

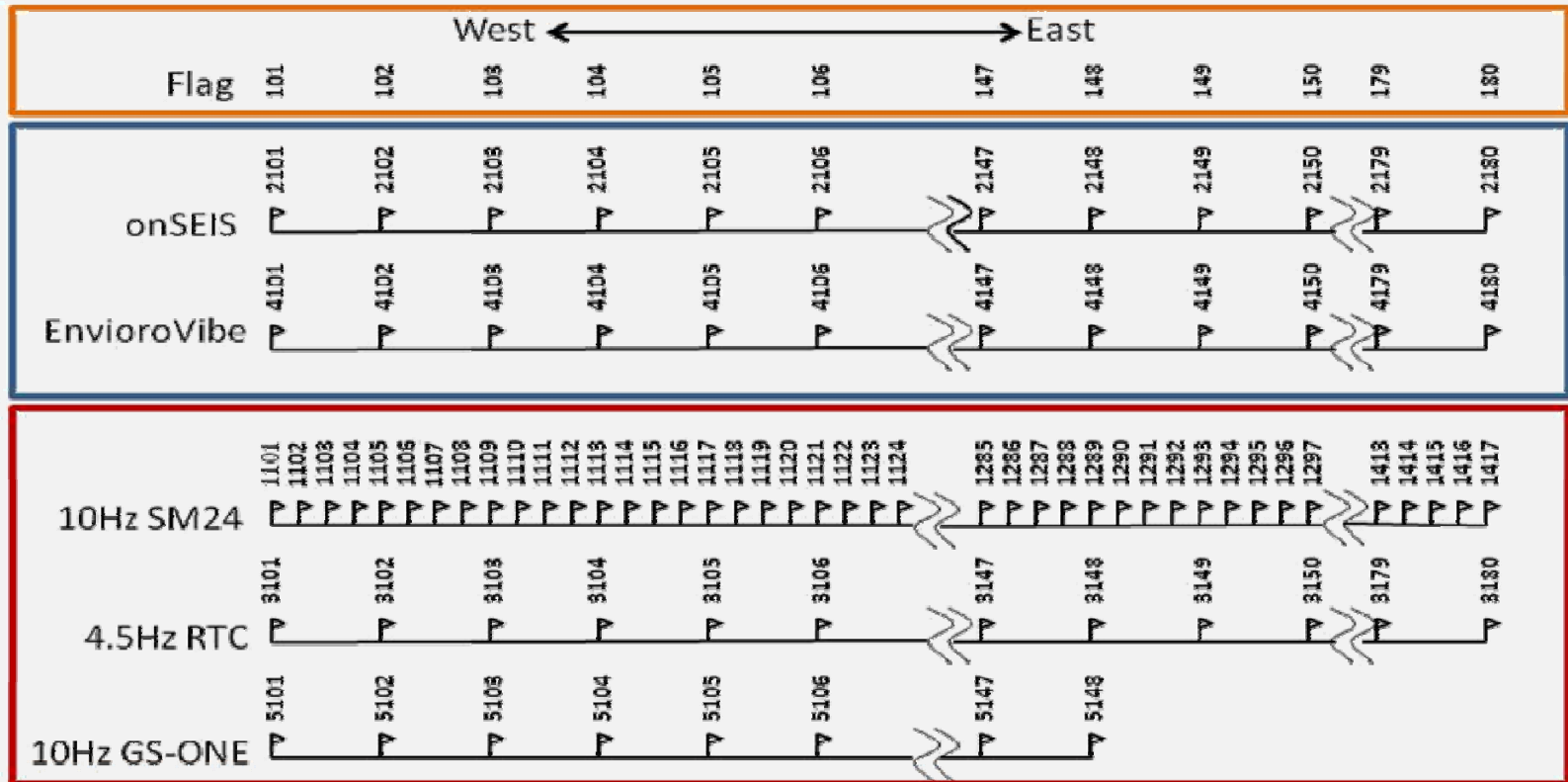
# Source and receiver comparisons from Priddis and Hussar

Malcolm B. Bertram, J. Helen Isaac, Kevin W. Hall, Kevin L. Bertram and Gary F. Margrave



# The Priddis survey

- Date: 7-10 December 2010
- Sources comparison: onSEIS and EnviroVibe
- Geophone comparison: Sensor SM24, RTC4.5, Oyo-Geospace GS-One
- Recording system: U of C Aries SPMLite



# Priddis source comparison:



## EnviroVibe

Hold down: 15,000 lb  
Sweeps per vibe point: 4  
Length of sweep: 20 seconds  
Sweep: Linear 10-200 Hz  
Shot spacing: 10m

Industrial Vehicles International, Inc



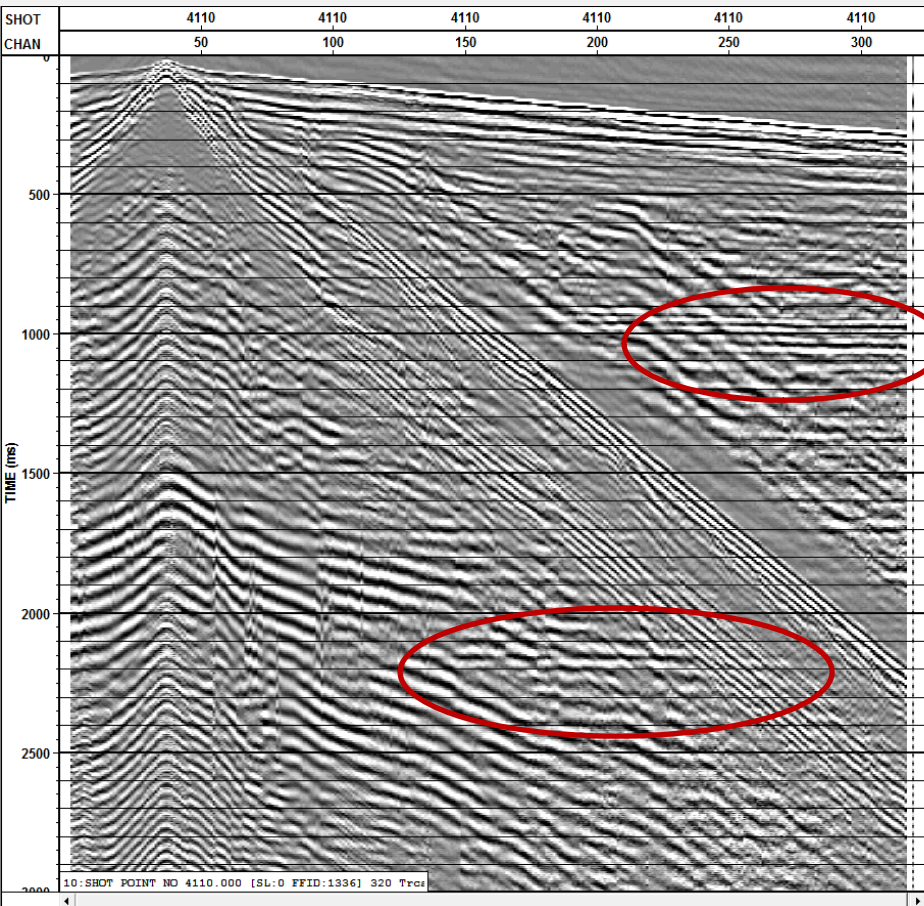
## onSEIS

Dual electro-magnetic impact units  
Impacts per shot point: 16  
Shot spacing: 10m

