

Instruction for C++ package of visco-elastic multiparameter FWI in the frequency domain

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ABSTRACT

The frequency domain full-waveform inversion (FWI) is a nonlinear optimization problem where large matrices such as the Helmholtz matrix and many derivatives are saved and utilized. In many inversion tests involving multiple variables and larger-scale models, the computational cost and consumption of computer resources should be considered. Matlab is presumably the best platform for solving large linear systems, manipulating matrices, and intuitively analyzing the intermediate results. However, its massive memory occupation and limited computational effectiveness can hamper going to 3-D problems or some larger 2-D FWI. Motivated by this, we developed a C++ version of the current 2-D frequency domain multi-parameter visco-elastic FWI, which can be carried out on relatively larger models. The reduced cost also allows us to go to the 3-dimensional inverse problems or the probabilistic approaches. Essential tools and concepts for working within the C++ ecosystem are covered in this instructive report, with examples of how to use this package.

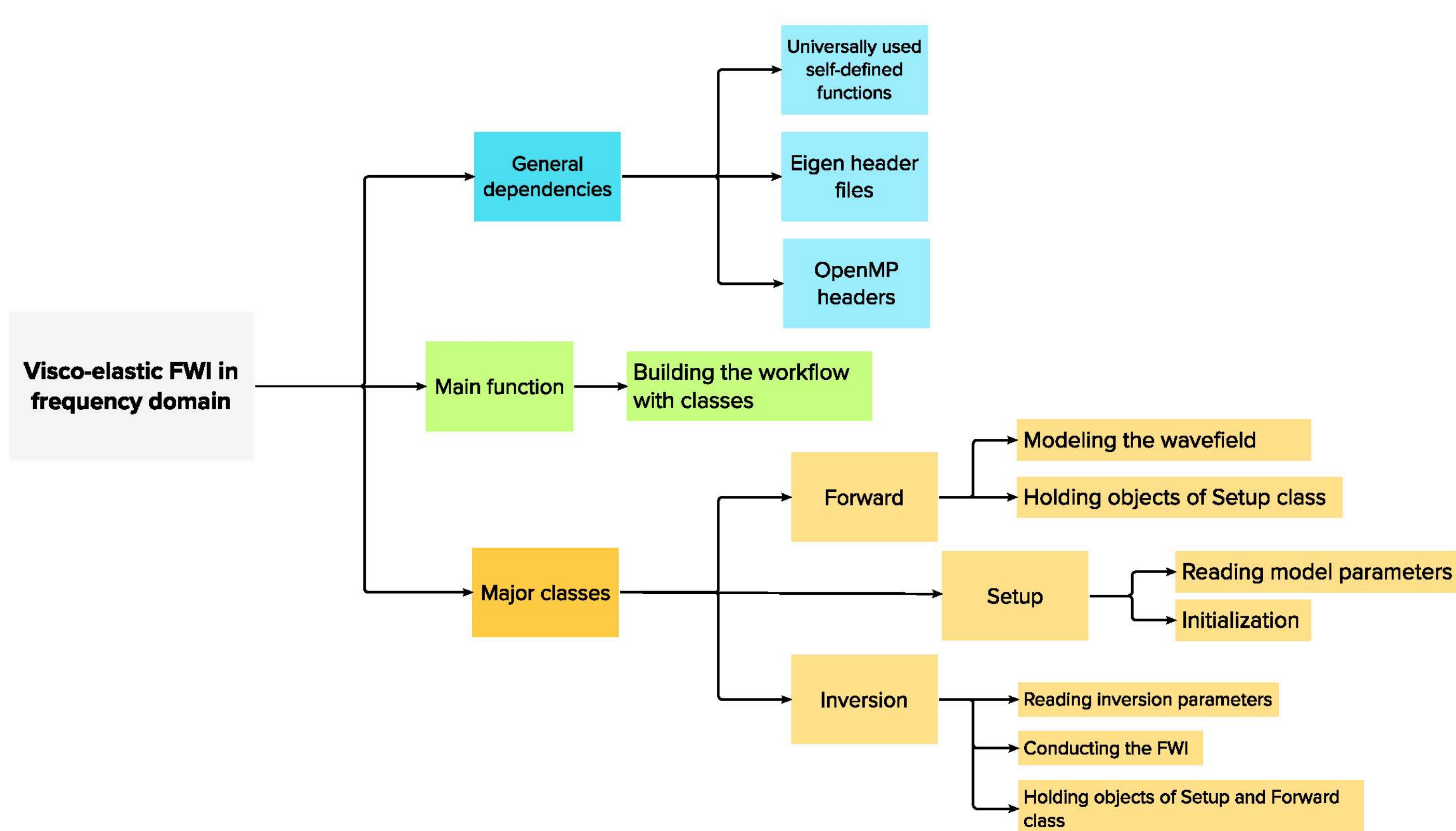


Figure 1. Basic structure of the VEFWI package.

