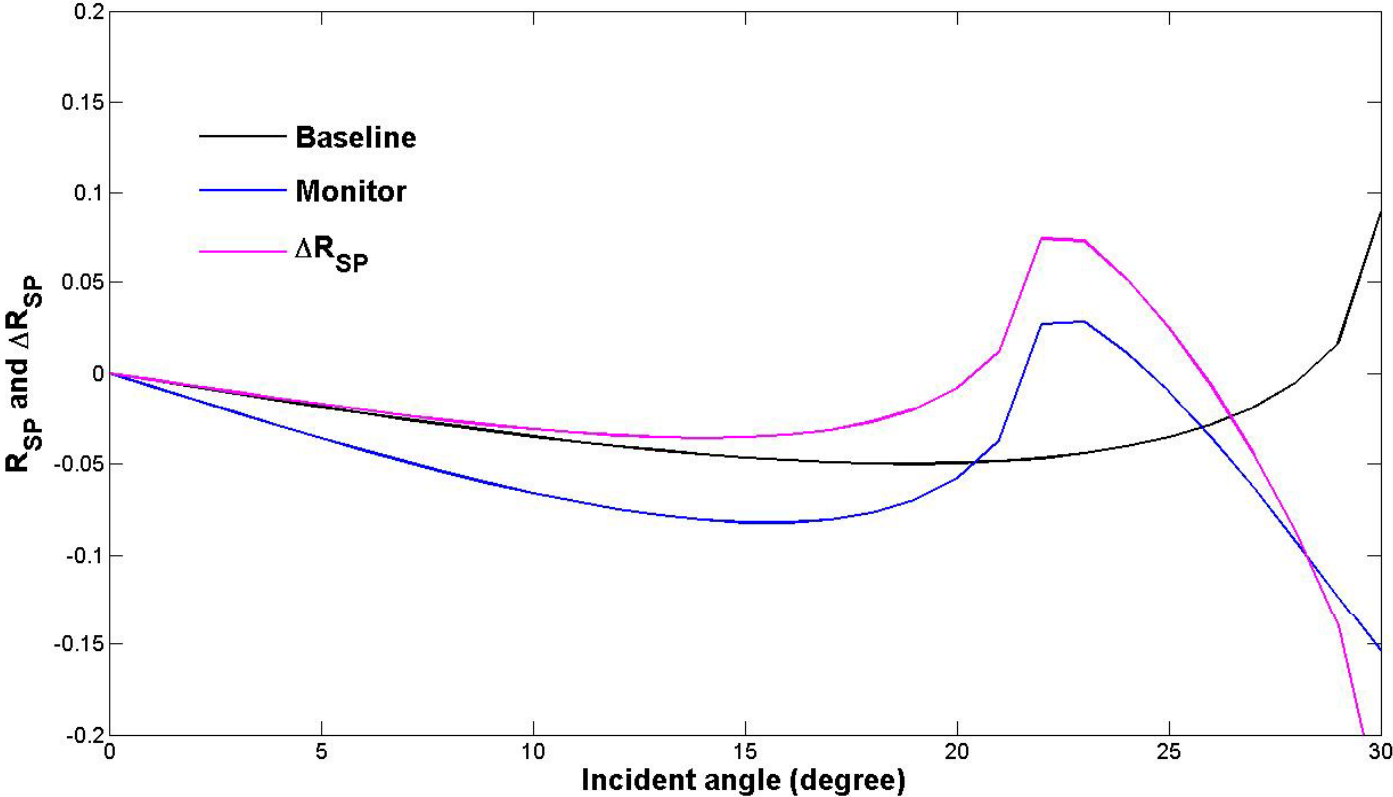
$$\rho_m=2300 \text{ kg/m}^3$$

# $R_{PS}$ for baseline and monitoring survey

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# $R_{SP}$ for baseline and monitoring survey



# Linear and higher order $\Delta R_{PS}$

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$$\Delta R_{PS}^{(1)}(\theta) = k_1^1 a_{VS} + k_2^1 a_{\rho}$$

$$\Delta R_{PS}^{(2)}(\theta) = k_1^2 a_{VS}^2 + k_2^2 a_{\rho}^2 + k_3^2 a_{\rho} b_{\rho} + k_4^2 a_{VS} b_{VS} + k_5^2 (a_{VP} a_{VS} + a_{VP} b_{VS} + b_{VP} a_{VS}) \\ + k_6^2 (a_{VP} a_{\rho} + a_{VP} b_{\rho} + b_{VP} a_{\rho} + a_{VS} a_{\rho} + b_{VS} a_{\rho} + a_{VS} b_{\rho})$$

$$\Delta R_{PS}^{(3)}(\theta) = k_1^3 a_{VS}^3 + k_2^3 a_{\rho}^3 + k_3^3 (b_{VS} a_{VS}^2 + a_{VS} b_{VS}^2) + k_4^3 (a_{VS} a_{\rho}^2 + a_{VS} b_{\rho}^2 + b_{VS} a_{\rho}^2) \\ + k_5^3 (a_{\rho} b_{VS}^2 + a_{\rho} a_{VS}^2 + b_{\rho} b_{VS}^2) + k_6^3 (b_{\rho} a_{VP}^2 + a_{\rho} b_{VP}^2 + a_{\rho} a_{VP}^2 + a_{VP} b_{\rho}^2 + a_{VP} a_{\rho}^2 + b_{VP} a_{\rho}^2) \\ + k_7^3 (b_{VS} a_{VP}^2 + a_{VS} b_{VP}^2 + a_{VS} a_{VP}^2 + a_{VS} b_{VP} b_{VS} + a_{VP} b_{VS} a_{VS}) + \dots$$