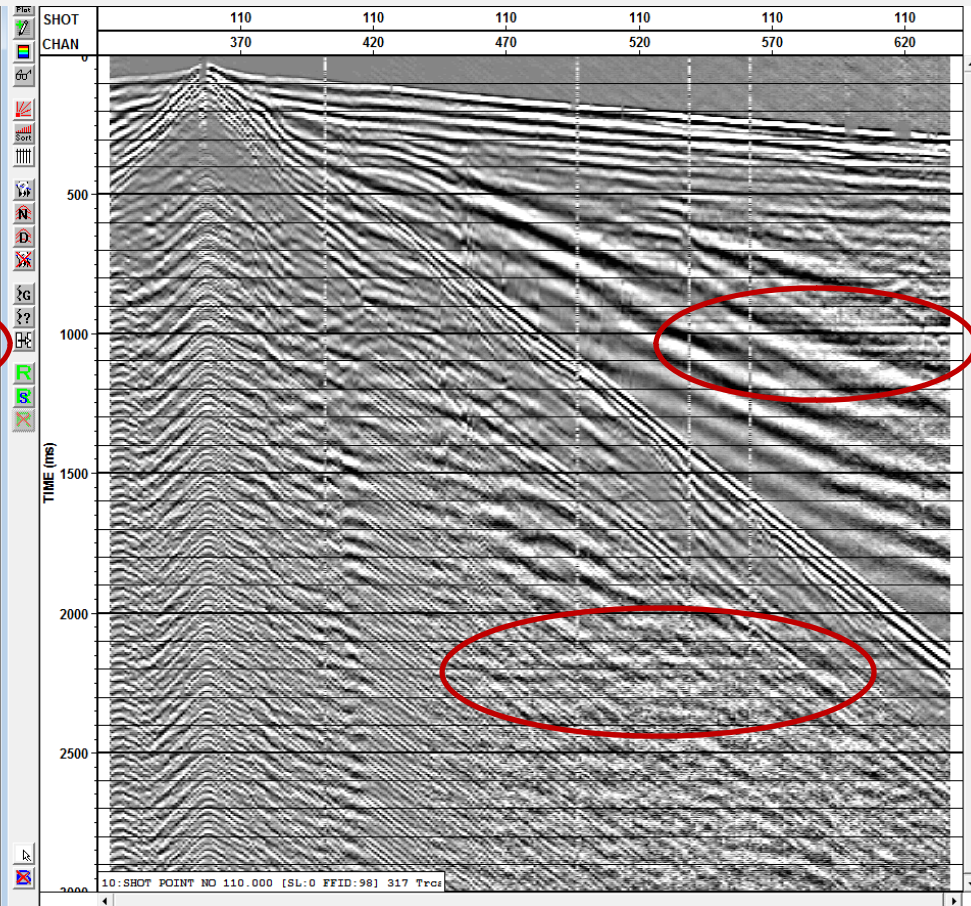
Yeniseigeofizika OJSC



# Shot gathers at flag 110 (SM-24 geophones @ 2.5m)



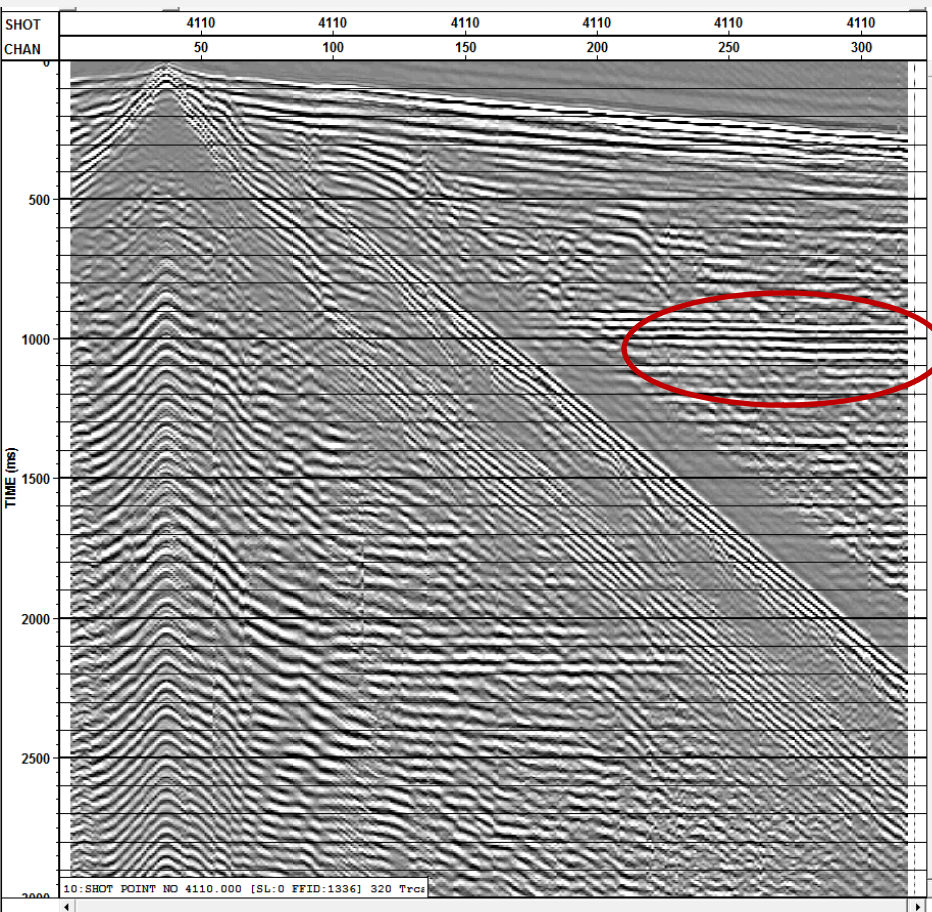
EnviroVibe



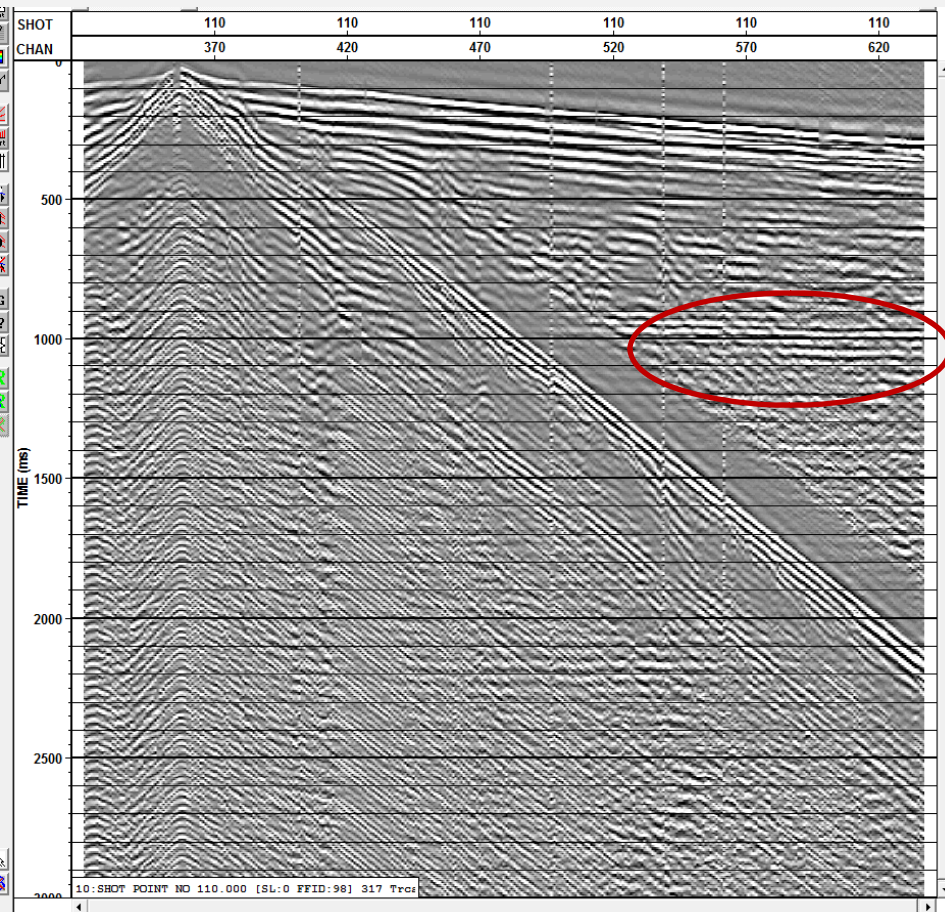
onSEIS



# Shot gathers at flag 110 (SM-24 geophones @ 2.5m)



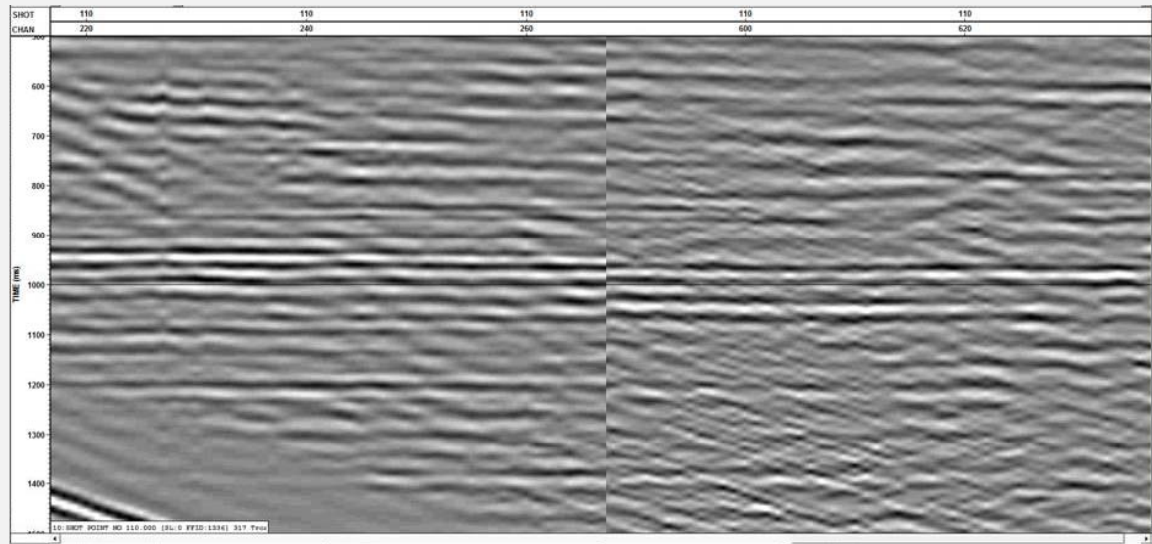
EnviroVibe



onSEIS

Filters: 20-25-60-80

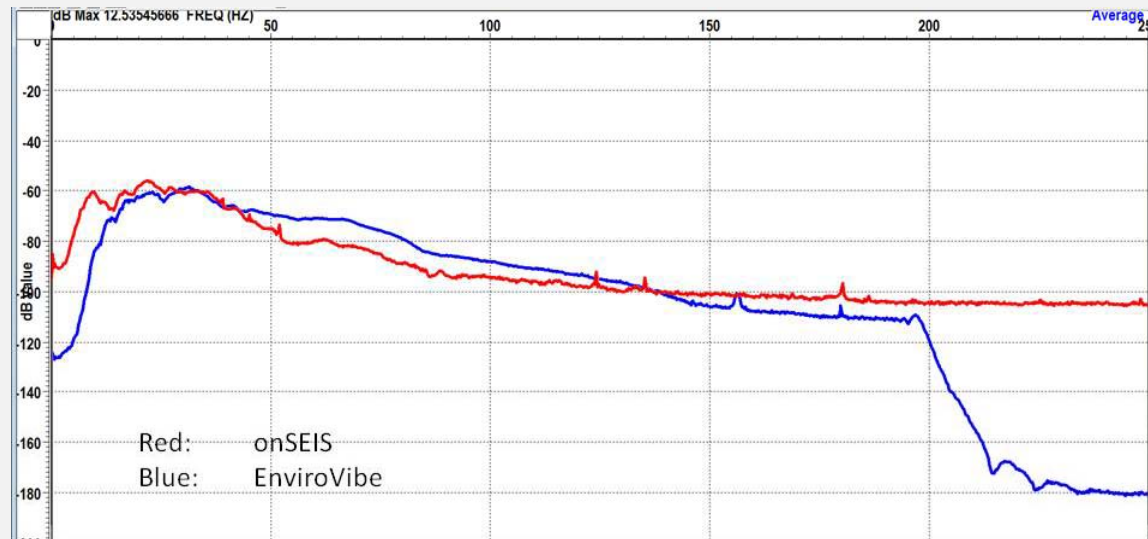
## The event at 1 second



EnviroVibe

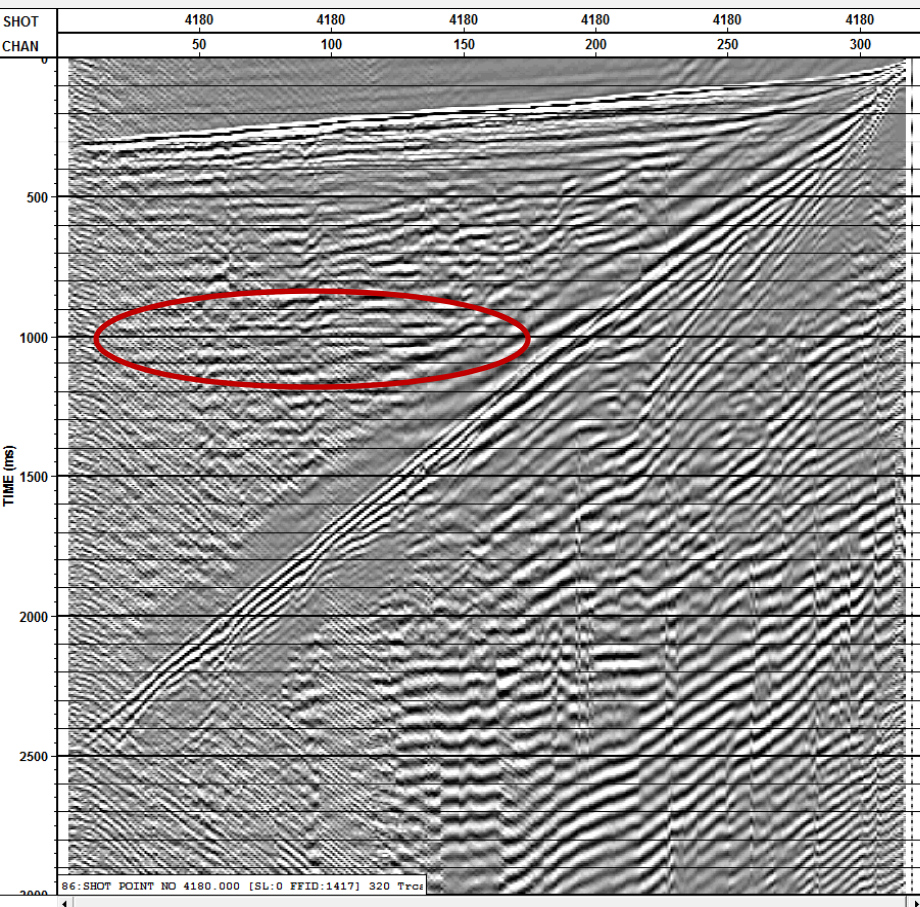
onSEIS

## Spectra of the gathers

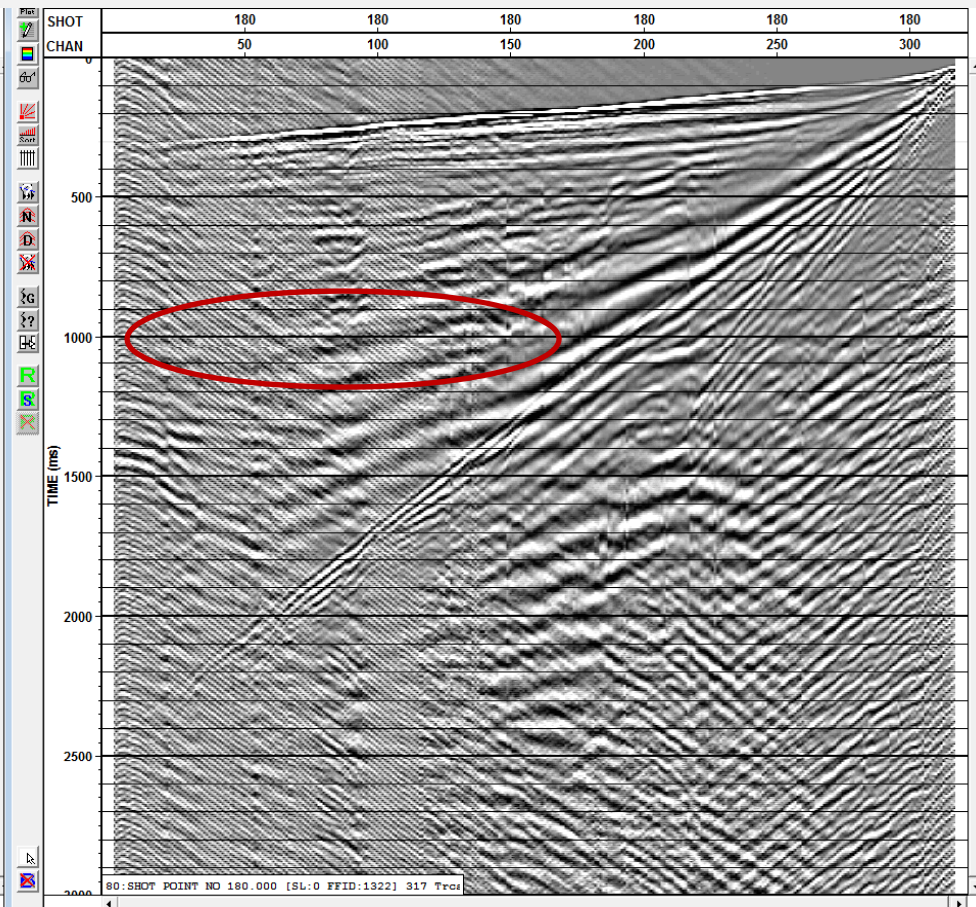




# Shot gathers at flag 180 (SM-24 geophones @ 2.5m)



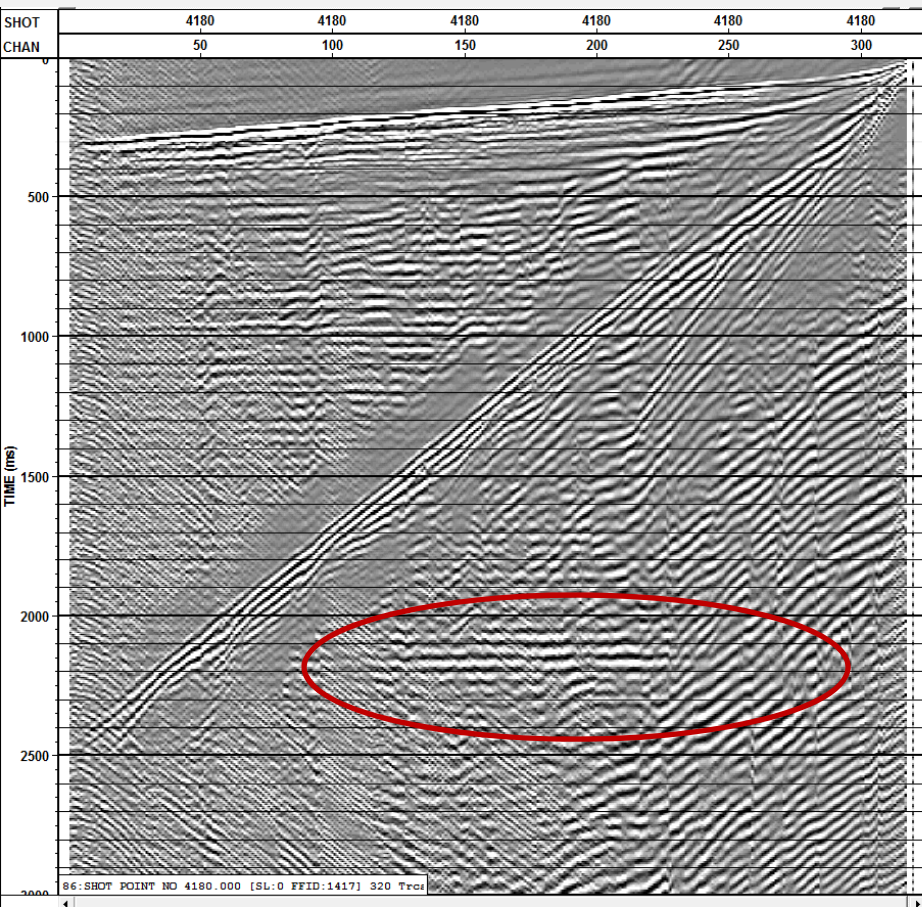
EnviroVibe



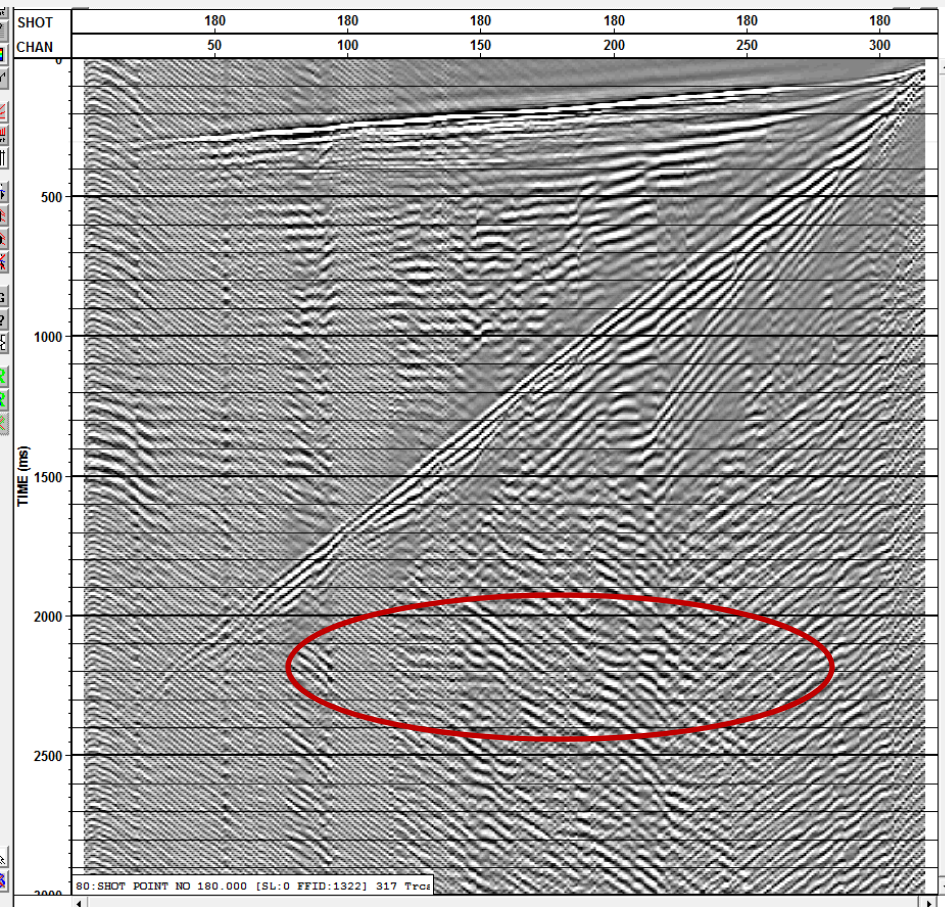
onSEIS



