

Forward modeling in elastic media using SINTEF Tiger and AMM method

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Motivation

- i. We seek a robust anisotropy forward modeling tool
- ii. AVAZ modeling and interpretation of anisotropic models
 - iii. For future fracture parameter estimations

Objective

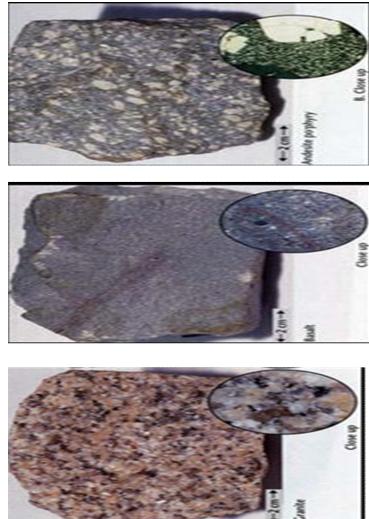
- i. SINTEF Tiger finite difference modeling toolbox
- ii. P.F. Daley's Reflectivity finite-difference code
 - iii. AVO analysis of results
- iv. AVAZ analysis @ 3 different azimuths

Outline

- Anisotropy in Rocks
- Parameterization
- Forward Modeling tools
- Model Parameter Estimation
- Amplitude Analysis
- Conclusion

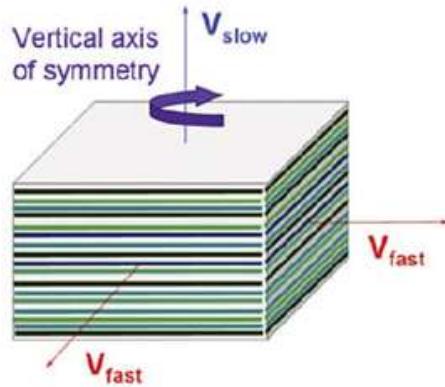
Anisotropy in Rocks

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Parameterization

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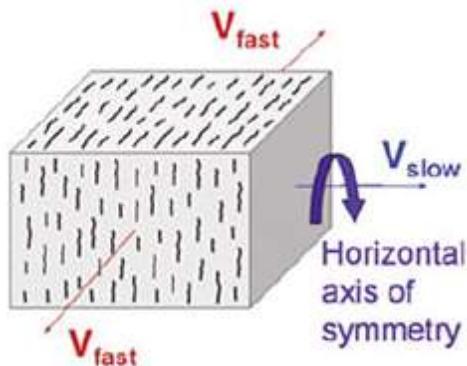


$$\rho v_p^2(\theta) = \frac{1}{2} [C_{33} + C_{44} + (C_{11} - C_{33}) \sin^2 \theta + D]$$

$$\rho v_{sv}^2(\theta) = \frac{1}{2} [C_{33} + C_{44} + (C_{11} - C_{33}) \sin^2 \theta - D]$$

$$\rho v_{sh}^2(\theta) = C_{44} \cos^2 \theta + C_{66} \sin^2 \theta$$

c_{ij} – stiffness coefficients
 v_i – phase velocity
 θ – phase angle



$$D = \left\{ (C_{33} - C_{44})^2 + 2 \left[2(C_{13} + C_{44})^2 - (C_{33} - C_{44})(C_{11} + C_{33} - 2C_{44}) \right] \sin^2 \theta + \left[(C_{11} + C_{33} - 2C_{44})^2 - 4(C_{13} + C_{44})^2 \right] \sin^4 \theta \right\}$$

Parametrization (Thomsen, 1984)

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Vertical velocities

$$v_{P0} = \sqrt{\frac{C_{33}}{\rho}} \quad v_{S0} = \sqrt{\frac{C_{44}}{\rho}}$$

Anisotropy parameters

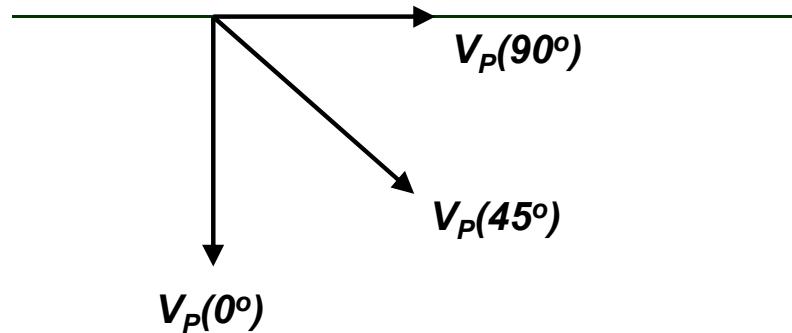
$$\epsilon = \frac{C_{11} - C_{33}}{2C_{33}}$$

$$\delta = \frac{(C_{13} + C_{33})^2 - (C_{33} - C_{44})^2}{2C_{33}(C_{33} - C_{44})}$$

$$\gamma = \frac{C_{66} - C_{44}}{2C_{44}}$$

Phase Velocity along symmetry axis and symmetry plane

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$v_{P0} \rightarrow$ P – wave velocity $v_{P0} \rightarrow$ S – wave velocity

$$\varepsilon = \delta = \gamma = 0$$

Isotropy reduction

$$v_P^2 \left(\frac{\pi}{2} \right) = v_{P0}^2 (1 + 2\varepsilon)$$

$$v_{SV}^2 \left(\frac{\pi}{2} \right) = v_{S0}^2$$

$$v_{SH}^2 \left(\frac{\pi}{2} \right) = v_{S0}^2 (1 + 2\gamma)$$

Propagation along Isotropy

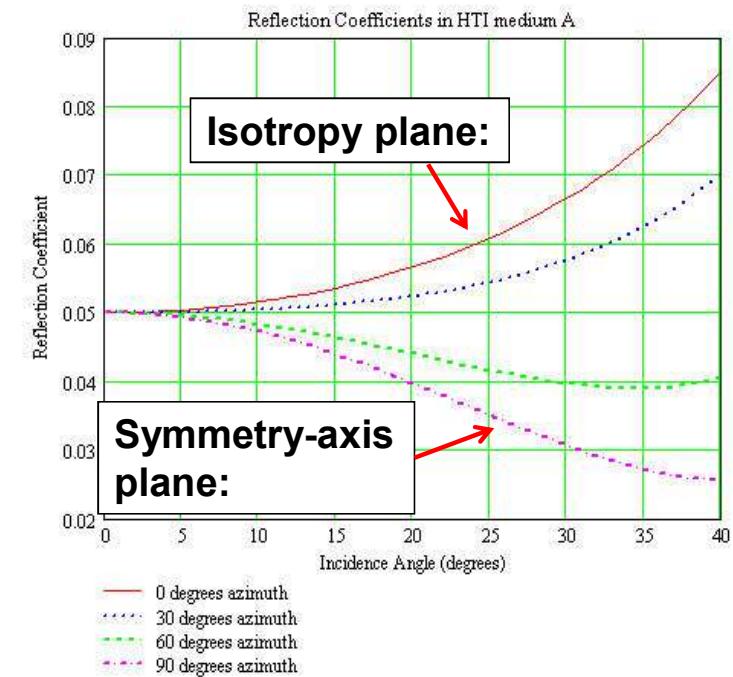
Ruger Approximation

$$R_{HTI} = A + (B + B_{HTI} \cos^2 \phi) \sin^2 \theta \\ \cdots + (C + C_{HTI} \cos^2 \phi) \sin^2 \theta \tan^2 \theta$$

where :

$$B_{HTI} = \frac{1}{2} \left[\Delta \delta^{(V)} + 8 \left[\frac{V_S}{V_P} \right]^2 \Delta \gamma \right],$$

