

Full wavefield migration in the frequency-wavenumber domain

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Department of Geoscience



- Motivation
- Theory
- Numerical examples
- Conclusion and future work



Motivation

Multiples can provide additional information for subsurface structures

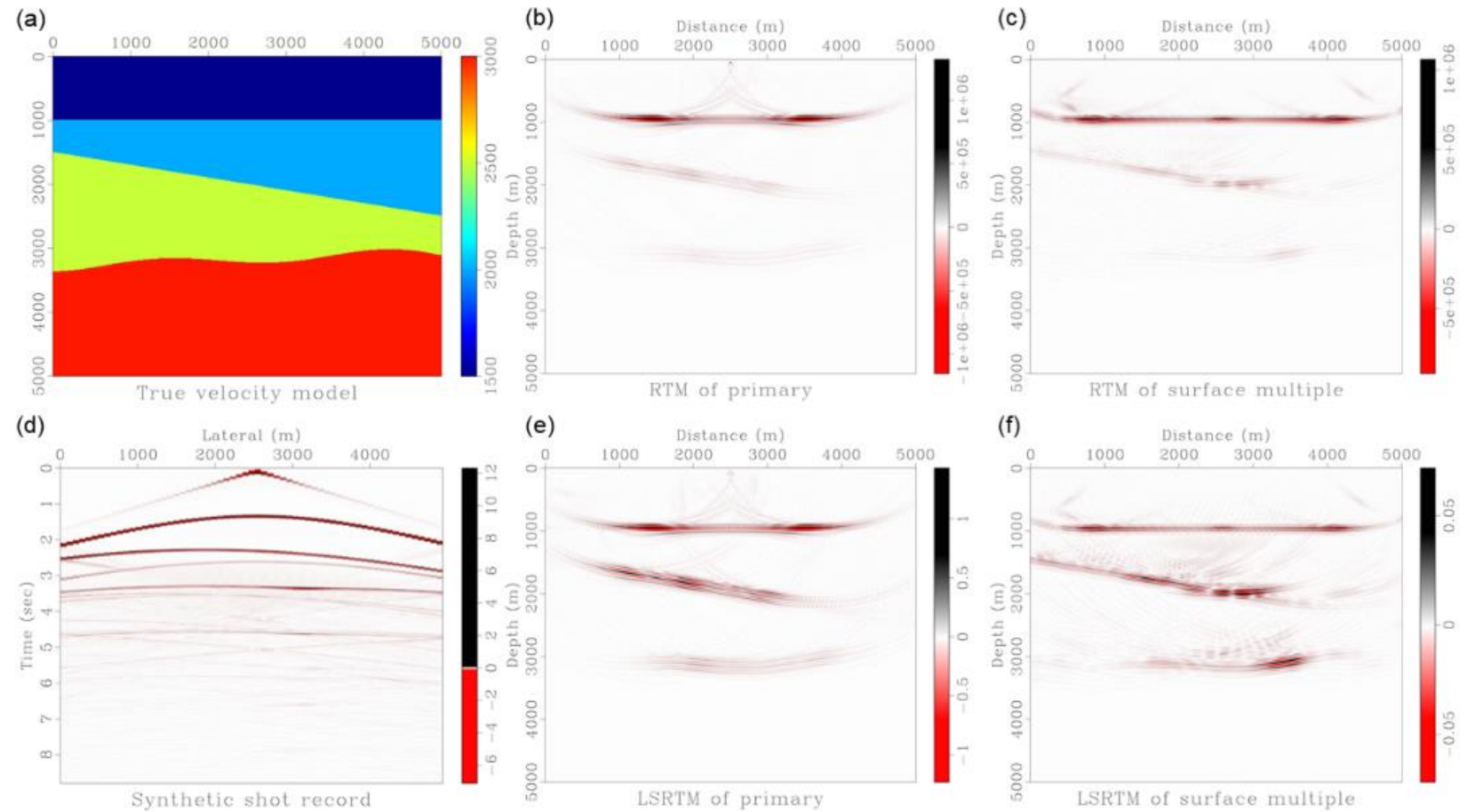


Figure from Huang and Trad (2019)



Multiples can provide additional information for subsurface structures

FWM (Berkhout, 2014; Verschuur and Berkhout, 2015; Davydenko and Verschuur, 2016):

- Inversion-based method
- Frequency-space domain
- Cross-correlation imaging condition



Multiples can provide additional information for subsurface structures

FWM (Berkhout, 2014; Verschuur and Berkhout, 2015; Davydenko and Verschuur, 2016):

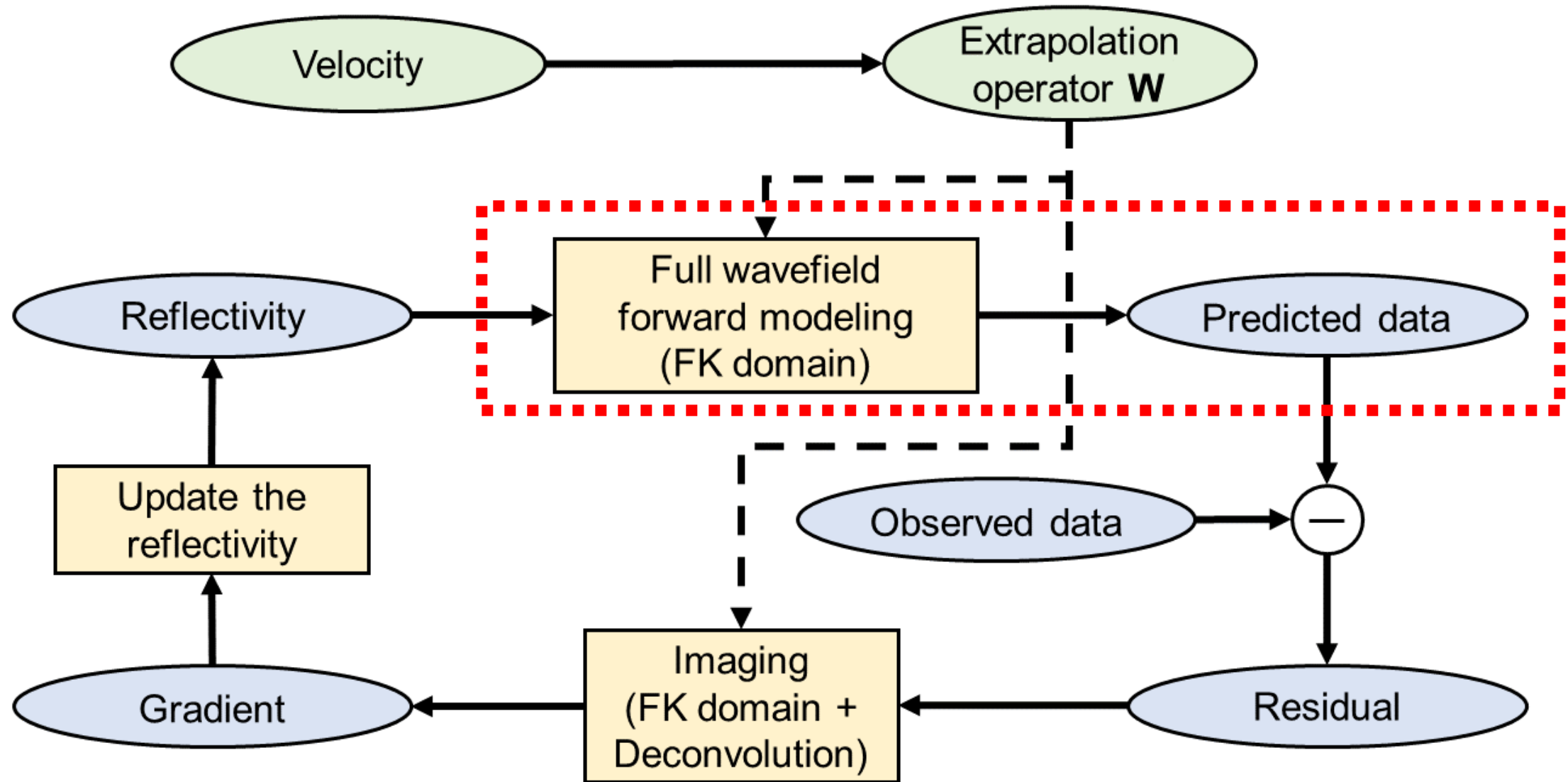
- Inversion-based method
- Frequency-space domain
- Cross-correlation imaging condition

In this project:

- Inversion-based
- Frequency-wavenumber domain
- Deconvolution imaging condition

