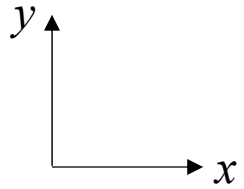


3D time-lapse RTM of data from the Snowflake 2018-2022 experiments

Xiaohui Cai, Kris Innanen, Ziguang Su, Don Lawton

CREWES Annual Meeting

Banff AB CA Dec 7 2023

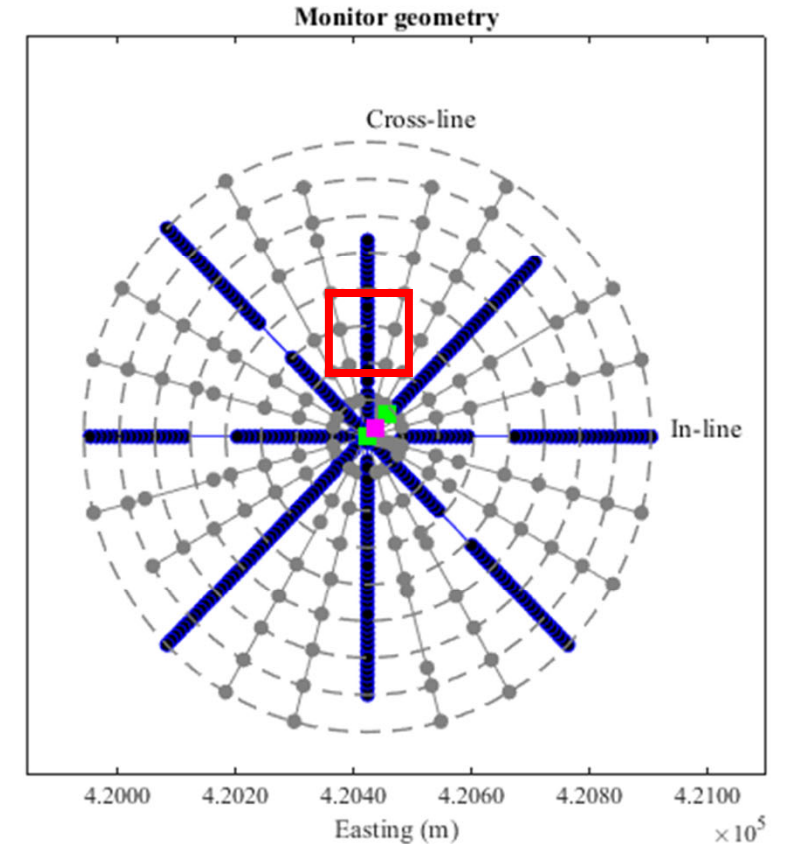
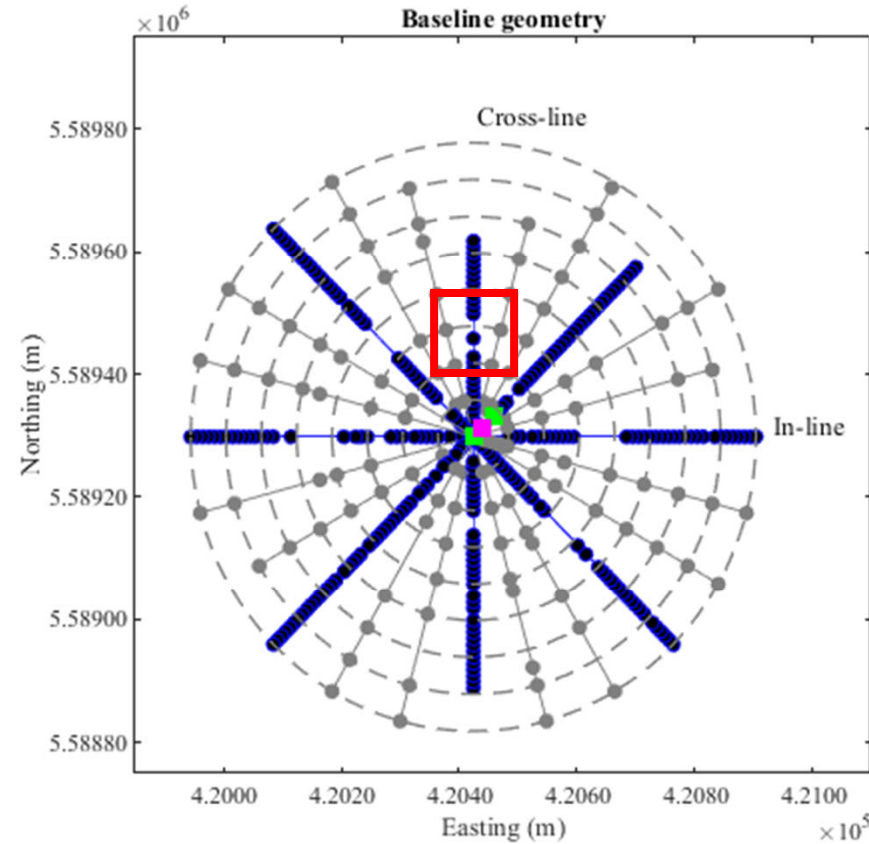


2018

2022

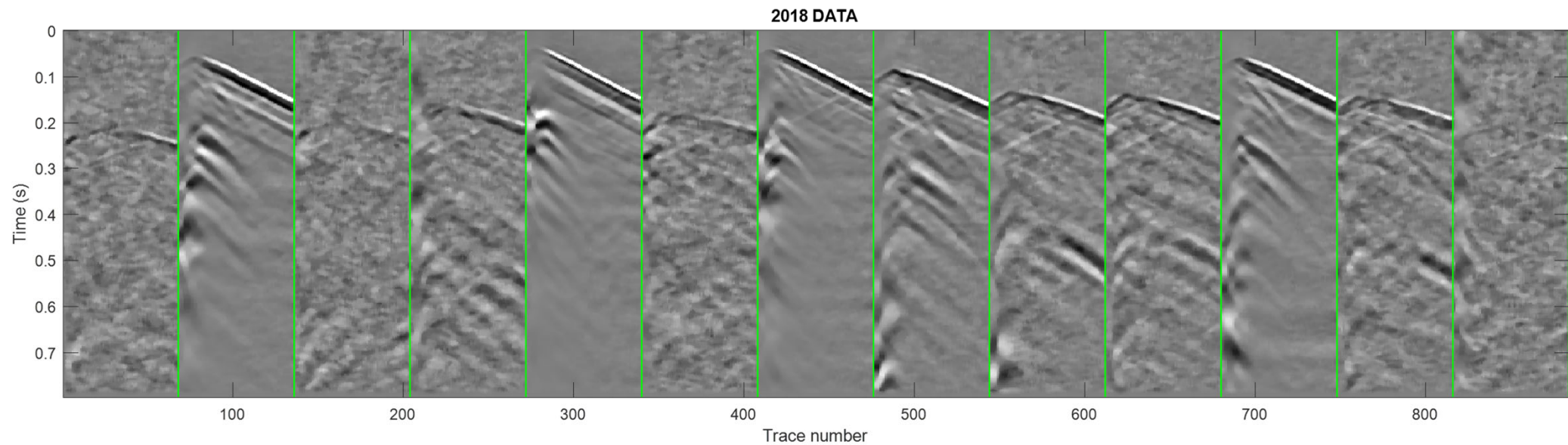
Injection depth:
290 m-305 m

DAS space interval:
0.667 in 2018
1 m in 2022.

