# Wave mode separation for a surface with slope using the free-surface response Saul E. Guevara\*, Gary F. Margrave and Don C. Lawton seguevar@ucalgary.ca

### INTRODUCTION

- Each one of the orthogonal components on multicomponent receivers can record P and S- wave modes. The separation of these two wave-modes would be advisable for processing and analysis.
- At the earth's surface the free surface has an effect on both wavefield phase and amplitude. This effect has been taken into account for wavemode separation by Dankbaar (1985), assuming a horizontal free surface, with receivers normal to it.
- However, if the receivers are placed vertically and there is a slope, as in the case of rough topography, this method is not applicable. This work extends the method to the case of a free surface with slope.
- It can contribute to improvement of the seismic data in rough terrain for P- and S-waves.

### DANKBAAR'S METHOD

- Wave mode separation taking into account the free surface effect. The response characteristics of the vertical and horizontal receivers are defined as a function of the velocities Vp and Vs and horizontal slowness p, are defined as  $R_z^P(p)$ ,  $R_z^S(p)$ ,  $R_x^P(p)$ , and  $R_x^S(p)$ , where the R subscripts indicate the direction and the superscripts the wave mode.
- For example  $R_{\chi}^{P}(p) = 4V_{P}p * E * N/R_{0}(p)$  where

$$E = (T^2 - V_S^2 p^2)^{1/2}$$
,  $N = (1 - V_S^2 p^2)^{1/2}$ , and  $R_0(p) = (1 - 2V_S^2 p^2)^2 + 4p^2 V_S^2 * E * N$ .

• Thus, the response of the vertical and horizontal receivers can be defined as:

$$U_z = P_{in}R_z^P + S_{in}R_z^S$$
 and  $U_x = P_{in}R_x^P + S_{in}R_x^S$ ,

where  $P_{in}$  is the incident P-wave and  $S_{in}$  is the incident S-wave.

- Then if we know the response characteristics of the vertical and horizontal components, and the field data it would be possible to obtain  $P_{in}$  and  $S_{in}$ .
- It is carried using a plane wave decomposition method, such as Fourier or t-p transforms.

# $P_{I}$ $\theta$ $\phi$ $P_{R}$ $X_{\xi}$ SURRACE

# THE SLOPING SURFACE

- FIG. 1: The sloping surface case: The slope has an angle ξ.
- $P_I$  corresponds to the incident P –wave,  $P_R$  to the reflected P-wave, and  $S_R$  to the reflected S-wave.
- The sloping surface case is illustrated in Fig. 1 for an incident P-wave.
- Two orthogonal coordinate axes are defined, one corresponding to the vertical and horizontal directions  $(x_0-z_0)$  and the other one to the directions parallel and normal to the surface  $(x_\xi-z_\xi)$ .
- The relations between the recorded components in the vertical and horizontal axes and the components in the axes normal and parallel to the surface are:

$$U_{z\xi} = U_{z0} * \cos \xi - U_{x0} * \sin \xi$$
 and  $U_{x\xi} = U_{x0} * \cos \xi + U_{z0} * \sin \xi$ 

• These equations allow us to rotate the data recorded in the vertical and horizontal directions, and then apply the method corresponding to the directions parallel and normal to the surface.

### **EXAMPLE**

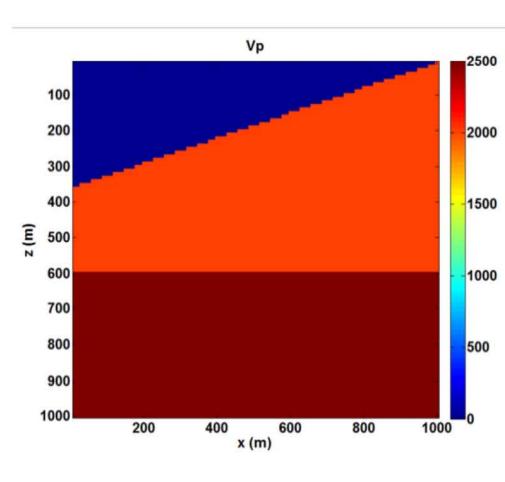


FIG. 2. Geological model to test the method, illustrated by the P-wave velocity.

 Sources and receivers are located on the sloping surface.

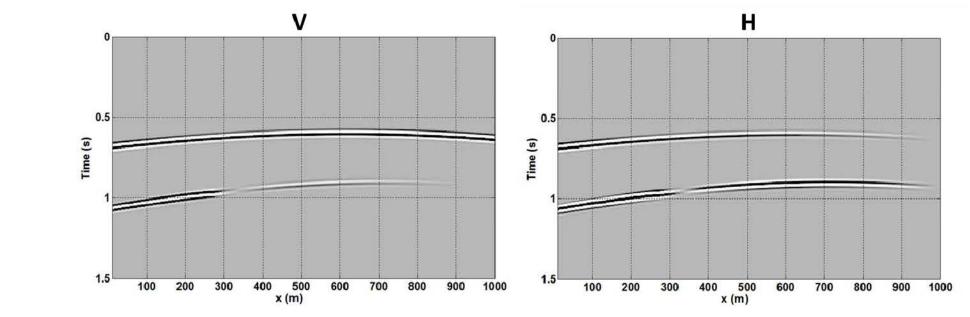


FIG. 3. Common receiver gathers at the receiver located in x=1000.

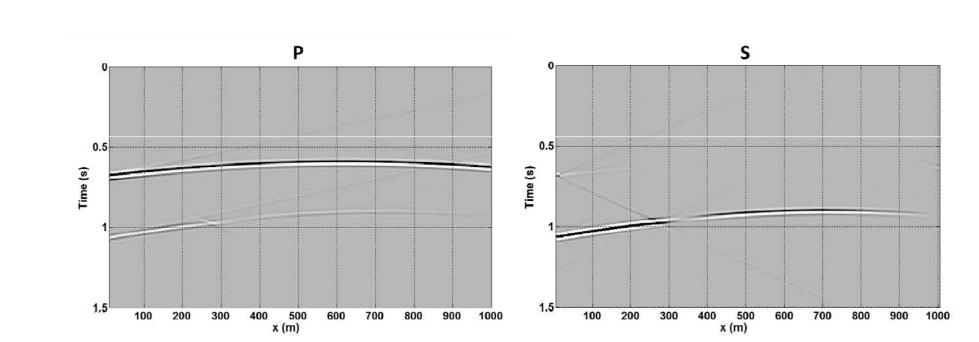


FIG. 4. P- and S- wave fields after the wave mode separation for the receiver at x=1000 m

# CONCLUSIONS

- A method for wave mode separation for a sloping surface has been proposed, taking into account the free surface response.
- The examples, from a simple model and with data generated by using ray tracing, show expected characteristics for such a wave mode separation method.
- A possible application of this method is the improvement of P and S-wave data in rough terrain.

## **ACKNOWLEDGEMENTS**

The financial support of the CREWES sponsors and the technical support of CREWES staff allowed to complete this work.





