

Local optimization approaches for simultaneous AVO inversion based on re-parameterized Zoeppritz equations

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CRSNG**



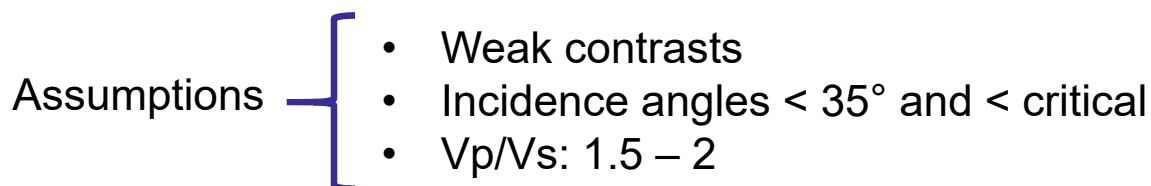
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Introduction

Weighted stacking technique:

Smith and Gidlow (1987)
Stewart (1990) and Larsen
(1999)



Objective: Inversion strategy suitable for long-offset acquisitions



Forward Problem: Zoeppritz equations

$$\mathbf{P} \begin{bmatrix} R_{pp} \\ R_{ps} \\ T_{pp} \\ T_{ps} \end{bmatrix} = \mathbf{b}$$



$$\frac{\Delta I}{I} \quad \frac{\Delta J}{J} \quad \frac{\Delta \rho}{\rho}$$



$$\frac{\Delta q}{q} = \frac{\Delta I}{I} - \frac{\Delta J}{J}$$

$$\mathbf{P} = \begin{bmatrix} -X & -\sqrt{1-B^2X^2} & CX & \sqrt{1-D^2X^2} \\ \frac{X}{\sqrt{1-X^2}} & -BX & \frac{CX}{\sqrt{1-C^2X^2}} & -DX \\ 2B^2X\sqrt{1-X^2} & B(1-2B^2X^2) & 2AD^2X\sqrt{1-C^2X^2} & AD(1-2D^2X^2) \\ -(1-2B^2X^2) & 2B^2X\sqrt{1-B^2X^2} & AC(1-2D^2X^2) & -2AD^2X\sqrt{1-D^2X^2} \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} X \\ \frac{X}{\sqrt{1-X^2}} \\ 2B^2X\sqrt{1-X^2} \\ 1-2B^2X^2 \end{bmatrix}$$

where:

$$A = \frac{\rho_2}{\rho_1} \quad B = \frac{\beta_1}{\alpha_1} \quad C = \frac{I_2 \rho_1}{I_1 \rho_2} \quad D = B \frac{J_2 \rho_1}{J_1 \rho_2} \quad X = \sin \theta_1$$

$$\frac{Y_2}{Y_1} = \left(1 + \frac{1}{2} \frac{\Delta Y}{Y} \right) / \left(1 - \frac{1}{2} \frac{\Delta Y}{Y} \right)$$

Forward Problem: raytracing

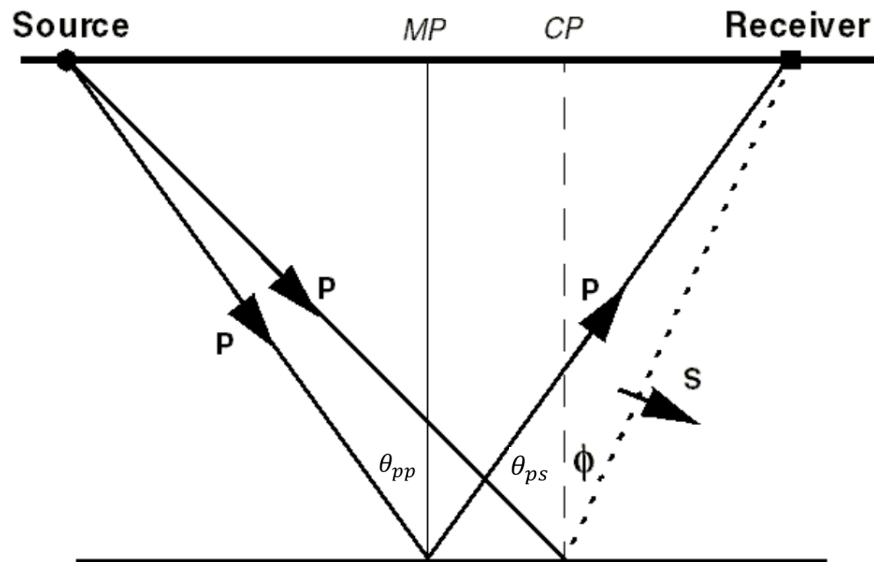


Figure modified from Stewart et al. (1999)

$$\mathbf{P} \begin{bmatrix} R_{pp} \\ R_{ps} \\ T_{pp} \\ T_{ps} \end{bmatrix} = \mathbf{b} \begin{cases} X = \sin \theta_{pp_j} \\ X = \sin \theta_{ps_j} \end{cases} \quad j = 1 \dots N$$

$$\mathbf{d}_{\text{pred}} = \mathbf{S}\mathbf{u} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} R_{pp} \\ R_{ps} \\ T_{pp} \\ T_{ps} \end{bmatrix} = \begin{bmatrix} R_{pp} \\ R_{ps} \end{bmatrix}$$



Simultaneous inversion: unconstrained optimization

$$\phi(\mathbf{m}) = \frac{1}{2} \sum_{j=1}^N \left(\underbrace{\mathbf{S}\mathbf{u}(\mathbf{m}, \theta_j)}_{\text{predicted}} - \mathbf{d}_{\text{obs}}(\theta_j) \right)^T \underbrace{\mathbf{W}^T \mathbf{W}}_{\text{predicted}} \left(\underbrace{\mathbf{S}\mathbf{u}(\mathbf{m}, \theta_j)}_{\text{predicted}} - \mathbf{d}_{\text{obs}}(\theta_j) \right) \longrightarrow \mathbf{W} = \begin{bmatrix} 1/\sigma_{pp} & 0 \\ 0 & 1/\sigma_{ps} \end{bmatrix}$$