Advantages:

- 1 Endogenously faster
- 2 Easy to couple with industry
- 3 Multi-platform
- 4 Memory manipulation
- 5 Open source

Prerequisites:

- Eigen
- OpenMP
- Basic Linear Algebra Subprograms (BLAS)
- Linear Algebra package (LAPACK)

COMPUTATIONAL CONSIDERATIONS ON MATRIX VIEW

The 2-D frequency domain elastic wave equation can be represented by matrix multiplications, thus making it an implicit finite-difference approach denoted by a system of linear equations shown below:

$$S(\omega)u(\omega) = f(\omega), \quad (1)$$

where S is the impedance matrix, u is the wavefield, and f is the source term. In the 2-D space, the dimensionality of S will be $2 \times nx \times nz$ by $2 \times nx \times nz$, and the nonzero values are $9 \times nx \times nz$. The resolution of this system is also expensive because of the memory for saving LU factors.

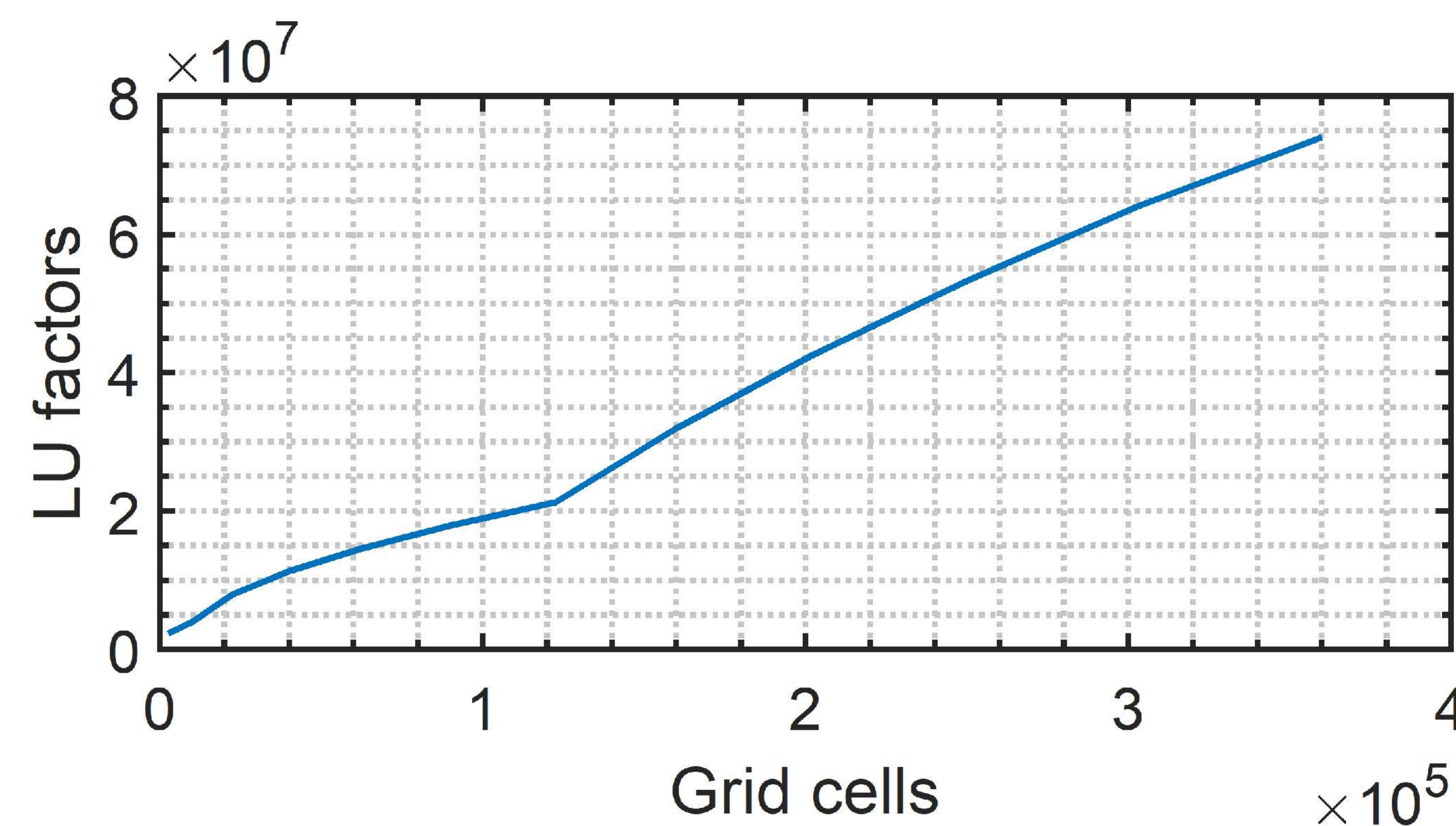


Figure 2. Amount of LU factors as a function of the grid cell number.