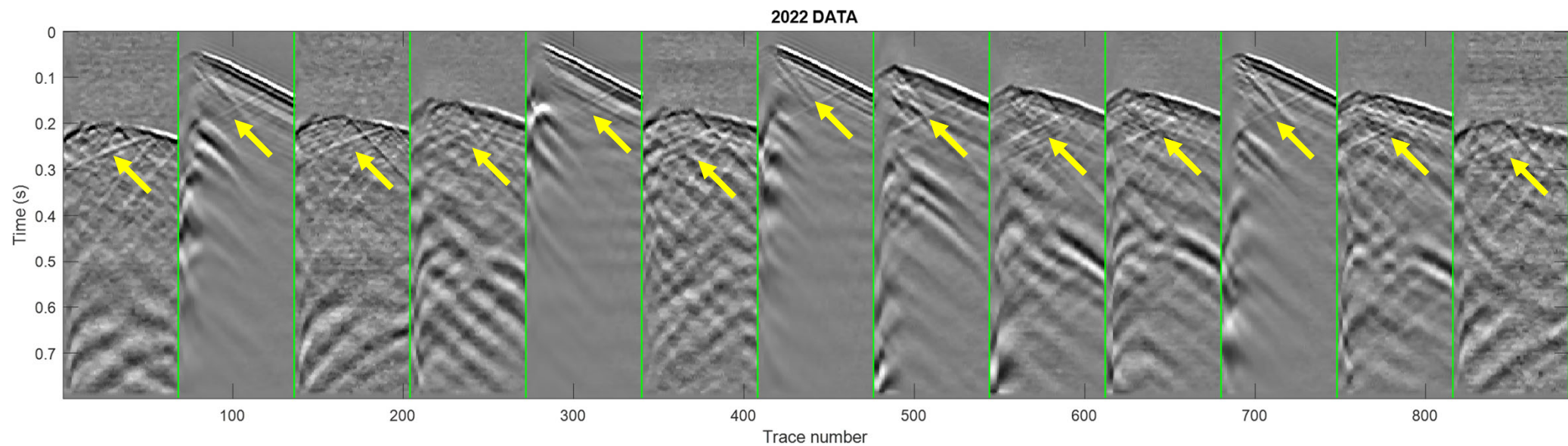




2018

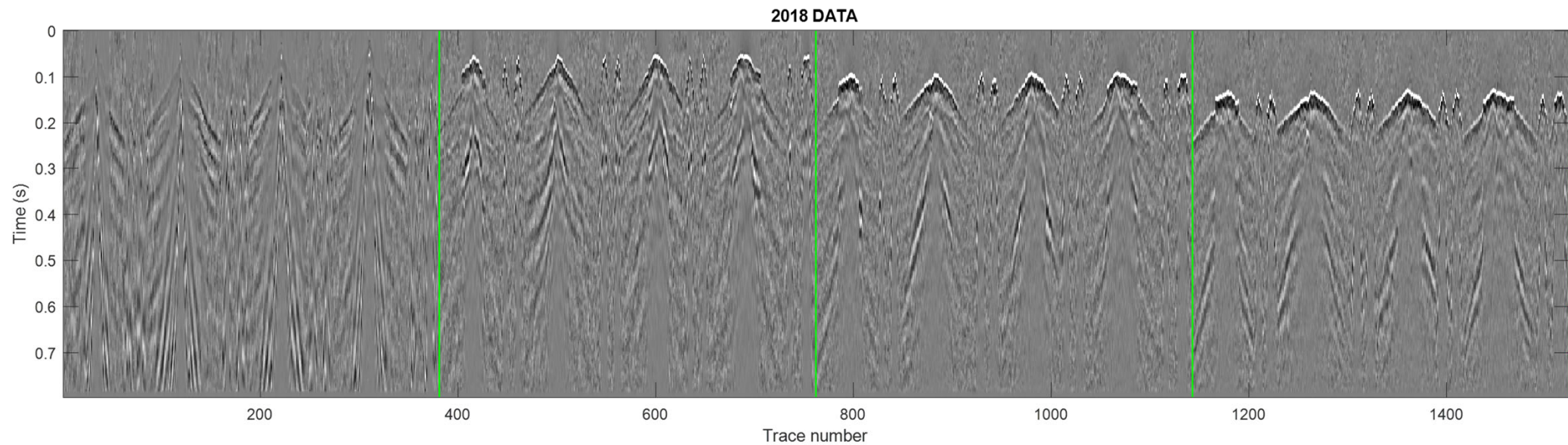


2022

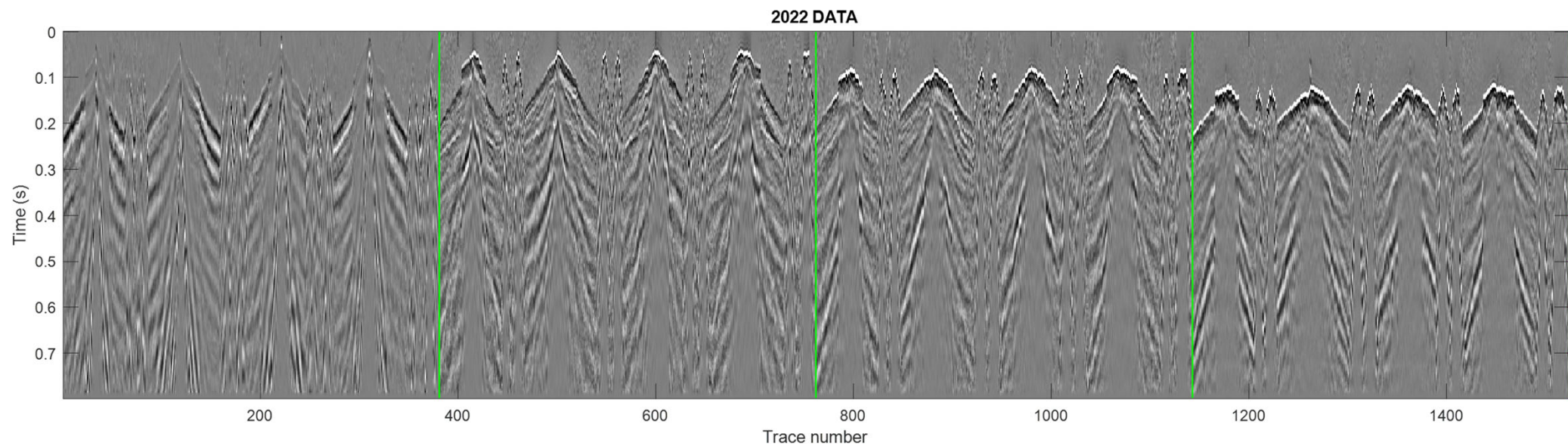




2018



2022





3D Reverse-Time Migration Strategy

- 3D finite-difference modeling based on optimal least-squares (Cai et al., 2015)
- 3D hybrid absorbing boundary condition (Liu and Sen., 2010)
- Crosscorrelation imaging conditions (Chattopadhyay and McMechan, 2008)
- **Azimuth-dependent RTM**

Parallel Computing Strategy

- Effective boundary and checkpointing strategy (Clapp, 2008)
- GPU and POSIX thread (Cai et al., 2018)



3D acoustic wave equation:

$$\frac{1}{v^2} \frac{\partial^2 p}{\partial t^2} = \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} + \frac{\partial^2 p}{\partial z^2}$$

Conventional finite-difference coefficients

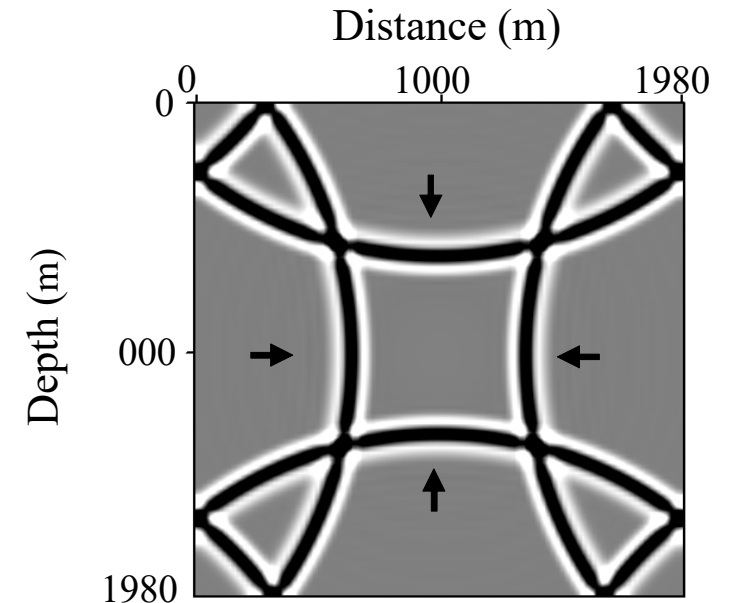
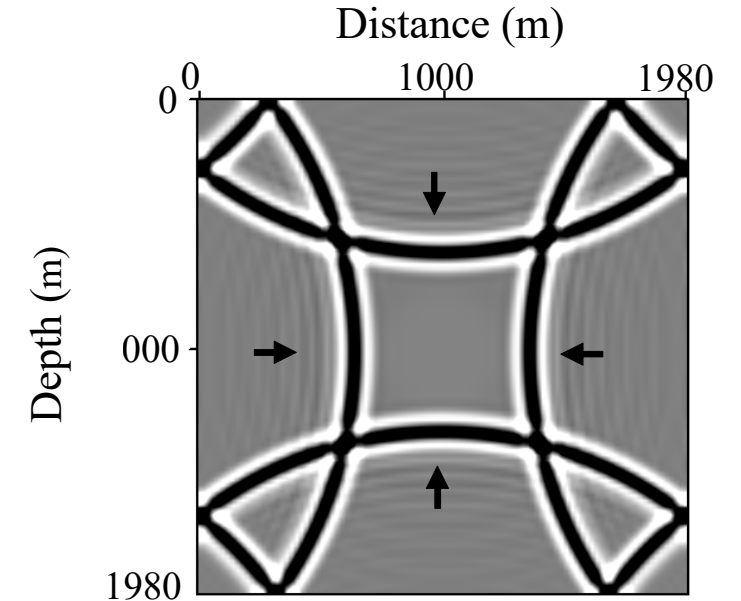
$$a_m = \frac{(-1)^{m+1}}{m^2} \prod_{1 \leq n \leq M, n \neq m} \left| \frac{n^2}{n^2 - m^2} \right|, m = 1, 2, \dots, M$$

Finite-difference coefficients based on optimal LS

$$\sum_{m=1}^M \left(\int_0^b \int_0^\pi \int_0^{2\pi} \varphi_m(\beta, \theta, \phi) \varphi_n(\beta, \theta, \phi) d\beta d\theta d\phi \right) a_m = \int_0^b \int_0^\pi \int_0^{2\pi} \varphi_n(\beta, \theta, \phi) d\beta d\theta d\phi$$

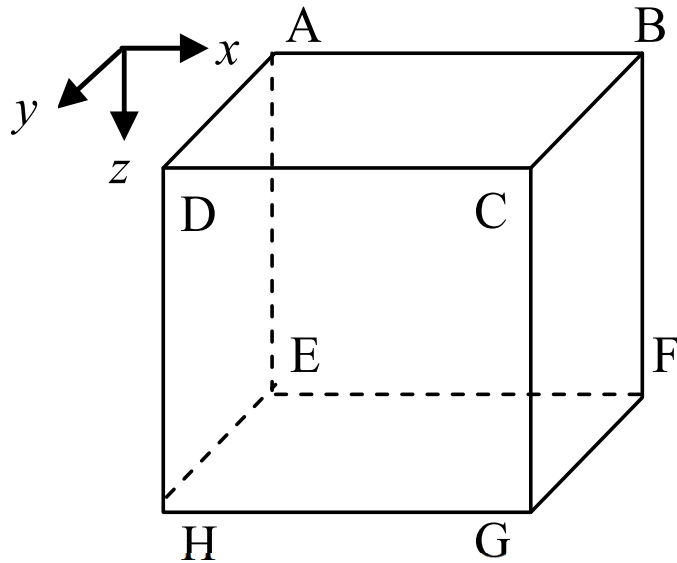
$$\varphi_m(\beta, \theta, \phi) = \frac{\cos(mk_x h) + \cos(mk_y h) + \cos(mk_z h) - 3}{r^{-2} (\cos(w\tau) - 1)},$$

