

An analytic approach to minimum phase signals

Michael P. Lamoureux and Gary F. Margrave

November 29, 2007



Minimum phase introduction

- ▶ certain physical signals have energy concentrated at the front
 - impulsive seismic sources (hammers, dynamite, airgun blast)
 - signals traveling through lossy media

Minimum phase introduction

- ▶ certain physical signals have energy concentrated at the front
 - impulsive seismic sources (hammers, dynamite, airgun blast)
 - signals traveling through lossy media
- ▶ traditionally called minimum phase

Minimum phase introduction

- ▶ certain physical signals have energy concentrated at the front
 - impulsive seismic sources (hammers, dynamite, airgun blast)
 - signals traveling through lossy media
- ▶ traditionally called minimum phase
- ▶ such signals can be recovered from the amplitude spectrum alone; the phase is uniquely determined.

Minimum phase introduction

- ▶ certain physical signals have energy concentrated at the front
 - impulsive seismic sources (hammers, dynamite, airgun blast)
 - signals traveling through lossy media
- ▶ traditionally called minimum phase
- ▶ such signals can be recovered from the amplitude spectrum alone; the phase is uniquely determined.
- ▶ useful in seismic processing.

Minimum phase introduction

- ▶ certain physical signals have energy concentrated at the front
 - impulsive seismic sources (hammers, dynamite, airgun blast)
 - signals traveling through lossy media
- ▶ traditionally called minimum phase
- ▶ such signals can be recovered from the amplitude spectrum alone; the phase is uniquely determined.
- ▶ useful in seismic processing.
- ▶ Eg: in deconvolution, where the reflectivity and the wavelet are separated from the recorded seismic data.

Filter background

- ▶ terminology comes from filter theory.

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).
- ▶ impulse response has energy is maximally concentrated at the front.

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).
- ▶ impulse response has energy is maximally concentrated at the front.
- ▶ causal stable filter with causal stable inverse (def'n).

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).
- ▶ impulse response has energy is maximally concentrated at the front.
- ▶ causal stable filter with causal stable inverse (def'n).
- ▶ all poles and zeros of the filter lie inside the unit circle (def'n).

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).
- ▶ impulse response has energy is maximally concentrated at the front.
- ▶ causal stable filter with causal stable inverse (def'n).
- ▶ all poles and zeros of the filter lie inside the unit circle (def'n).
- ▶ FIR, IIR filter converted to min phase by reflecting poles, zeros across unit circle.

Filter background

- ▶ terminology comes from filter theory.
- ▶ min phase filter has minimum group delay of all possible filters with a given amplitude spectrum (a misnomer).
- ▶ impulse response has energy is maximally concentrated at the front.
- ▶ causal stable filter with causal stable inverse (def'n).
- ▶ all poles and zeros of the filter lie inside the unit circle (def'n).
- ▶ FIR, IIR filter converted to min phase by reflecting poles, zeros across unit circle.
- ▶ or via Hilbert transform on log amplitude spectrum.

Min phase vs zero phase

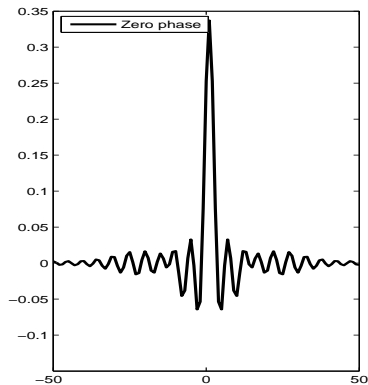
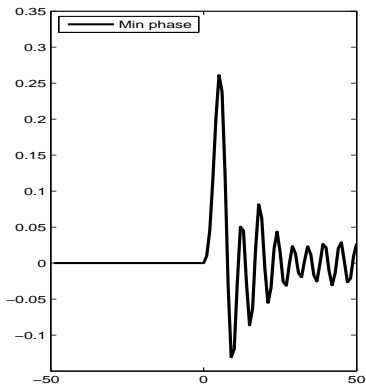


Figure: A minimum phase IIR filter response and zero phase equivalent.

Fundamental difficulty: applying filter theory to signals

- ▶ Filter response is a poor model for general signals.