Gradient: $\mathbf{g} = \sum_{j=1}^N \mathbf{J}_j^T \mathbf{W}^T \mathbf{W} \left(\mathbf{S}\mathbf{u}(\mathbf{m}, \theta_j) - \mathbf{d}_{\text{obs}}(\theta_j) \right) \quad J_{\mu}^i = -S_K^i (P^{-1})_L^K \frac{\partial P_M^L}{\partial m^{\mu}} u^M$

Hessian: $\mathbf{H} = \sum_{j=1}^N \mathbf{J}_j^T \mathbf{W}^T \mathbf{W} \mathbf{J}_j$

$i = 1, 2$
 $j = 1, 2, 3$
 $K = M = L = 1, 2, 3, 4$

Updates:

$$\Delta \mathbf{m} = -\mathbf{B}^{-1} \mathbf{g}$$

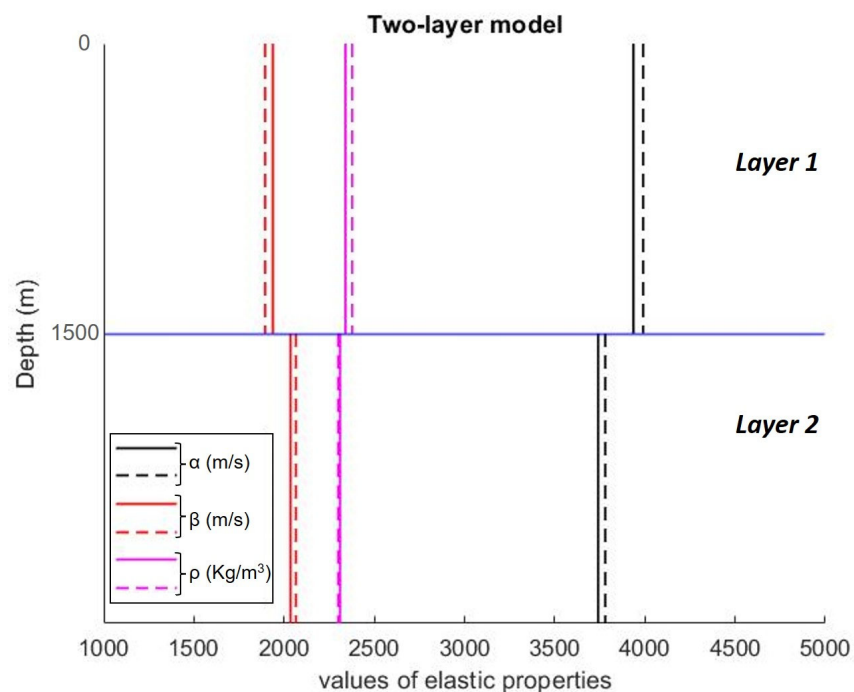
- $\mathbf{B} = \mathbf{I} \rightarrow$ Steepest Descent
- $\mathbf{B} = \mathbf{H} \rightarrow$ Gauss-Newton
- $\mathbf{B} = \mathbf{H} + \lambda \text{diag}(\mathbf{H}) \rightarrow$ Levenberg-Marquardt