(Cai et al., 2015)





Method——3D hybrid absorbing boundary condition (ABC)



x=0 slice

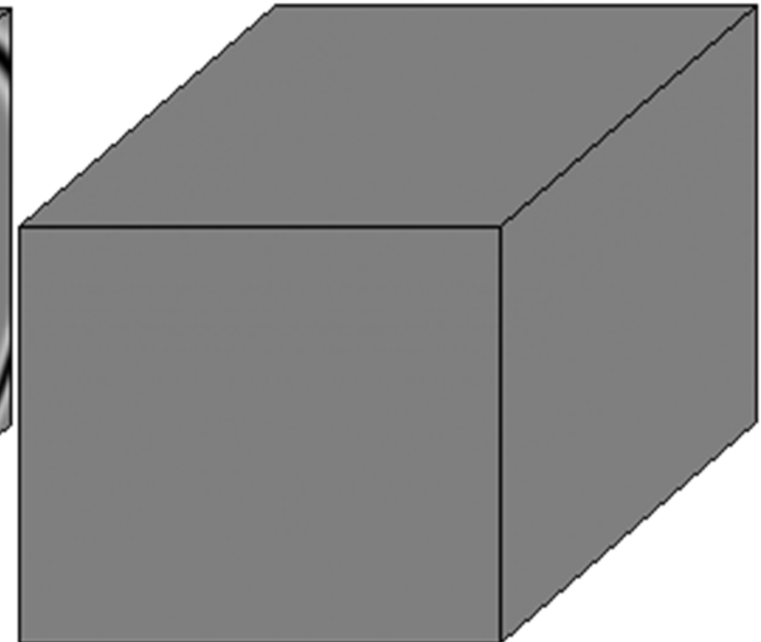
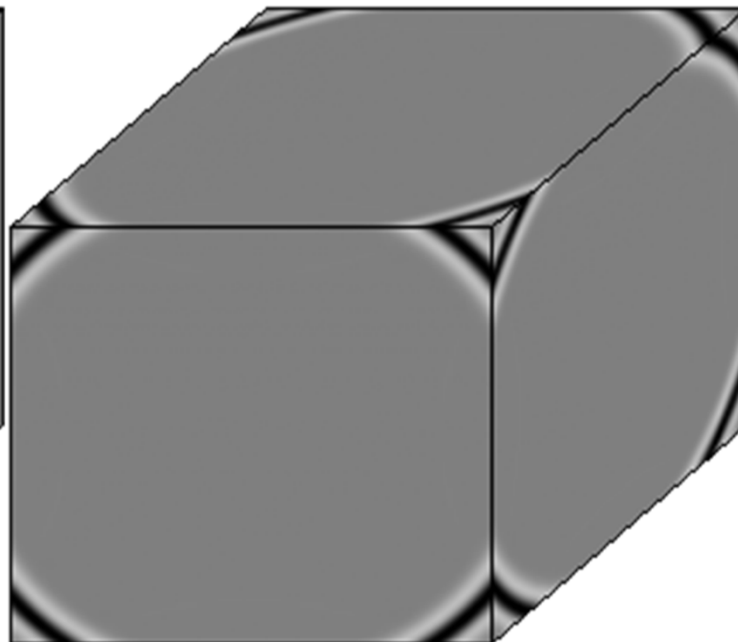
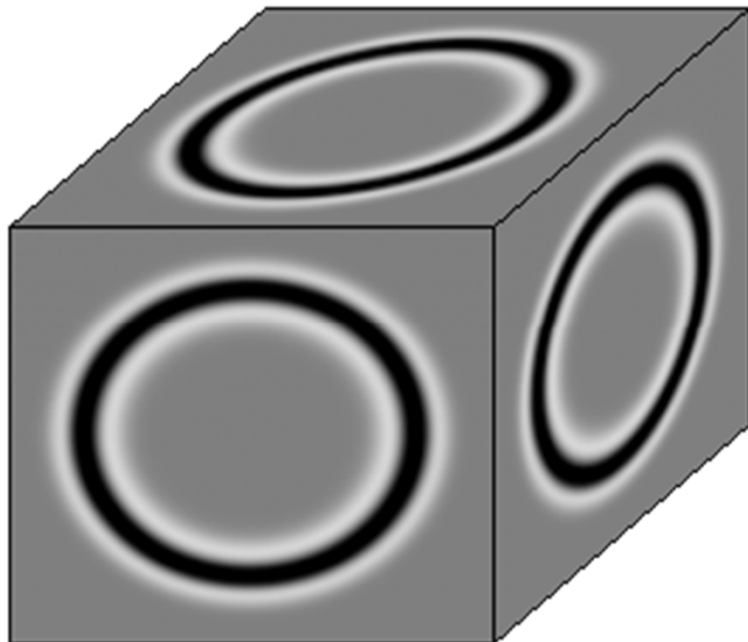
$$\frac{1}{v} \frac{\partial^2 p}{\partial t^2} - \frac{\partial^2 p}{\partial x \partial t} - \frac{v}{2} \left(\frac{\partial^2 p}{\partial y^2} + \frac{\partial^2 p}{\partial z^2} \right) = 0$$

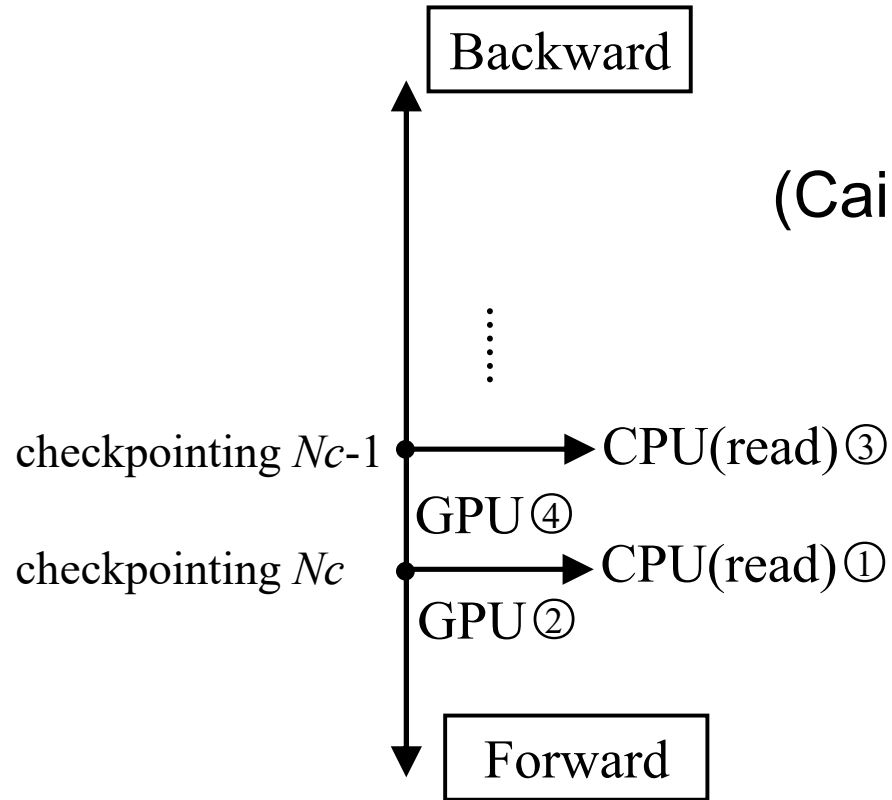
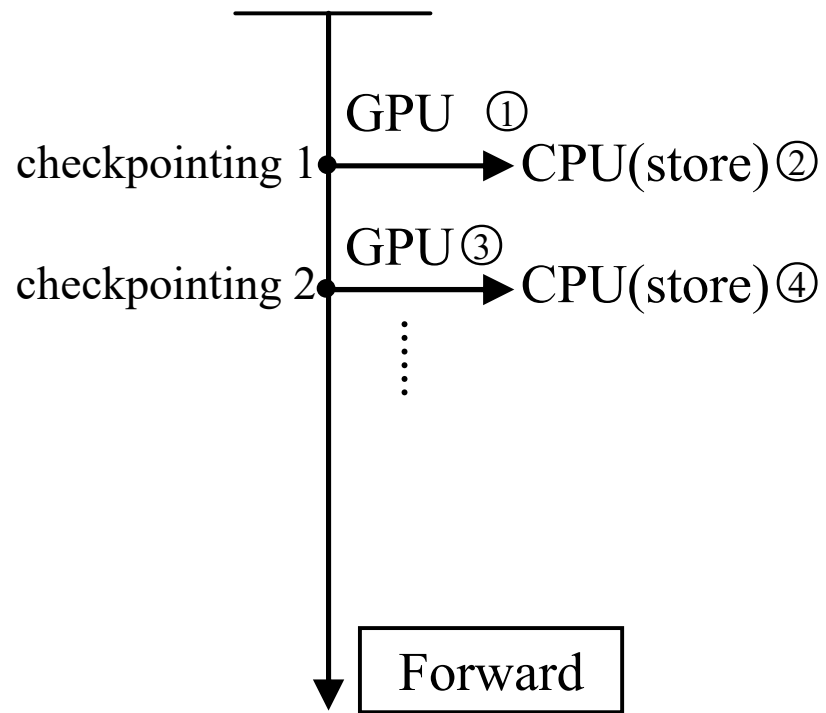
x=0, y=0 edge

$$-\frac{\partial p}{\partial x} - \frac{\partial p}{\partial y} + \frac{\sqrt{2}}{v} \frac{\partial p}{\partial t} = 0$$

x=0, y=0, z=0 corner

$$-\frac{\partial p}{\partial x} - \frac{\partial p}{\partial y} - \frac{\partial p}{\partial z} + \frac{1 + \sqrt{2}}{v} \frac{\partial p}{\partial t} = 0$$