# Shot gathers at flag 180 (SM-24 geophones @ 2.5m)



EnviroVibe

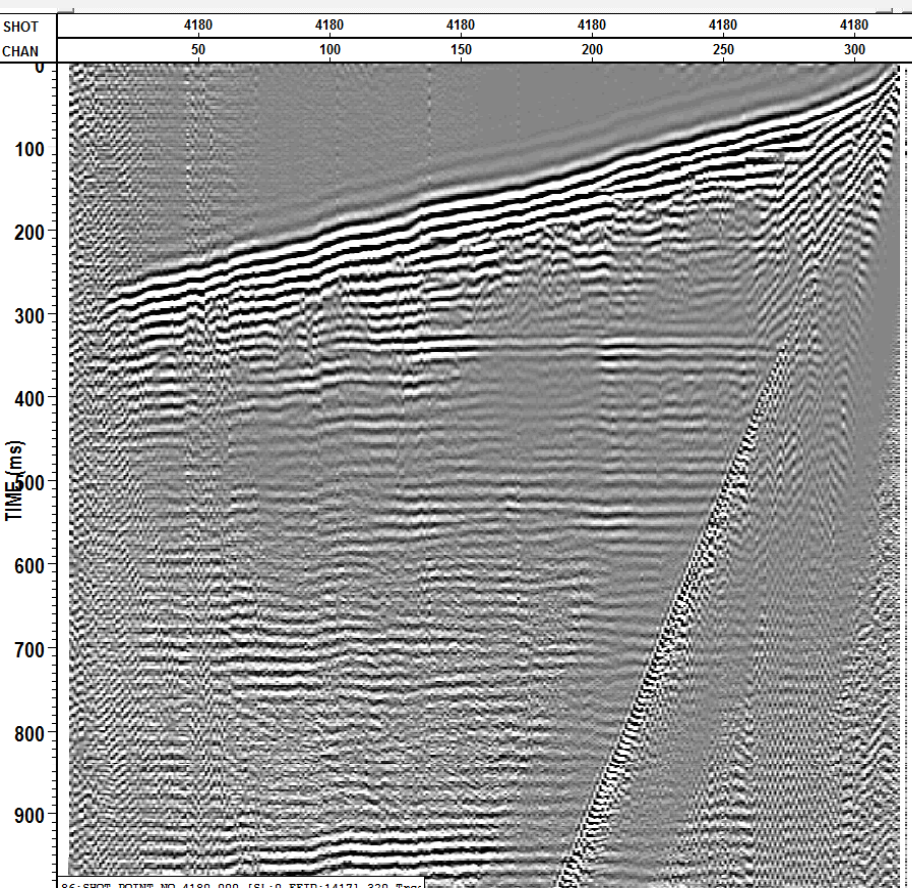


onSEIS

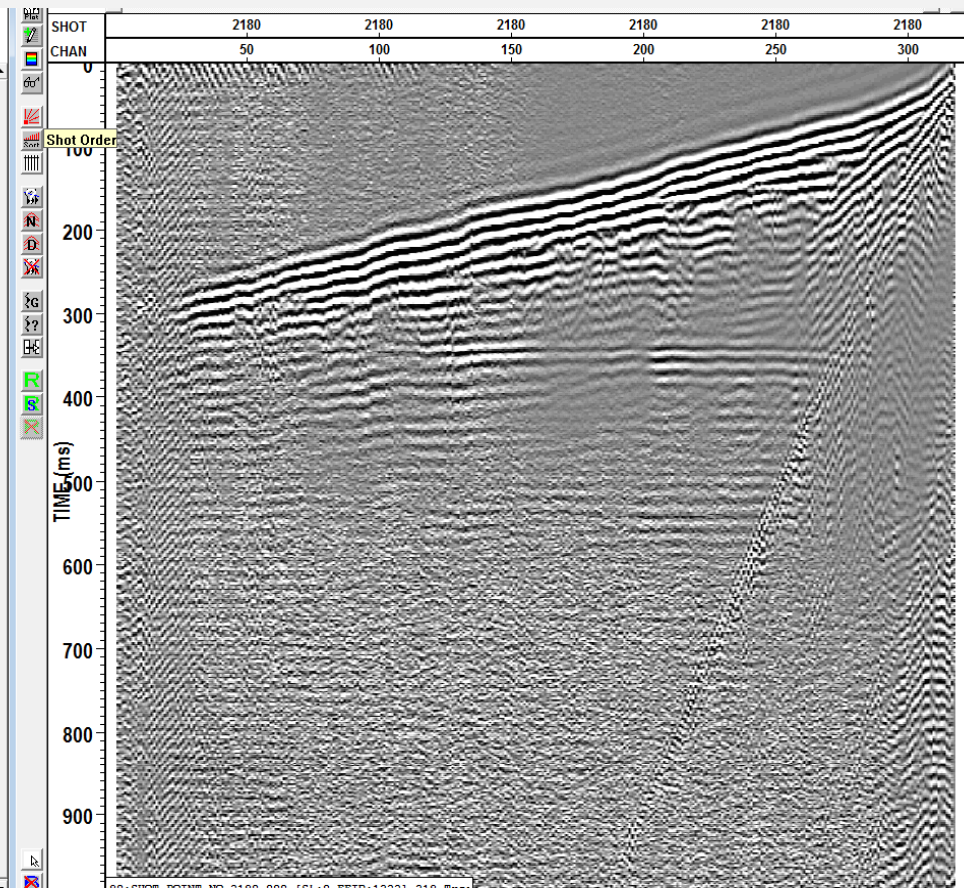
Filters: 20-25-60-80



# Shot gathers at flag 180 (SM-24 geophones @ 2.5m)



EnviroVibe

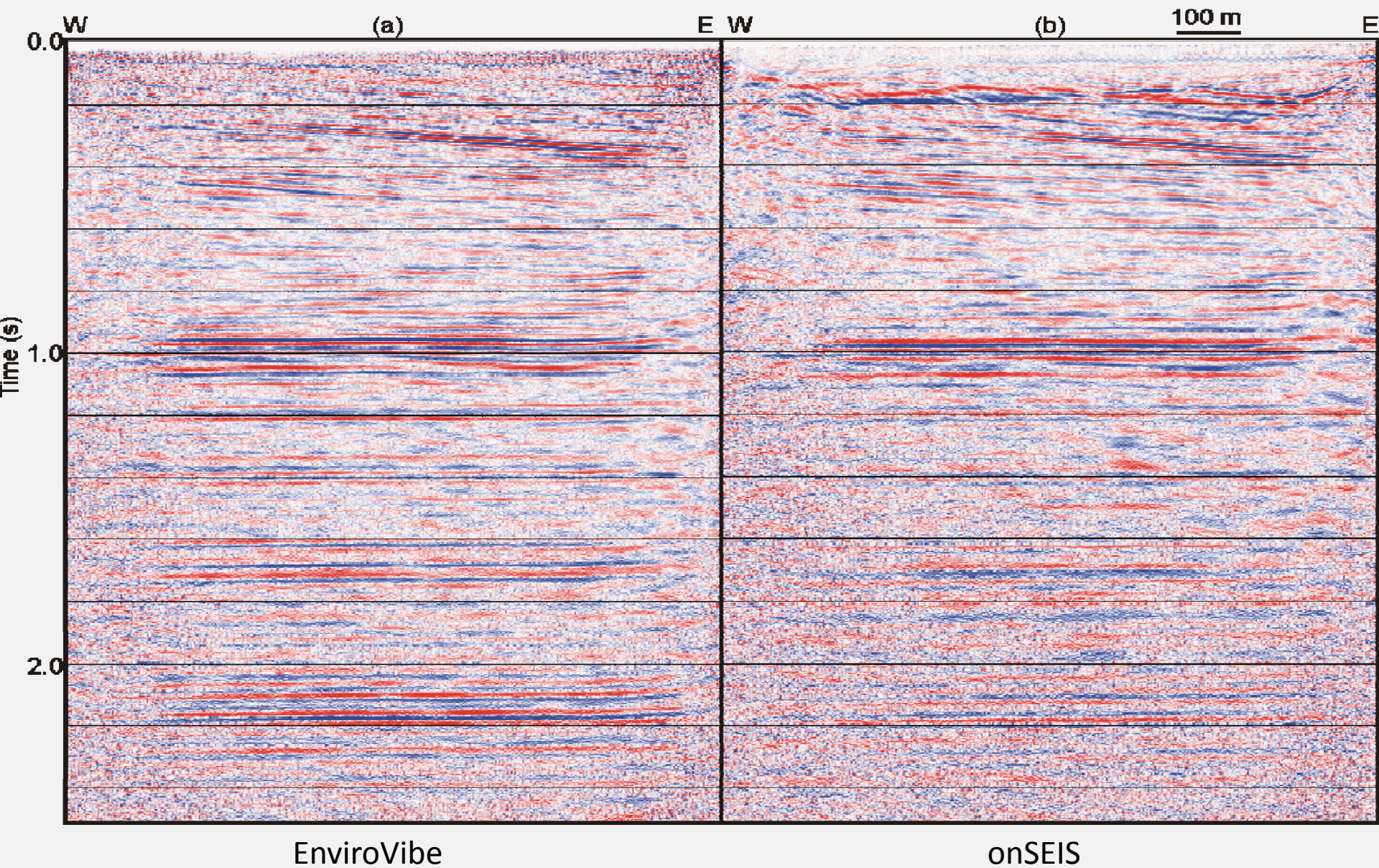


onSEIS

First second of gathers with filters: 45-70-250-250

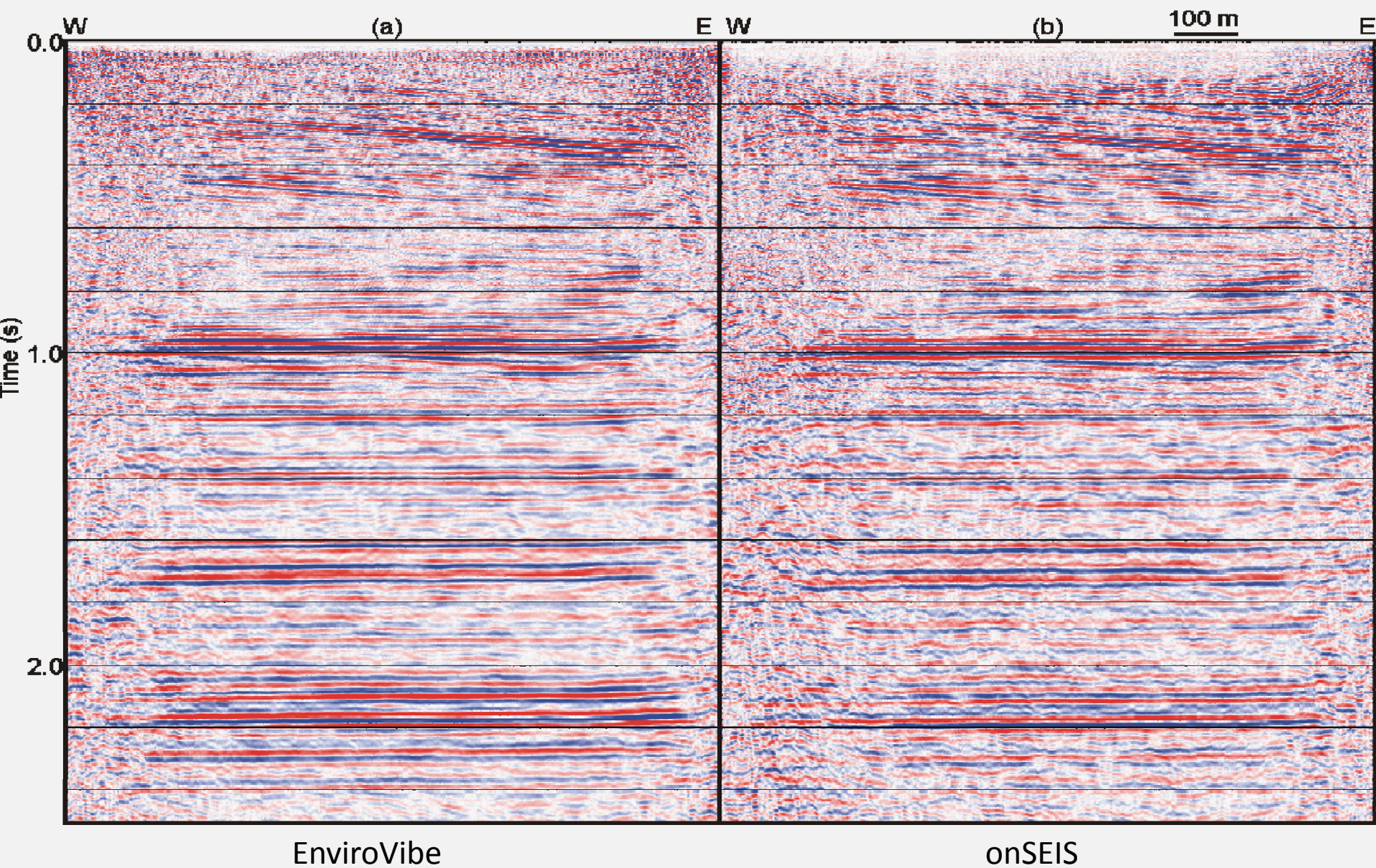


# Stacked section with no filter applied





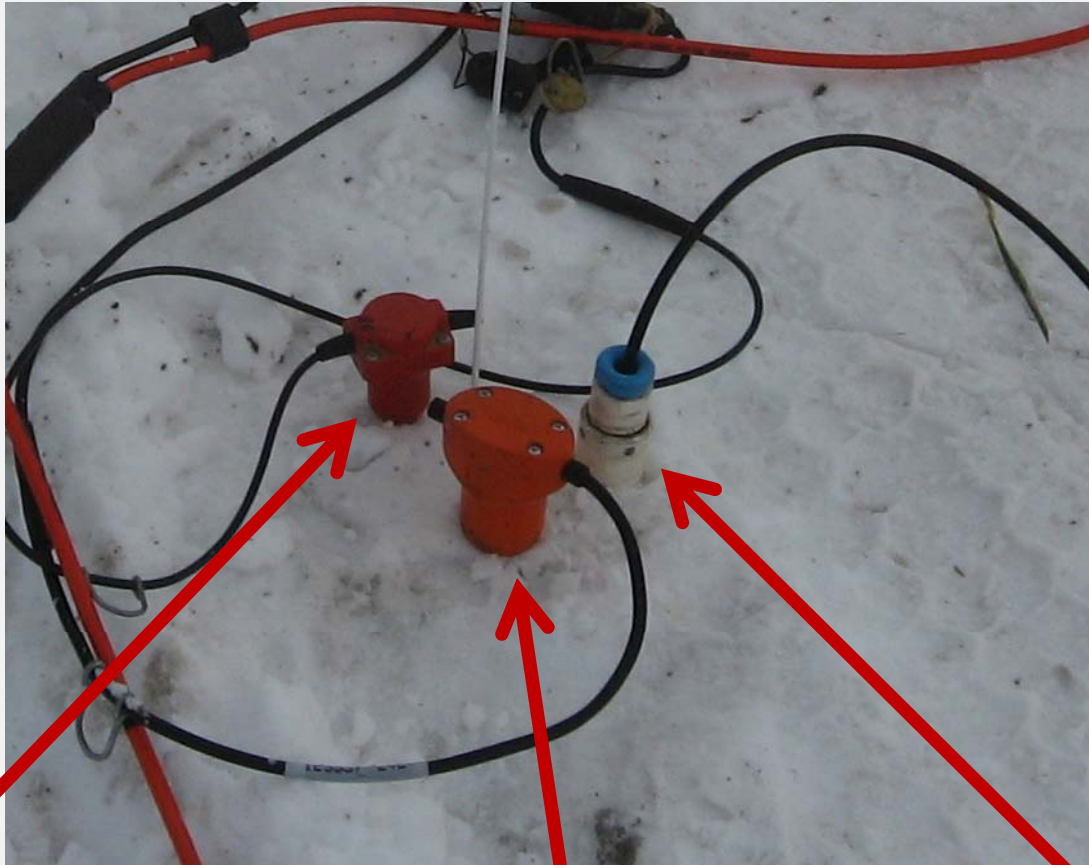
# Stacked section with time variant filter applied



# Conclusions on the source comparison

- Both sources provide data to better than 2 seconds in this area
- Both sources provide good data for the shallow events