Fundamental difficulty: applying filter theory to signals

- ▶ Filter response is a poor model for general signals.
- ▶ Signals typically don't have zeros and poles.

Fundamental difficulty: applying filter theory to signals

- ▶ Filter response is a poor model for general signals.
- ▶ Signals typically don't have zeros and poles.
- ▶ Impossible to have a causal stable signal with causal stable inverse on \mathbb{R} .

Fundamental difficulty: applying filter theory to signals

- ▶ Filter response is a poor model for general signals.
- ▶ Signals typically don't have zeros and poles.
- ▶ Impossible to have a causal stable signal with causal stable inverse on \mathbb{R} .
- ▶ Hilbert transform not defined on arbitrary log spectrum.

Why no causal stable signal with causal stable inverse?

- ▶ Signal $f : \mathbb{R} \rightarrow \mathbb{R}$ with inverse g means

$$f * g = \delta_0, \text{ the Dirac delta function.}$$

Why no causal stable signal with causal stable inverse?

- ▶ Signal $f : \mathbb{R} \rightarrow \mathbb{R}$ with inverse g means

$$f * g = \delta_0, \text{ the Dirac delta function.}$$

- ▶ But, f, g nice functions, implies $f * g$ also a function.
NOT a distribution.

Why no causal stable signal with causal stable inverse?

- ▶ Signal $f : \mathbb{R} \rightarrow \mathbb{R}$ with inverse g means

$$f * g = \delta_0, \text{ the Dirac delta function.}$$

- ▶ But, f, g nice functions, implies $f * g$ also a function.
NOT a distribution.
- ▶ For instance, locally integrable (“stable”) implies the convolution is locally integrable.

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.
- ▶ For those not in the know, it is some integral formula.

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.
- ▶ For those not in the know, it is some integral formula.
- ▶ Involves $\log(\text{abs}(\text{Fourier transform}))$.

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.
- ▶ For those not in the know, it is some integral formula.
- ▶ Involves $\log(\text{abs}(\text{Fourier transform}))$.
- ▶ Log blows up at the zeros of the Fourier transform.

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.
- ▶ For those not in the know, it is some integral formula.
- ▶ Involves $\log(\text{abs}(\text{Fourier transform}))$.
- ▶ Log blows up at the zeros of the Fourier transform.
- ▶ Try to fix by inserting a stability constant to remove zeros.
 $\log(\text{abs}(\text{Fourier transform}) + \epsilon)$

Why Hilbert transform a problem?

- ▶ For those in the know, we use the Hilbert transform to compute min phase.
- ▶ For those not in the know, it is some integral formula.
- ▶ Involves $\log(\text{abs}(\text{Fourier transform}))$.
- ▶ Log blows up at the zeros of the Fourier transform.
- ▶ Try to fix by inserting a stability constant to remove zeros.
 $\log(\text{abs}(\text{Fourier transform}) + \epsilon)$
- ▶ Does that work?

Analytic approach

- ▶ Given a causal, stable signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$, define

$$F(z) = \sum_{n=0}^{\infty} f_n z^n, \quad \text{for complex numbers } z \text{ with } |z| < 1.$$

Analytic approach

- ▶ Given a causal, stable signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$, define

$$F(z) = \sum_{n=0}^{\infty} f_n z^n, \quad \text{for complex numbers } z \text{ with } |z| < 1.$$

- ▶ $F(e^{i\omega})$ is just the usual Fourier transform. $F(z)$ is an extension of the spectrum to the disk.

Analytic approach

- ▶ Given a causal, stable signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$, define

$$F(z) = \sum_{n=0}^{\infty} f_n z^n, \quad \text{for complex numbers } z \text{ with } |z| < 1.$$

- ▶ $F(e^{i\omega})$ is just the usual Fourier transform. $F(z)$ is an extension of the spectrum to the disk.
- ▶ $F(z)$ is a power series, differentiable everywhere on the unit disk. An analytic function. A function in Hardy space $H^1(\mathbb{D})$.

Amazing facts in Hardy spaces

- ▶ An analytic function can't be zero on an interval (or curve) in the disk, unless it is zero everywhere.

Amazing facts in Hardy spaces

- ▶ An analytic function can't be zero on an interval (or curve) in the disk, unless it is zero everywhere.
- ▶ Similarly, a causal signal can't have an interval of zeros in its spectrum.