(Cai et al., 2018)

Imaging condition:

$$Image(x, y, z) = \frac{\sum_{time} S(x, y, z, t) R(x, y, z, t)}{\sum_{time} S^2(x, y, z, t)}$$

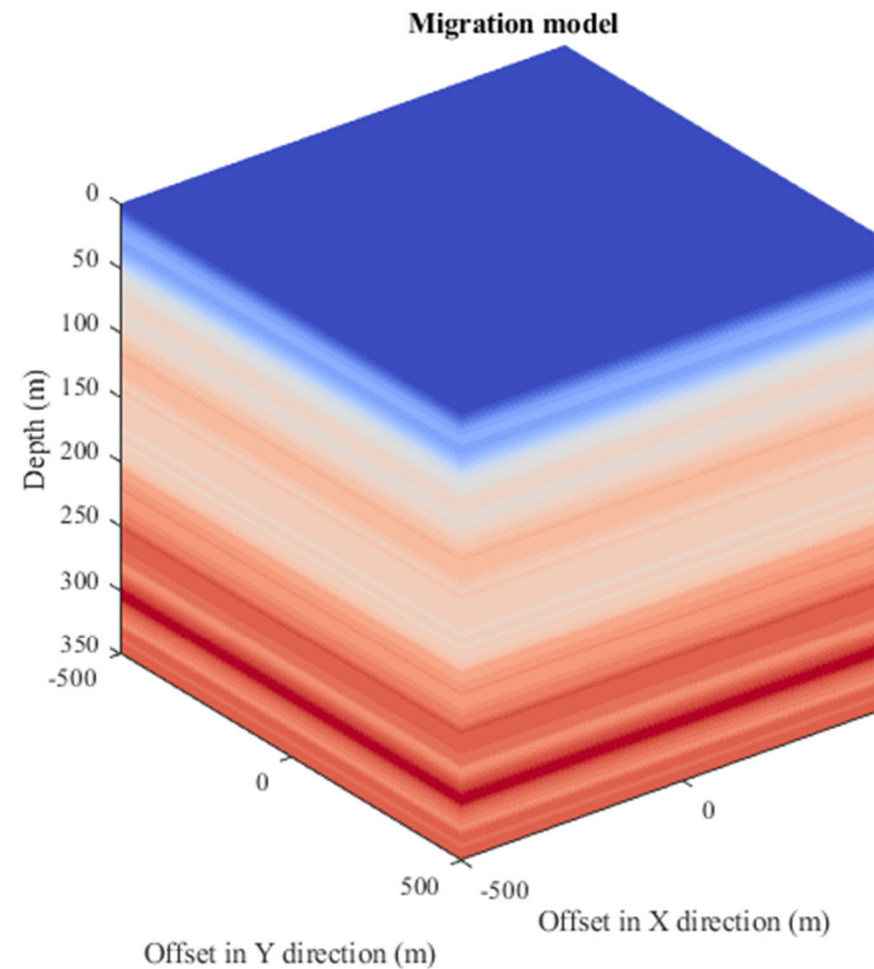
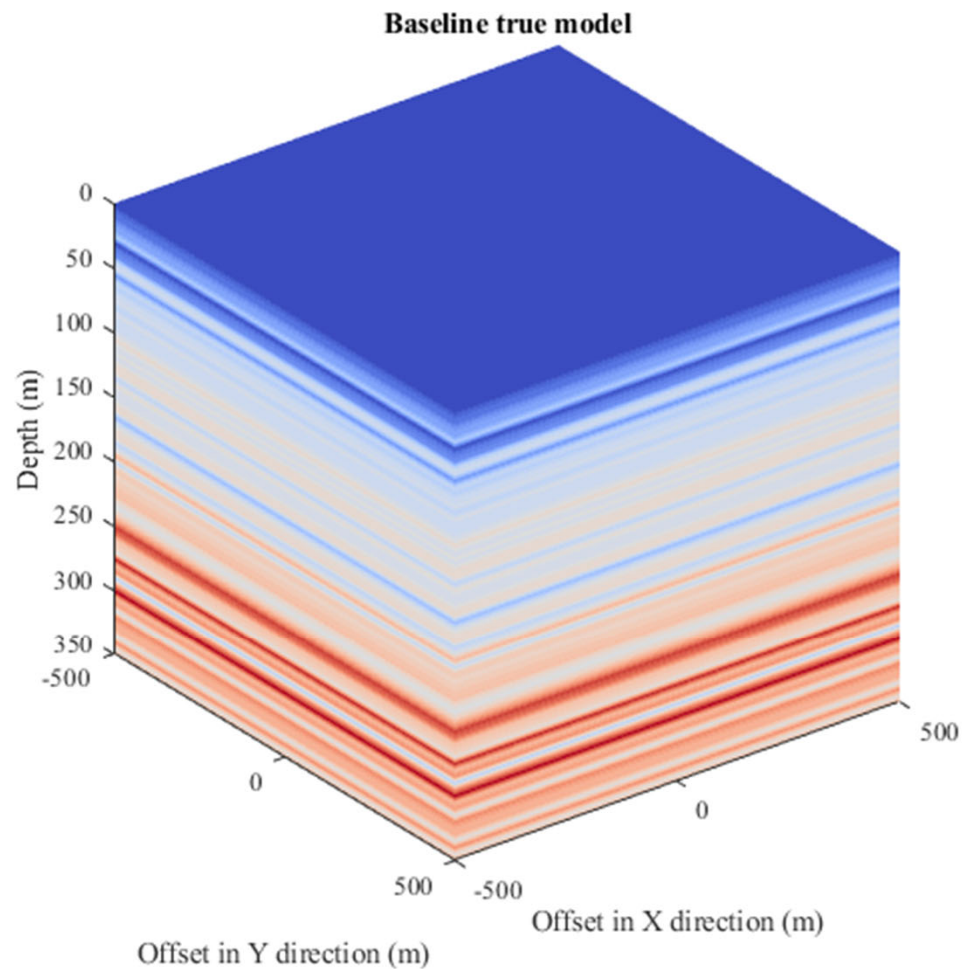
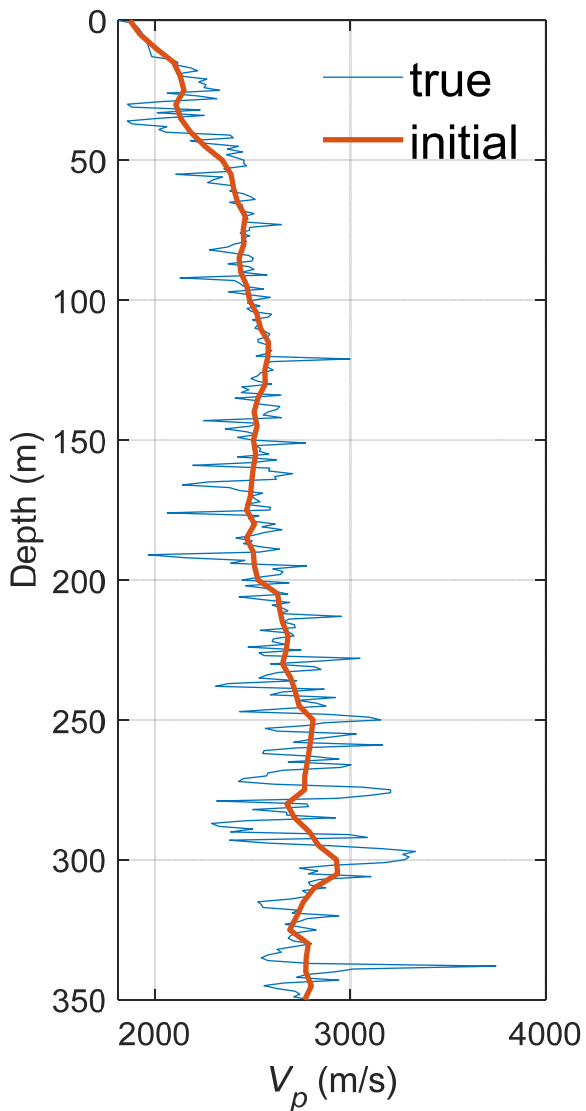
(Chattopadhyay and McMechan, 2008)