- The onSEIS is a lower frequency source than the EnviroVibe
- The cycle time of the two sources is about the same for 4 x 20 second sweeps and 16 impacts per shot point

# Priddis geophone comparison:



YO-Geospace GS-One

RTC4.5

Ion-Sensor SM-24

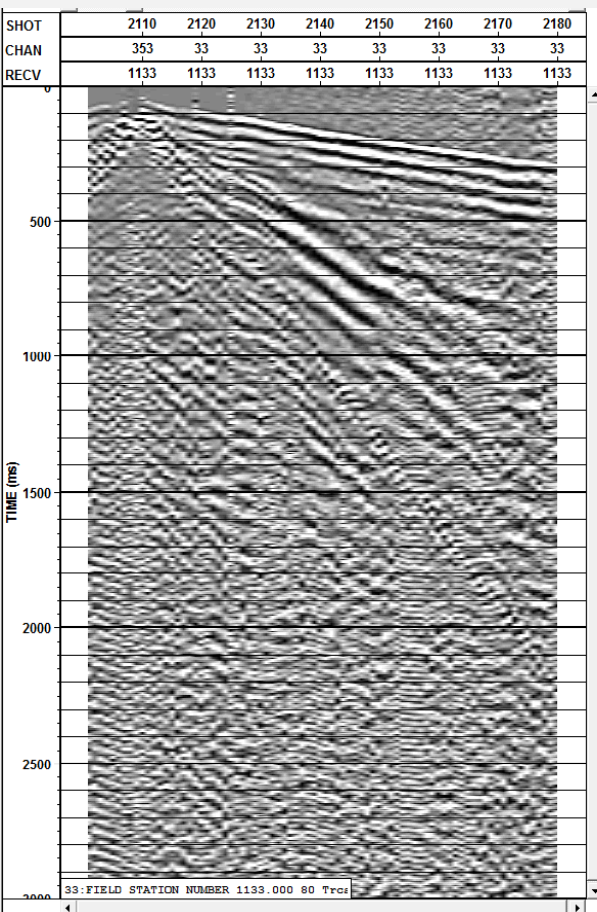


# The specifications of the geophones

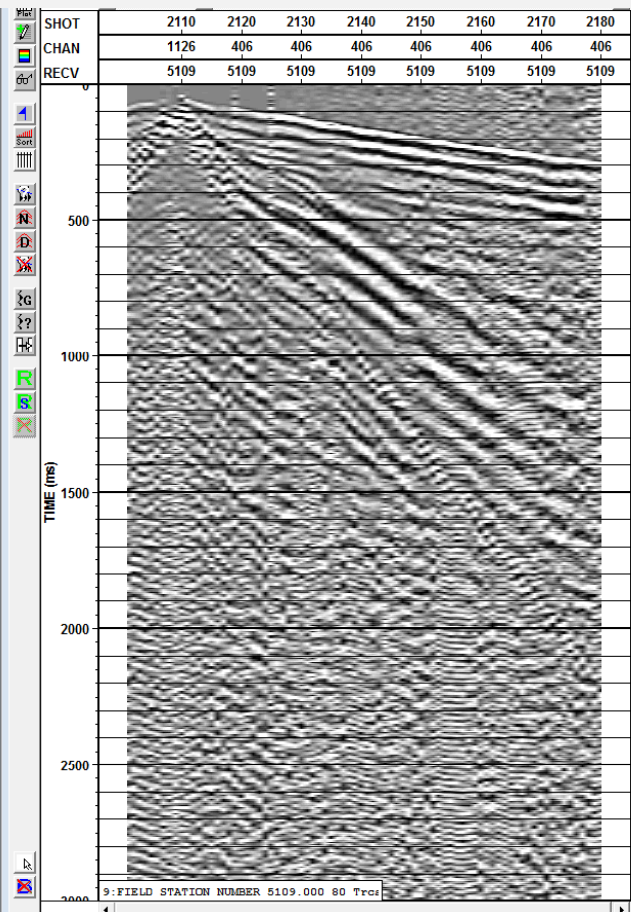
Geophone	Damping	Sensitivity V/m/s	Comparative output (db)
SM-24 (10Hz)	69%	21	0.00
RTC4.5 (4.5Hz)	70%	23.4	0.94
GS-One (10Hz)	70%	78.7	11.48

- The comparisons are made using receiver gathers at different locations
- The onSEIS data is used to make the comparisons

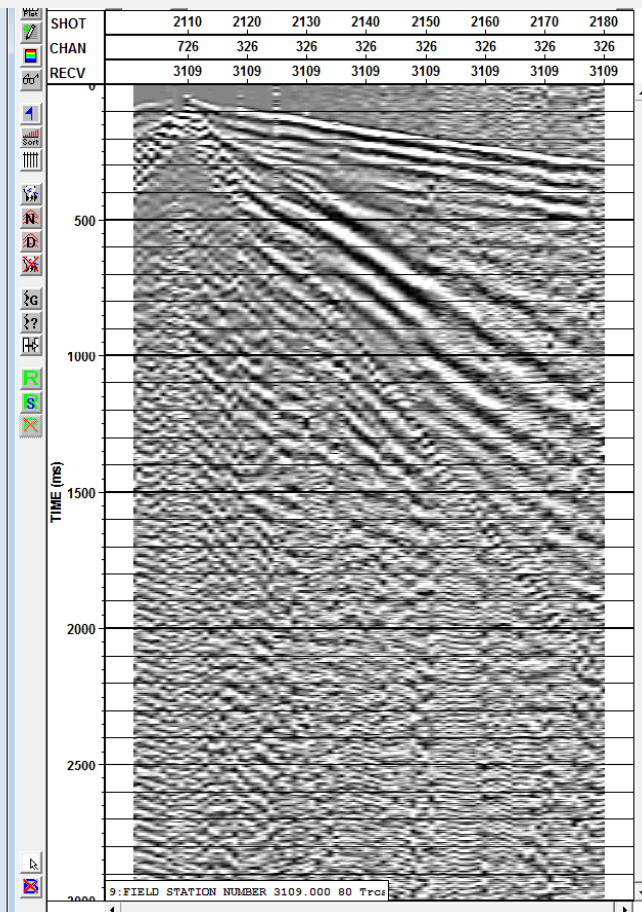
# Receiver gather at flag 109 for all onSEIS shots with offsets >30m