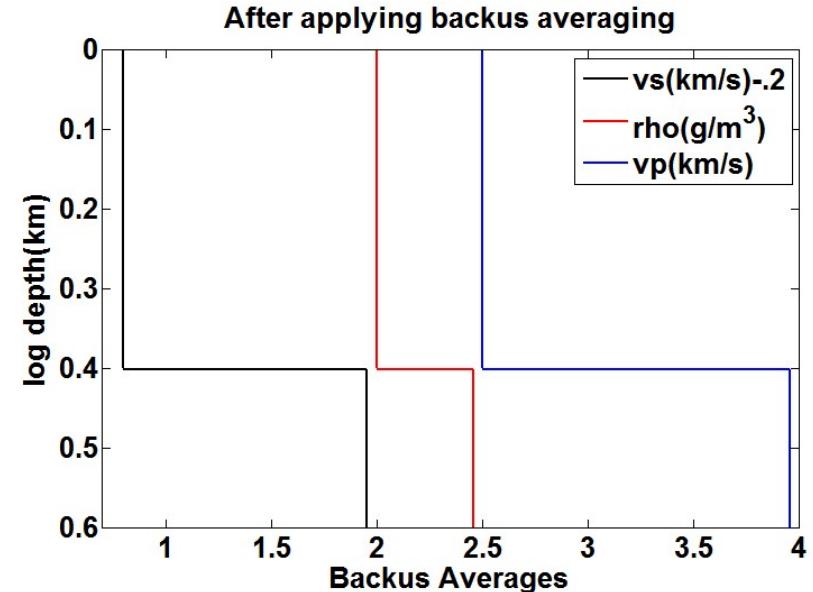
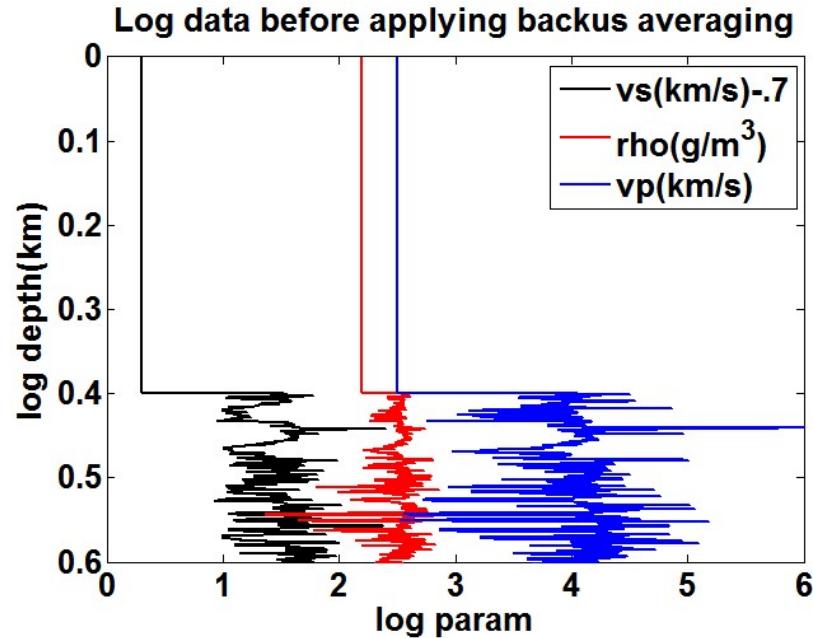
$$C_{HTI} = \frac{1}{2} [\Delta \delta^{(V)} \sin^2 \phi - \Delta \varepsilon^{(V)}]$$



The reflection coefficients for a model where only γ changes, as a function of incidence angle for 0, 30, 60 and 90 degrees azimuth.

Model Parameterization

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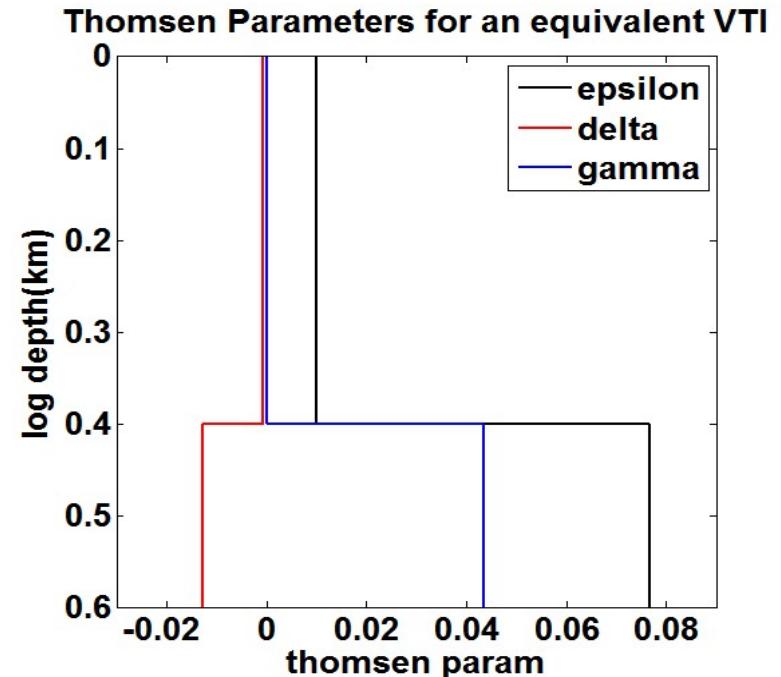
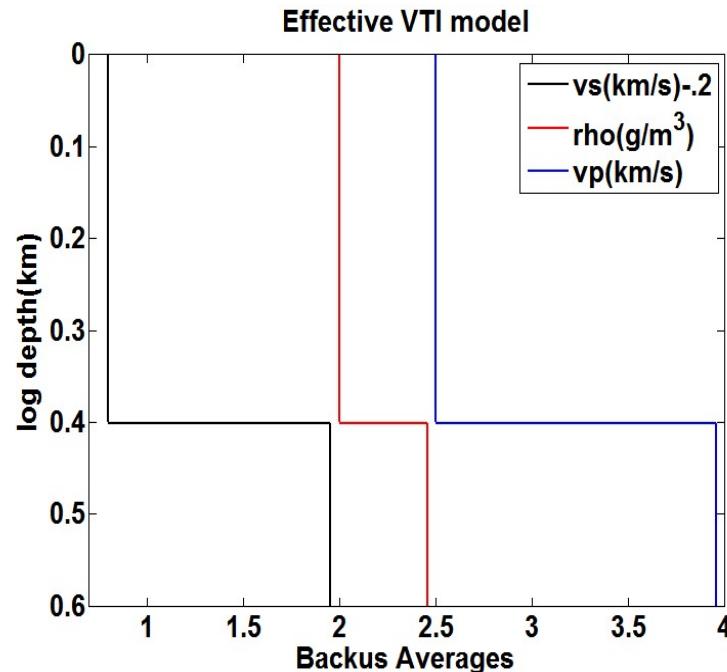


$$c = 1.0e+10 *$$

4.2513	1.6329	1.5549	0	0	0
1.6329	4.2513	1.5549	0	0	0
1.5549	1.5549	3.9115	0	0	0
0	0	0	1.1550	0	0
0	0	0	0	1.1550	0
0	0	0	0	0	1.3092

Model Parameterization

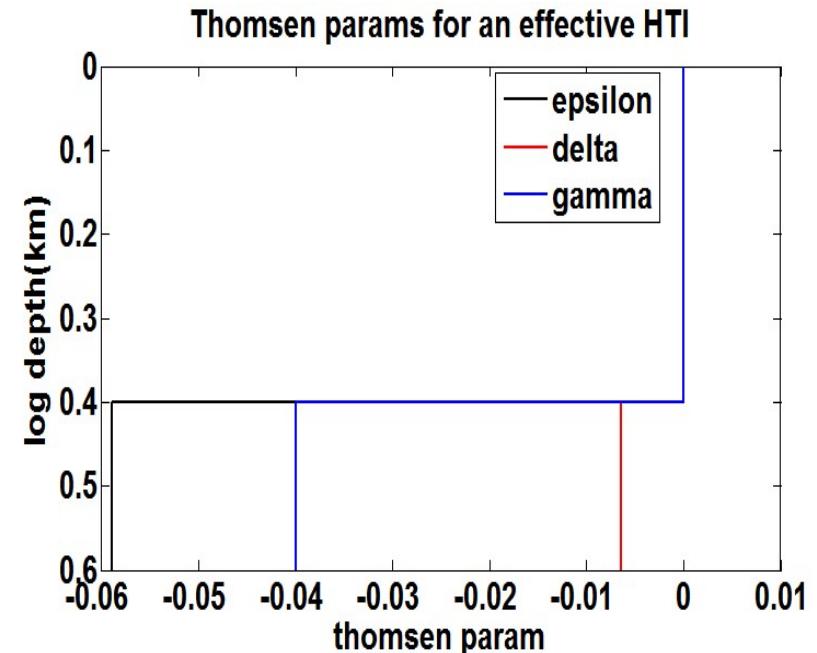
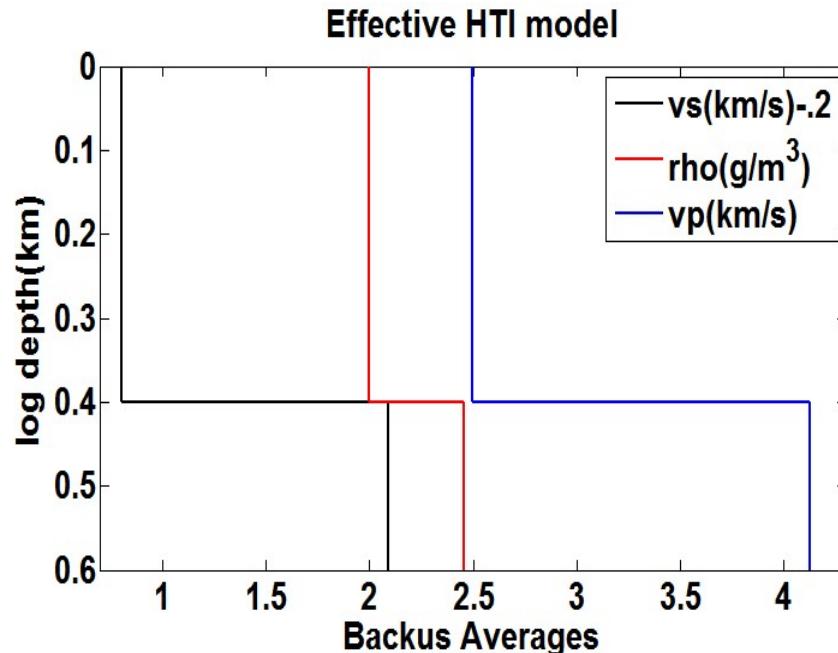
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$$\text{VTI}(\text{vp}, \text{vsh}, \text{vsv}) = (3.9591 \quad 2.1513 \quad 2.1513) * 1.0\text{e+03}$$
$$\text{Thomsen_VTI} = \quad 0.0434 \quad 0.0668 \quad -0.0118$$