Synthetic Test—Snowflake model example

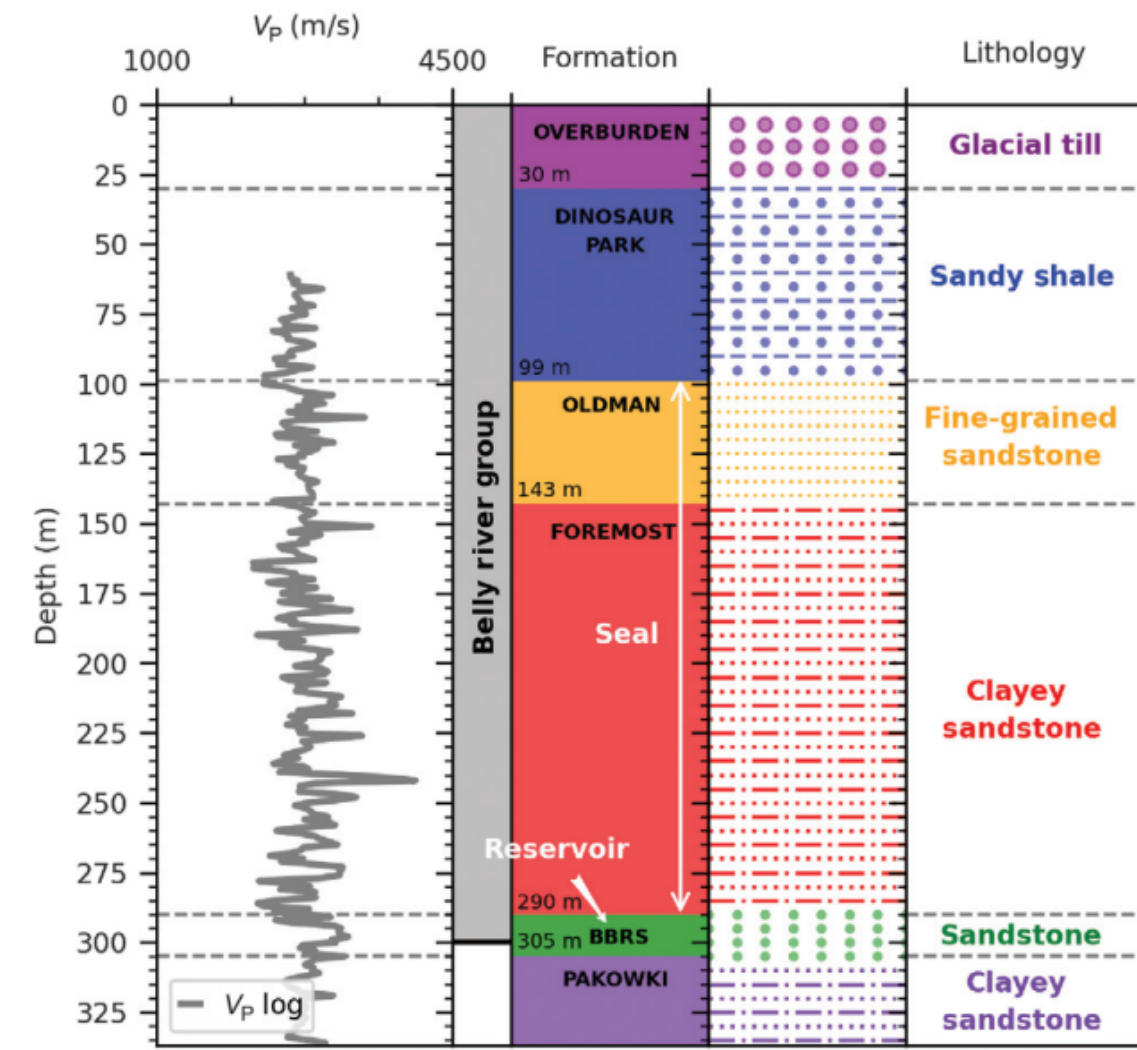
Size: 201*201*71

Space interval: 5 m * 5 m * 5 m

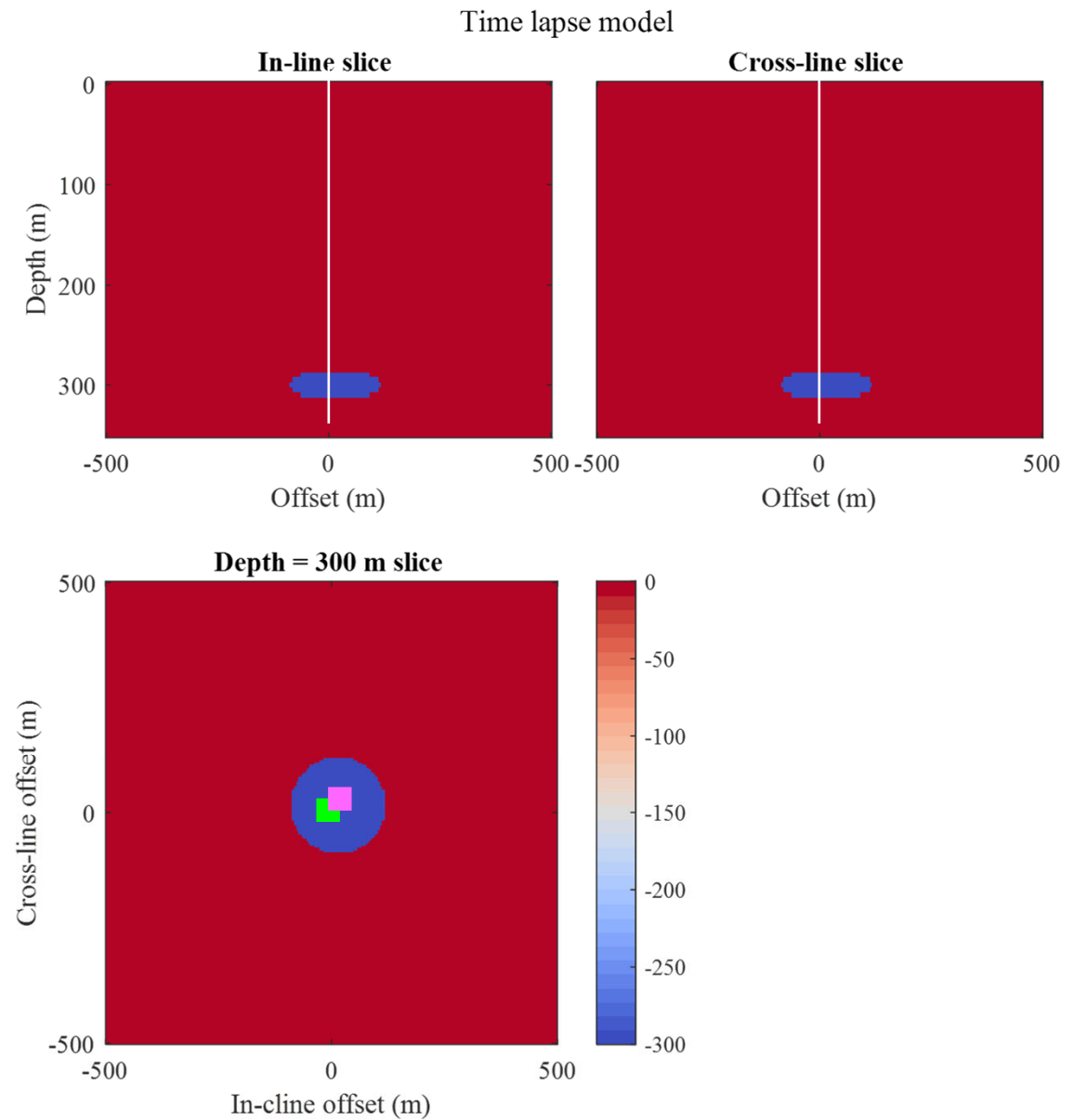




Synthetic Test — Snowflake model example

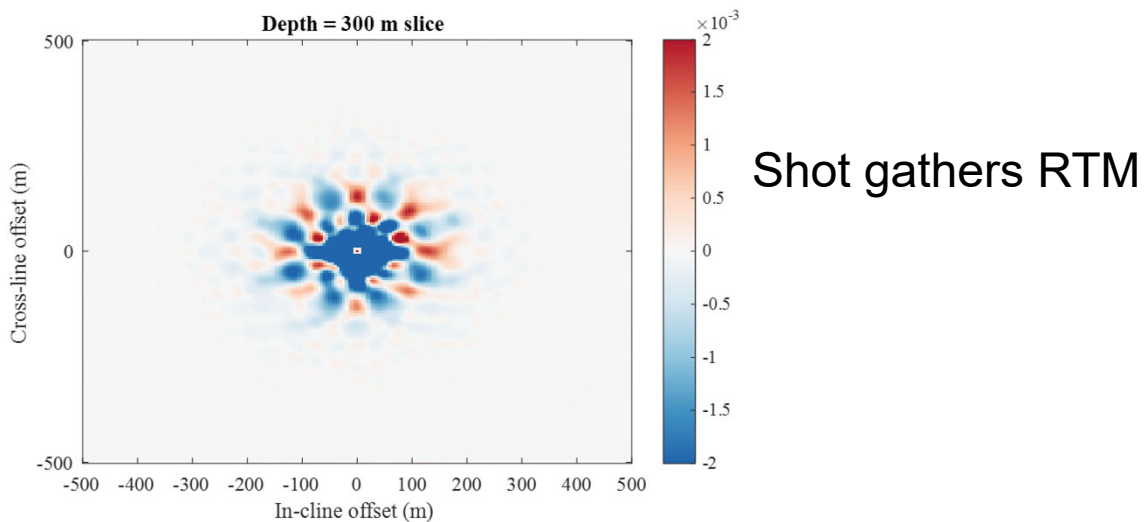
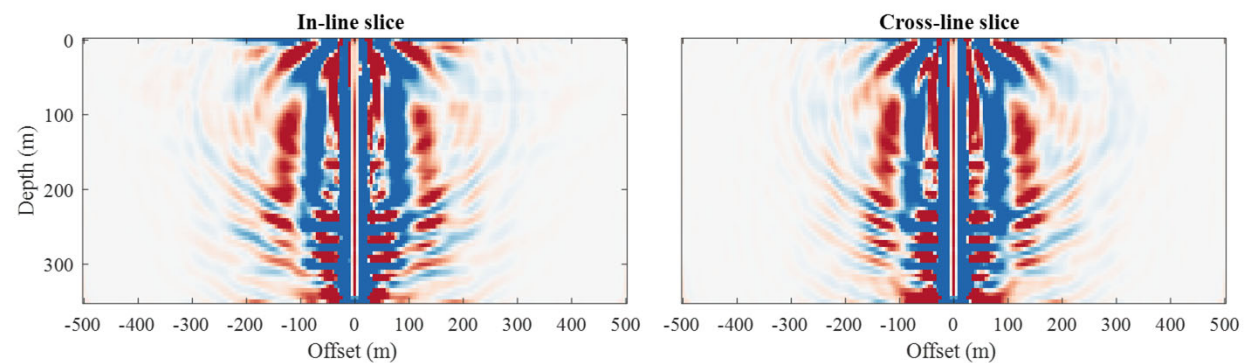