SM24

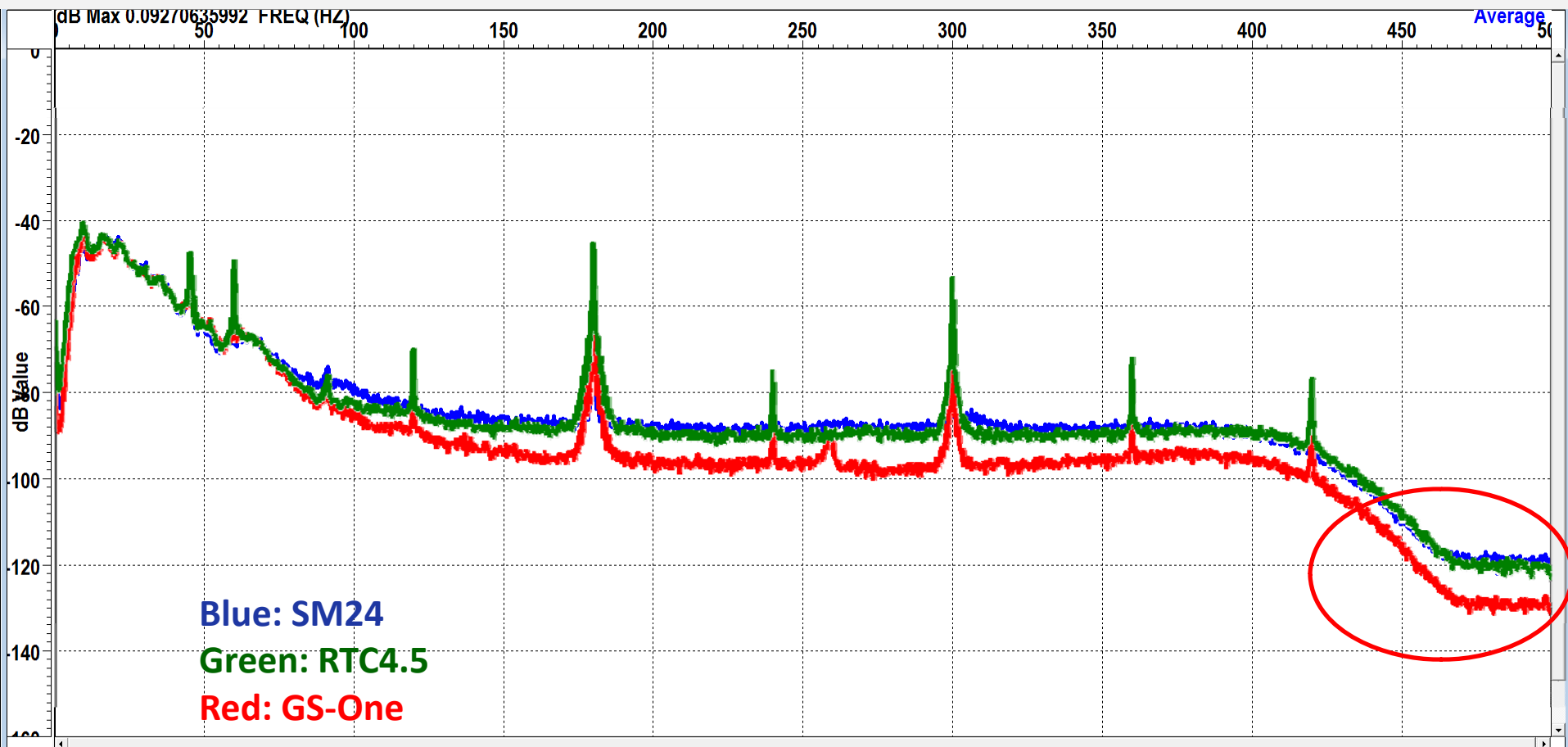


GS-One



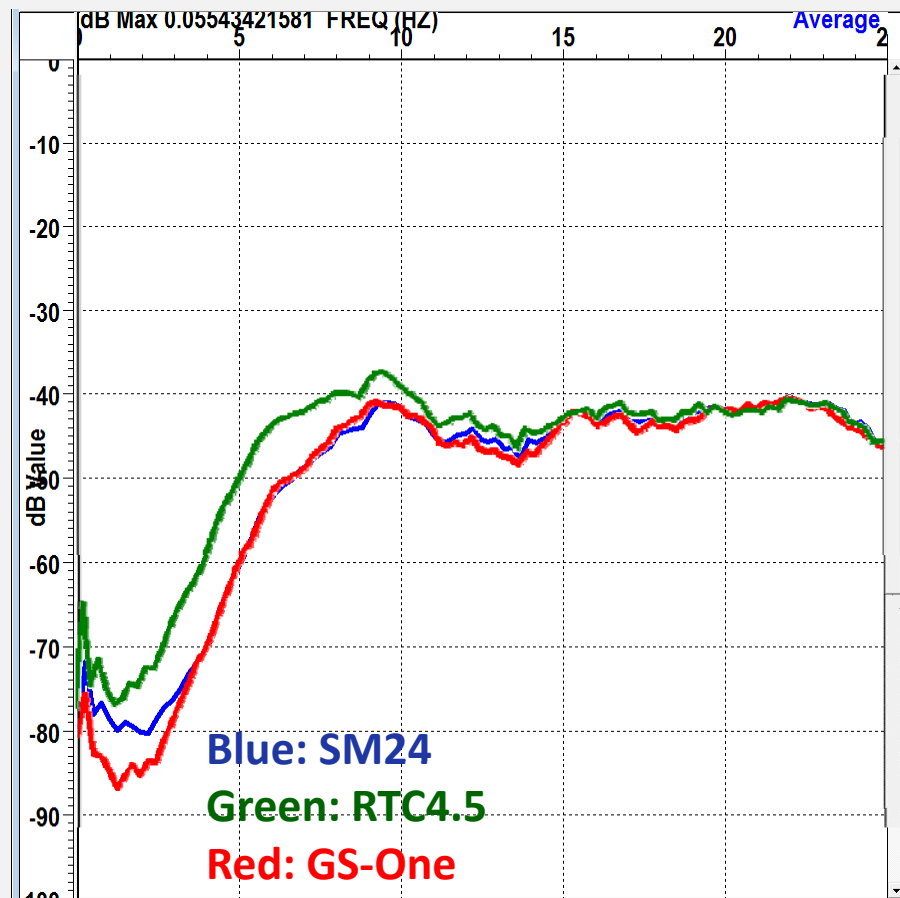
RTC4.5

# Spectra of the receivers from the gathers at flag 109

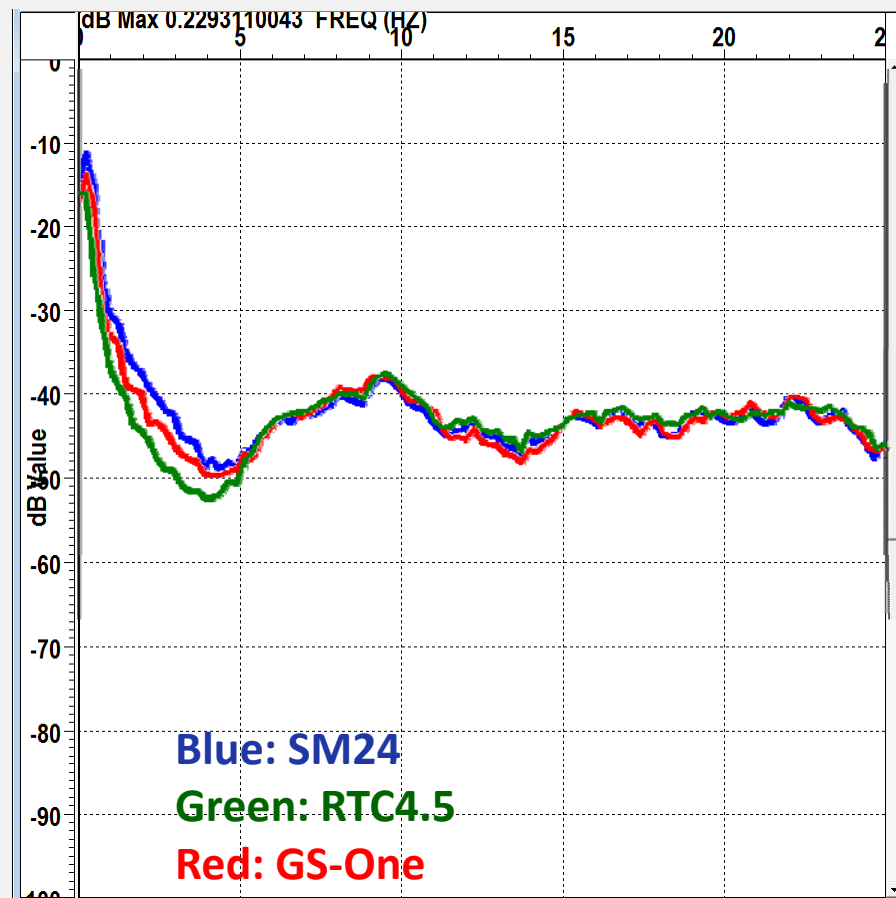




# Expanded spectra of the receivers from the gathers at flag 109

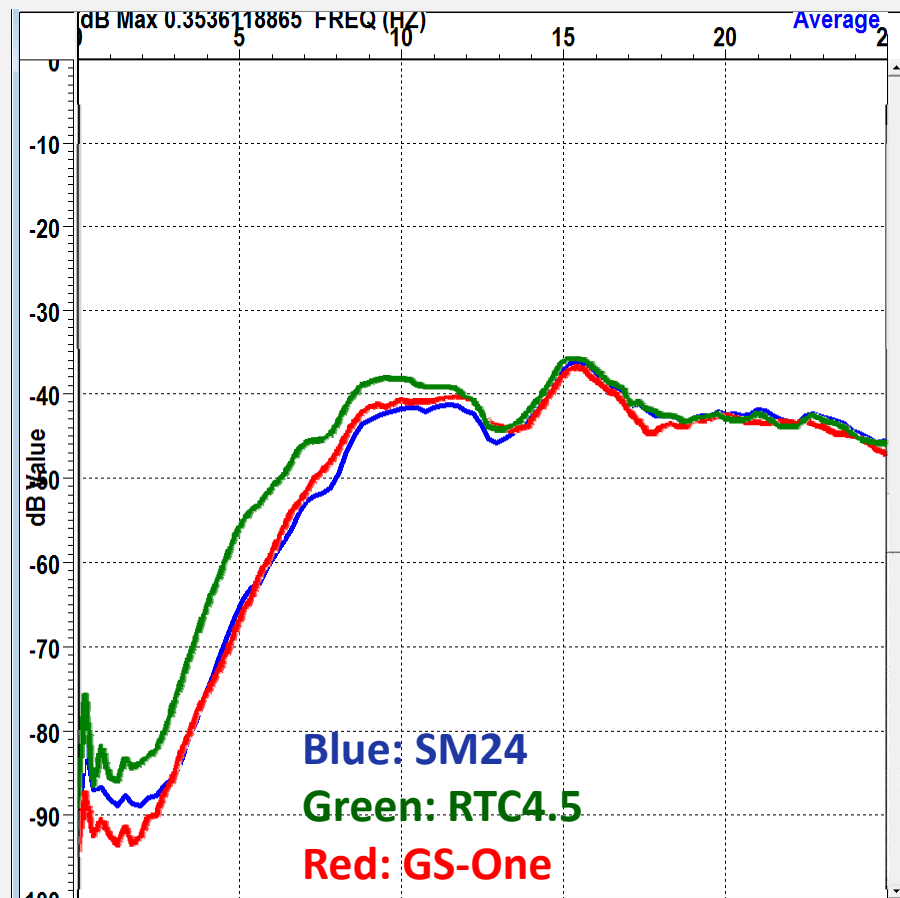


Raw

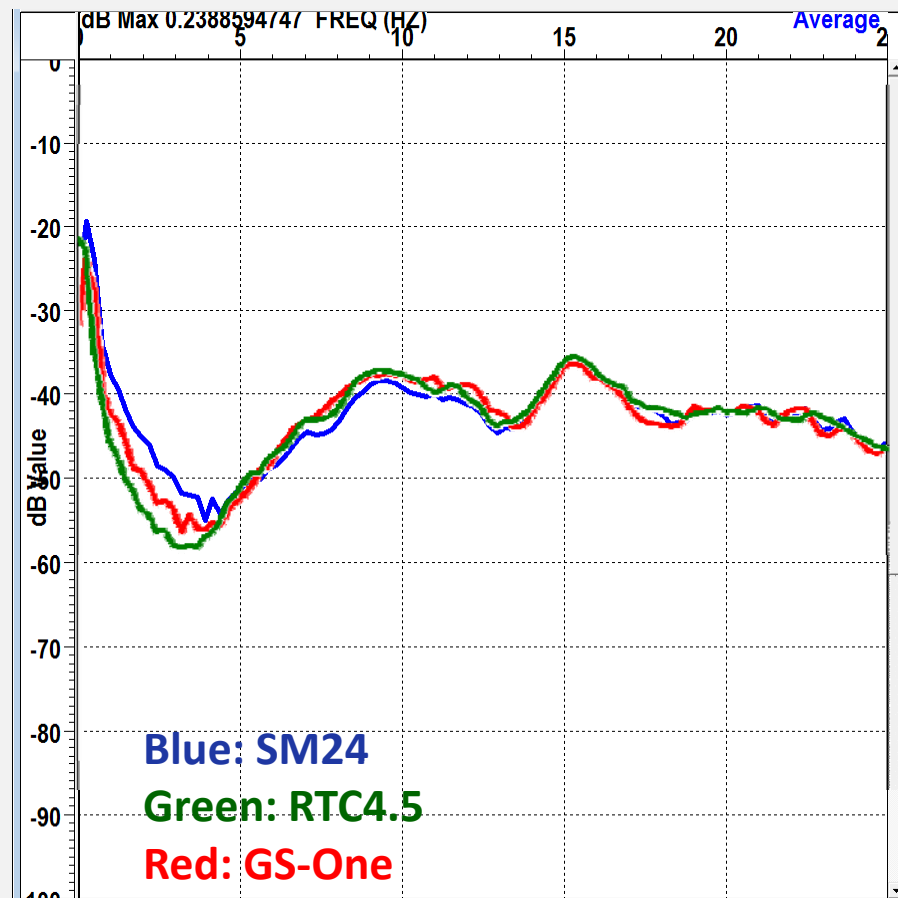


After low frequency recovery

# Spectra of the receivers from the gathers at flag 148



Raw



After low frequency recovery

# Conclusions on the geophone comparison

- After low frequency recovery, all geophones track very closely down to 5Hz, below which the RTC4.5 shows a better noise floor
- The three geophones show the expected difference in output levels measured at the noise floor
- The GS-One devolves into noise about 1Hz below the SM24, and the RTC4.5 about 1Hz below that
- For this type of survey, any of the geophones would be adequate, since there is very little data below 5Hz for the onSEIS, 10Hz for the EnviroVibe



# Hussar sensor comparison



Ion-Sensor SM-24-1k8

Ion-Sensor SM7 3C

Wei Hai Sunfull PS-4.5B

Vectorseis 3C

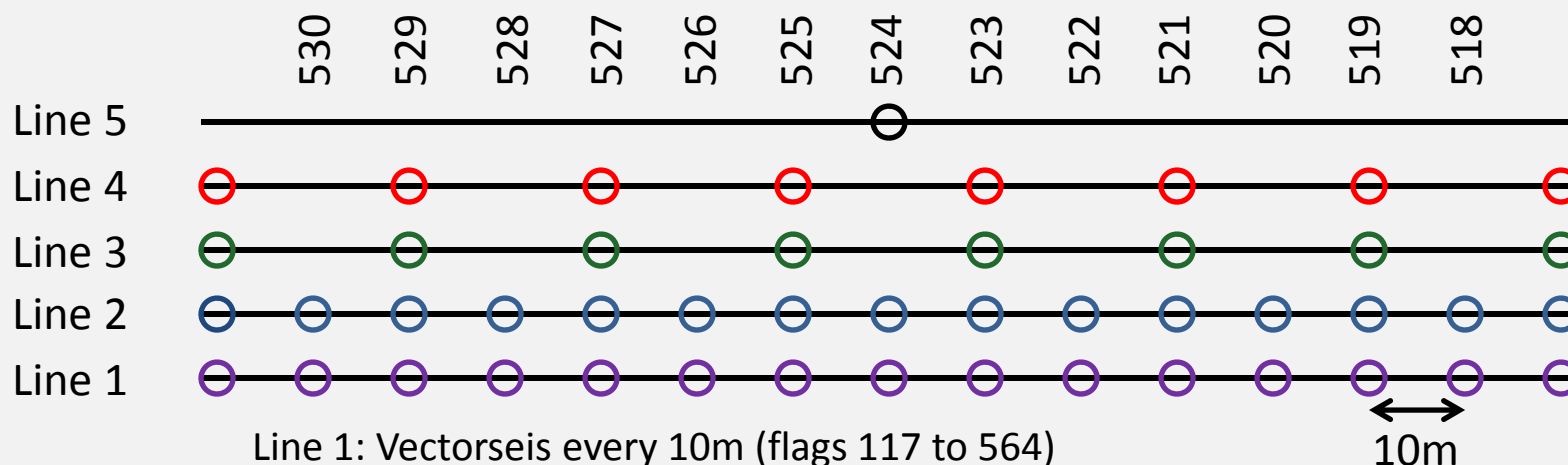
Nanometrics Trillium Compact



# The specifications of the geophones

Geophone	Sensitivity v/m/s (open circuit)	Sensitivity v/m/s (damped)	db wrt sm7
<b>SM7</b>	<b>28.8</b>	<b>21</b>	<b>0.00</b>
<b>PS-4.5B</b>	<b>28.8</b>	<b>28.8</b>	<b>2.74</b>
<b>SM24-1k8</b>	<b>82</b>	<b>75.2</b>	<b>11.08</b>
<b>Trillium</b>	<b>750</b>	<b>750</b>	<b>31.06</b>