Model Parameterization

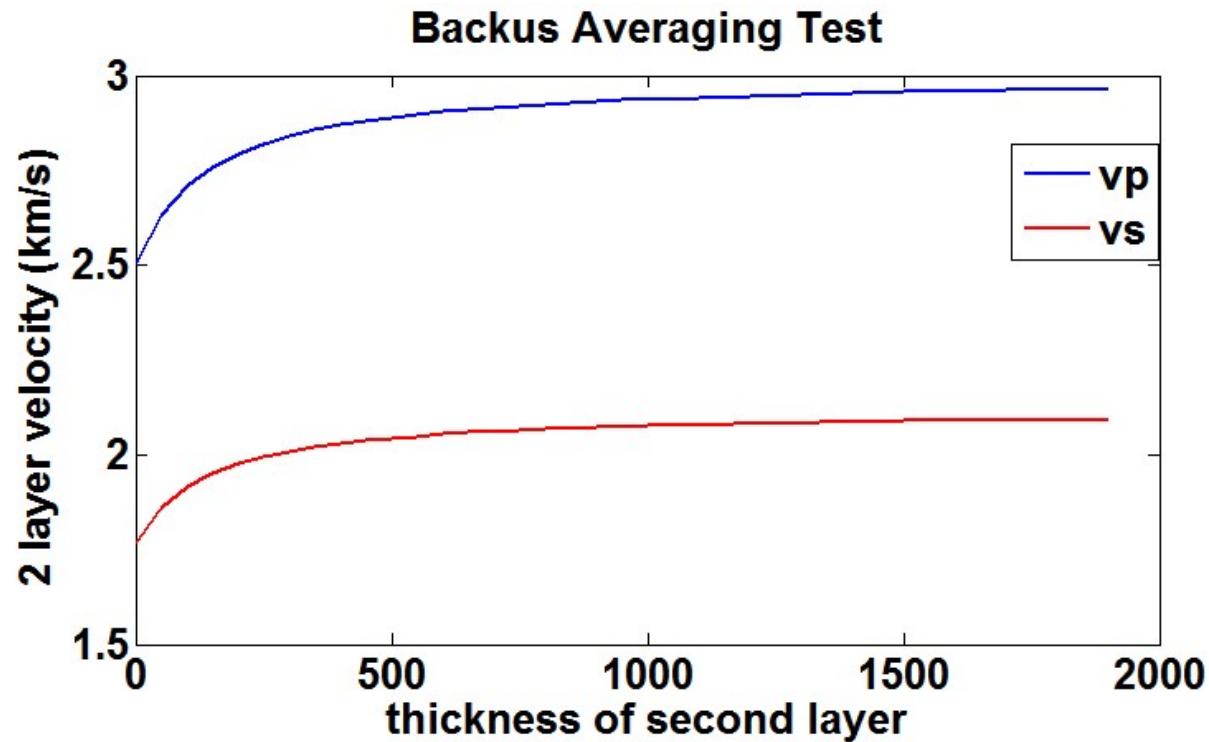
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$$\begin{aligned} \text{HTI}(vp_2, vsh_2, vsv_2) &= (4.1275 \quad 2.2904 \quad 2.1513) * 1.0e+03 \\ \text{Thom_HTI} &= -0.0400 \quad -0.0589 \quad -0.0064 \end{aligned}$$

Averaging Test

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Forward Modeling tools

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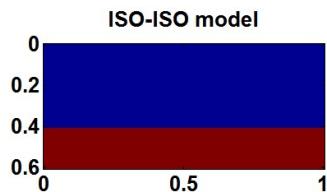
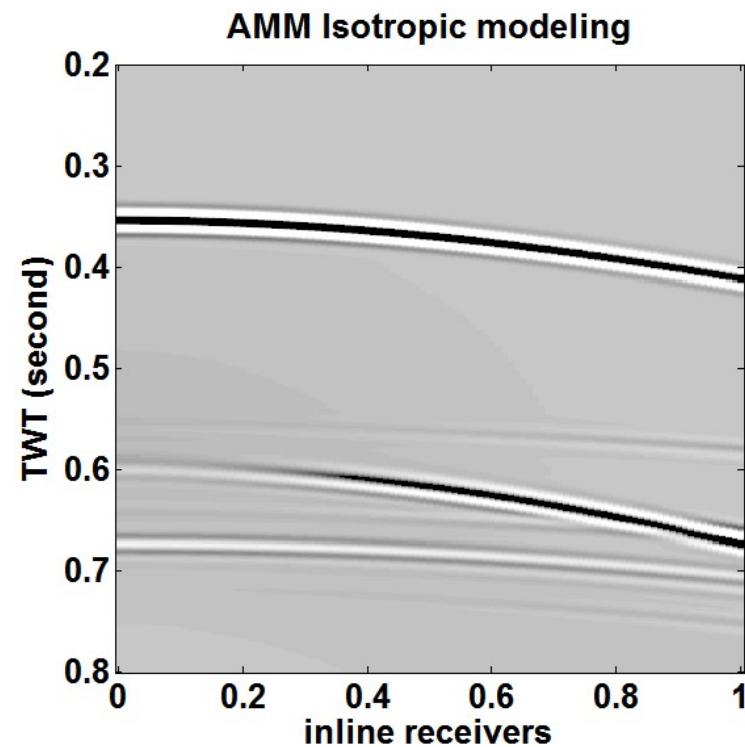
AMM

- Reflectivity-Finite Difference Code (by P.F Daley)
- Hybrid method
- Reflectivity method (Fuchs and Mueller) with finite difference in depth or time
- Source wavelet is Gabor
- Fast
- Isotropic codes work well but TI code needs some work
- Amplitude computations need to be calibrated

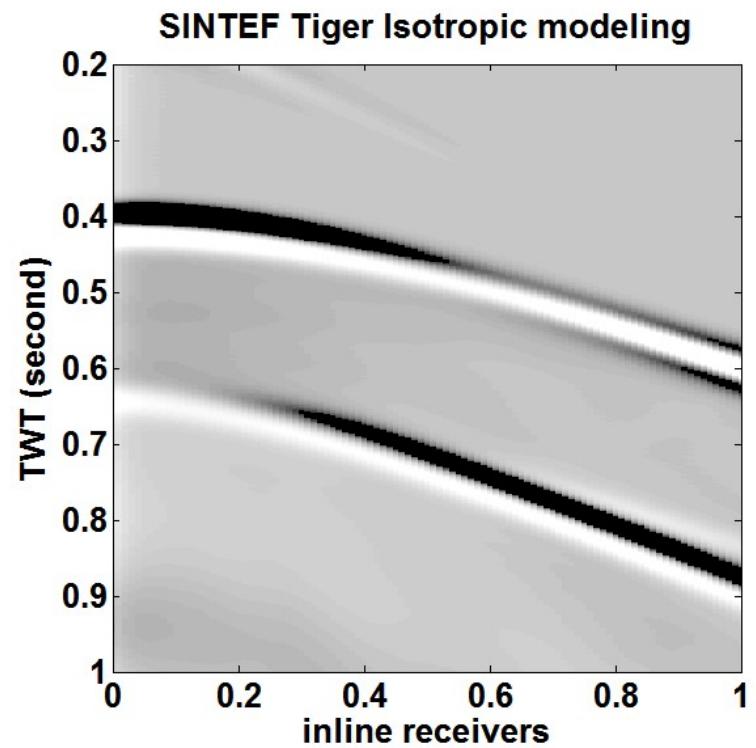
SINTEF TIGER

- Finite difference method
- Fast (depending on grid and/or model size)
- Options for importing anisotropic models
- Has options for anelastic modeling
- Explosive source or dipole source
- Grid dispersion well taken care of
- Robust