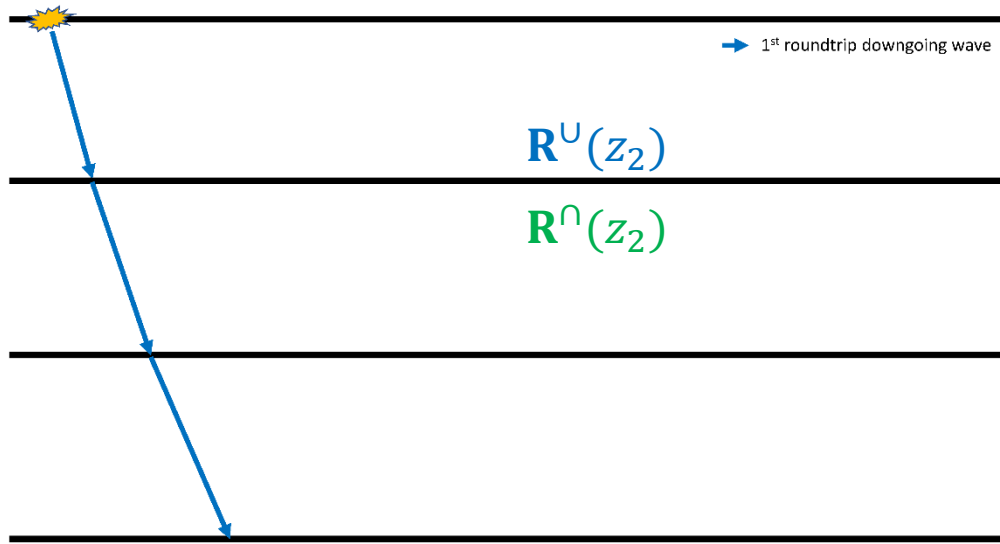


Full-wavefield migration (FWM) workflow





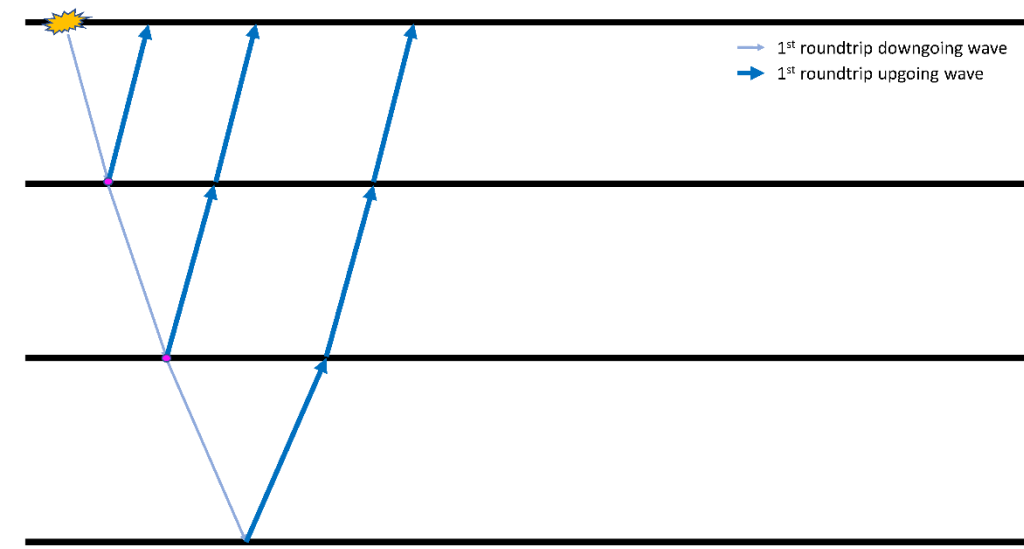
First roundtrip downgoing wavefield



$$\vec{P}^+(z_m) = \sum_{n < m} \mathbf{W}(z_m, z_n) [\vec{S}^+(z_n) + \delta \vec{S}(z_n)] \quad (1)$$

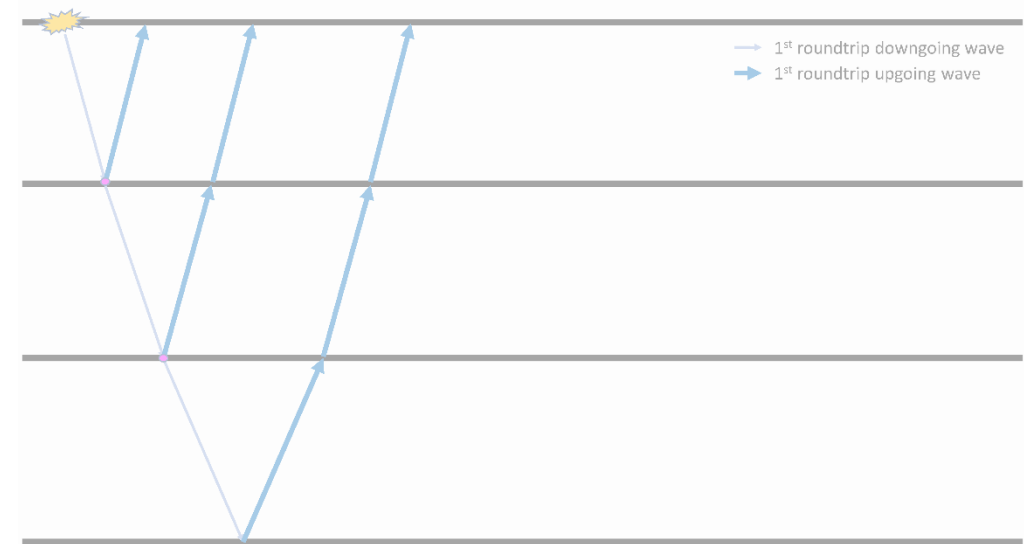
$$\delta \vec{S}(z_m) = \mathbf{R}^U(z_m) \vec{P}^+(z_m) + \mathbf{R}^N(z_m) \vec{P}^-(z_m) \quad (2)$$

First roundtrip upgoing wavefield



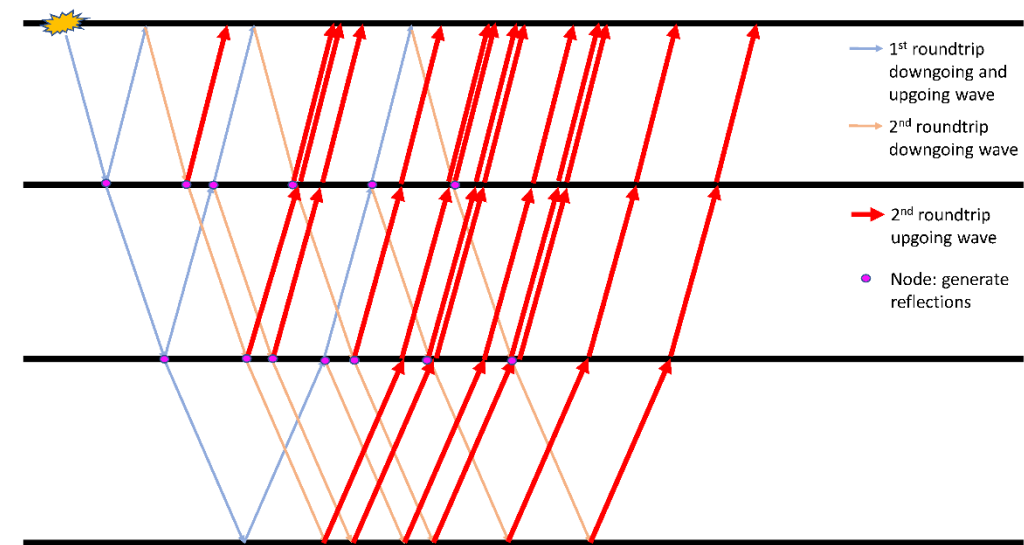
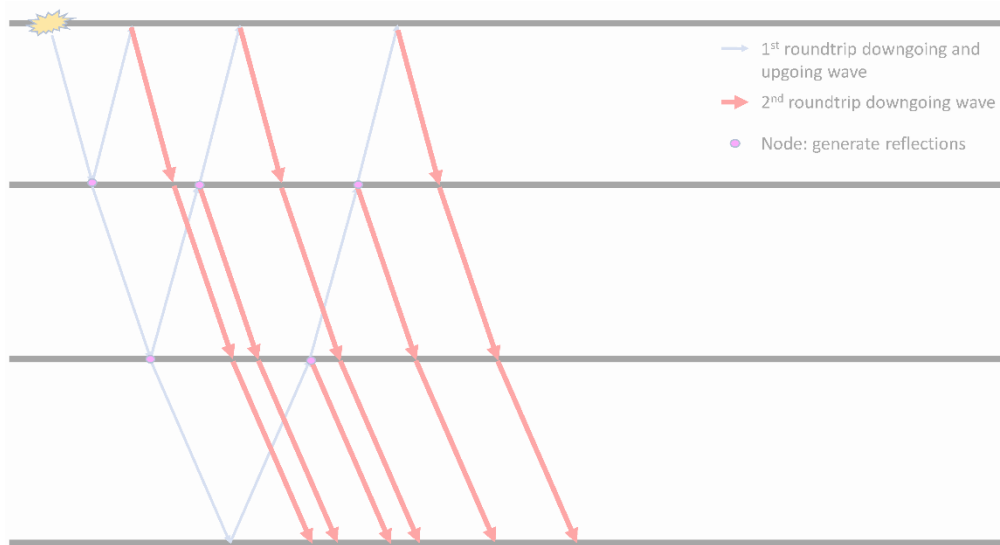
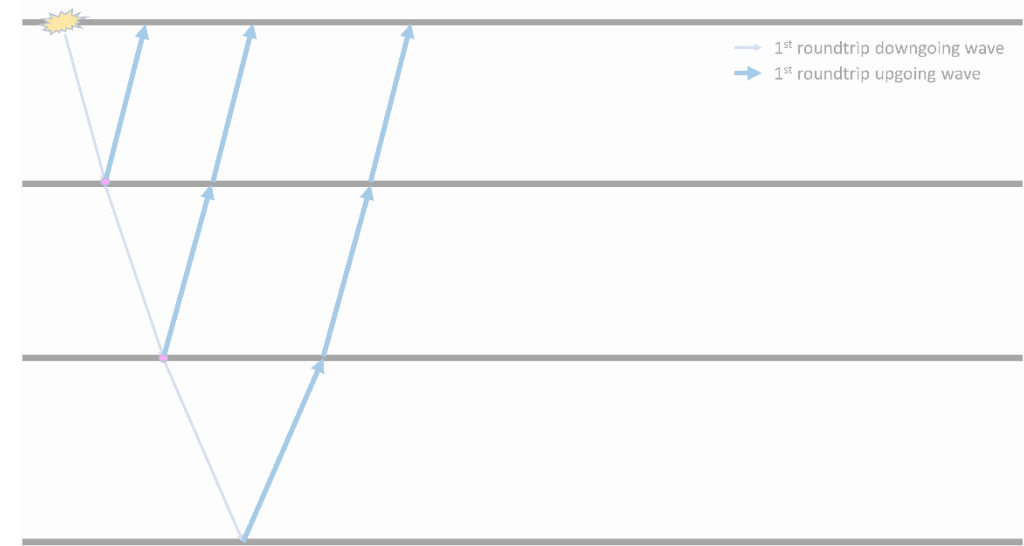
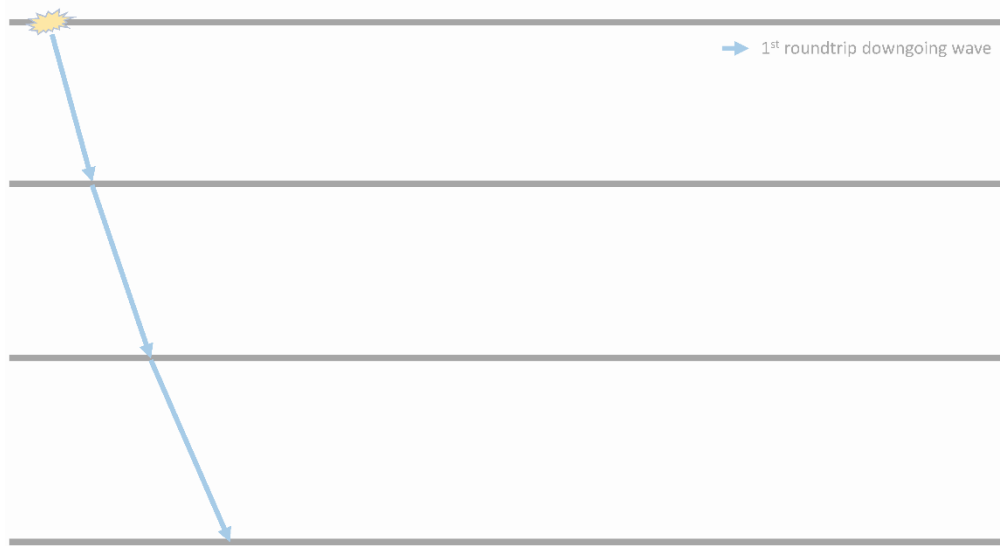
$$\vec{P}^-(z_m) = \sum_{n>m} \mathbf{W}(z_m, z_n) \delta \vec{S}(z_n) \quad (3)$$