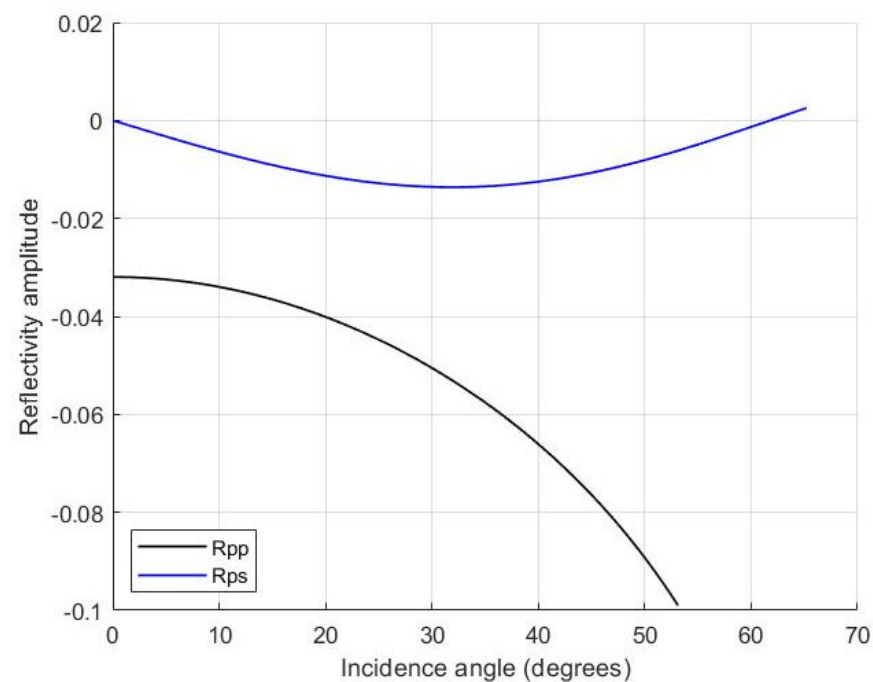
True model features

Dashed lines: initial model

Continuous lines: true model



Underlying assumptions of weighted stacking inversion

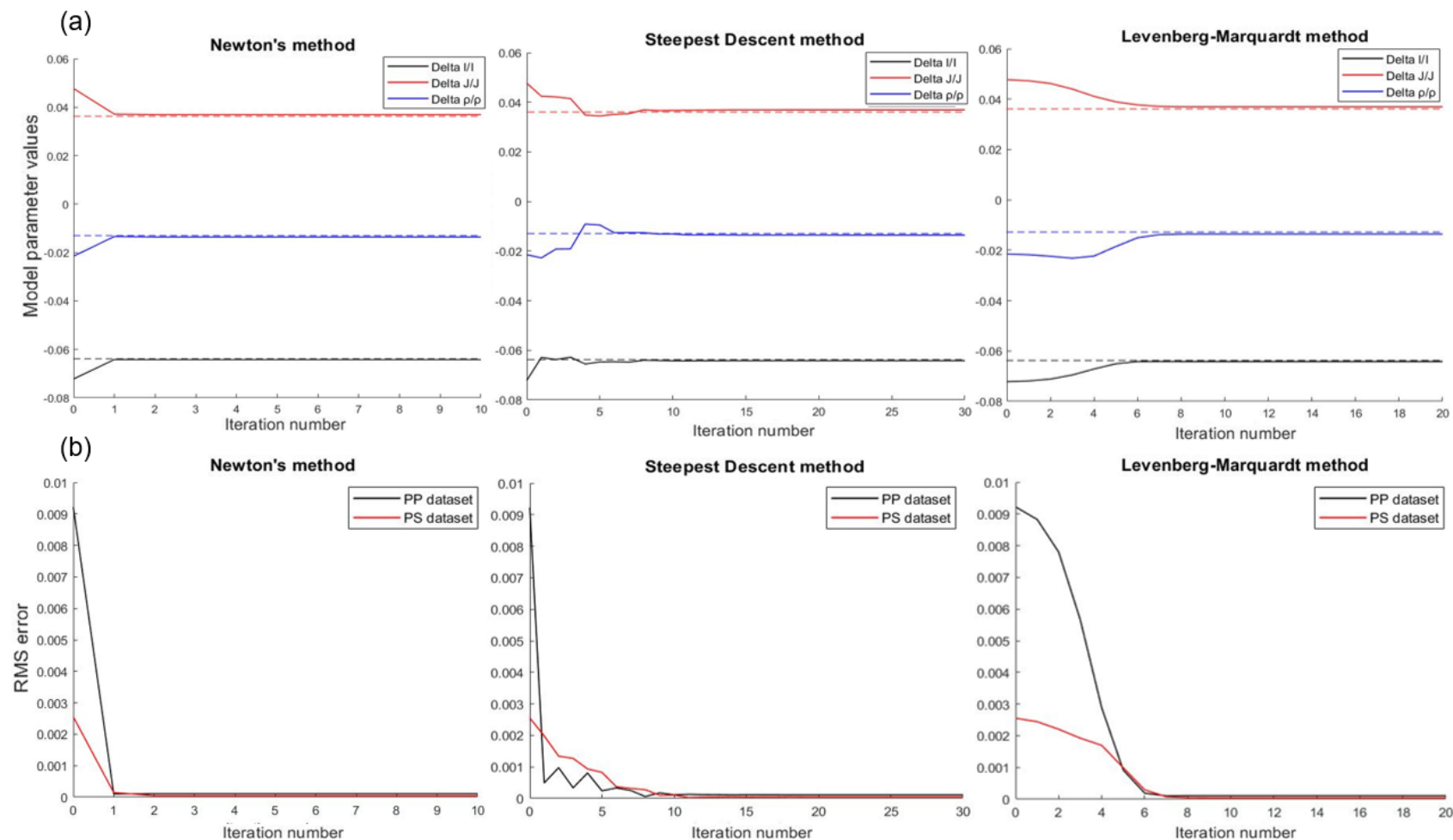


Maximum P-P angle: 53°