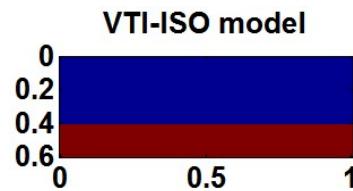
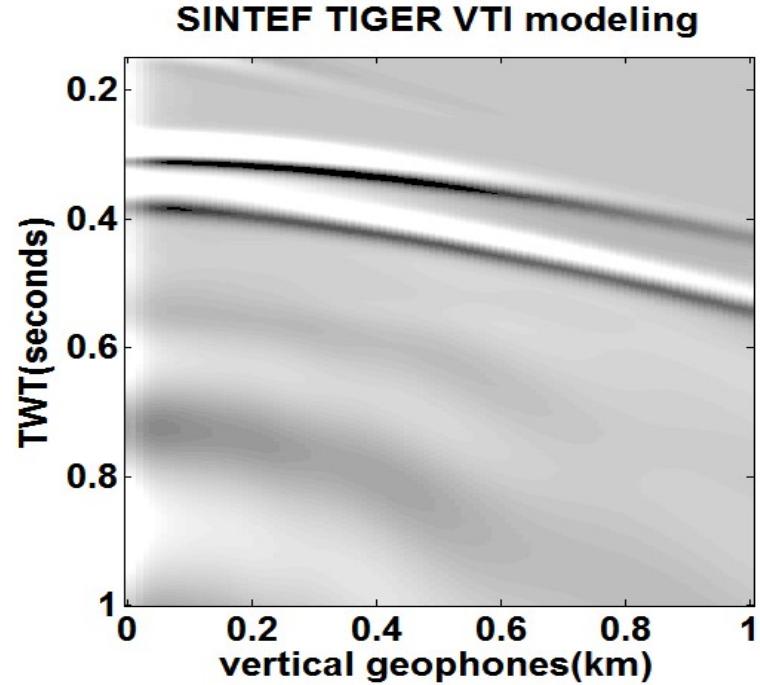
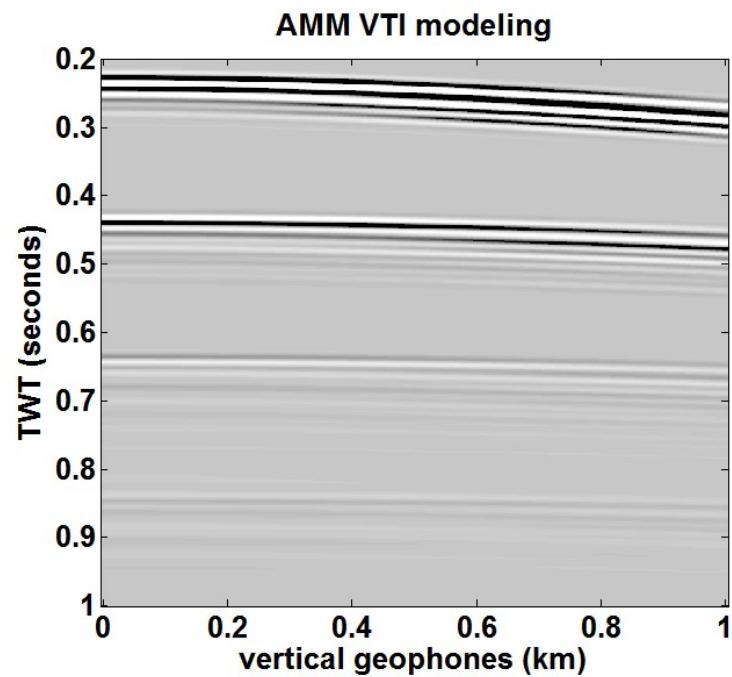
Isotropic modeling



```
rho=[2200 2495] ; vp=[2500 4128] ; vs=[1000 2290] ;  
delta=[0 0]' ; epsilon=[0 0]' ; gamma=[0 0]';
```

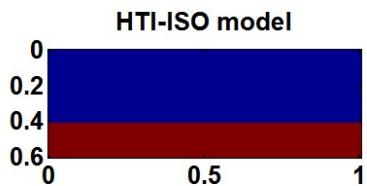
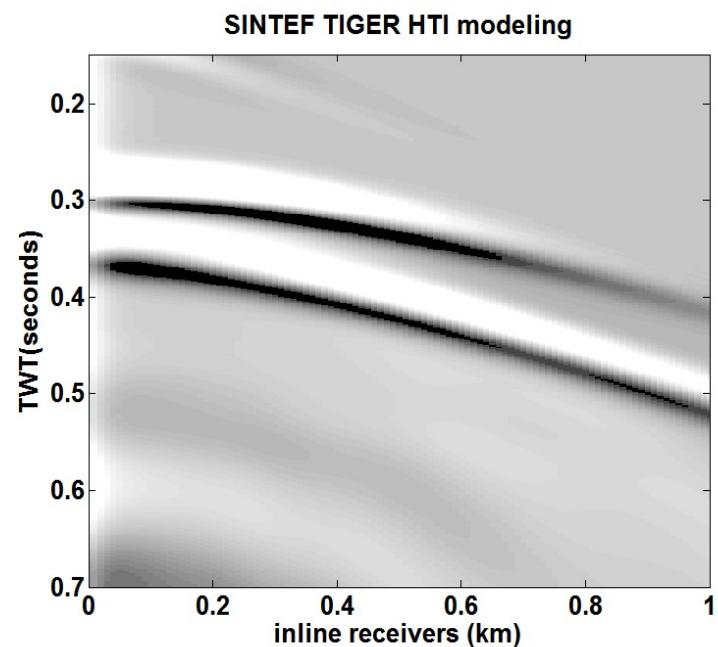
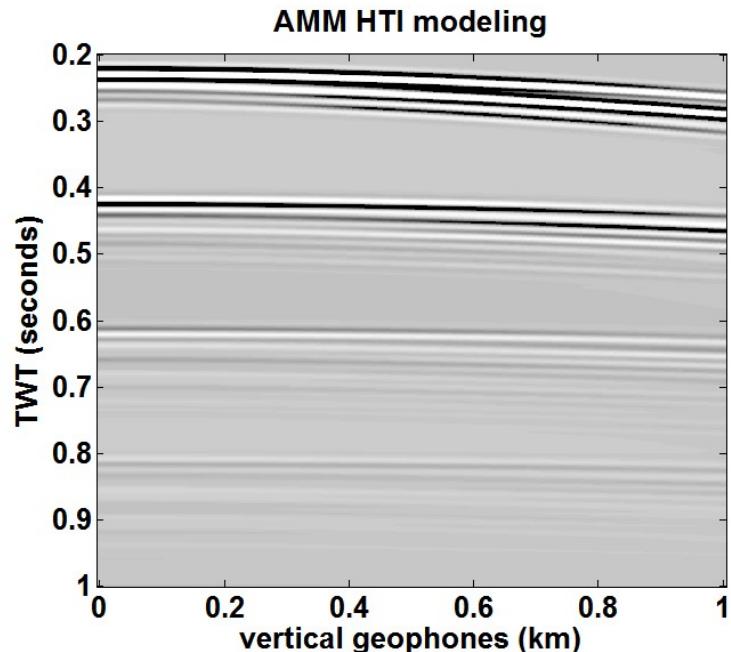


Effective VTI modeling



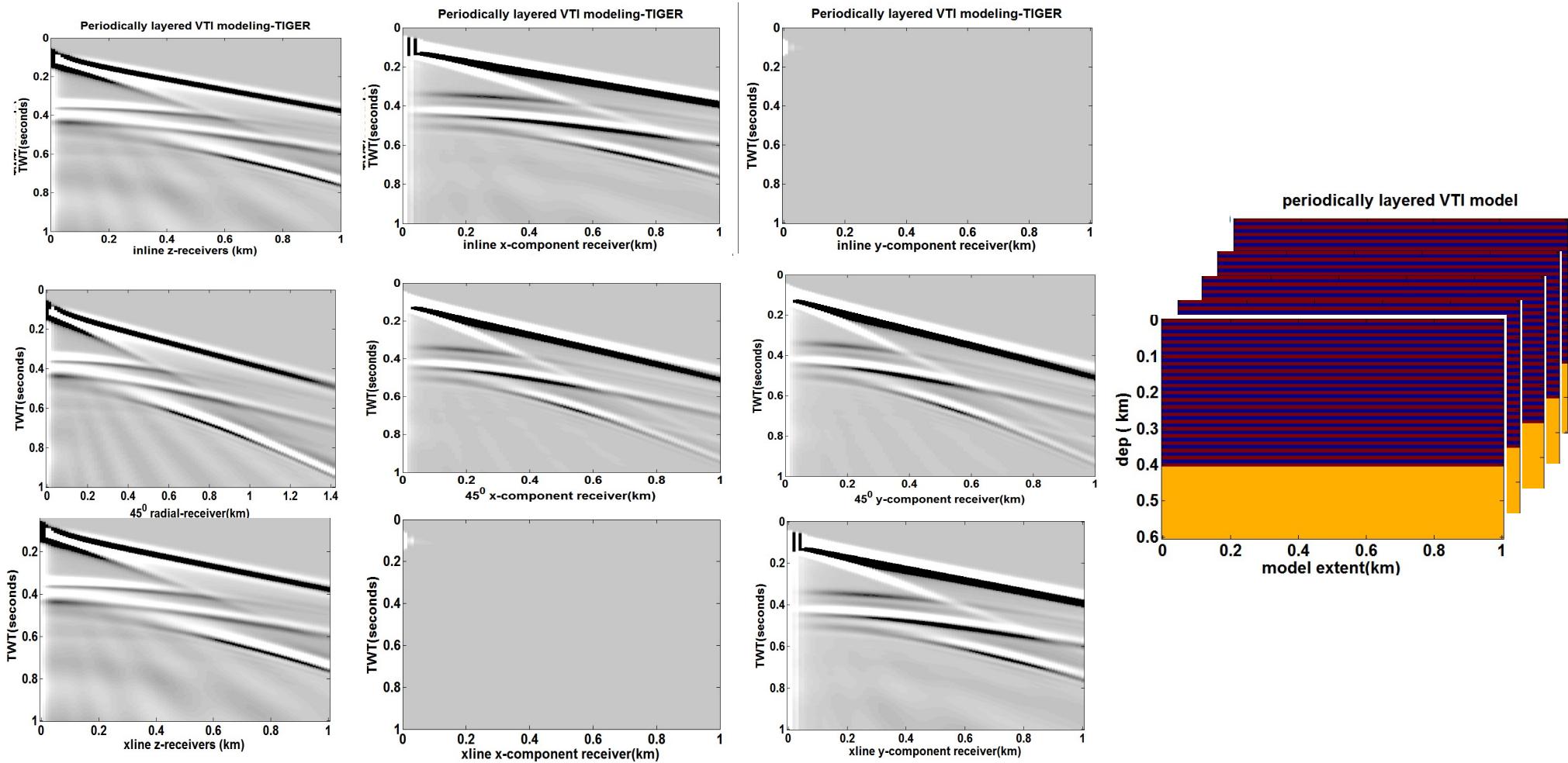
```
den=[2.495 2.200]'; alpha=[3.959 2.500]'; beta=[2.151 1.000]';
delta=[-0.00118 0]'; epsilon=[0.0668 0]'; gamma=[0.0434 0]';
```