All coefficients are functions of  $\sin\theta$  and  $V_{S0}/V_{P0}$

# Linear and higher order $\Delta R_{SP}$

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$$\Delta R_{SP}^{(1)}(\varphi) = l_1^1 a_{VS} + l_2^1 a_{\rho}$$

$$\begin{aligned} \Delta R_{SP}^{(2)}(\varphi) = & l_1^2 a_{VS}^2 + l_2^2 a_{\rho}^2 + l_3^2 a_{\rho} b_{\rho} + l_4^2 a_{VS} b_{VS} + l_5^2 (a_{VP} a_{VS} + a_{VP} b_{VS} + b_{VP} a_{VS}) \\ & + l_6^2 (a_{VP} a_{\rho} + a_{VP} b_{\rho} + b_{VP} a_{\rho} + a_{VS} a_{\rho} + b_{VS} a_{\rho} + a_{VS} b_{\rho}) \end{aligned}$$

$$\begin{aligned} \Delta R_{SP}^{(3)}(\varphi) = & l_1^3 a_{VS}^3 + l_2^3 (a_{\rho}^3 + a_{VS} b_{\rho} b_{VS} + a_{VS} a_{\rho} b_{VS} + a_{\rho} b_{VS}^2 + a_{\rho} a_{VS}^2 + a_{\rho} b_{VS}^2) \\ & + l_3^3 (a_{VS} b_{\rho} b_{VP} + a_{VS} a_{\rho} b_{VP} + b_{VS} b_{\rho} a_{VP} + b_{VS} a_{\rho} a_{VP} + b_{VS} a_{\rho} b_{VP} + a_{VS} b_{\rho} a_{VP} + a_{VS} a_{\rho} a_{VP}) \\ & + l_4^3 (a_{VS} b_{\rho} a_{\rho} + b_{VS} b_{\rho} a_{\rho}) + l_5^3 (a_{VS} a_{\rho}^2 + b_{VS} a_{\rho}^2 + a_{VS} b_{\rho}^2) + l_6^3 (b_{\rho} a_{\rho}^2 + a_{\rho} b_{\rho}^2) \\ & + l_7^3 (b_{VP} a_{\rho}^2 + a_{VP} b_{\rho}^2 + a_{VP} a_{\rho}^2 + b_{\rho} b_{VP}^2 + a_{\rho} a_{VP}^2 + a_{\rho} b_{VP}^2) + \dots \end{aligned}$$

All coefficients are functions of  $\sin\varphi$  and  $V_{S0}/V_{P0}$

# Relative seismic parameter changes

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$$\frac{\Delta V_P}{V_P} = 2 \frac{V_{Pb} - V_{P0}}{V_{Pb} + V_{P0}}, \quad \frac{\Delta V_S}{V_S} = 2 \frac{V_{Sb} - V_{S0}}{V_{Sb} + V_{S0}}, \quad \frac{\Delta \rho}{\rho} = 2 \frac{\rho_b - \rho_0}{\rho_b + \rho_0}$$

$$\frac{\delta V_P}{V_P} = 2 \frac{V_{Pm} - V_{Pb}}{V_{Pm} + V_{Pb}}, \quad \frac{\delta V_S}{V_S} = 2 \frac{V_{Sm} - V_{Sb}}{V_{Sm} + V_{Sb}}, \quad \frac{\delta \rho}{\rho} = 2 \frac{\rho_m - \rho_b}{\rho_m + \rho_b}$$

# Time-lapse AVO in terms of relative seismic parameter changes

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$$b_{VP} = 2 \left( \frac{\Delta V_P}{V_P} \right) - 2 \left( \frac{\Delta V_P}{V_P} \right)^2 + \frac{3}{2} \left( \frac{\Delta V_P}{V_P} \right)^3 - \dots$$

$$a_{VP} = 2 \left( \frac{\delta V_P}{V_P} \right) - 2 \left( \frac{\delta V_P}{V_P} \right)^2 + \frac{3}{2} \left( \frac{\delta V_P}{V_P} \right)^3 - \dots$$

$$\dots$$

$$\Delta R_{PS}^{(1)}(\theta) = \left( -2 \frac{V_S}{V_P} \sin \theta \right) \frac{\delta V_S}{V_S} - \frac{1}{2} \left( 2 \frac{V_S}{V_P} + 1 \right) \sin \theta \frac{\delta \rho}{\rho}$$

$$\dots$$

$$\Delta R_{SP}^{(1)}(\varphi) = \left( -2 \frac{V_S}{V_P} \sin \varphi \right) \frac{\delta V_S}{V_S} - \frac{1}{2} \left( 2 \frac{V_S}{V_P} + 1 \right) \sin \varphi \frac{\delta \rho}{\rho}$$