ALGORITHM IMPLEMENTATION

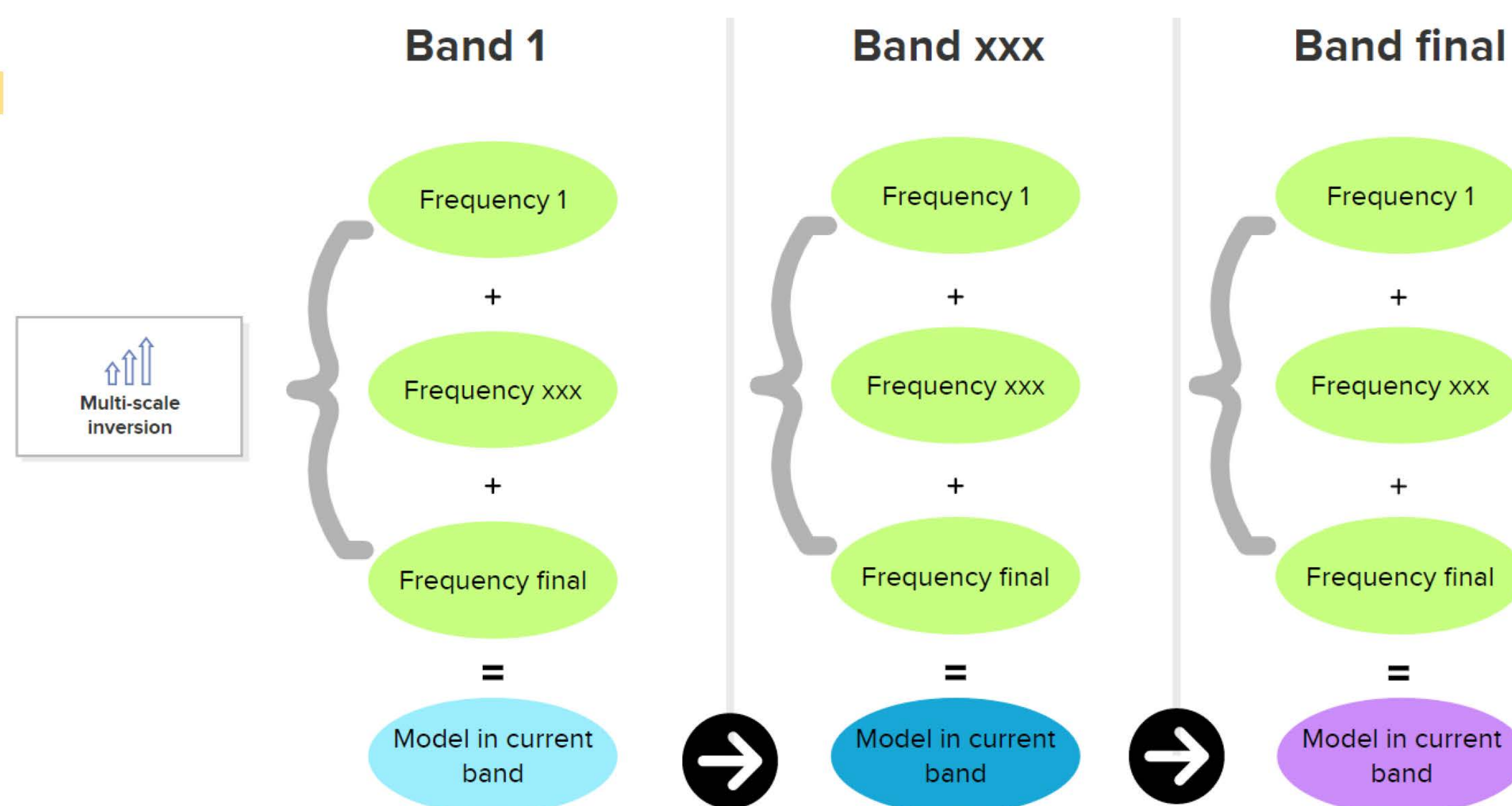


Figure 3. Multi-scale inversion logic.

```
1 for (int n = 0; n < frequency_band.size(); n++){
2   freqs = frequency_band(n);
3   // get the current frequency band.
4   subD = D(freqs);
5   // slice the dataset within the current band.
6   for (int i = 0; i < outer_iter; i++){
7     gradient = Gradient_VE(current model parameters, subD);
8     // compute the gradient term. (OpenMP parallelized)
9     descent_d = LBFGS_solve_linear(current model parameters,
10      gradient);
11    // compute the descent direction. Hessian-vector product is
12    // calculated many times (controlled by "maxits"). (OpenMP
13    // parallelized)
14    alpha = Linesearch_Nocedal_Full(model parameters, descent_d);
15    // get the updating step via line search.
16    model = model + alpha * descent_d;
17    // update the model in current band.
18  }
```

Figure 4. Pseudo code of inversion process.