Amazing facts in Hardy spaces

- ▶ An analytic function can't be zero on an interval (or curve) in the disk, unless it is zero everywhere.
- ▶ Similarly, a causal signal can't have an interval of zeros in its spectrum.
- ▶ There are no band limited, causal signals.

Amazing facts in Hardy spaces

- ▶ An analytic function can't be zero on an interval (or curve) in the disk, unless it is zero everywhere.
- ▶ Similarly, a causal signal can't have an interval of zeros in its spectrum.
- ▶ There are no band limited, causal signals.
- ▶ There are no band limited, minimum phase signals.

No min phase, band limited spike

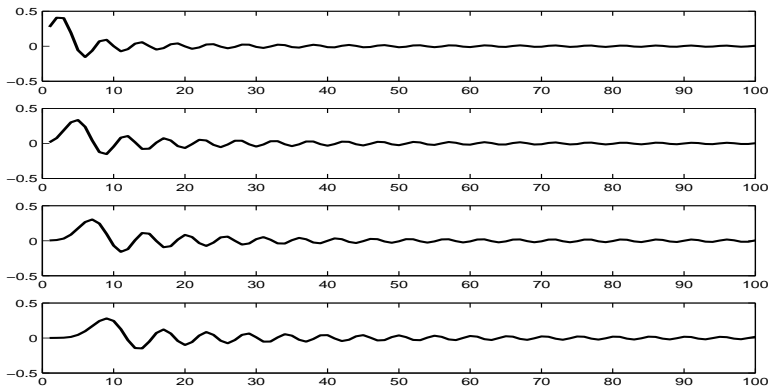


Figure: Trying to compute a min phase signal that does not exist.
Stability factor ϵ goes to zero....

Existence conditions

Theorem: An amplitude spectrum $|F(e^{i\omega})|$ is the spectrum of a causal signal if and only if

- ▶ $\int |F(e^{i\omega})| d\omega < \infty$, and
- ▶ $\int \log |F(e^{i\omega})| d\omega$ is finite.

Thus, the spectrum can not have an interval of zeros, since $\log 0 = -\infty$.

Theorem: Any causal signal has a minimum phase equivalent.

More facts about Hardy spaces.

- ▶ Each function $F(z)$ can be factored as $F(z) = G(z) H(z)$, where G is an outer function, H is an inner function.

More facts about Hardy spaces.

- ▶ Each function $F(z)$ can be factored as $F(z) = G(z) H(z)$, where G is an outer function, H is an inner function.
- ▶ Outer functions are like minimum phase filters.

More facts about Hardy spaces.

- ▶ Each function $F(z)$ can be factored as $F(z) = G(z) H(z)$, where G is an outer function, H is an inner function.
- ▶ Outer functions are like minimum phase filters.
- ▶ Inner functions are like all pass filters.

More facts about Hardy spaces.

- ▶ Each function $F(z)$ can be factored as $F(z) = G(z) H(z)$, where G is an outer function, H is an inner function.
- ▶ Outer functions are like minimum phase filters.
- ▶ Inner functions are like all pass filters.
- ▶ The inner, outer definitions (complicated) apply to general signals, not just filters.

A better definition for “min phase” signals.

- ▶ **Definition:** A causal signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$ is *front-loaded* if its partial energies are maximized, relative to any other causal signal with the same amplitude spectrum. That is,

$$\sum_{n=0}^N |g_n|^2 \leq \sum_{n=0}^N |f_n|^2, \quad \text{for each } N = 0, 1, 2, \dots$$

A better definition for “min phase” signals.

- ▶ **Definition:** A causal signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$ is *front-loaded* if its partial energies are maximized, relative to any other causal signal with the same amplitude spectrum. That is,

$$\sum_{n=0}^N |g_n|^2 \leq \sum_{n=0}^N |f_n|^2, \quad \text{for each } N = 0, 1, 2, \dots$$

- ▶ **Theorem:** A discrete signal $\mathbf{f} = (f_0, f_1, f_2, \dots)$ is front-loaded if and only if $F(z)$ is an outer function.

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.

New definition more general:

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.
- ▶ For causal stable signals: min phase implies front-loaded.