Maximum P-S angle: 65°

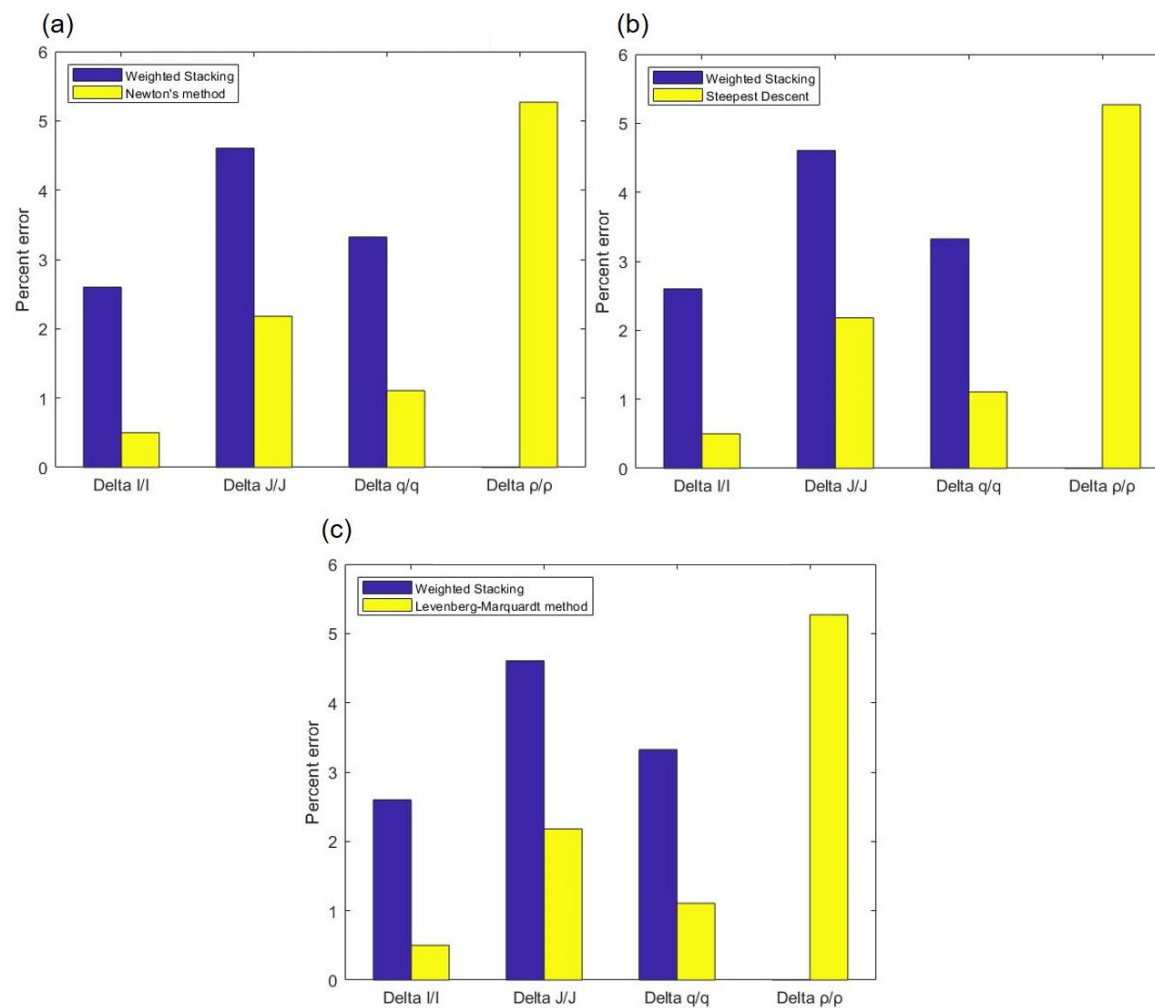


Results: broadband and noise free reflectivities





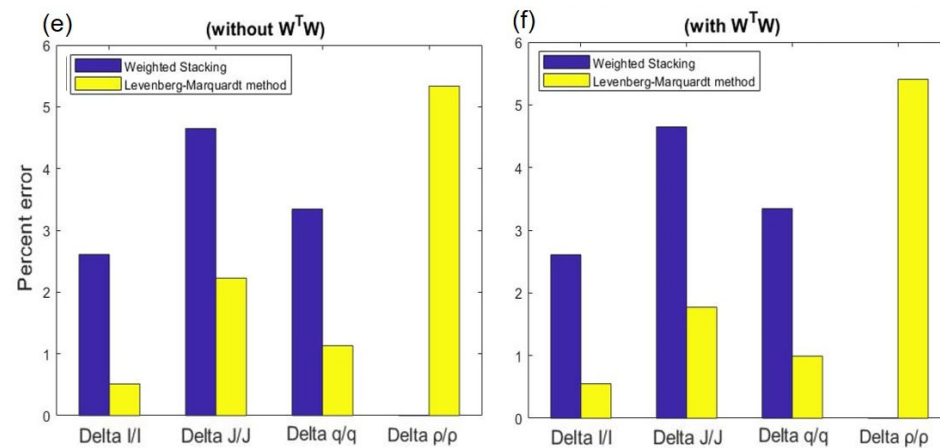
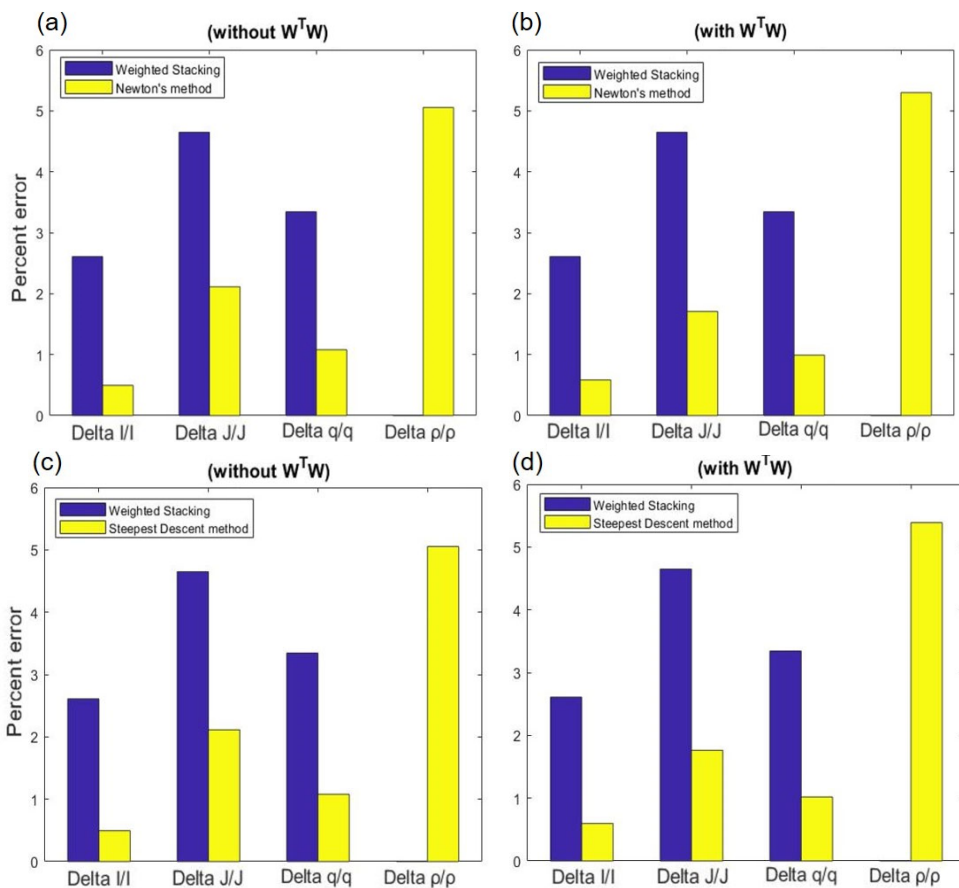
Results: broadband and noise free reflectivities