$$\delta \vec{S} = \mathbf{R}^U(z_m) \vec{P}^+(z_m) + \mathbf{R}^\cap(z_m) \vec{P}^-(z_m) \quad (2)$$

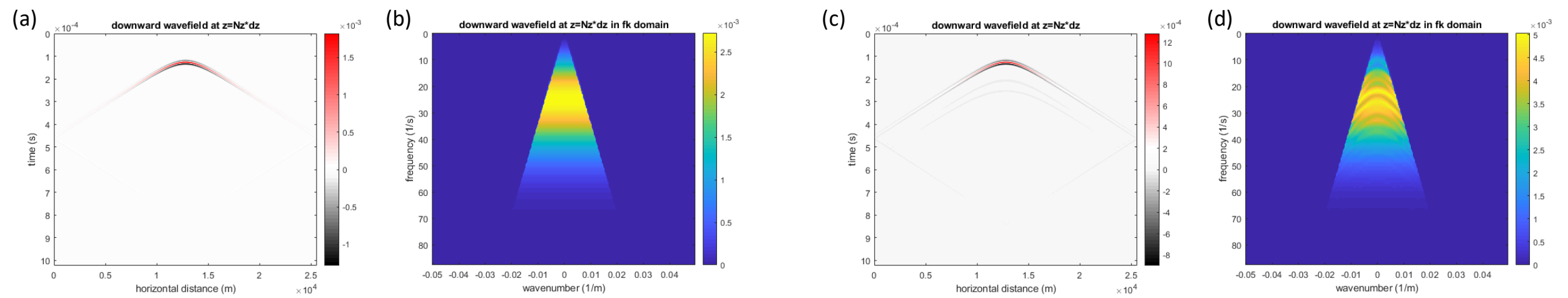




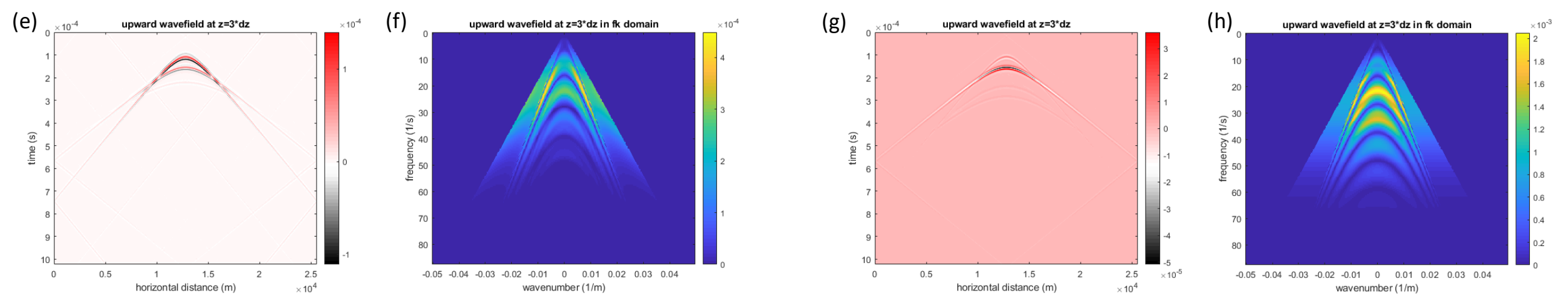
Second roundtrip upgoing wavefield



Downgoing wavefield (at $z=Nz*dz$) after the first and second iteration:

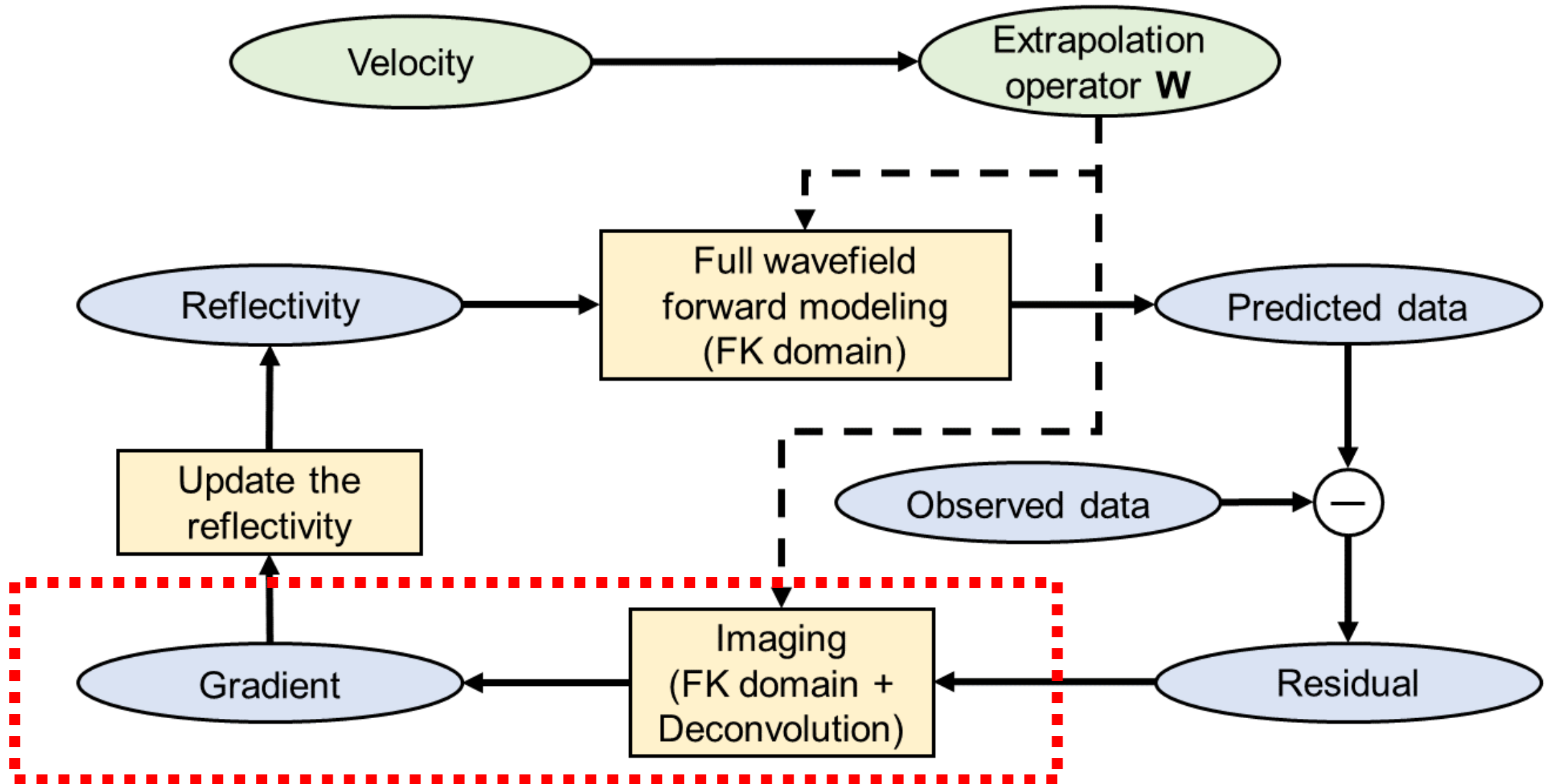


Upgoing wavefield (at $z=3*dz$) after the first and second iteration:





Full-wavefield migration (FWM) workflow





Imaging in full-wavefield migration (FWM)

- Objective function for FWM (Davydenko and Verschuur, 2016) but in the F-K domain:

$$J = ||\Delta \mathbf{P}||_2^2 + f(\mathbf{R}) = ||\mathbf{P}_{obs} - \mathbf{P}_{mod}||_2^2 + f(\mathbf{R}) \quad (4)$$

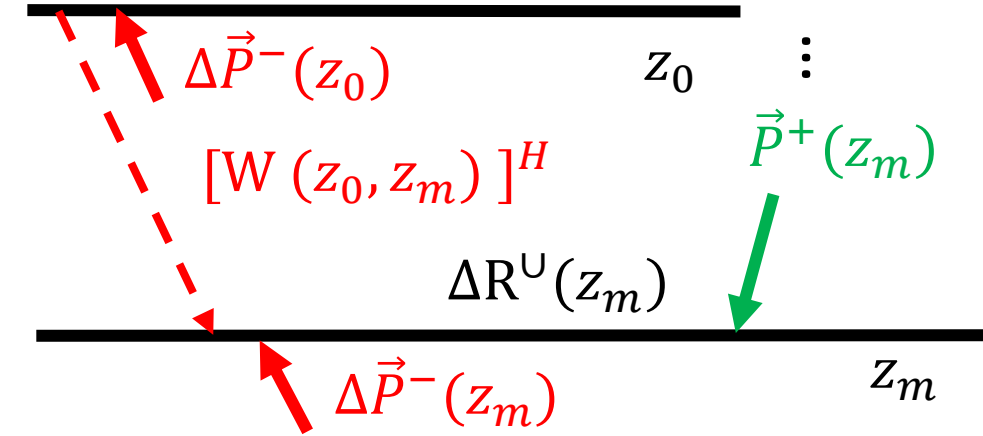


Fig 4. Reflectivity updates of both sides can be projected by cross-correlation between forward-modelled wavefield (green lines) and backward residuals (red lines).