(Pan et al, 2023)

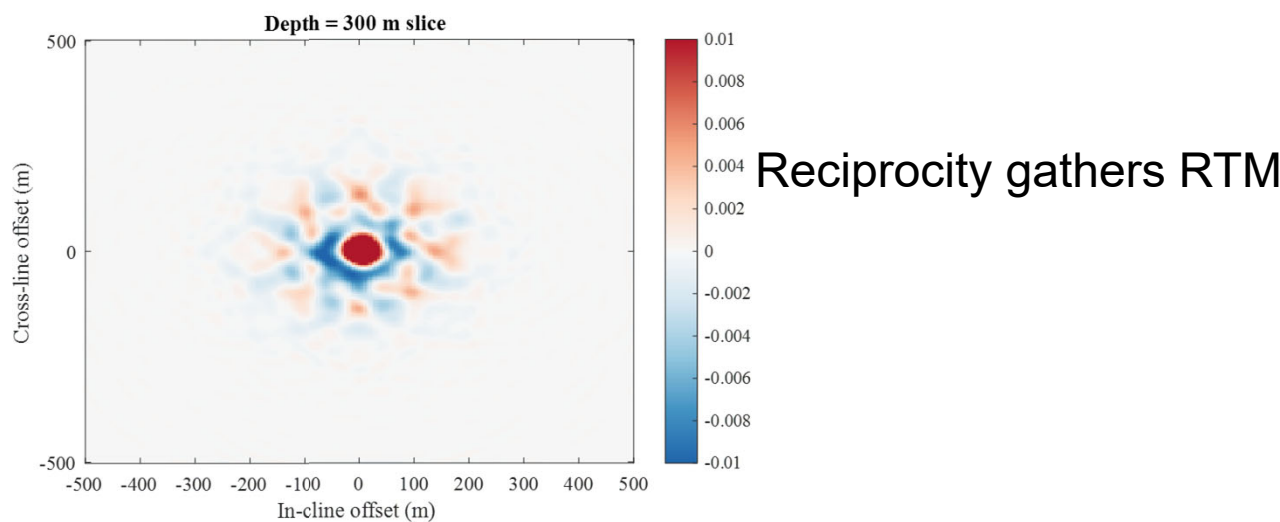
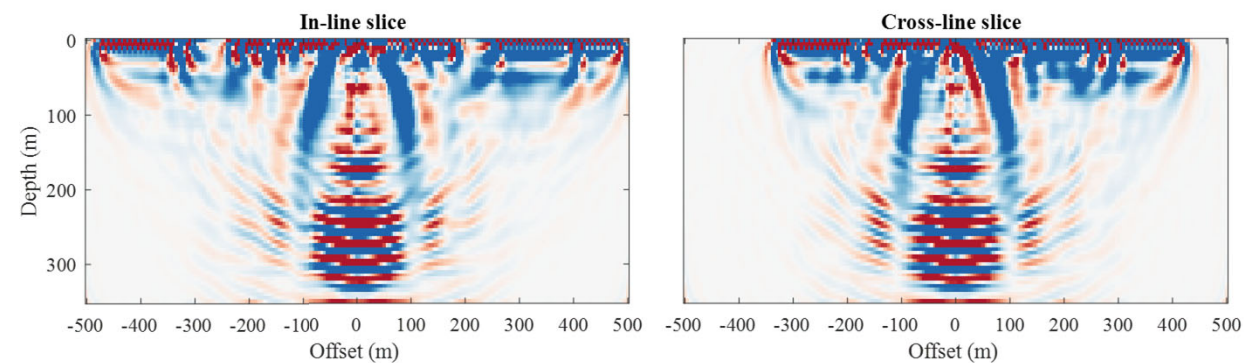




Synthetic Test—Baseline data RTM result



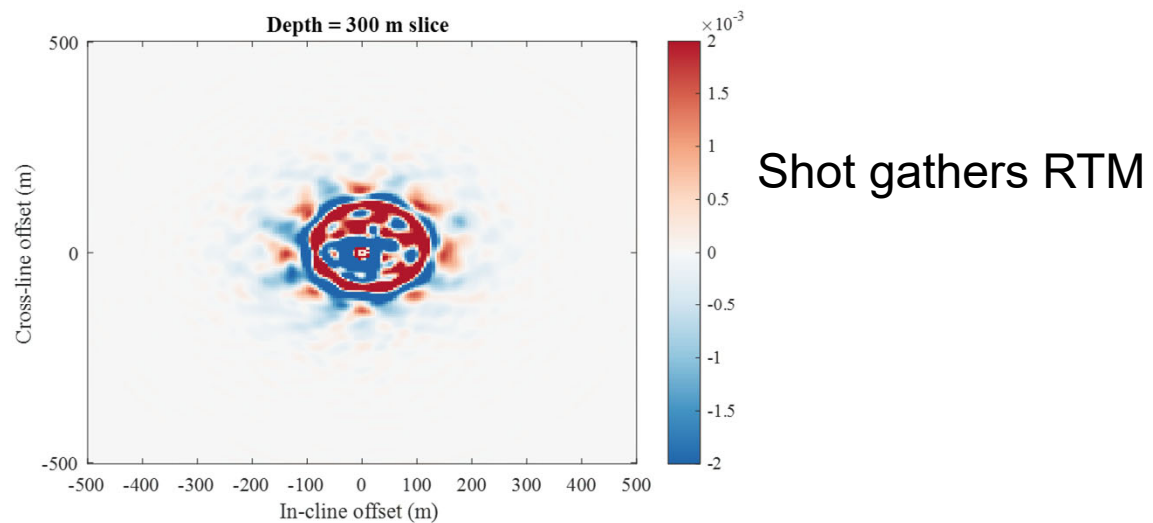
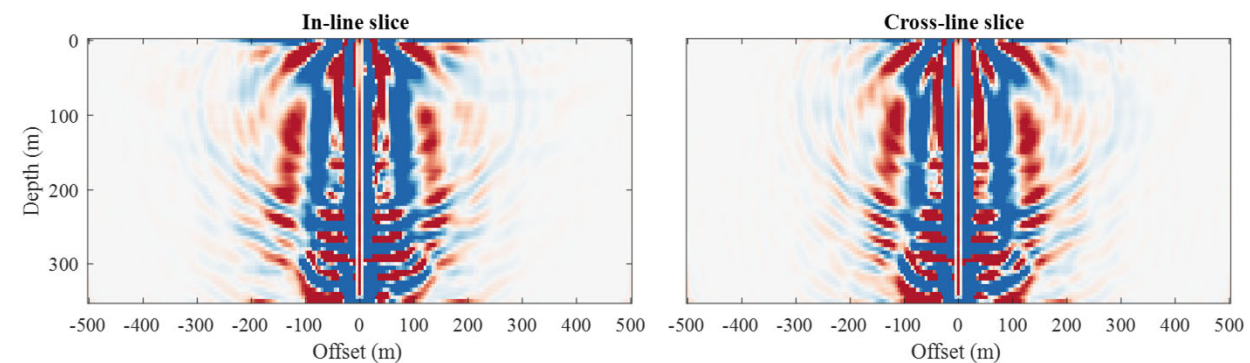
3617 seconds