Effective HTI modeling

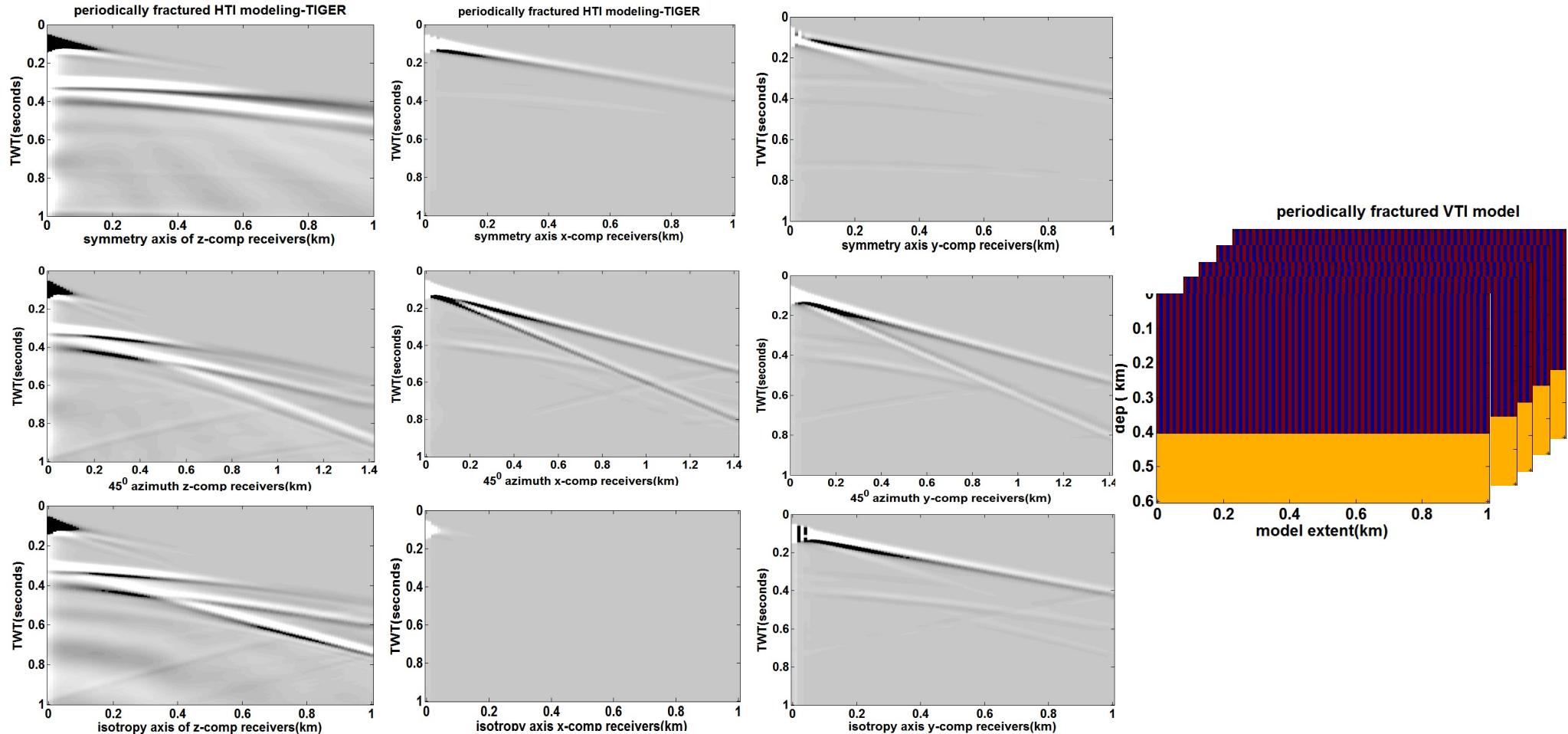


```
den=[2.495 2.200]'; alpha=[4.128 2.500]'; beta=[2.290 1.000]';
delta=[-0.0064 0]'; epsilon=[-0.0589 0]'; gamma=[-0.04 0]';
```