- The gradient of objective function (Valenciano and Biondi, 2003)

$$\begin{aligned} \mathbf{C}^U(z_m) &= [\Delta \mathbf{P}^-(z_m)][\mathbf{P}^+(z_m)]^H / ([\mathbf{P}^+(z_m)][\mathbf{P}^+(z_m)]^H + \varepsilon^2) \\ \mathbf{C}^\cap(z_m) &= [\Delta \mathbf{P}^+(z_m)][\mathbf{P}^-(z_m)]^H / ([\mathbf{P}^-(z_m)][\mathbf{P}^-(z_m)]^H + \varepsilon^2) \end{aligned} \quad (5)$$

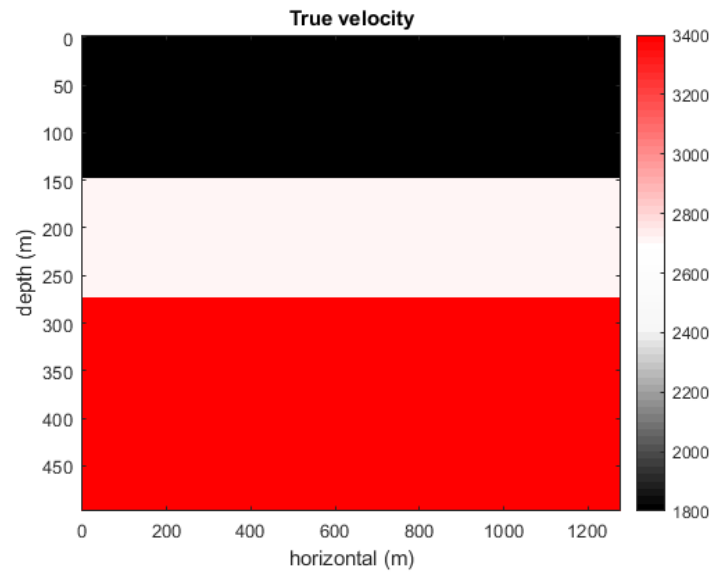
- Update reflectivity matrix

$$\begin{aligned} \Delta \mathbf{R}^U(z_m) &= \left(\sum_{k_x} \sum_{\omega} \mathbf{C}^U(z_m) \right) + f'(\mathbf{R}^U(z_m)) \\ \Delta \mathbf{R}^\cap(z_m) &= \left(\sum_{k_x} \sum_{\omega} \mathbf{C}^\cap(z_m) \right) + f'(\mathbf{R}^\cap(z_m)) \end{aligned} \quad (6)$$