## The spread layout



Line 1: Vectorseis every 10m (flags 117 to 564)

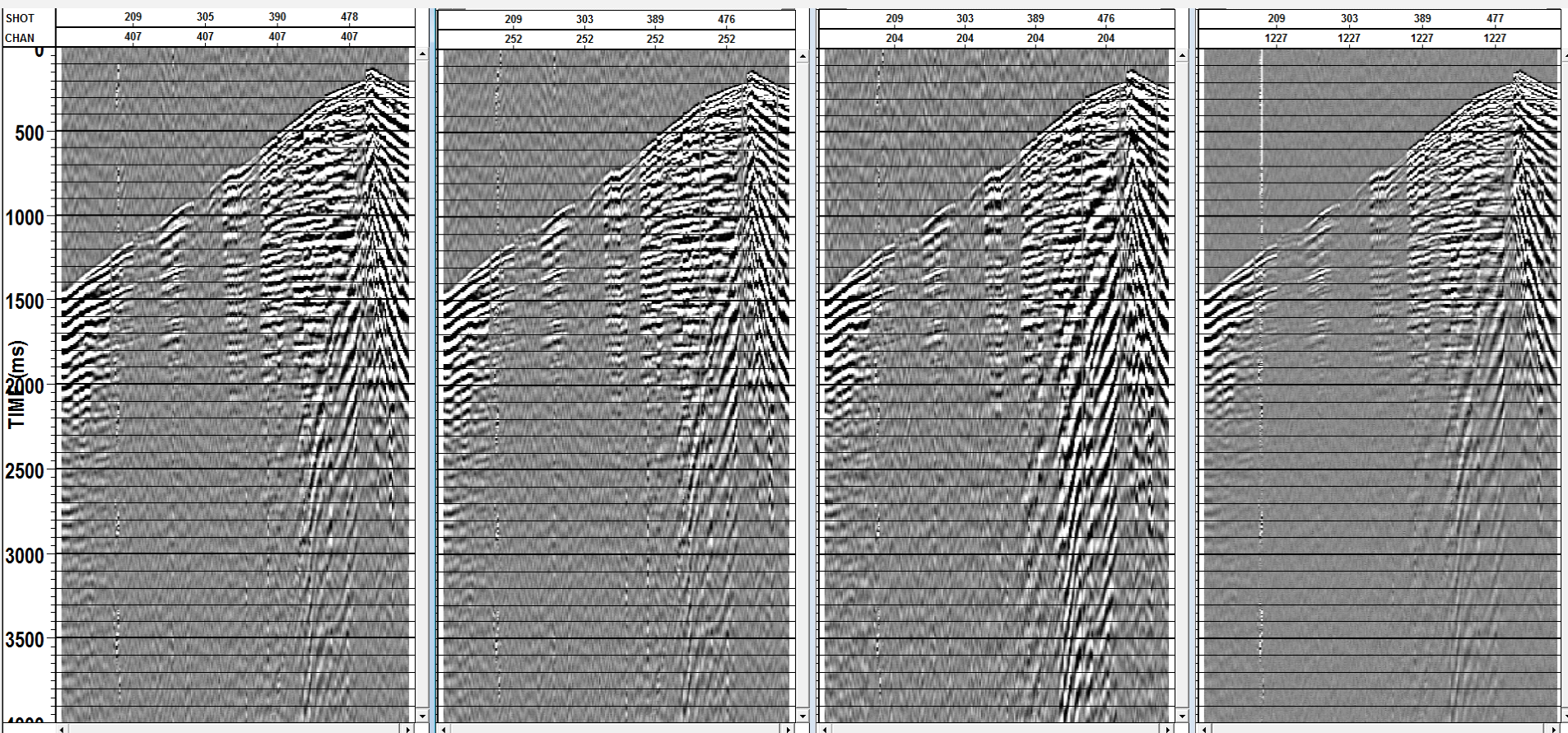
Line 2: Sensor SM7 3C every 10m (flags 117 to 564)

Line 3: PS-4.5B 1C every 20m (flags 117 to 563)

Line 4: Sensor SM124-1k8 1C every 20m (flag 469 to 563)

Line 5: Nanometrics Trillium Compact every 200m (spaced along line)

# Receiver gathers at flag 523 for dynamite shots with offset >140m



SM7

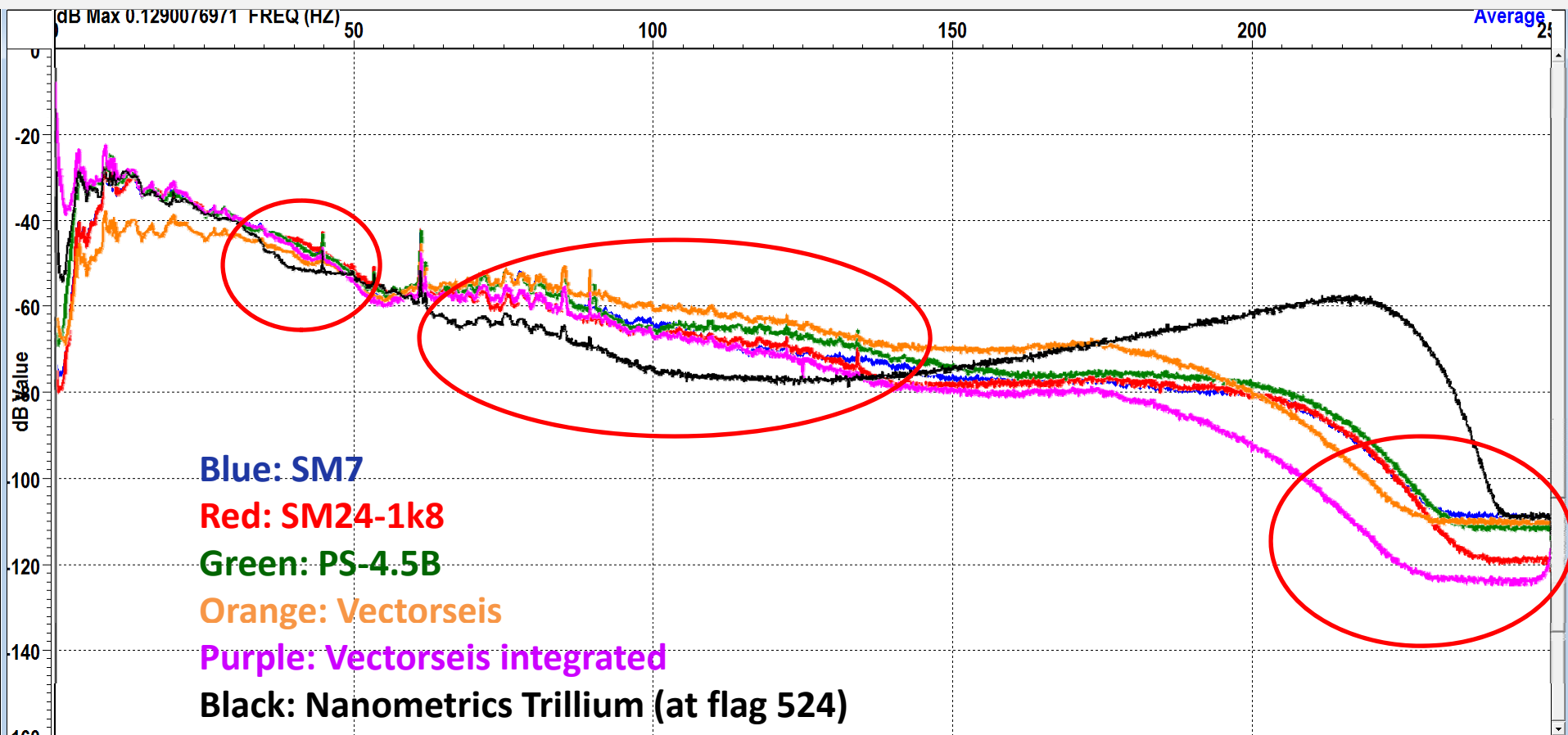
SM24-1k8

PS-4.5B

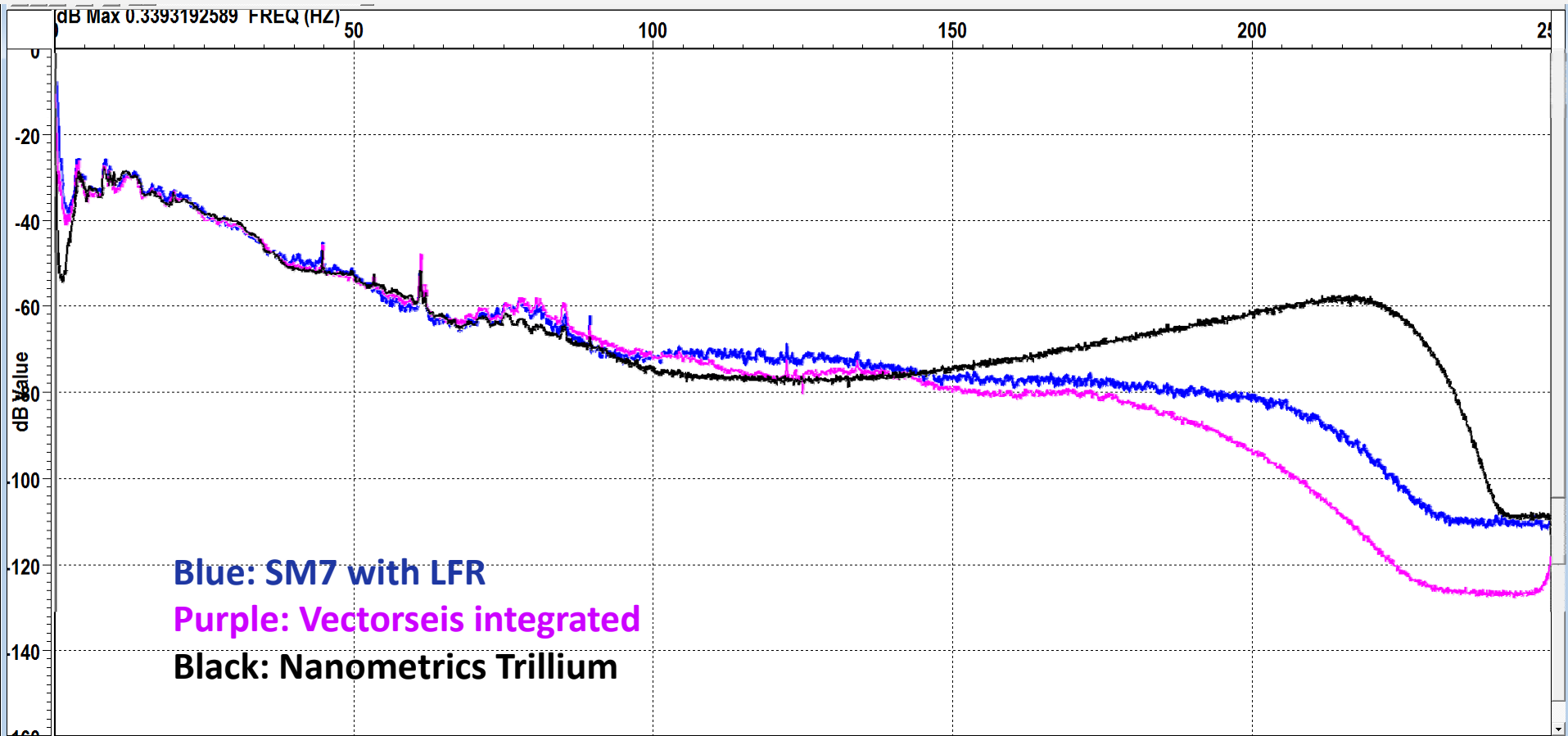
Vectorseis



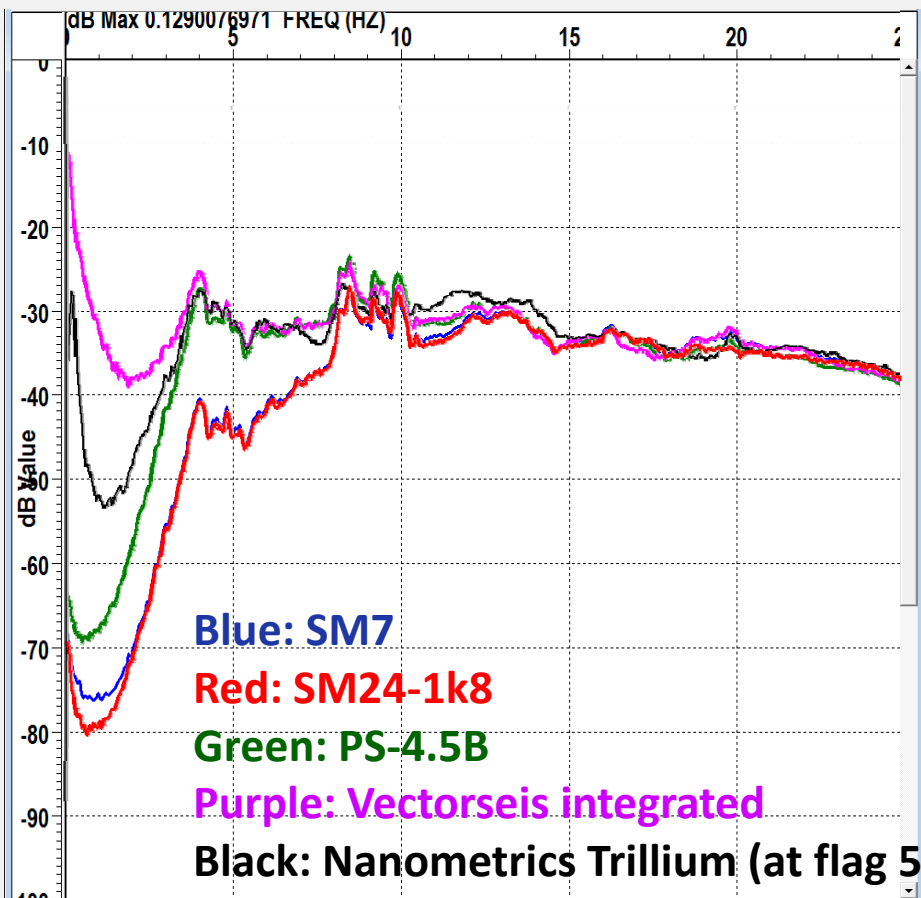
# Receiver gathers at flag 523 for dynamite shots with offset >140m