EXPERIMENTS

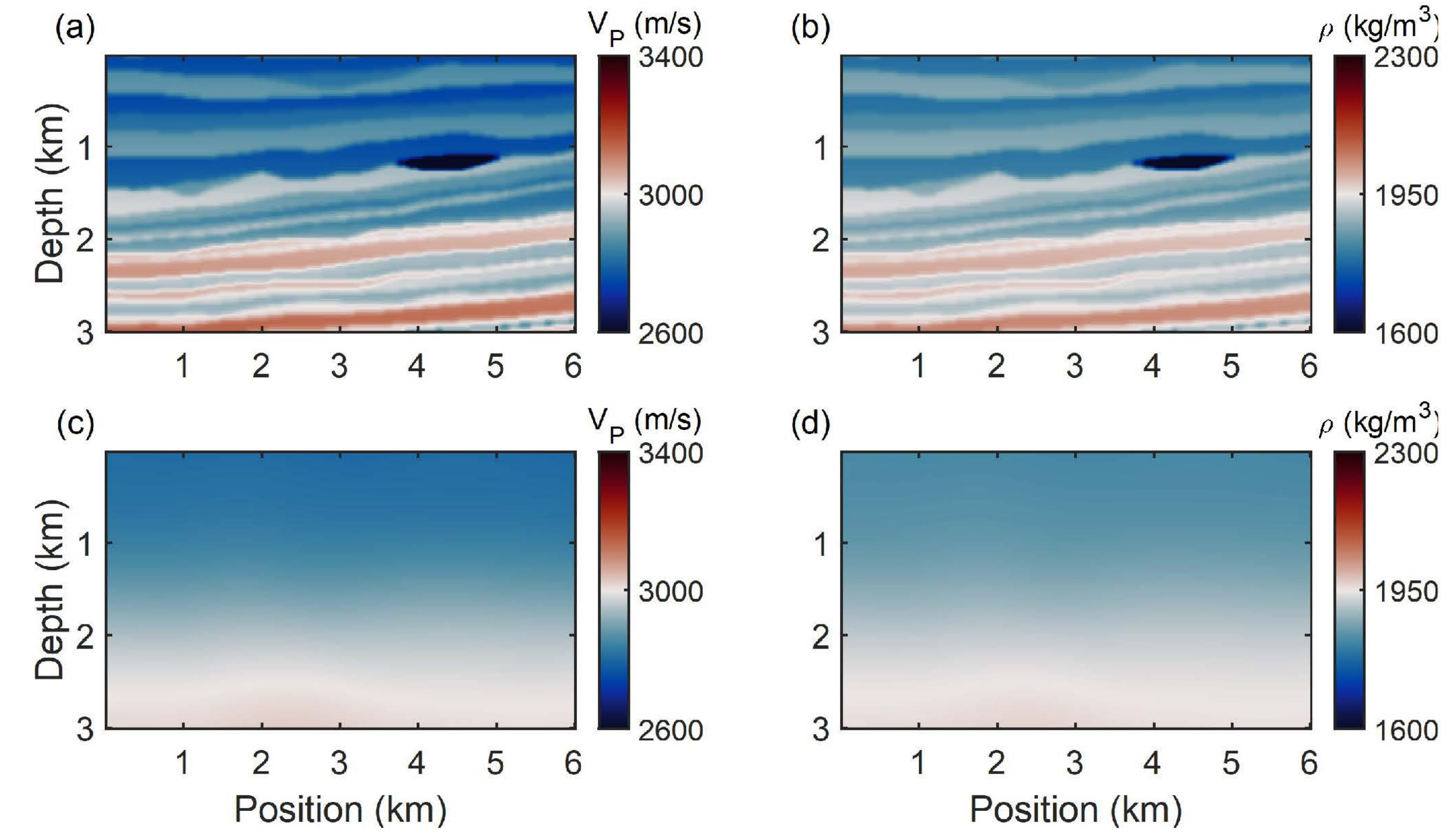


Figure 5. True and initial models.

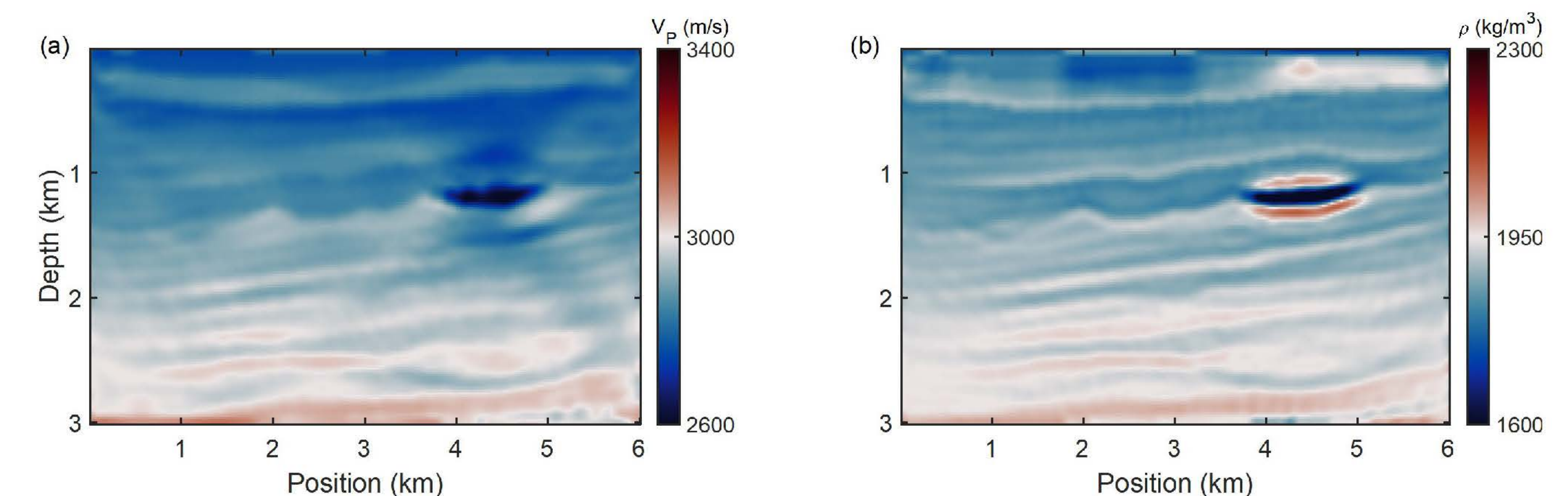


Figure 6. Estimated models.

Table 1: runtime measurement

Model size	Synthetic modeling	1 band inversion	Total runtime
50 × 50	6.23 s	58.1 s	581.3 s
100 × 50	15.31 s	162.93 s	1589.14 s
100 × 100	28.5 s	308.97 s	2097.9 s
150 × 100	57.59 s	655.6 s	6322.1 s
200 × 100	98.23 s	979.6 s	9701.43 s
250 × 100	143.76 s	1649 s	16351.6 s
300 × 100	215.45 s	1649 s	16351.6 s
300 × 150	371.71 s	3813.3 s	37017.1 s

Table 2: memory consumption

Model size	Synthetic modeling	Inversion
50 × 50	0.59 GB	1.47 GB
100 × 50	1.36 GB	2.52 GB
100 × 100	2.35 GB	4.51 GB
150 × 100	3.81 GB	8.25 GB
200 × 100	6.23 GB	11.9 GB
250 × 100	8.85 GB	15.1 GB
300 × 100	10.2 GB	20.8 GB
300 × 150	15.4 GB	26.2 GB

ACKNOWLEDGEMENTS

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