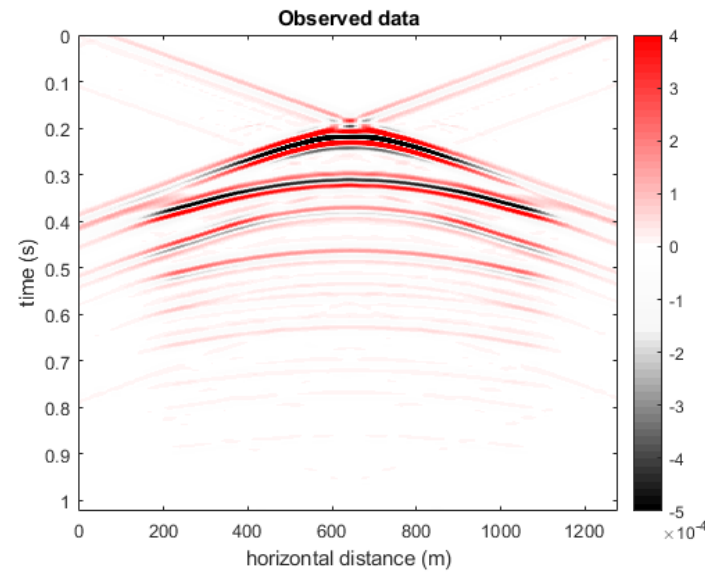


Example 1 – Horizontal-layered model

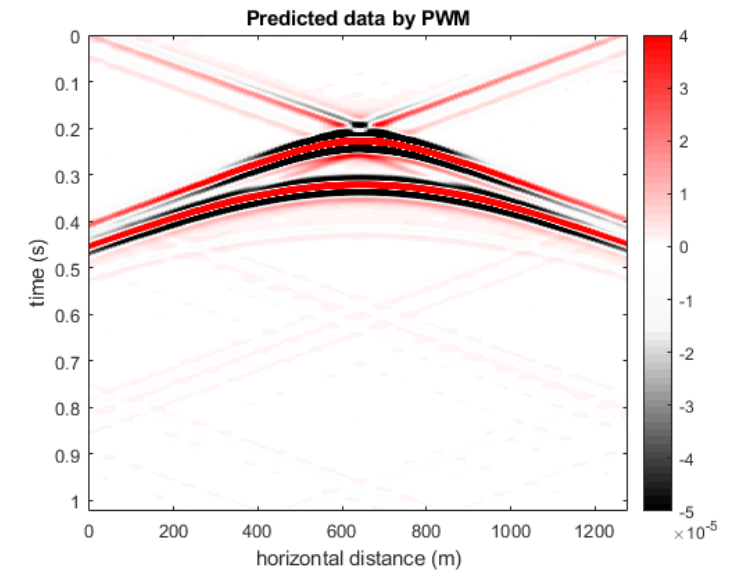
(a) True velocity model



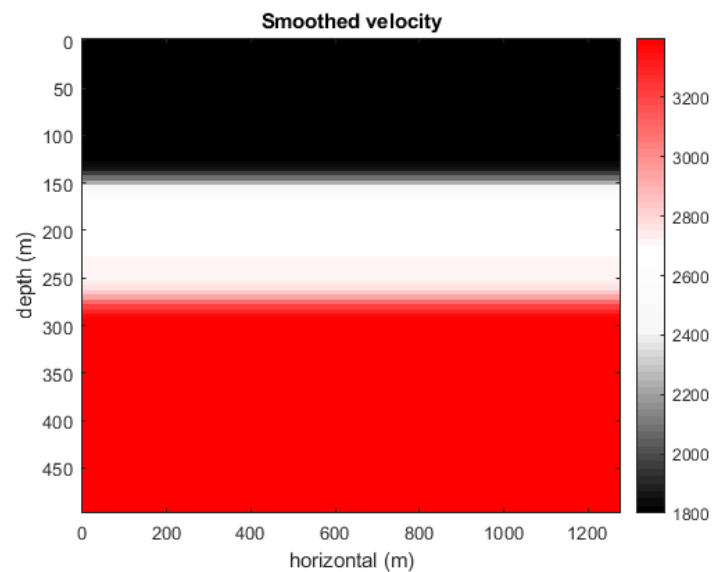
(b) Observed data



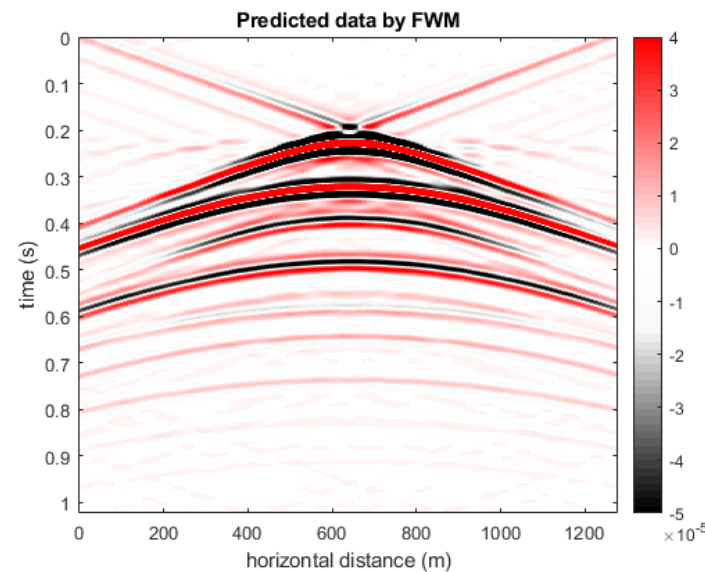
(c) Forward modeling in PWM



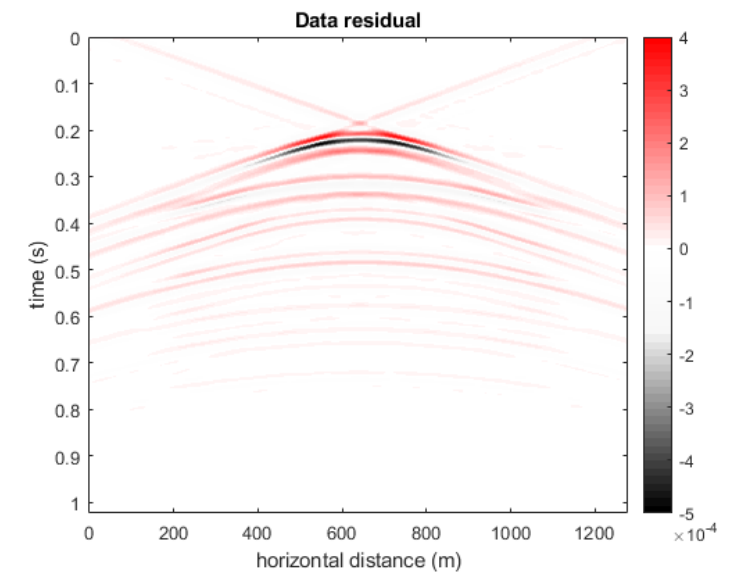
(d) Smoothed velocity model



(e) Forward modeling in FWM

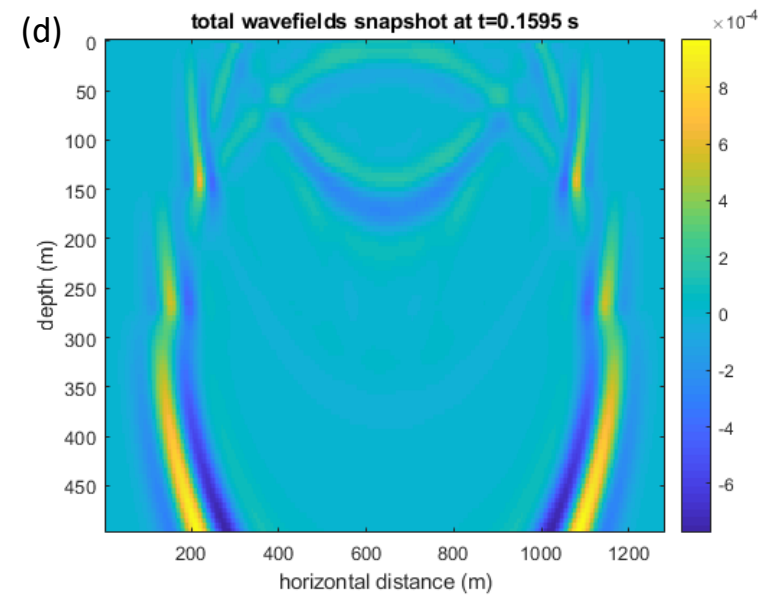
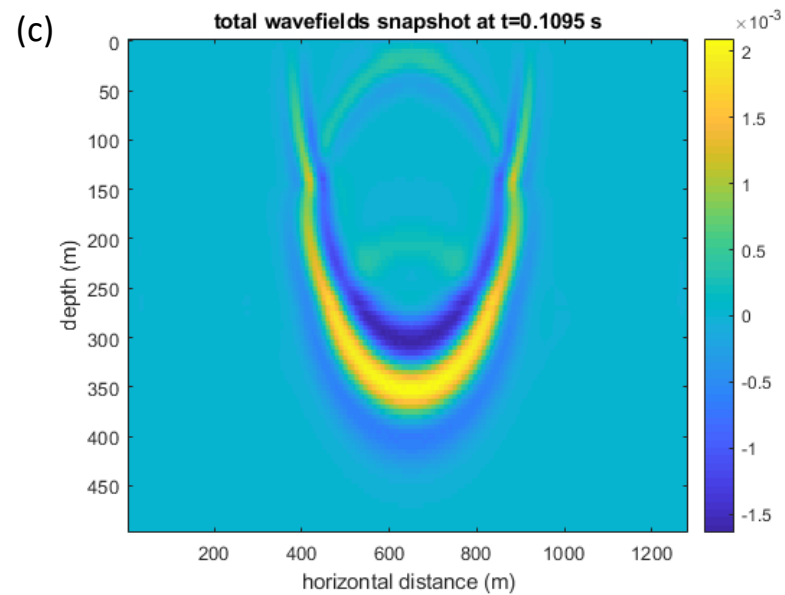
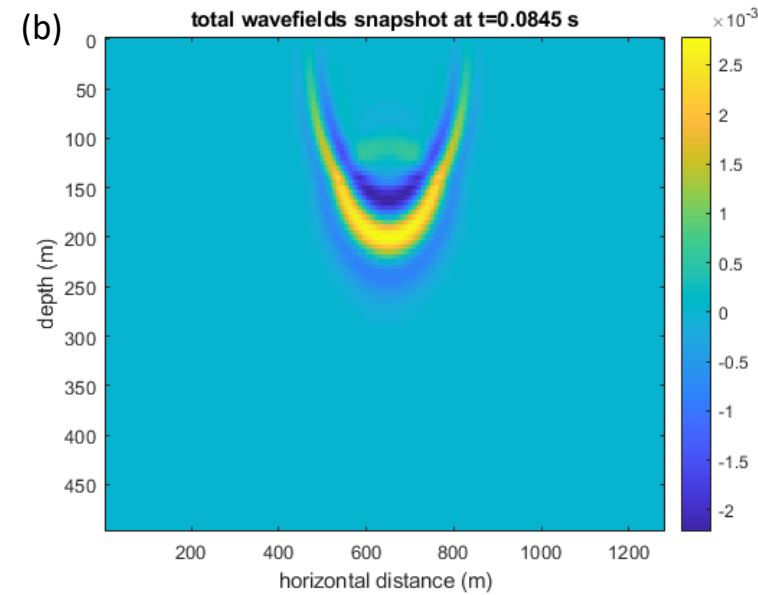
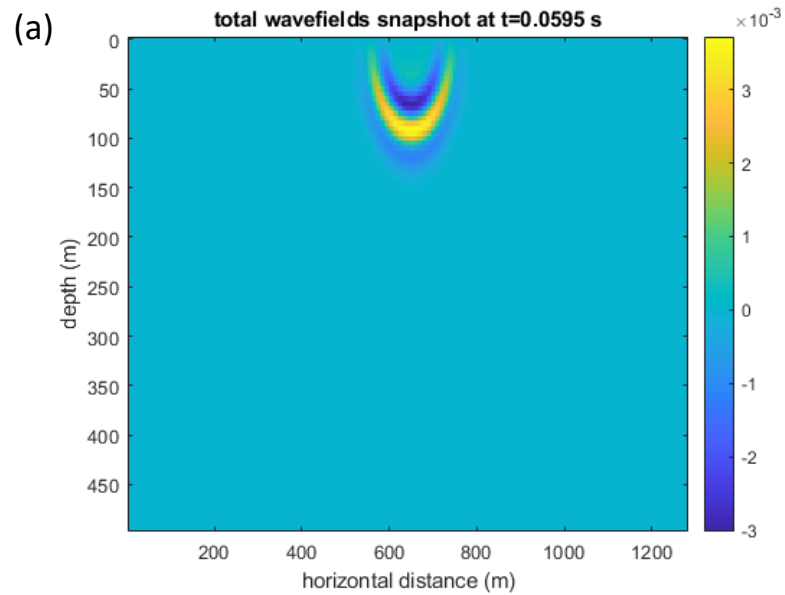


(f) Difference between (b) and (e)