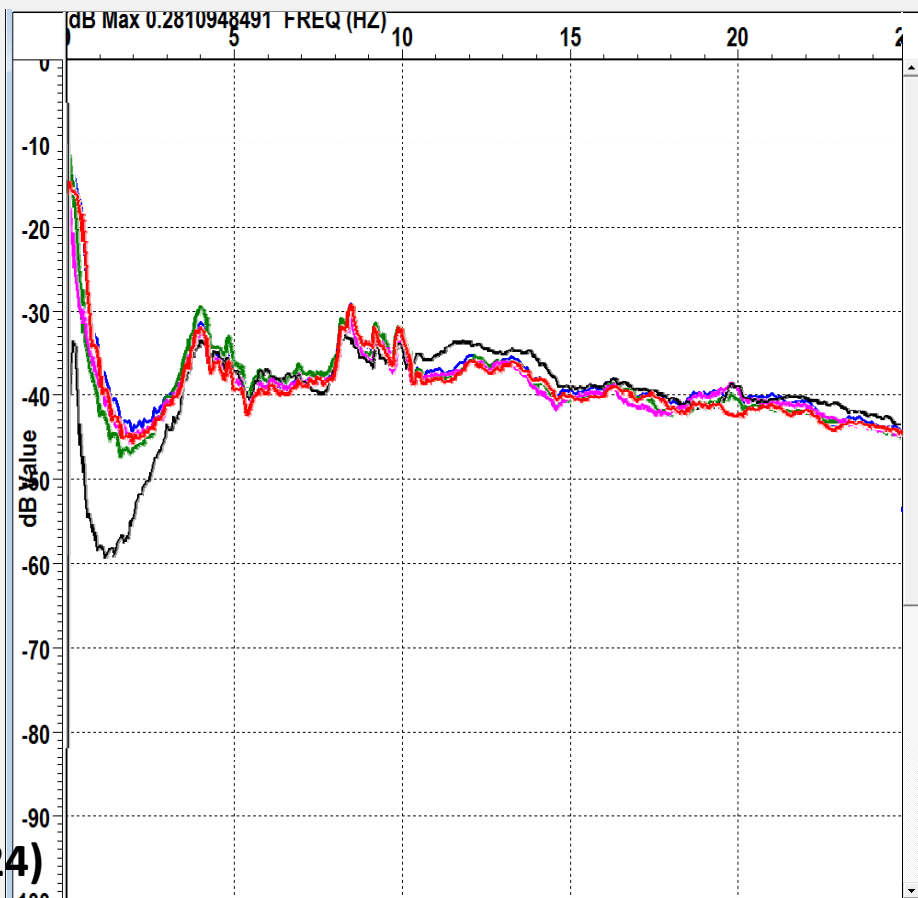
# Receiver gathers at flag 524 for dynamite shots with offset >140m