Results: broadband and noisy reflectivities

IID noise {
P-P SNR: 8
P-S SNR: 4

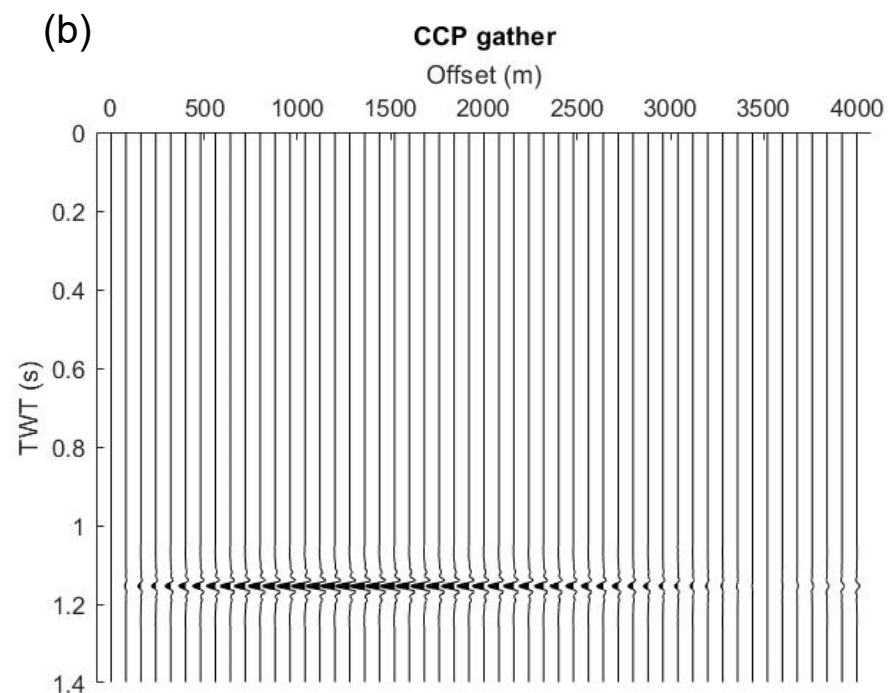
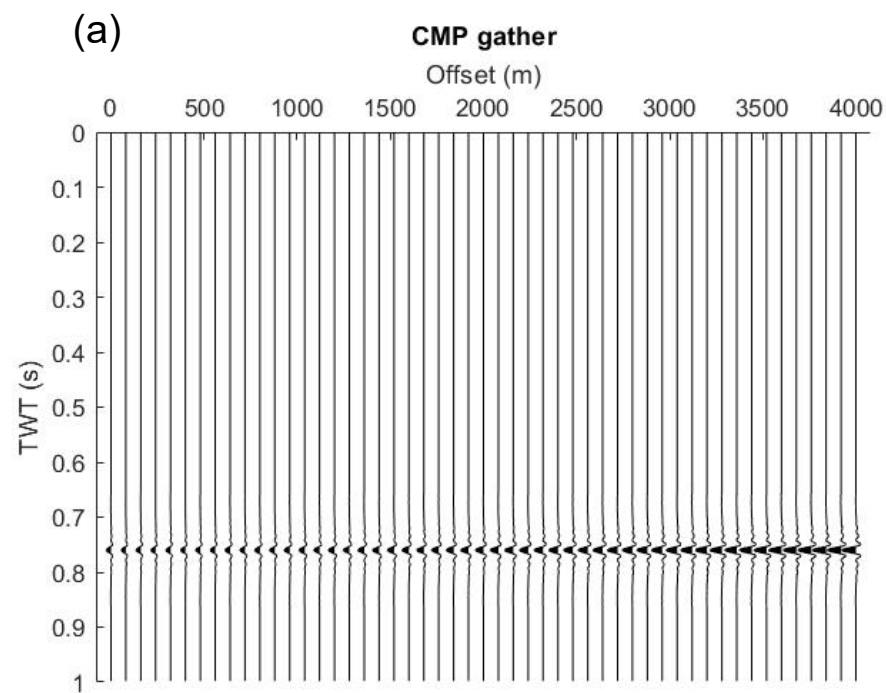


Maximum likelihood solutions



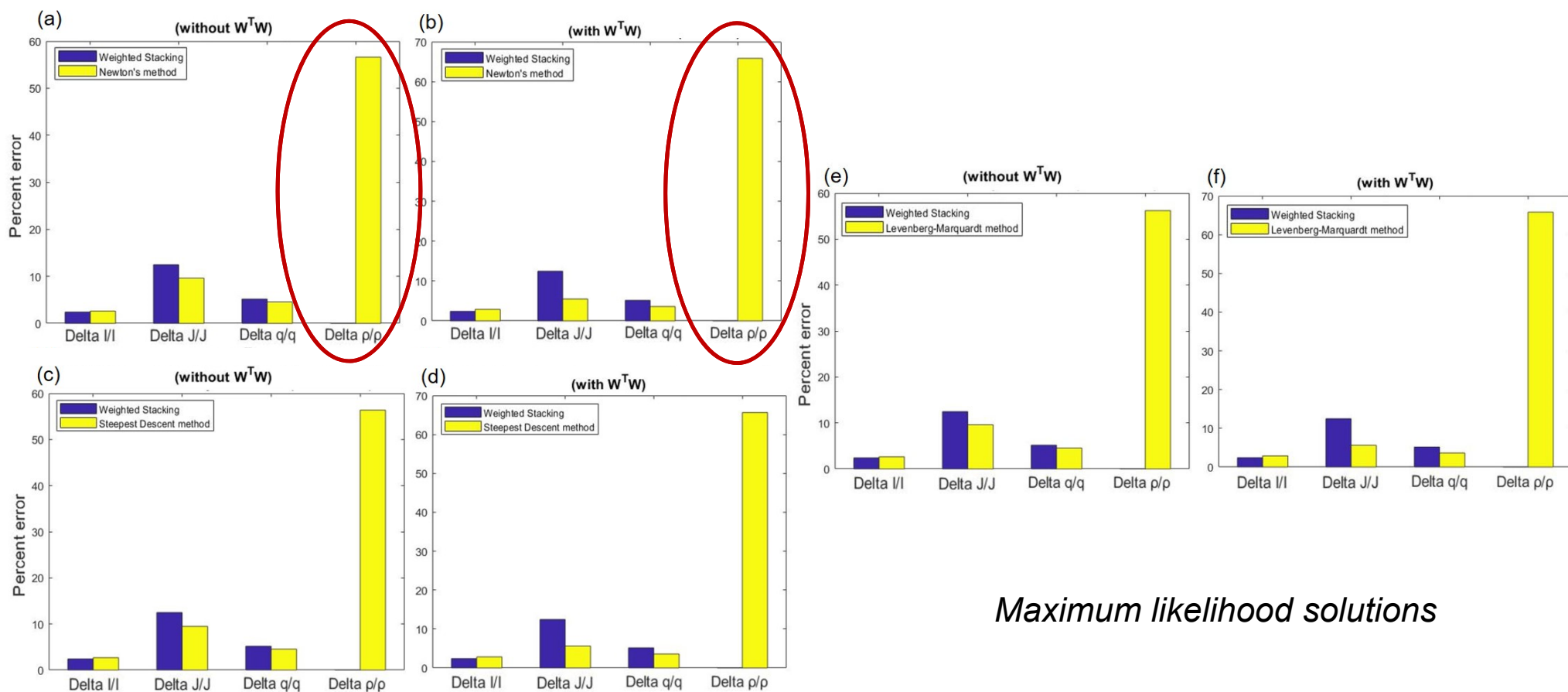
Results: band-limited and noisy reflectivities