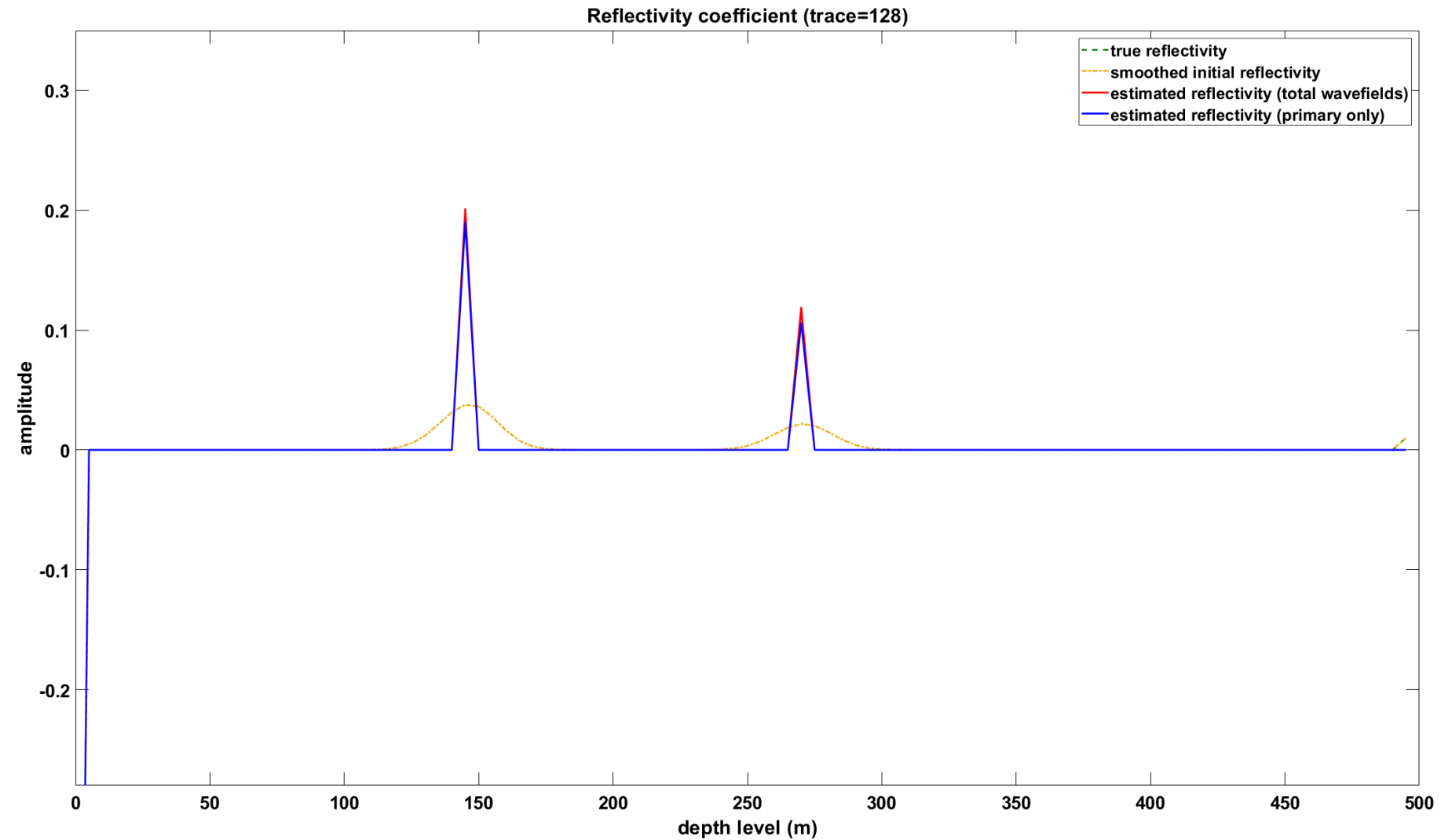


Example 1 – Total wavefields snapshots

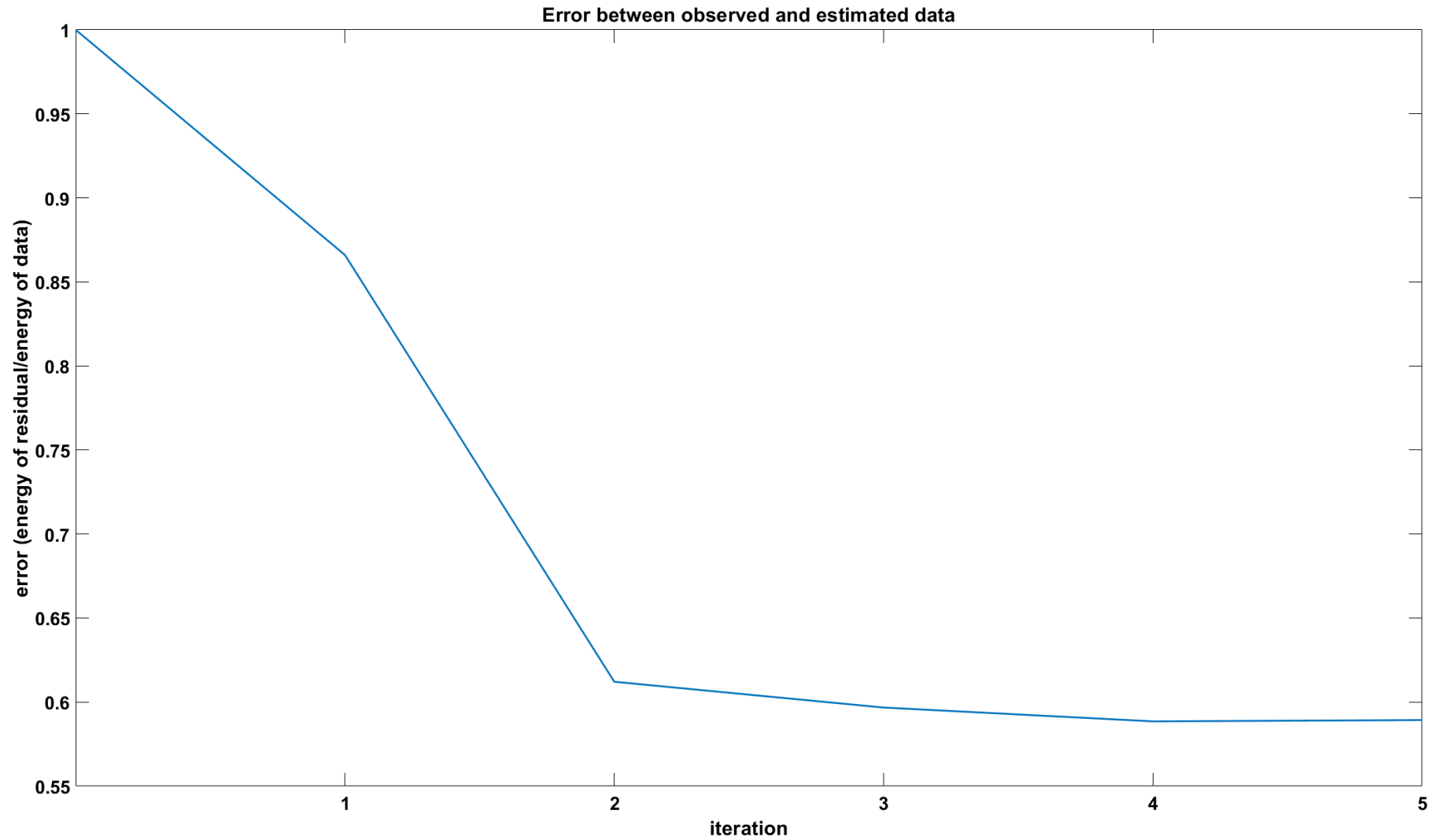




Example 1 – Reflectivity coefficient comparison

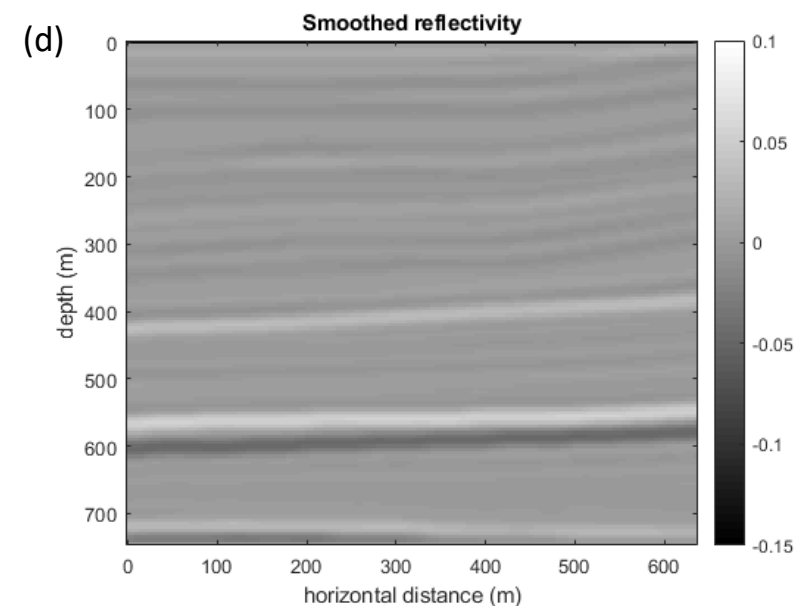
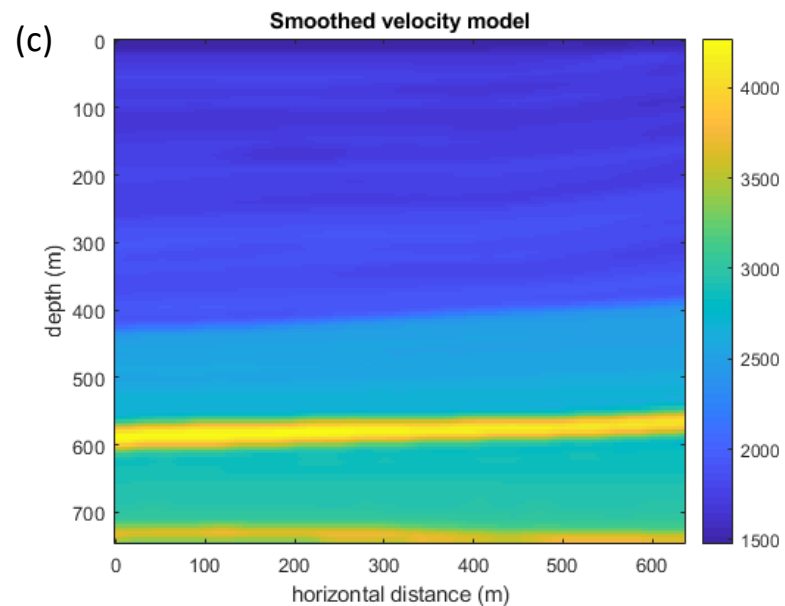
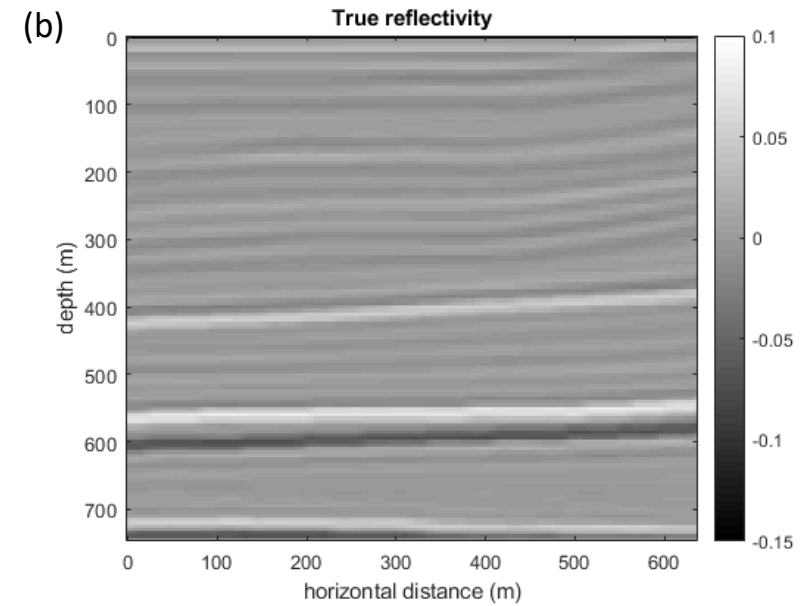
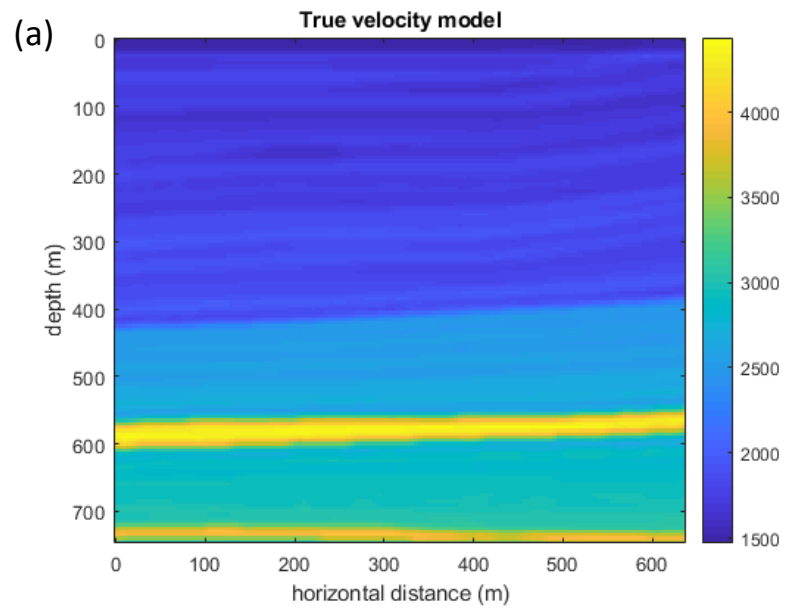