# Expanded spectra for receiver gathers at flag 523 for dynamite



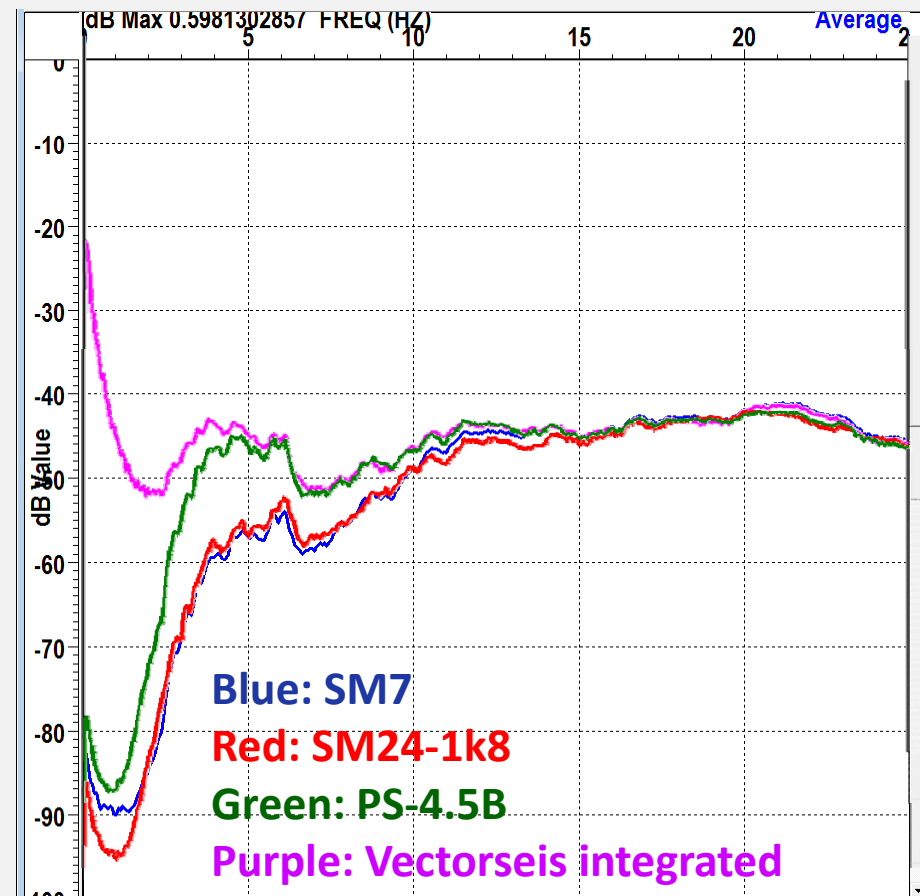
Raw



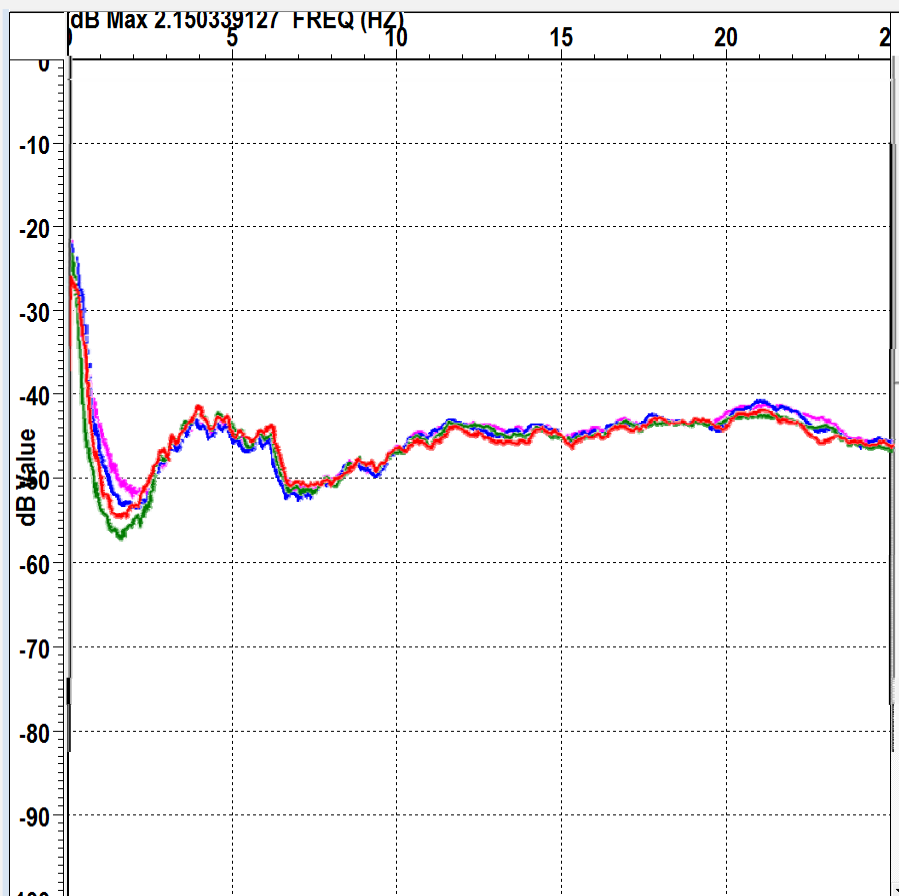
After low frequency recovery



# Expanded spectra for receiver gathers at flag 469 for dynamite

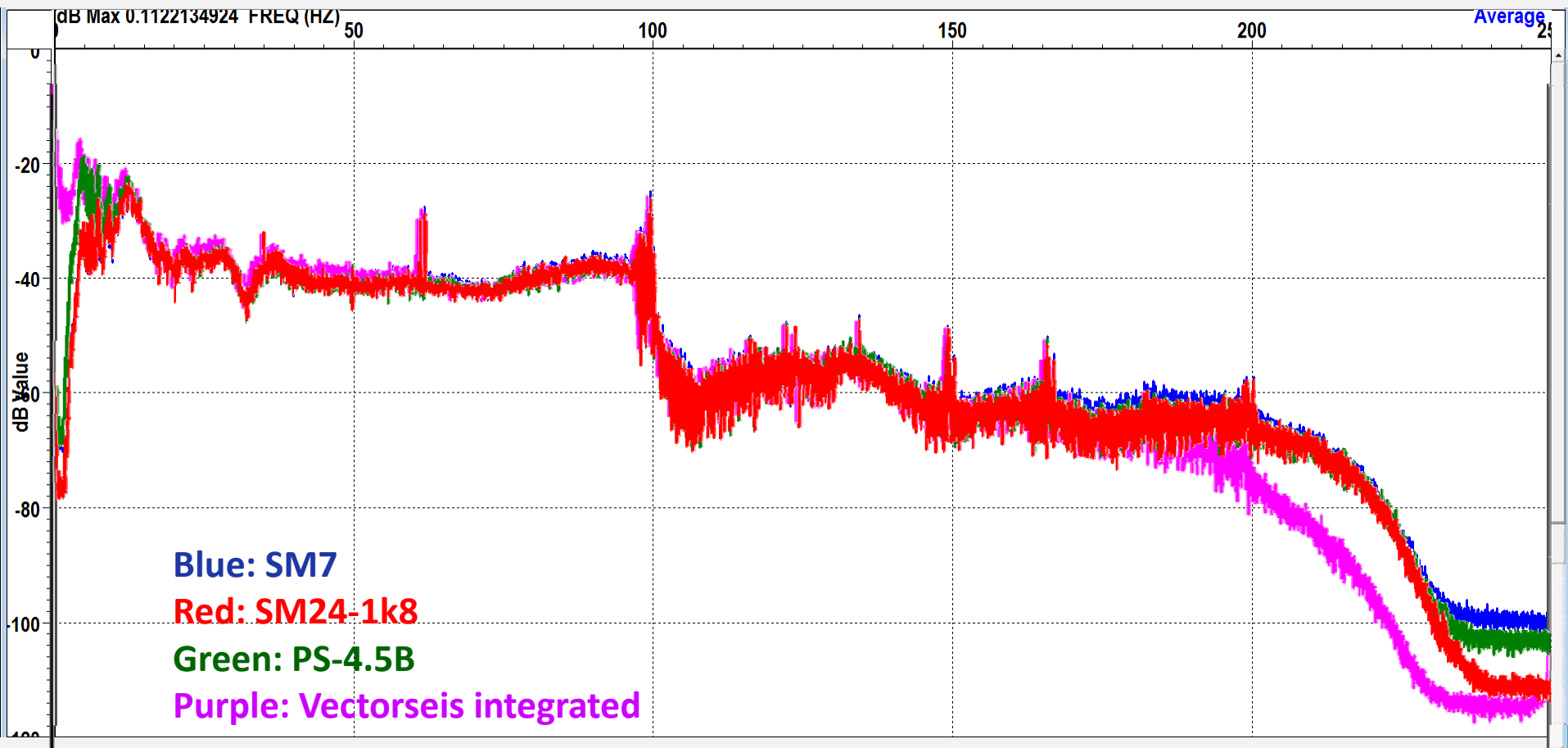


Raw



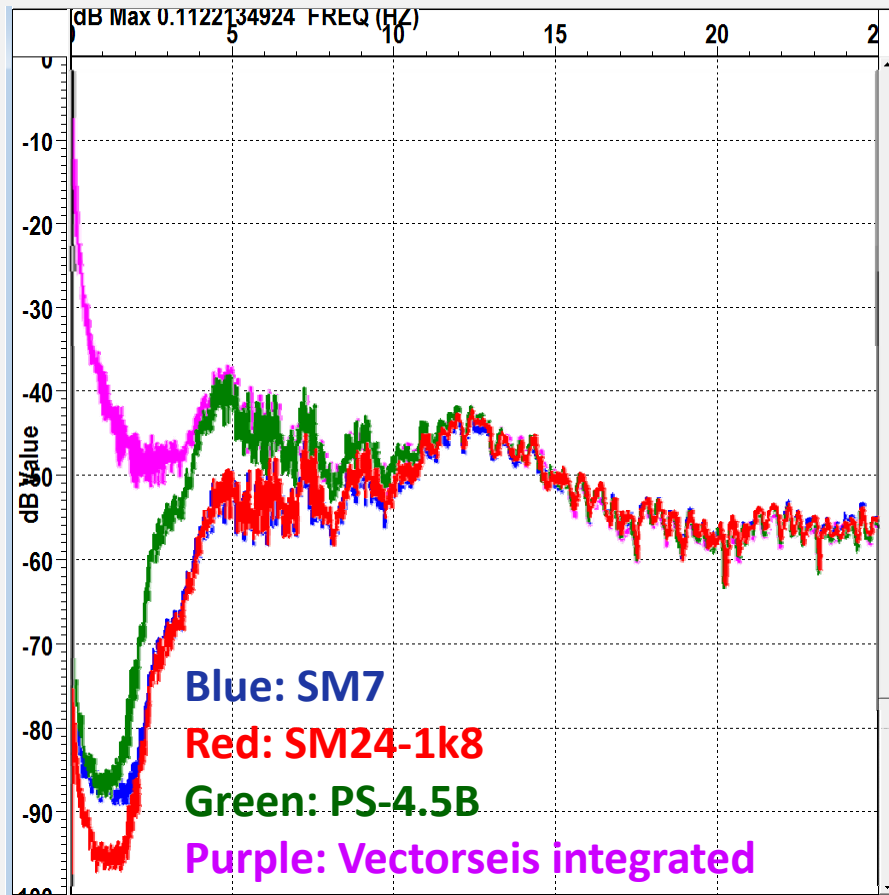
After low frequency recovery

# Uncorrelated stacked sweeps for Inova 364 low dwell at VP 449

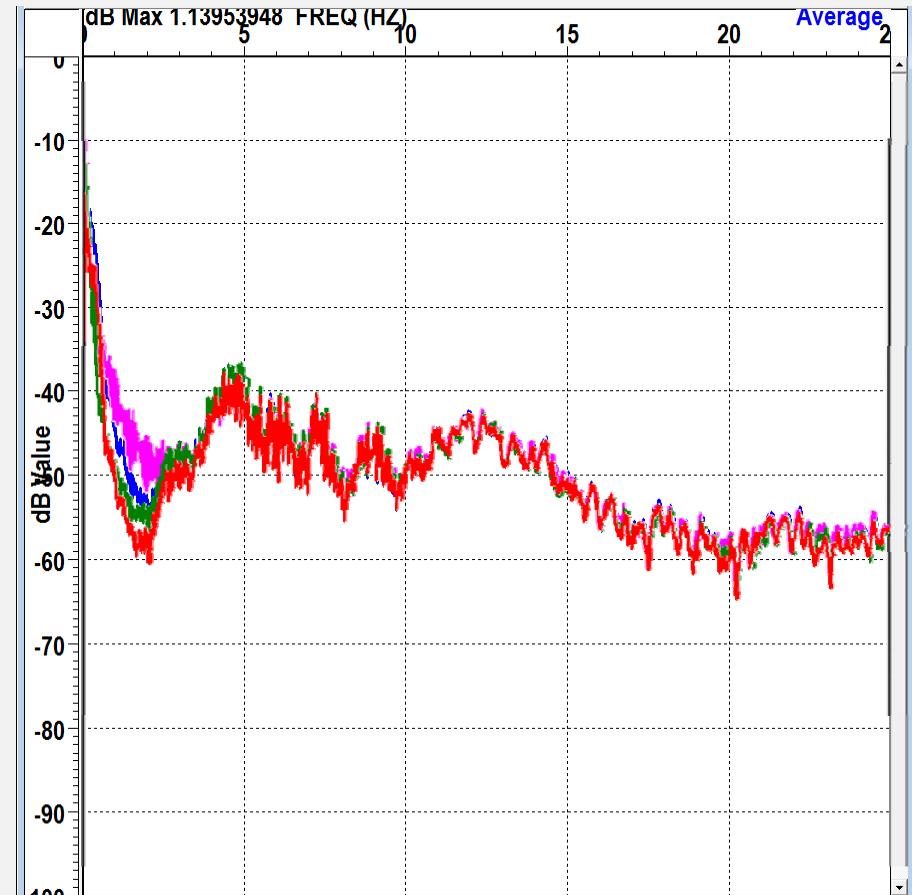




# Uncorrelated stacked sweeps for Inova 364 low dwell at VP 449



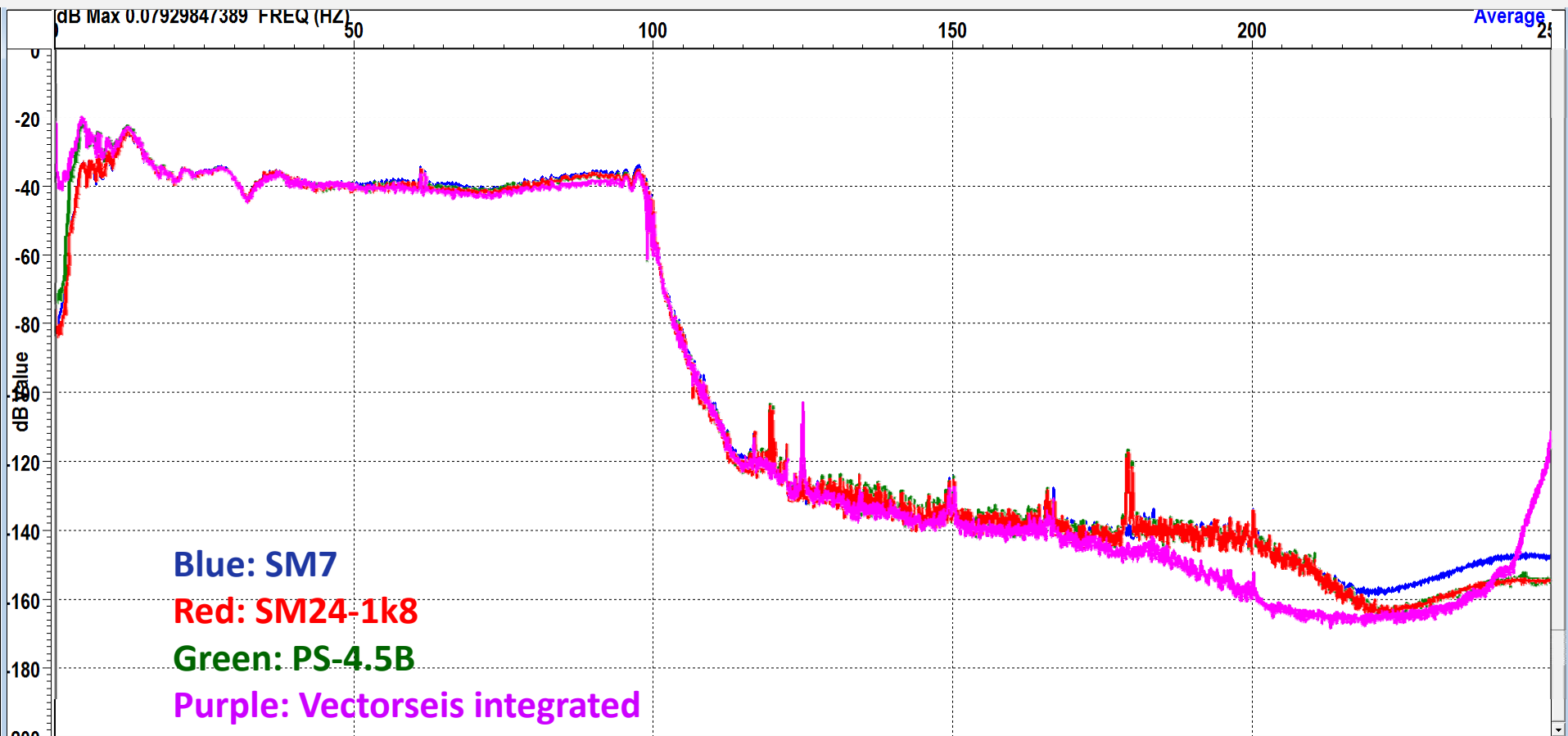
Raw



After low frequency recovery

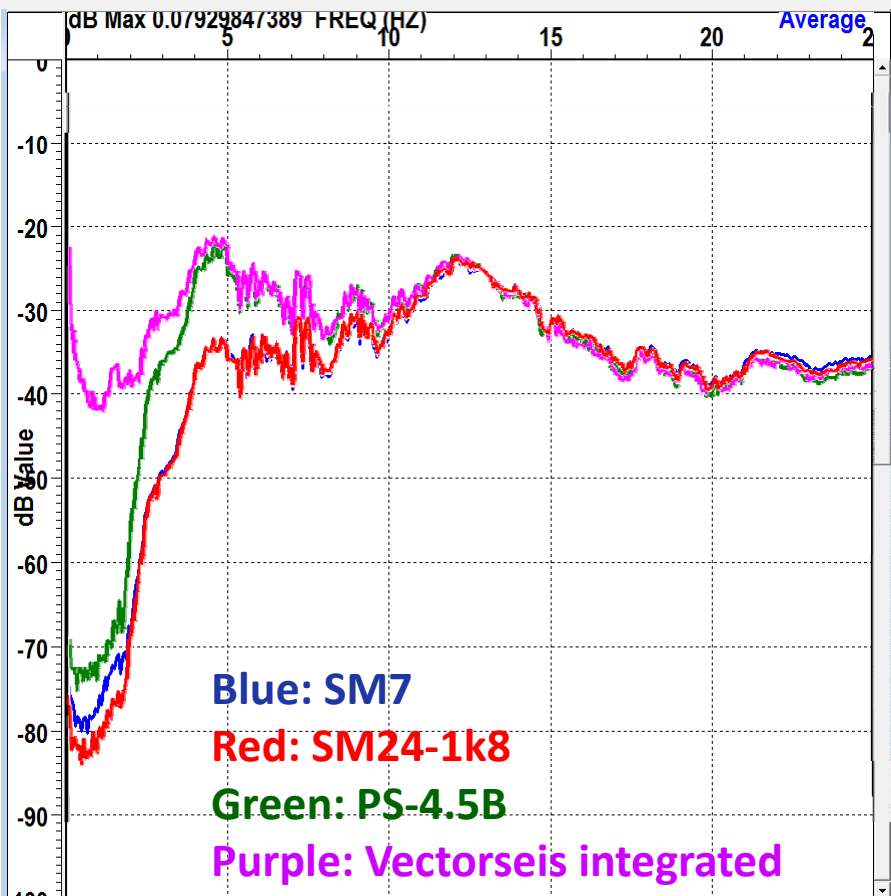
From the sensors at the odd flags between 469 and 563

# Correlated gather for Inova 364 low dwell at VP 449

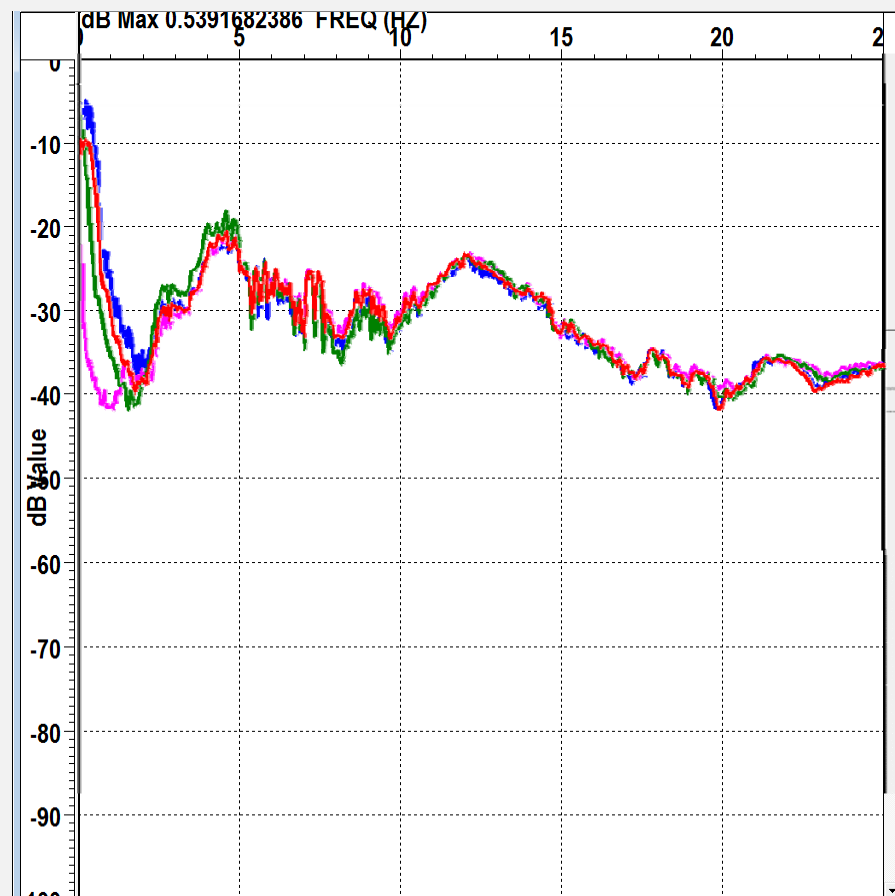




# Correlated gather for Inova 364 low dwell at VP 449



Raw



After low frequency recovery

From the sensors at the odd flags between 469 and 563

# Conclusions on the geophone comparison

- All four sensors provide good data down to about 3Hz
- The low frequency recovery is a valid method of improving the bandwidth for all the geophones
- The determination of noise vs signal below 5Hz needs to be better defined
- There is a lot more work required to investigate the very low frequency response of these sensors (1 – 5 Hz)

# Acknowledgments

For the Priddis survey:

- Geokinetics for the loan of the onSEIS seismic source and their assistance in the field
- OYO-Geospace for the loan of the GS-One 10Hz geophones

For the Hussar survey:

- Ion-Sensor for the donation of the SM24-1k8 geophones to CREWES
- INOVA for making the INOVA 364 vibrator available for this survey
- Geokinetics for the field work and co-ordination of the project
- Husky for making it possible
- Nanometrics for the loan of the Trillium Compact seismometers as a calibrated sensor for the comparison work

CREWES sponsors and NSERC