New definition more general:

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.
- ▶ For causal stable signals: min phase implies front-loaded.
- ▶ Extra conditions: then front-loaded implies min phase.

New definition more general:

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.
- ▶ For causal stable signals: min phase implies front-loaded.
- ▶ Extra conditions: then front-loaded implies min phase.

New definition more general:

- ▶ Signal $\mathbf{f} = (1, r, 0, 0, \dots)$ is min phase, front-loaded. ($|r| < 1$).

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.
- ▶ For causal stable signals: min phase implies front-loaded.
- ▶ Extra conditions: then front-loaded implies min phase.

New definition more general:

- ▶ Signal $\mathbf{f} = (1, r, 0, 0, \dots)$ is min phase, front-loaded. ($|r| < 1$).
- ▶ Signal $\mathbf{f} = (1, 1, 0, 0, \dots)$ is not min phase, but is front-loaded.

Compare with old definition

Old definition works:

- ▶ For causal, stable filters: min phase implies front-loaded.
- ▶ For causal stable signals: min phase implies front-loaded.
- ▶ Extra conditions: then front-loaded implies min phase.

New definition more general:

- ▶ Signal $\mathbf{f} = (1, r, 0, 0, \dots)$ is min phase, front-loaded. ($|r| < 1$).
- ▶ Signal $\mathbf{f} = (1, 1, 0, 0, \dots)$ is not min phase, but is front-loaded.
- ▶ Signal $\mathbf{f} = (1, 1, 1, 1, 1, 1, 0, \dots)$ is not min phase, but is front-loaded.

Technical details

- ▶ We divide up signals into outer and inner parts. Outers have the energy concentration.

Technical details

- ▶ We divide up signals into outer and inner parts. Outers have the energy concentration.
- ▶ A function $F(z)$ is *outer* if

$$F(z) = \lambda \exp \left(\int_0^1 \frac{e^{2\pi i\theta} + z}{e^{2\pi i\theta} - z} u(e^{2\pi i\theta}) d\theta \right)$$

where u is a real-valued integrable function on the unit circle, and λ is a complex number of modulus one.

Technical details

- ▶ We divide up signals into outer and inner parts. Outers have the energy concentration.
- ▶ A function $F(z)$ is *outer* if

$$F(z) = \lambda \exp \left(\int_0^1 \frac{e^{2\pi i\theta} + z}{e^{2\pi i\theta} - z} u(e^{2\pi i\theta}) d\theta \right)$$

where u is a real-valued integrable function on the unit circle, and λ is a complex number of modulus one.

- ▶ A function $F(z)$ is *inner* if $|F| \equiv 1$ on the unit circle.

Technical details

- ▶ We divide up signals into outer and inner parts. Outers have the energy concentration.
- ▶ A function $F(z)$ is *outer* if

$$F(z) = \lambda \exp \left(\int_0^1 \frac{e^{2\pi i\theta} + z}{e^{2\pi i\theta} - z} u(e^{2\pi i\theta}) d\theta \right)$$

where u is a real-valued integrable function on the unit circle, and λ is a complex number of modulus one.

- ▶ A function $F(z)$ is *inner* if $|F| \equiv 1$ on the unit circle.
- ▶ Every function can be written as outer times inner.

Non singular formula for discrete, min phase signal.

From Hardy theory, we get alternate formulas for min phase signals. Signal coefficients from the outer function:

$$f_n = \frac{1}{r^n} \int_0^1 F(re^{2\pi i\phi}) e^{-2\pi in\phi} d\phi, \quad \text{any } r < 1 .$$

Signal coefficients from the amplitude spectrum:

$$f_n = \frac{1}{r^n} \int_0^1 \exp \left(\int_0^1 \frac{e^{2\pi i\theta} + re^{2\pi i\phi}}{e^{2\pi i\theta} - re^{2\pi i\phi}} \log |F(e^{2\pi i\theta})| d\theta \right) e^{-2\pi in\theta} d\phi.$$

Signals on the real line.

- ▶ Similarly, we have

Definition: A causal signal $\mathbf{f} : \mathbb{R}^+ \rightarrow \mathbb{R}$ is *front-loaded* if its partial energies are maximized, relative to any other causal signal with the same amplitude spectrum. That is,

$$\int_0^T |g(t)|^2 dt \leq \int_0^T |f(t)|^2 dt \quad \text{for each } T > 0.$$

Signals on the real line.