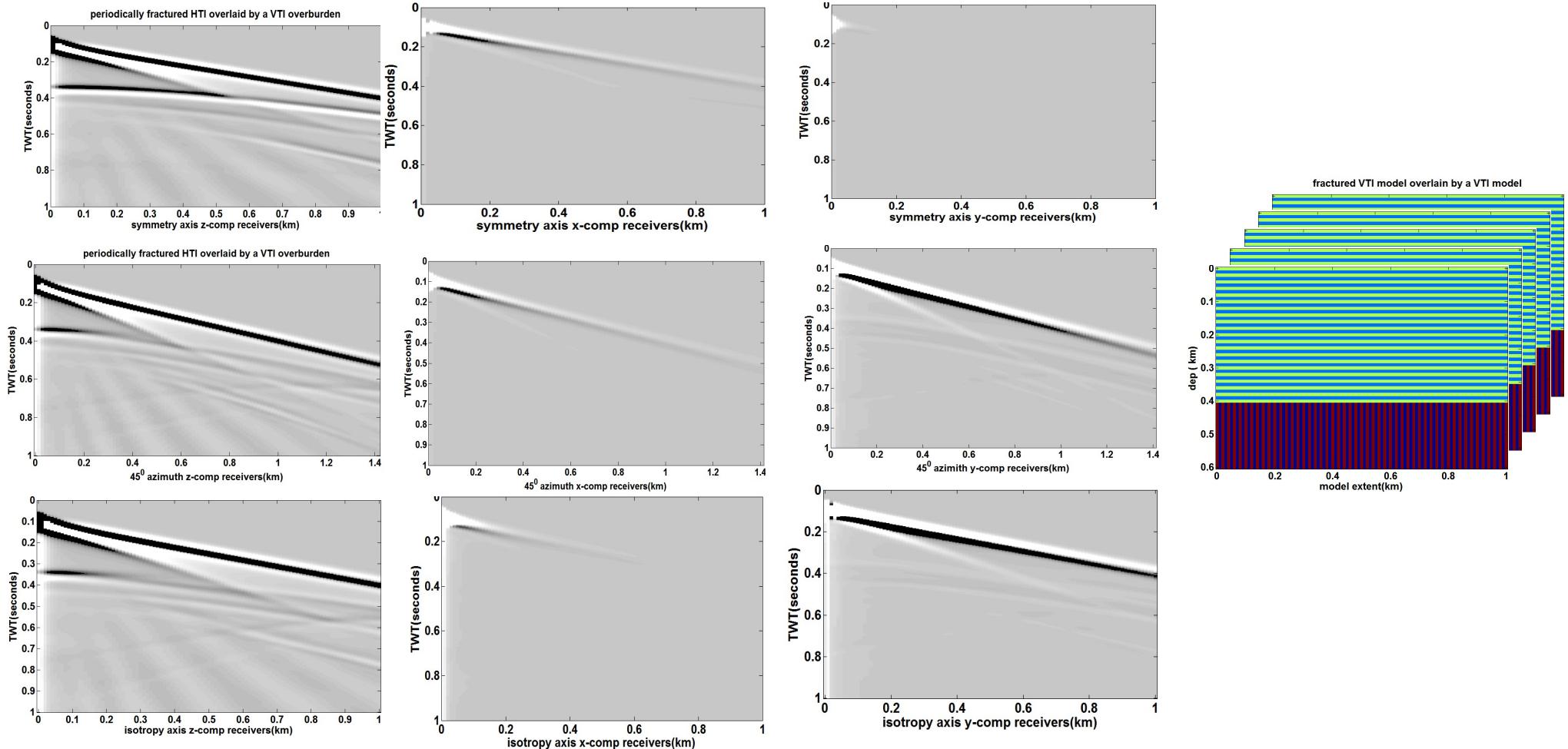
Overburden layered VTI modeling - TIGER



Fractured HTI modeling - TIGER

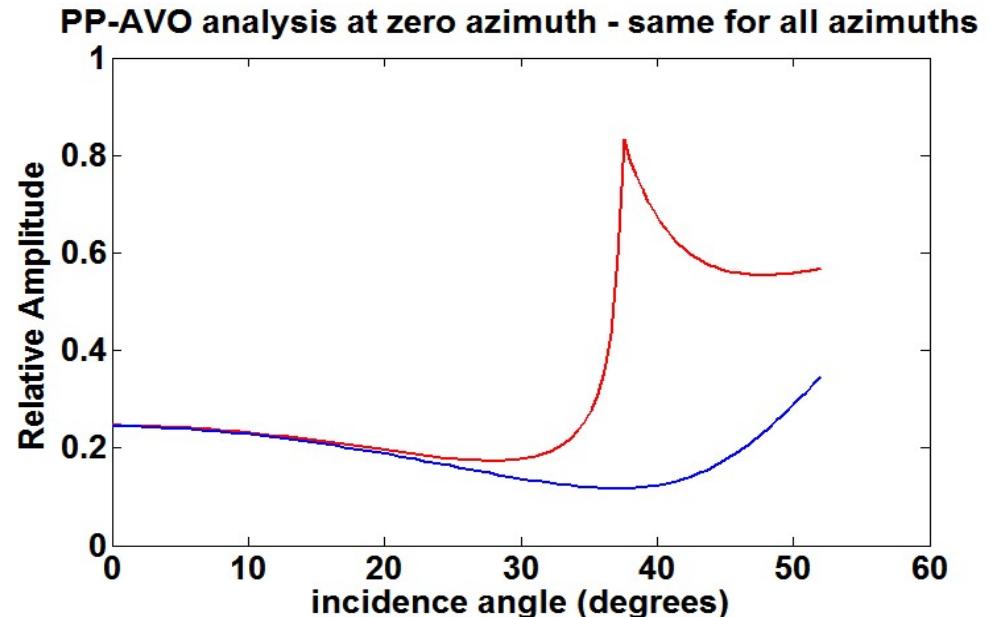
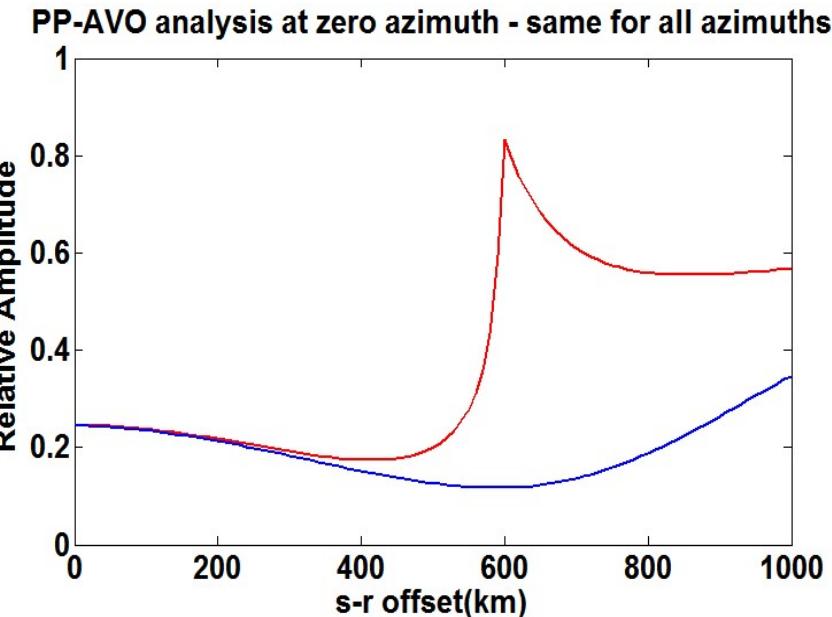


Fractured HTI medium overlain with layered VTI modeling - TIGER



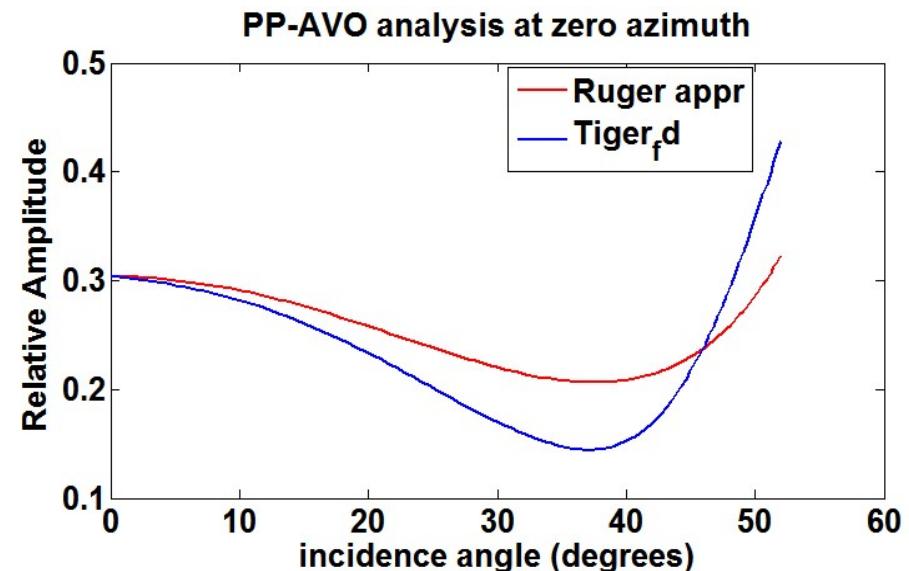
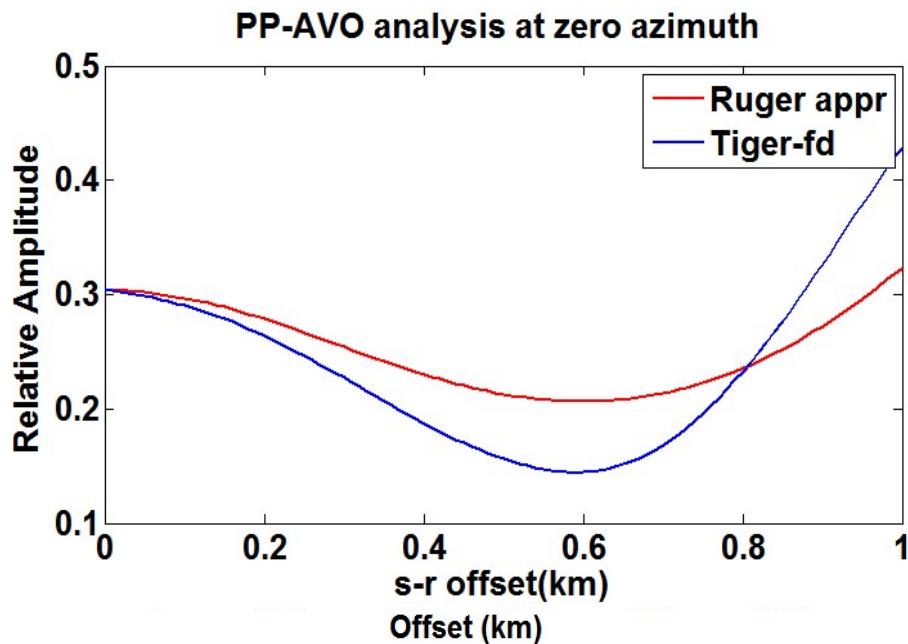
Amplitude Analysis