# Numerical example

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## □ Baseline survey

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## □ Monitor survey

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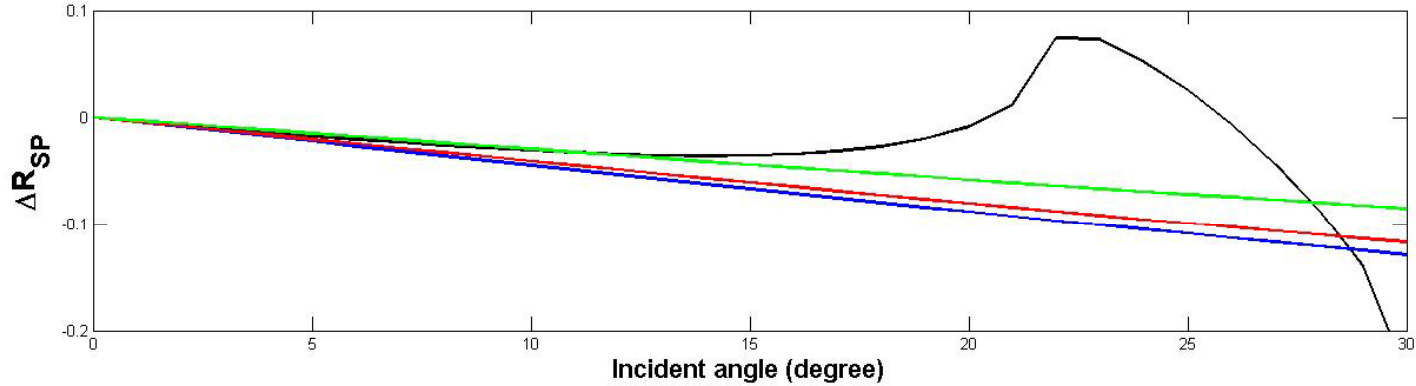
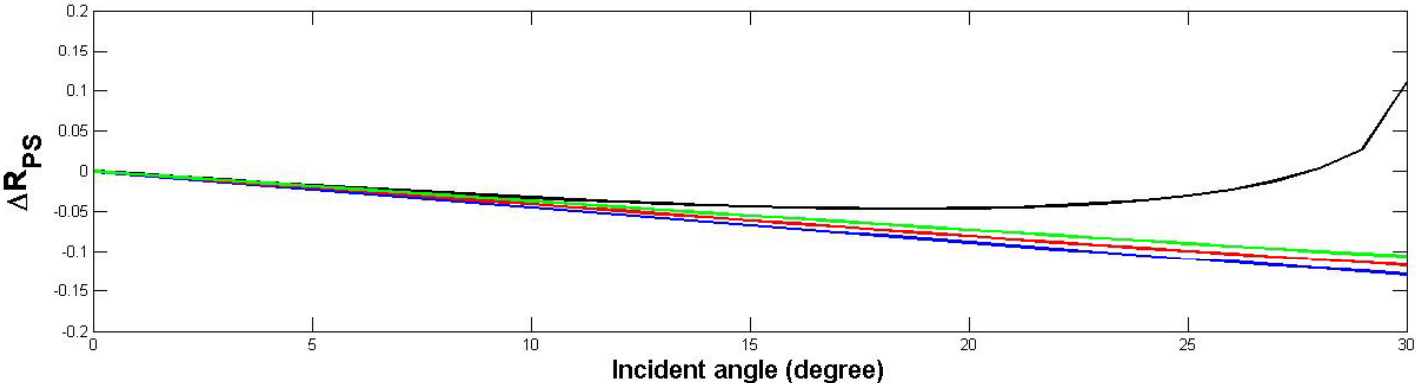
$$\rho_0=2000 \text{ kg/m}^3$$

$$V_{Pm}=4000 \text{ m/s}$$

$$V_{Sm}=1900 \text{ m/s}$$

$$\rho_m=2300 \text{ kg/m}^3$$

# Linear, second, and third order $\Delta R_{PS}$ and $\Delta R_{SP}$



- Exact
- Second order
- Linear
- Third order

# Conclusions

- Including higher order terms in  $\Delta R_{PS}$ , and  $\Delta R_{SP}$  improves the accuracy of approximating time lapse difference data.
- Higher order terms for  $\Delta R_{PS}$  and  $\Delta R_{SP}$  are different, which is not the case in the linear approximation.

# Future work

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- Further numerical, analytical examination of  $\Delta R_{PP}$ ,  $\Delta R_{PS}$ ,  $\Delta R_{SP}$ , and  $\Delta R_{SS}$
- Validation of time-lapse AVO formula using physical modeling data
- Modeling of inversion of field data example

# Acknowledgments

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# Questions