Example 1 – Error analysis





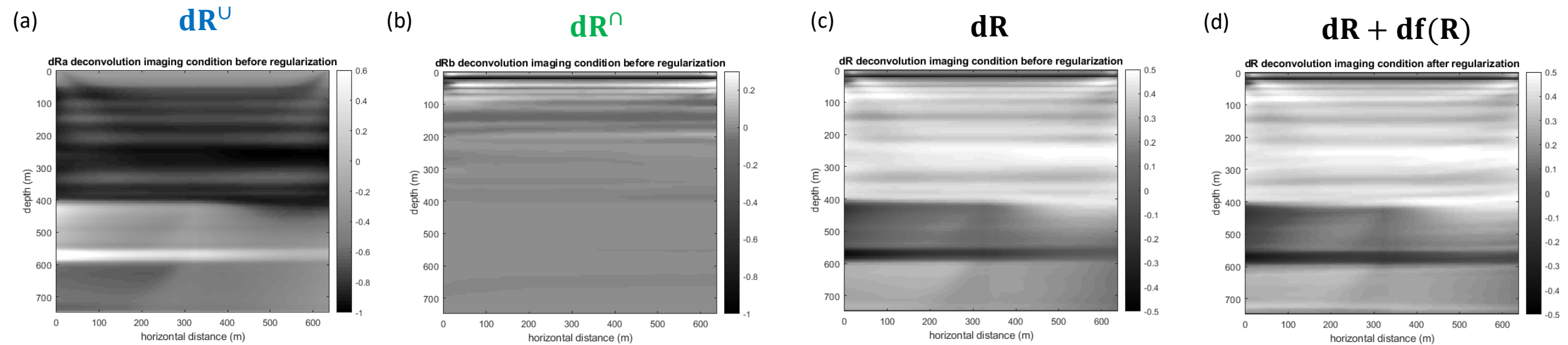
Example 2 – Left part of Marmousi model



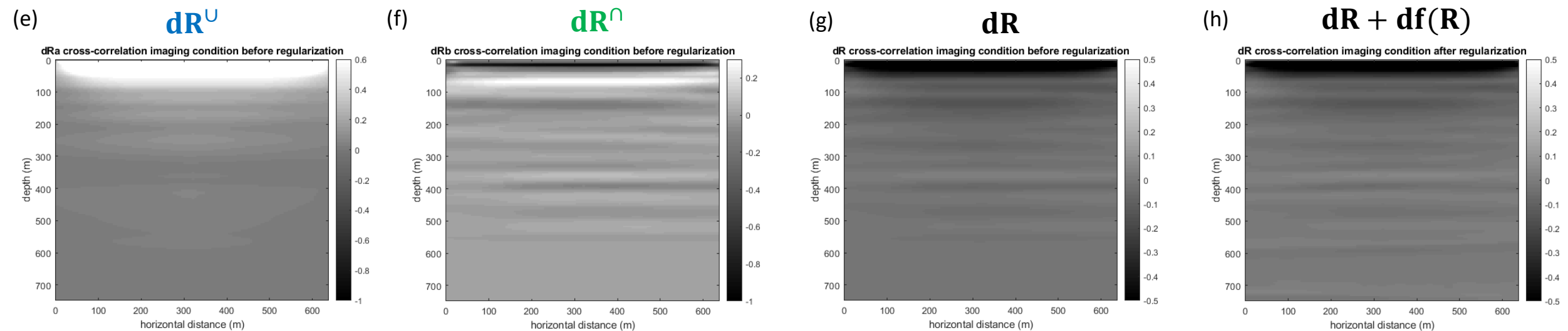


Example 2 – Using deconvolution imaging condition

Deconvolution imaging condition:

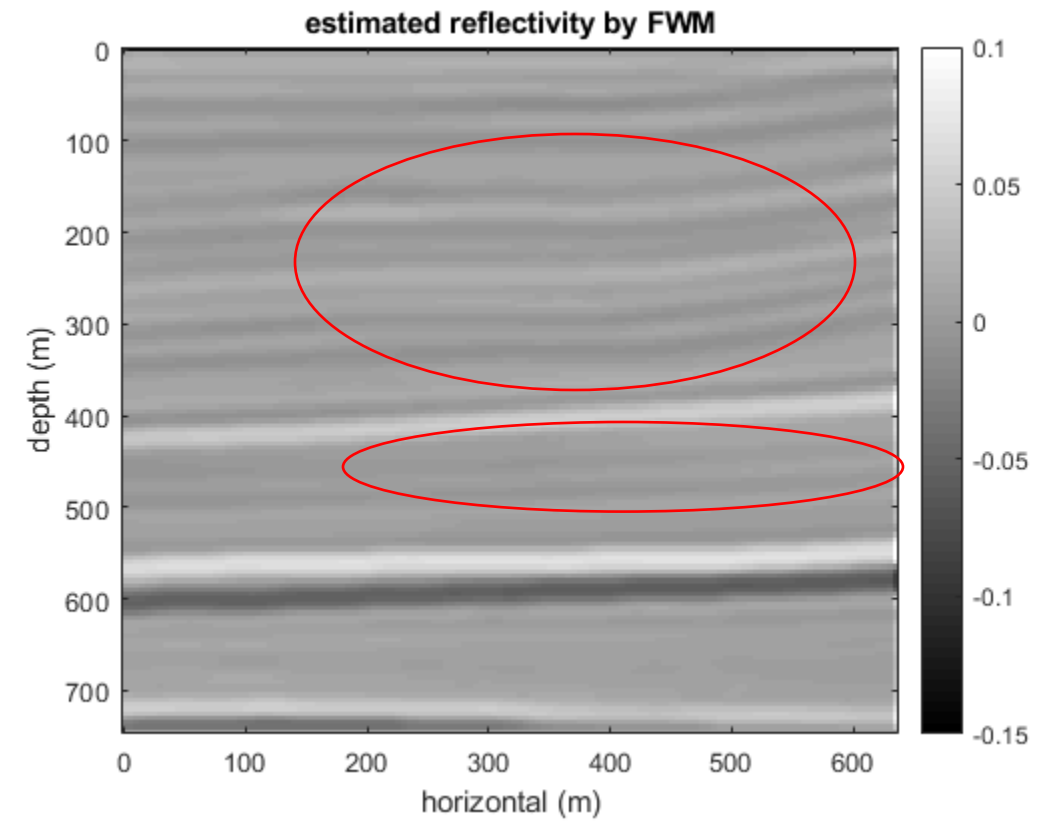
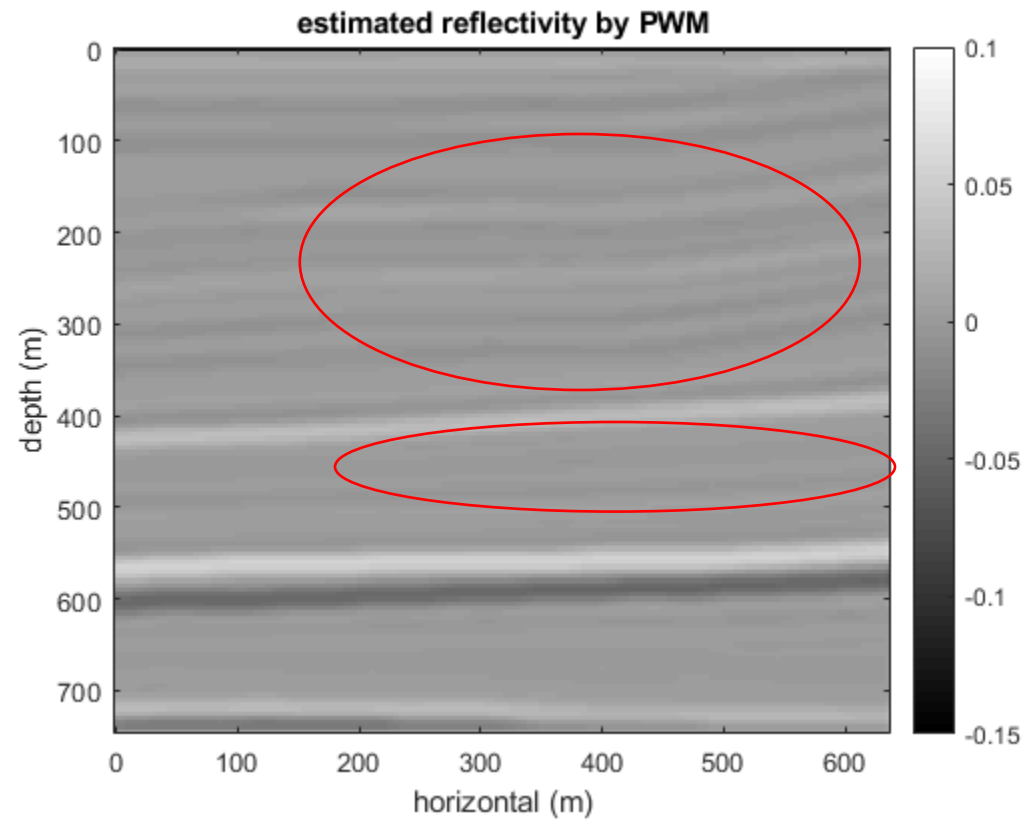


Cross-correlation imaging condition:



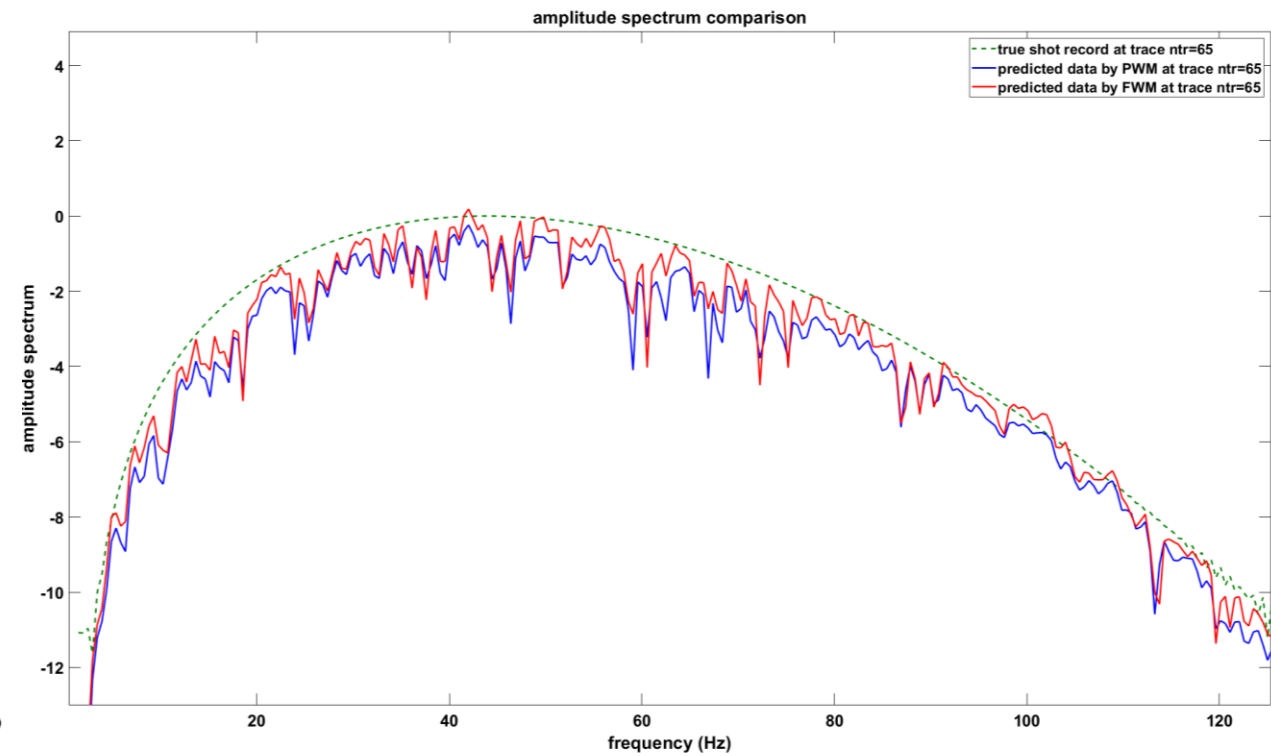
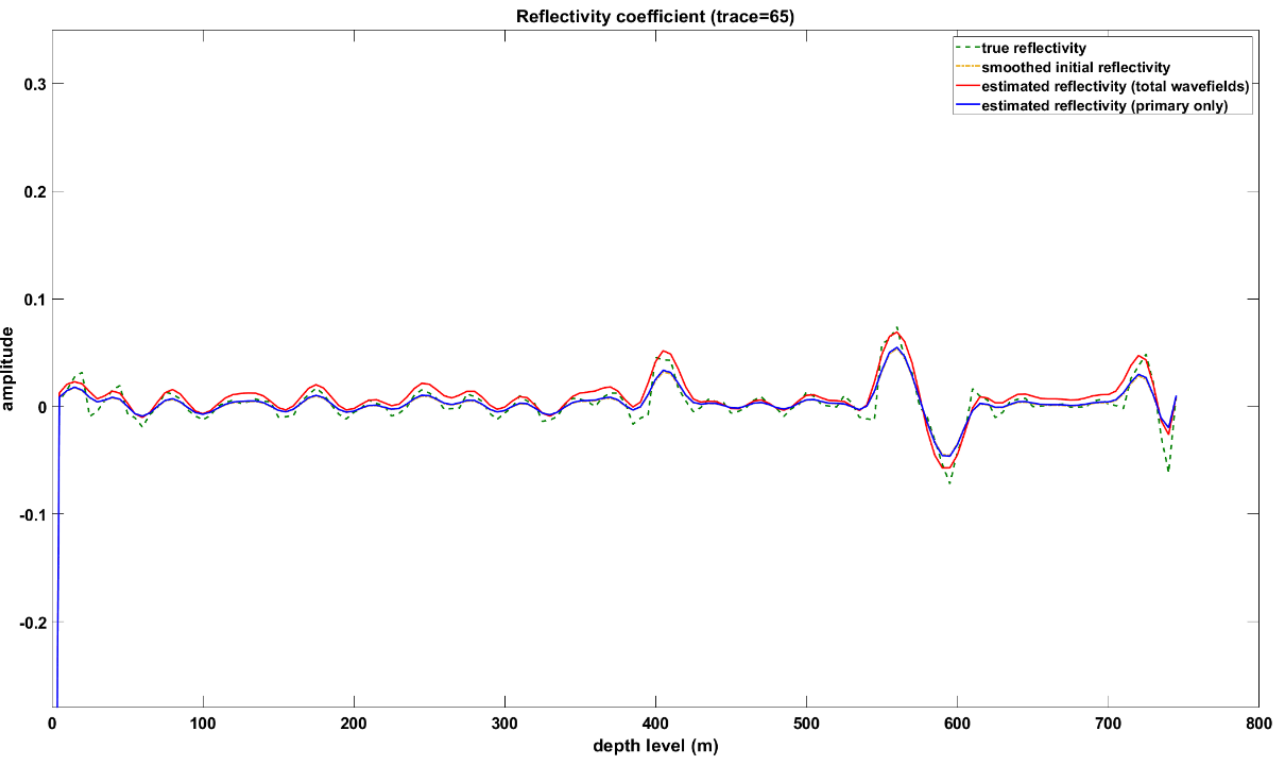


Migration results



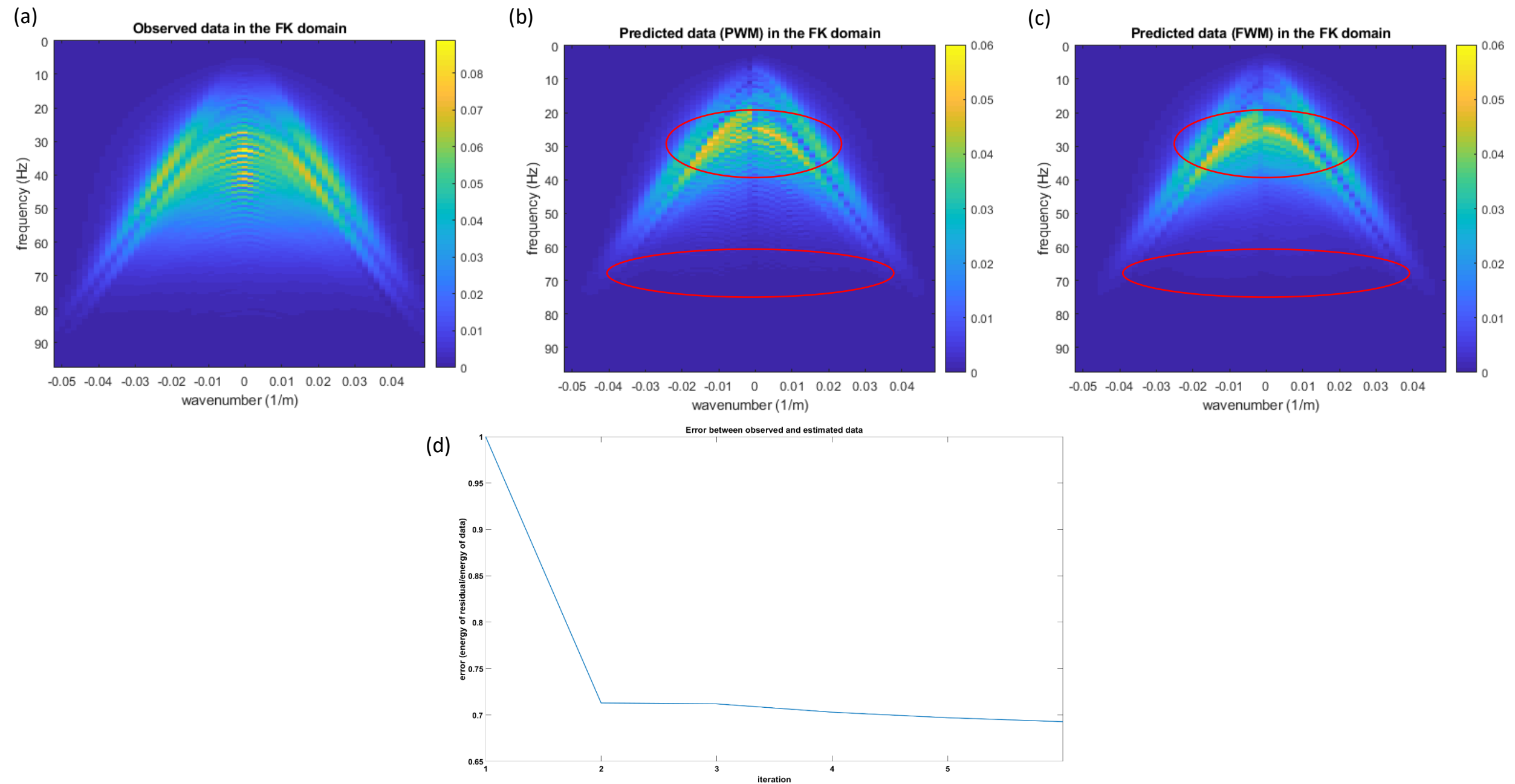


Example 2 – Reflection coefficient and amplitude spectrum comparison





F-K domain comparison





- Full wavefield modelling in the F-K domain can track the different orders of multiple reflections.
- Full wavefield migration result is more accurate than applying primary wavefield migration.
- Given wide offsets and a good initial background model, the deconvolution imaging condition can improve to predict subsurface layer locations with fewer artifacts.



- In future work, we should correct the amplitude and phase information showing in the F-K domain.
- The next step is trying to reduce the computational cost due to the three-dimensional data structure.
- Furthermore, we need to consider angle-dependent reflectivity or angle gathers into the migration process for better imaging results.



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Thank you!