- ▶ Similarly, we have

Definition: A causal signal $\mathbf{f} : \mathbb{R}^+ \rightarrow \mathbb{R}$ is *front-loaded* if its partial energies are maximized, relative to any other causal signal with the same amplitude spectrum. That is,

$$\int_0^T |g(t)|^2 dt \leq \int_0^T |f(t)|^2 dt \quad \text{for each } T > 0.$$

- ▶ **Theorem:** A causal signal $f : \mathbb{R}^+ \rightarrow \mathbb{R}$ with spectrum $F(z)$ an outer function, is front-loaded.

Signals on the real line.

- ▶ Similarly, we have

Definition: A causal signal $\mathbf{f} : \mathbb{R}^+ \rightarrow \mathbb{R}$ is *front-loaded* if its partial energies are maximized, relative to any other causal signal with the same amplitude spectrum. That is,

$$\int_0^T |g(t)|^2 dt \leq \int_0^T |f(t)|^2 dt \quad \text{for each } T > 0.$$

- ▶ **Theorem:** A causal signal $f : \mathbb{R}^+ \rightarrow \mathbb{R}$ with spectrum $F(z)$ an outer function, is front-loaded.
- ▶ **Conjecture:** This is if and only if.

Computing approximately band-limited min phase signals.

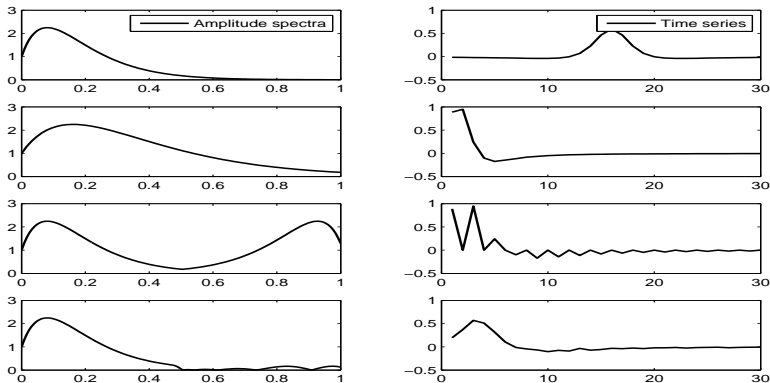


Figure: Step by step construction, using spectrum wrapping.

Conclusions

- ▶ Mathematical difficulties in applying minimum phase definition to signals.

Conclusions

- ▶ Mathematical difficulties in applying minimum phase definition to signals.
- ▶ Front-loaded, energy concentration a useful alternative definition.

Conclusions

- ▶ Mathematical difficulties in applying minimum phase definition to signals.
- ▶ Front-loaded, energy concentration a useful alternative definition.
- ▶ Front-load signals equivalent to outer functions in Hardy space.

Conclusions

- ▶ Mathematical difficulties in applying minimum phase definition to signals.
- ▶ Front-loaded, energy concentration a useful alternative definition.
- ▶ Front-load signals equivalent to outer functions in Hardy space.
- ▶ No band-limited causal signals, no band-limited min phase signals.

Conclusions

- ▶ Mathematical difficulties in applying minimum phase definition to signals.
- ▶ Front-loaded, energy concentration a useful alternative definition.
- ▶ Front-load signals equivalent to outer functions in Hardy space.
- ▶ No band-limited causal signals, no band-limited min phase signals.
- ▶ Hardy space theory gives useful formulations for computing min phase signals.

References

- ▶ Helson, H., 1995, Harmonic Analysis.
- ▶ Hoffman, K., 1962, Banach Spaces of Analytic Functions.
- ▶ Karl, J., 1989, An Introduction to Digital Signal Processing.
- ▶ Körner, T., Fourier Analysis.
- ▶ Openheim, A. V. and Schafer, R. W., 1998, Discrete-time Signal Processing.

Acknowledgements

This research is supported by

- ▶ the industrial sponsors of CREWES and POTSI
- ▶ the funding agencies NSERC and MITACS.