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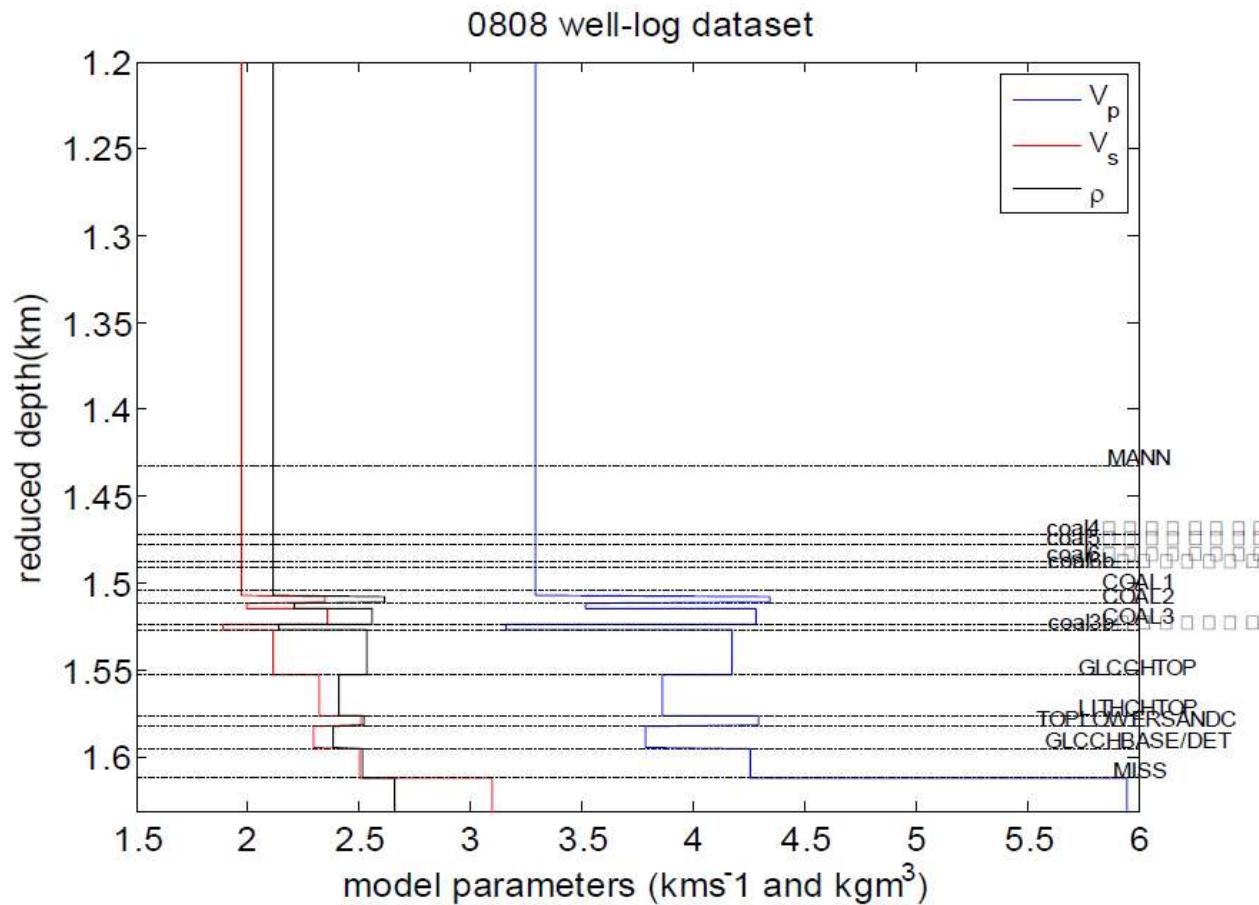


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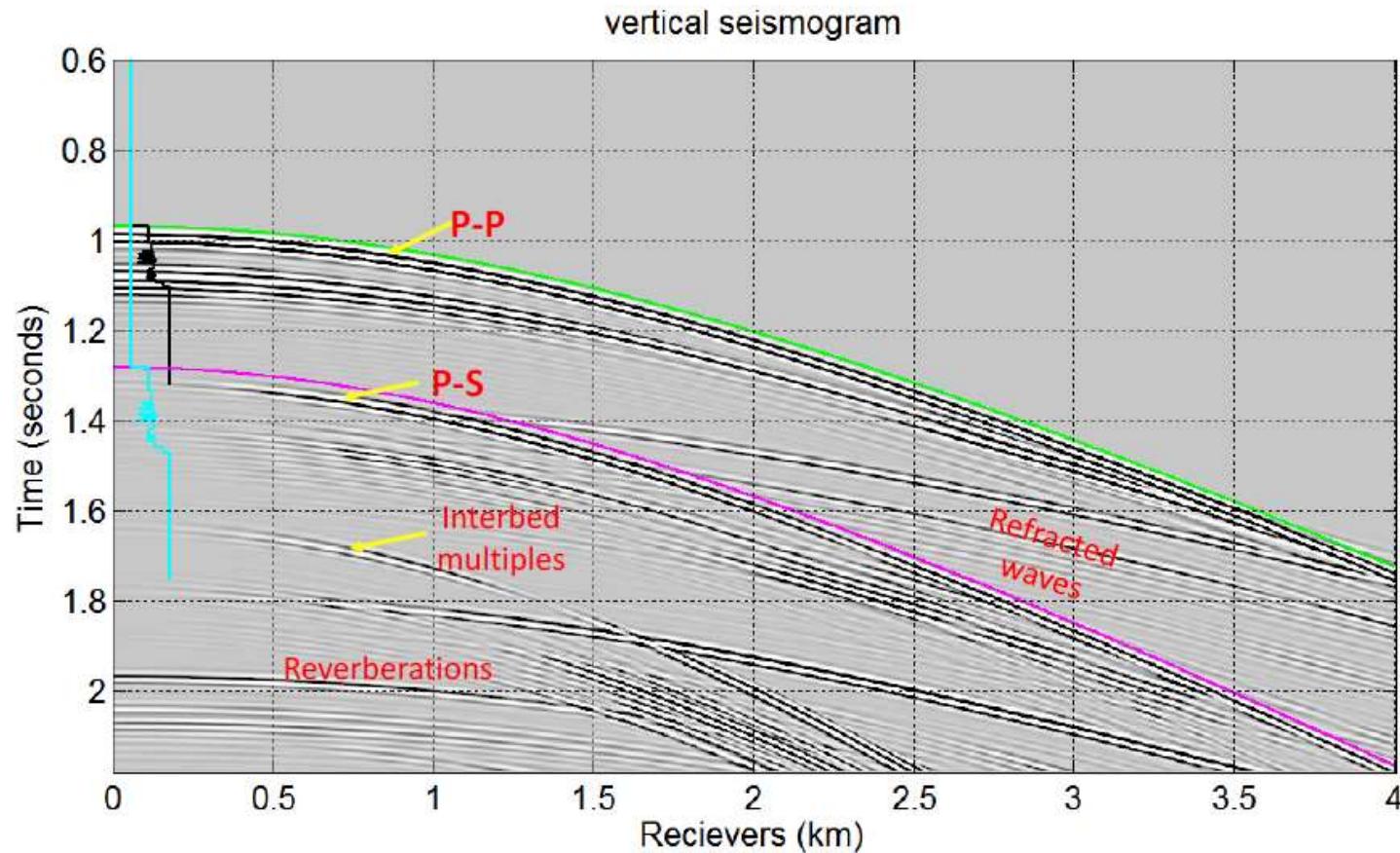
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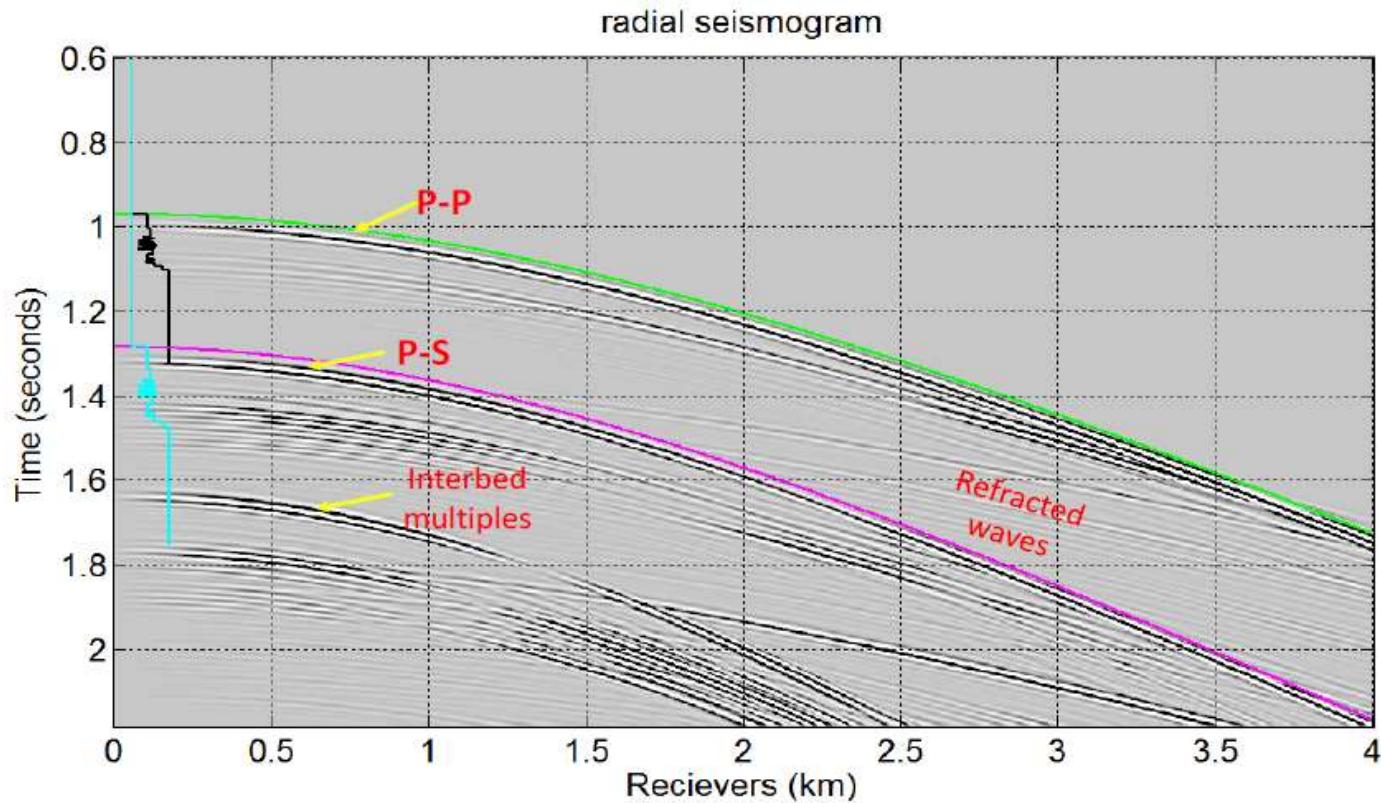
Previous Amplitude Analysis using AMM