Ormsby wavelet {
P-P dataset: → 5-10-60-75Hz
P-S dataset: → 5-10-40-55Hz





Results: band-limited and noisy reflectivities

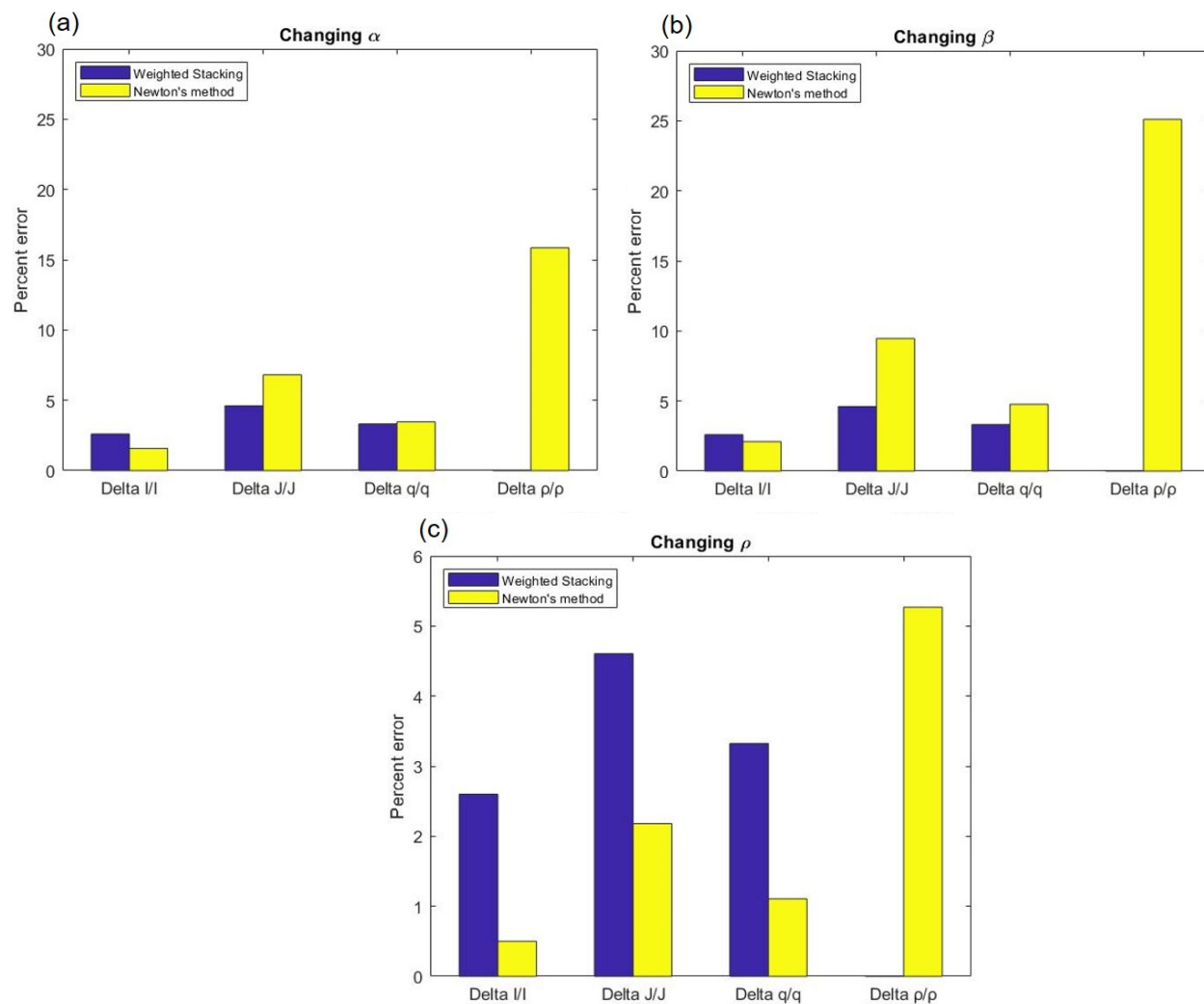
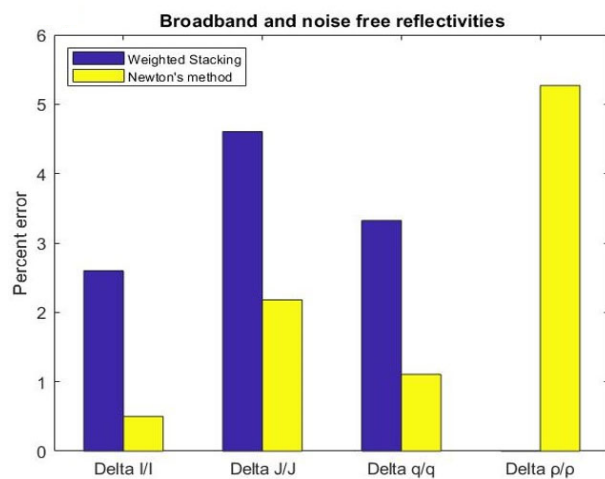