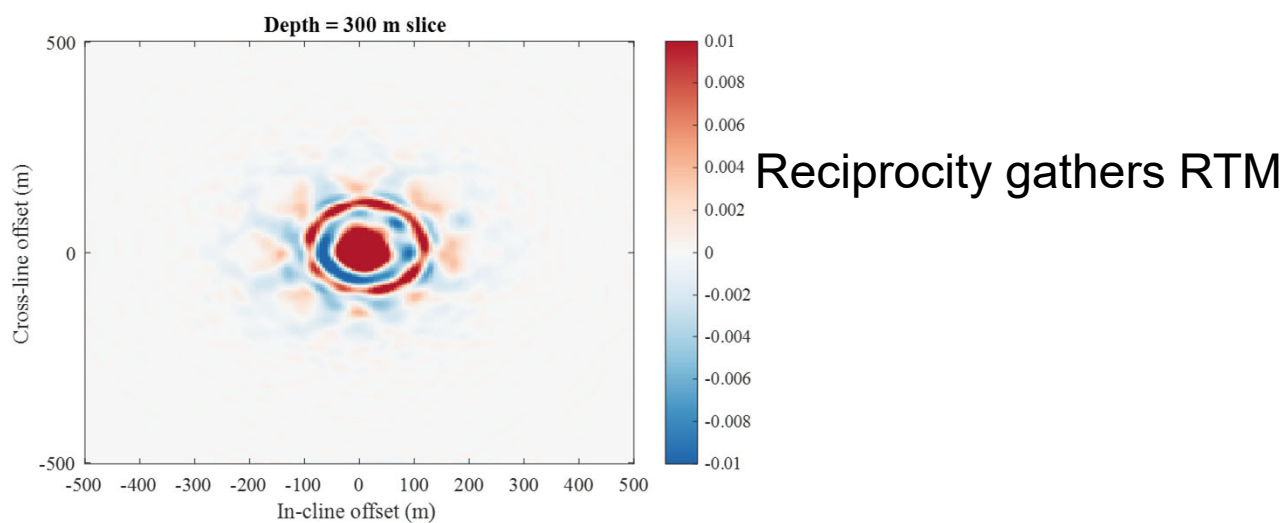
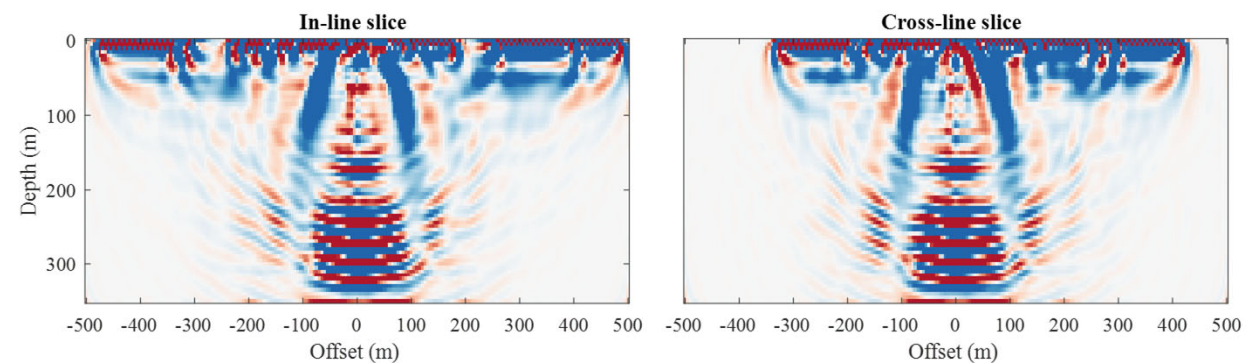
5896 seconds



Synthetic Test——Monitor data RTM result



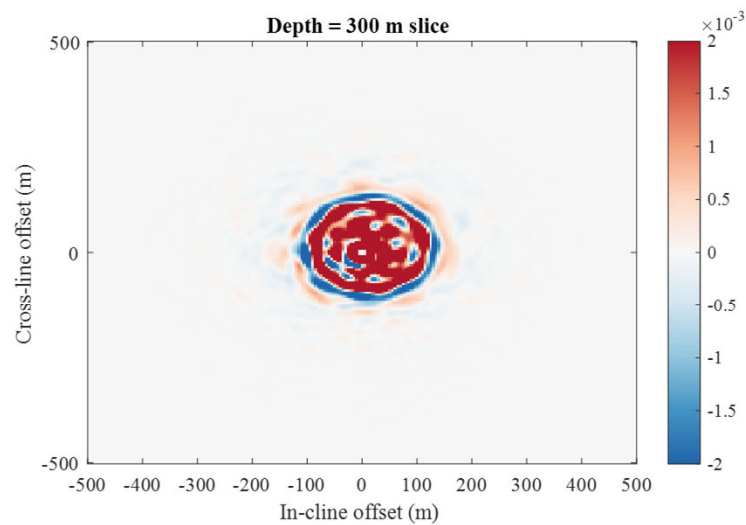
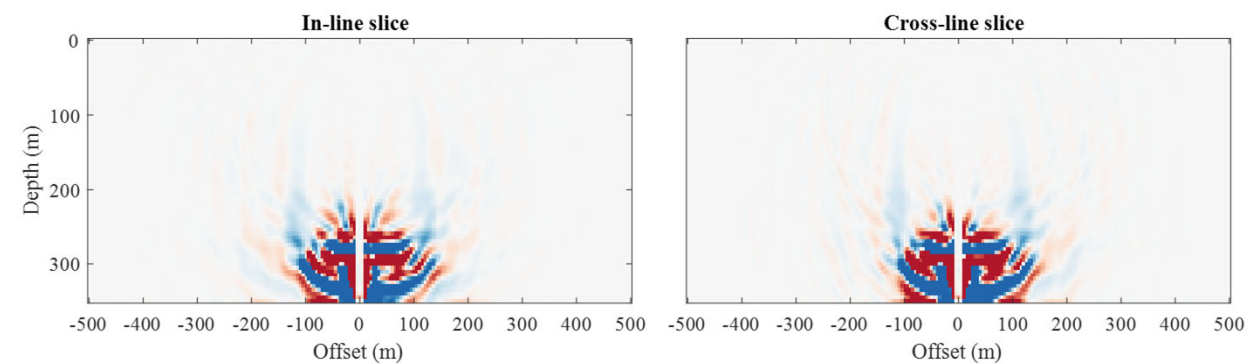
3536 seconds



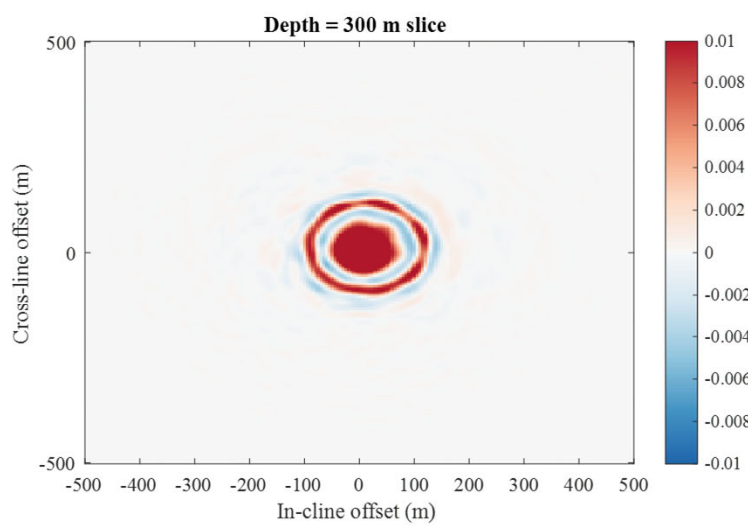
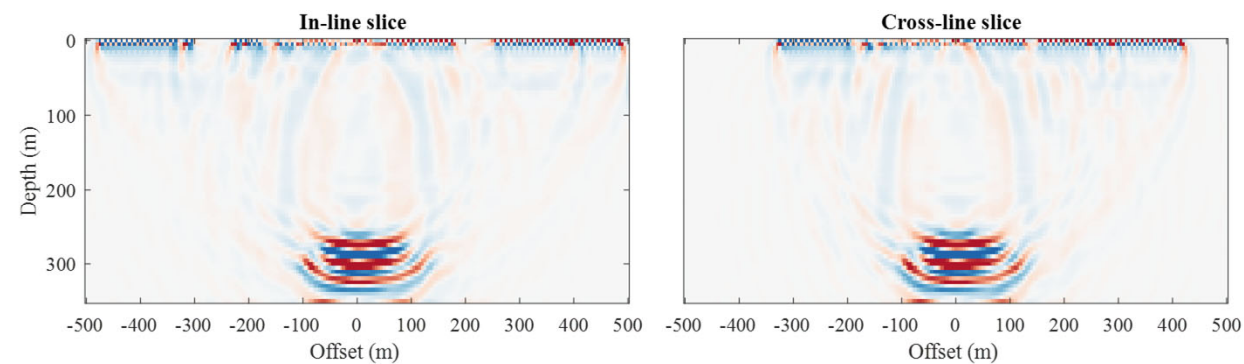
5910 seconds