Previous Amplitude Analysis using AMM

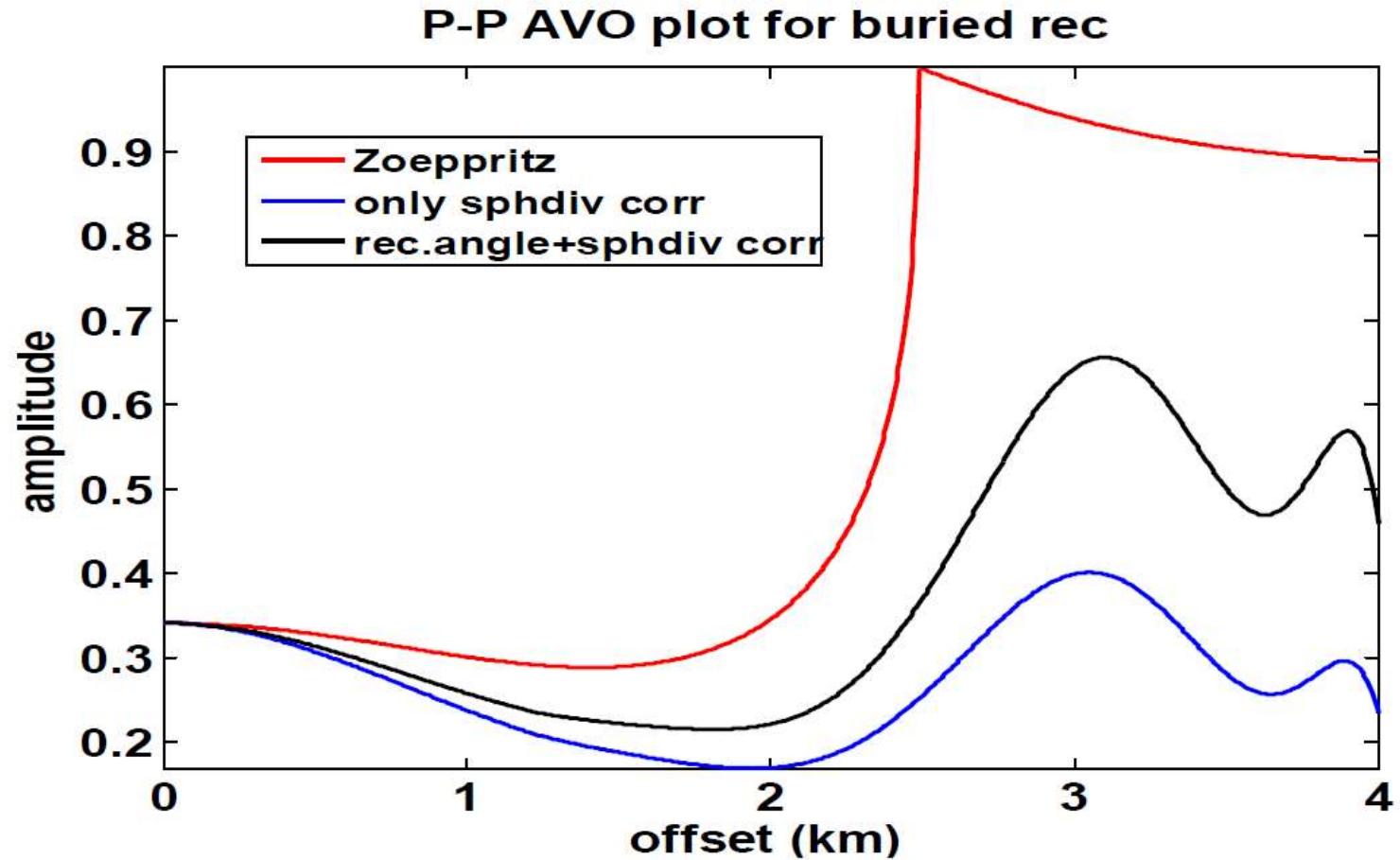


Previous Amplitude Analysis using AMM



Previous Amplitude Analysis using AMM

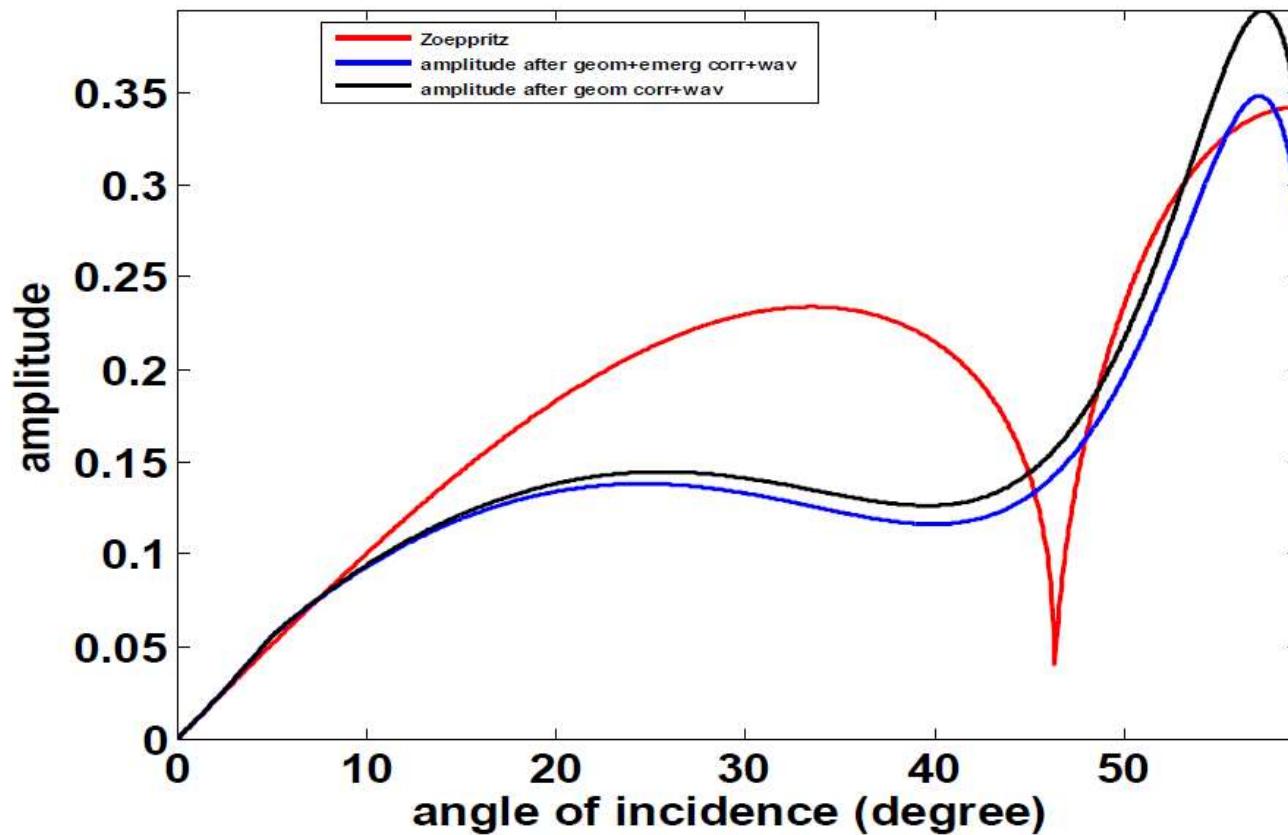
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P-S AVA plot for buried rec (0808 model)



Work in Progress

1. Further AVAZ analysis and comparison
 - I. Tiger FD
 - II. AMM (new modeling)
 - III. Ruger
2. Focus on processing Tiger FD result for fractured HTI media

Conclusion

- Backus averaging was used to estimate averages of elastic parameters and Thomsen's parameter
- The SINTEF TIGER Finite Difference tool is promising for all range of multicomponent seismic acquisition, processing and interpretation.
- The AMM code works well for isotropic and transversely Isotropy models with vertical symmetry,
- Work is still ongoing to improve its efficiency for anisotropic models.
- Work continues of further AVAZ analysis
- Good News!!! We can now import model into TIGER.

YEAH!

Acknowledgement

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- Students

Questions