Maximum likelihood solutions



Results: effects of the initial model

Results with original initial model





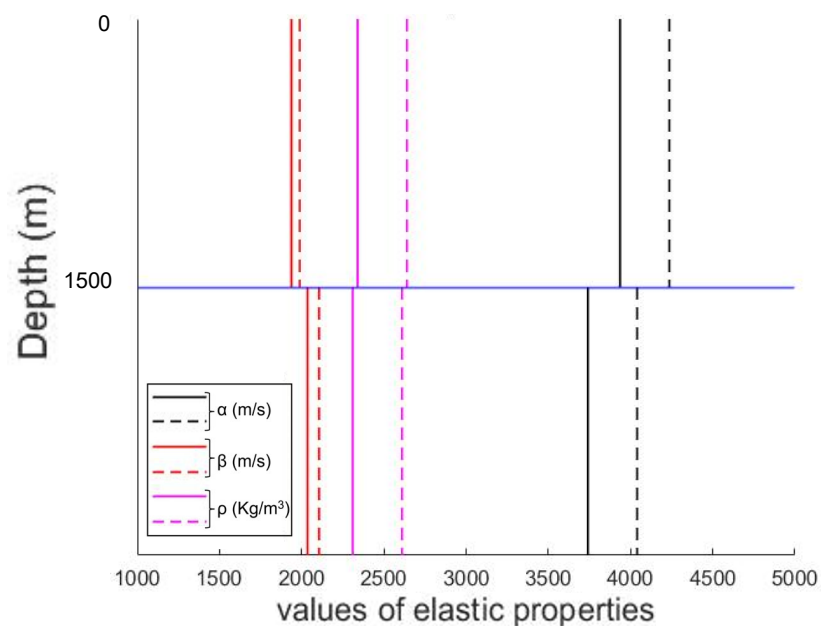
Results: effects of the initial model

Good initial
model

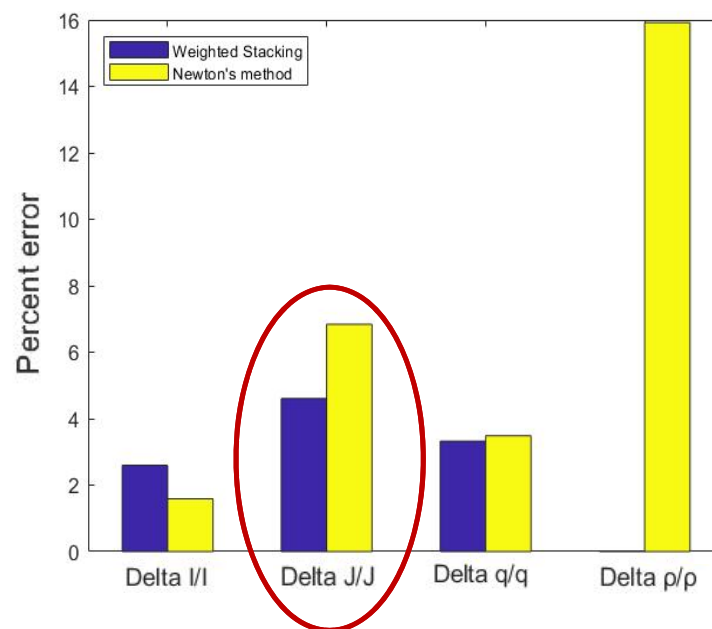
Close to true contrasts and
relationships between α and
 β perturbations

Dashed lines: new initial model

Continuous lines: true model



$\alpha:\beta \longrightarrow 6:1$



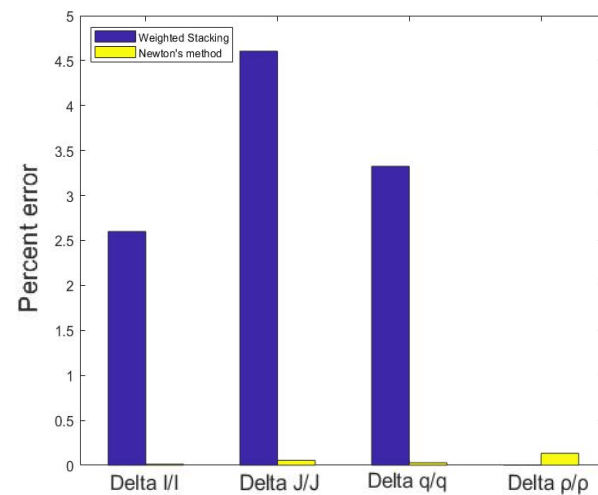
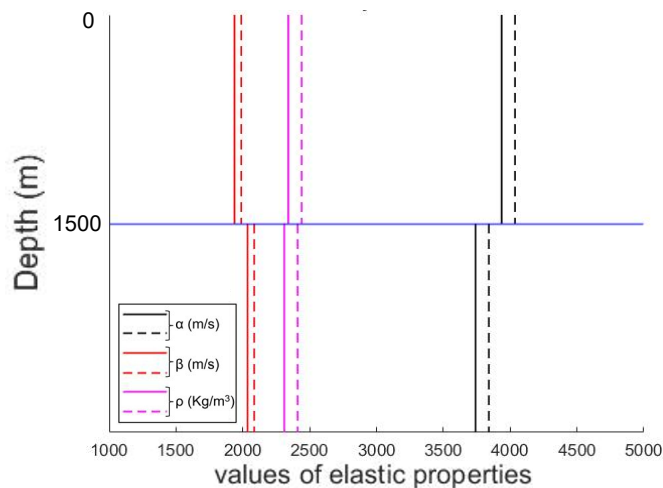
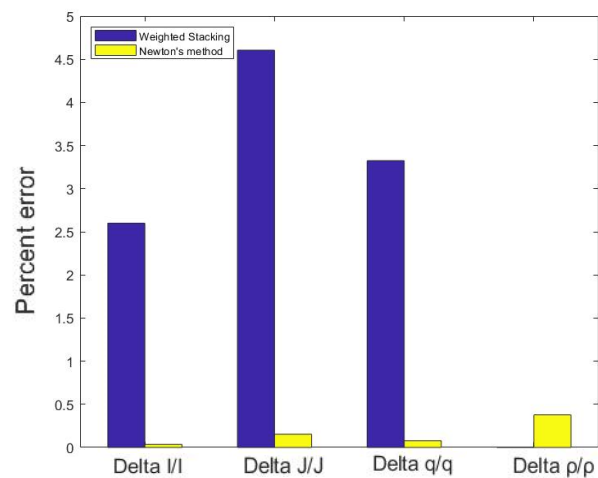
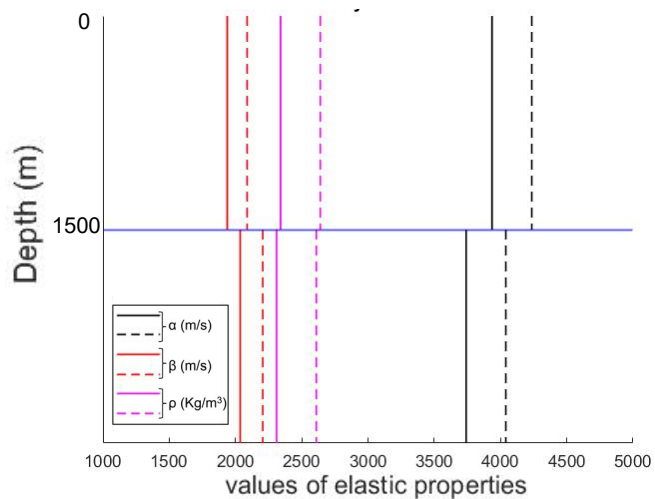


Results: effects of the initial model

$\alpha:\beta \rightarrow 2:1$

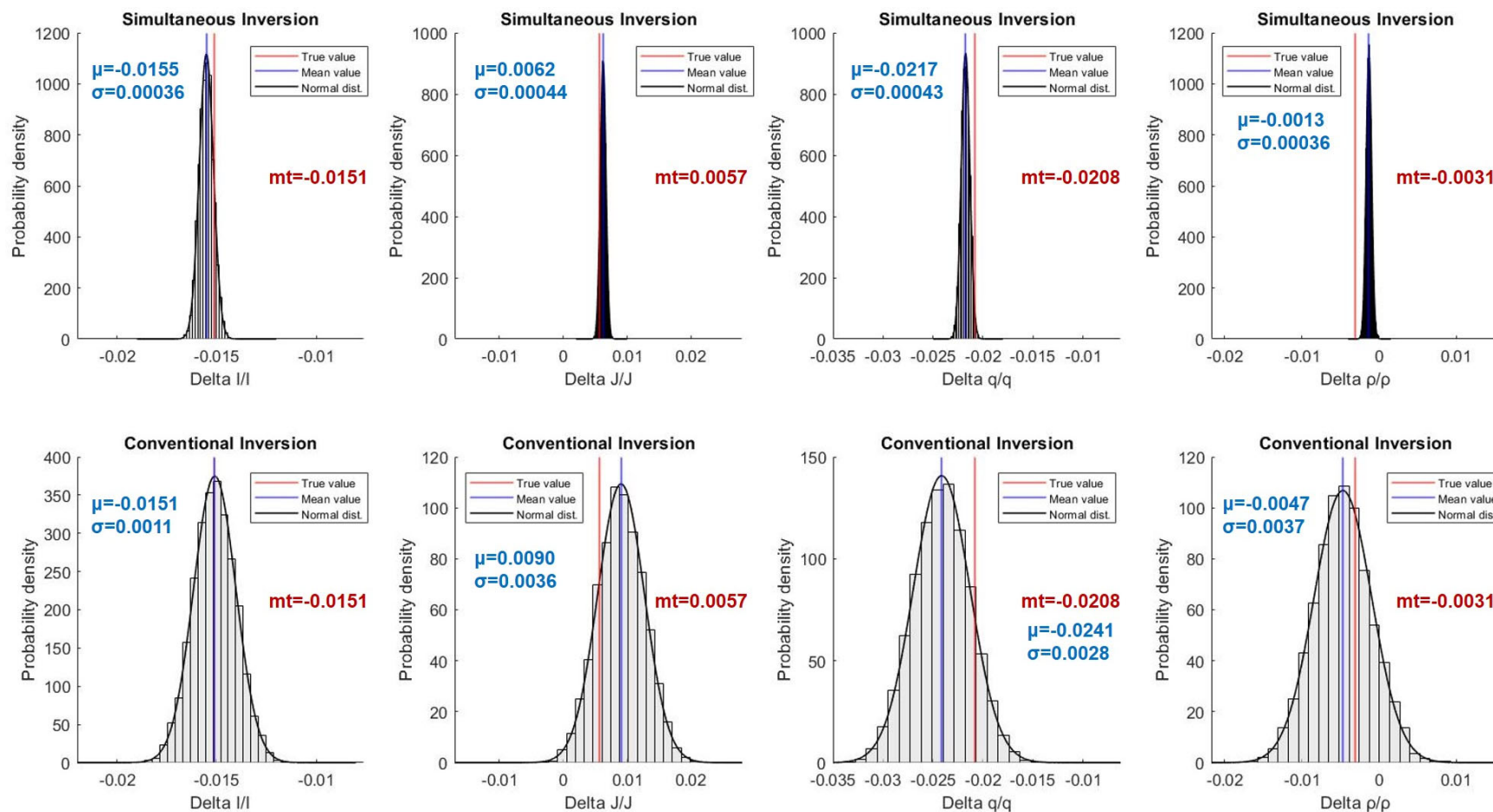
Dashed lines:
new initial model

Continuous lines: true model





Results: advantages of the simultaneous nonlinear inversion



mt:
Band-limited
true values

μ :
Maximum-
likelihood sol.

σ :
Standard
deviation



Conclusions

- Outperformance of the nonlinear inversion over the weighted stacking approach.
 - Convergence to the same minimum point with different convergence features.
- Including noise information produced improvements on the fractional shear impedance and fractional V_p/V_s ratio.
- High accuracy and precision of the simultaneous nonlinear inversion results.
 - Negative impact on the fractional density.



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References

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