Synthetic Test—Difference



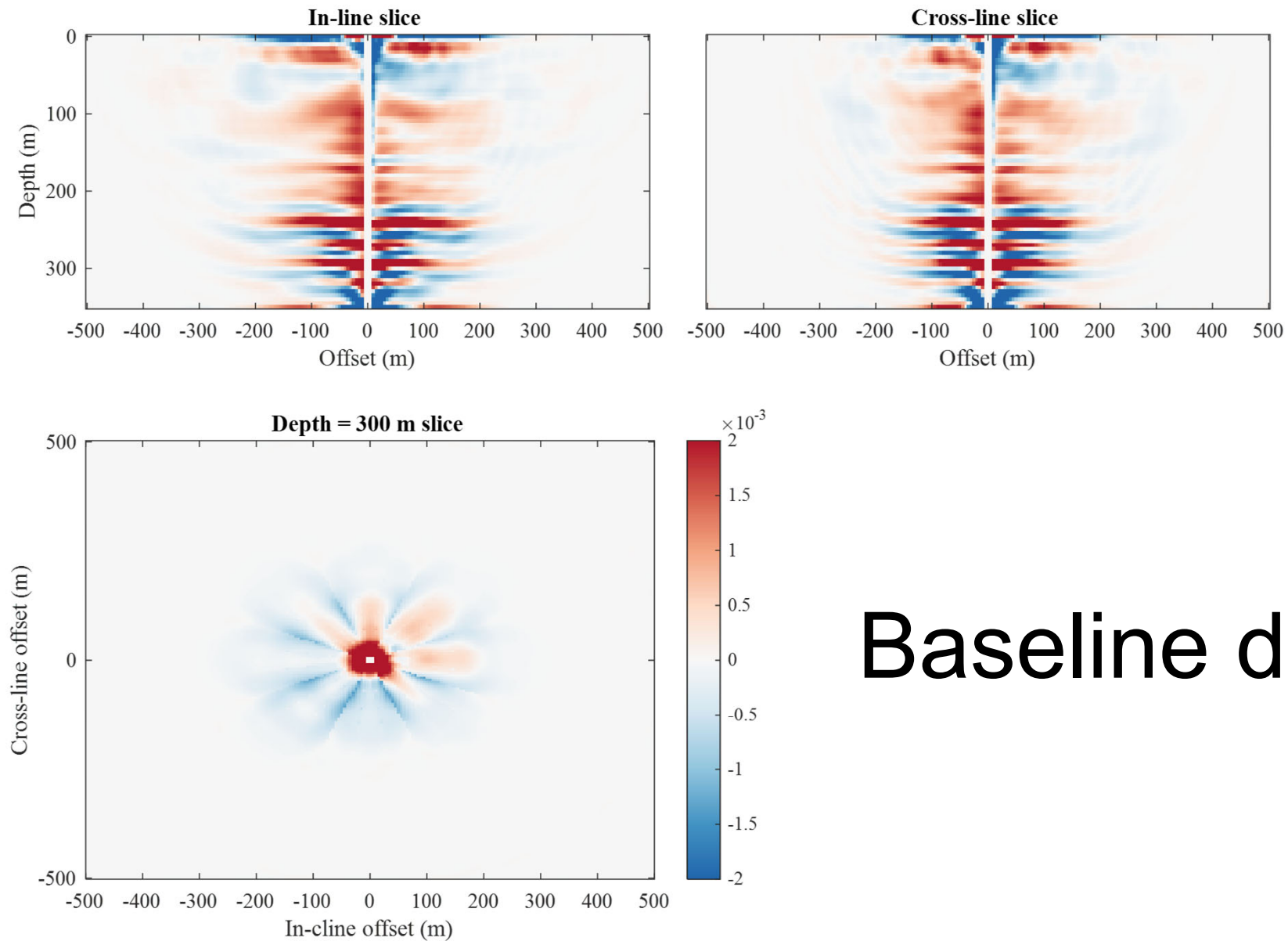
Shot gathers RTM



Reciprocity gathers RTM



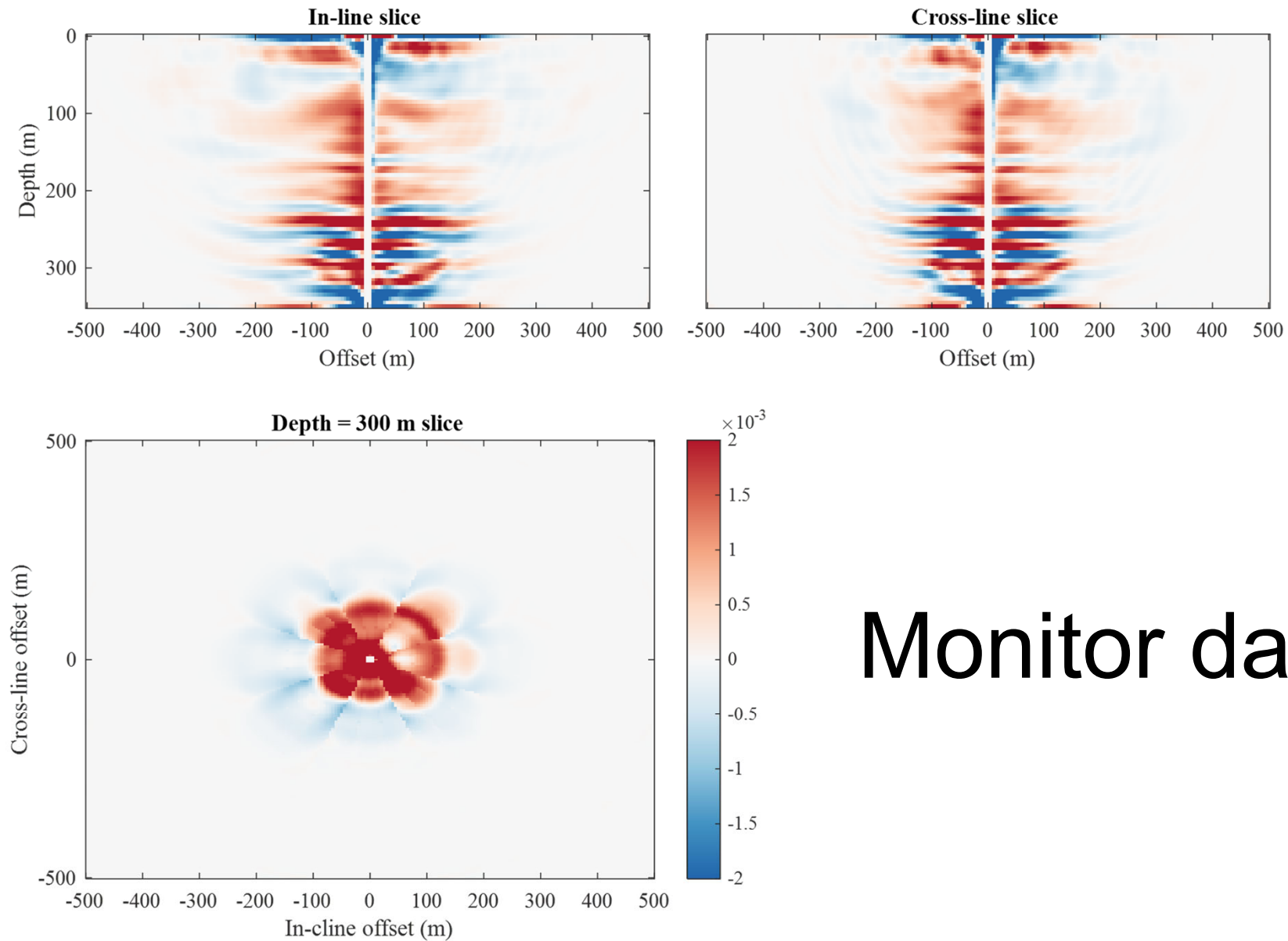
Synthetic Test—3D azimuth-dependent RTM result



Baseline data



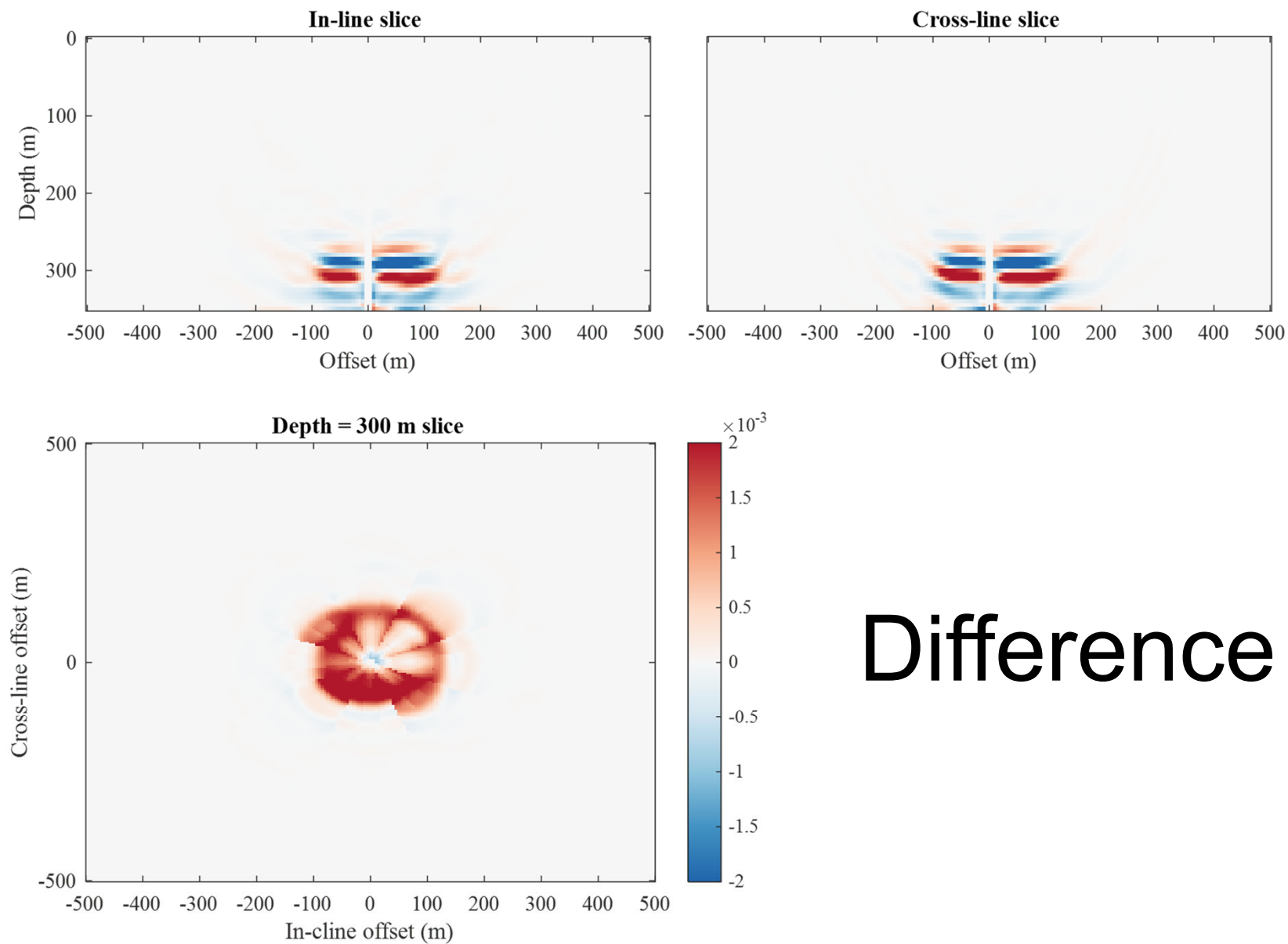
Synthetic Test—3D azimuth-dependent RTM result



Monitor data

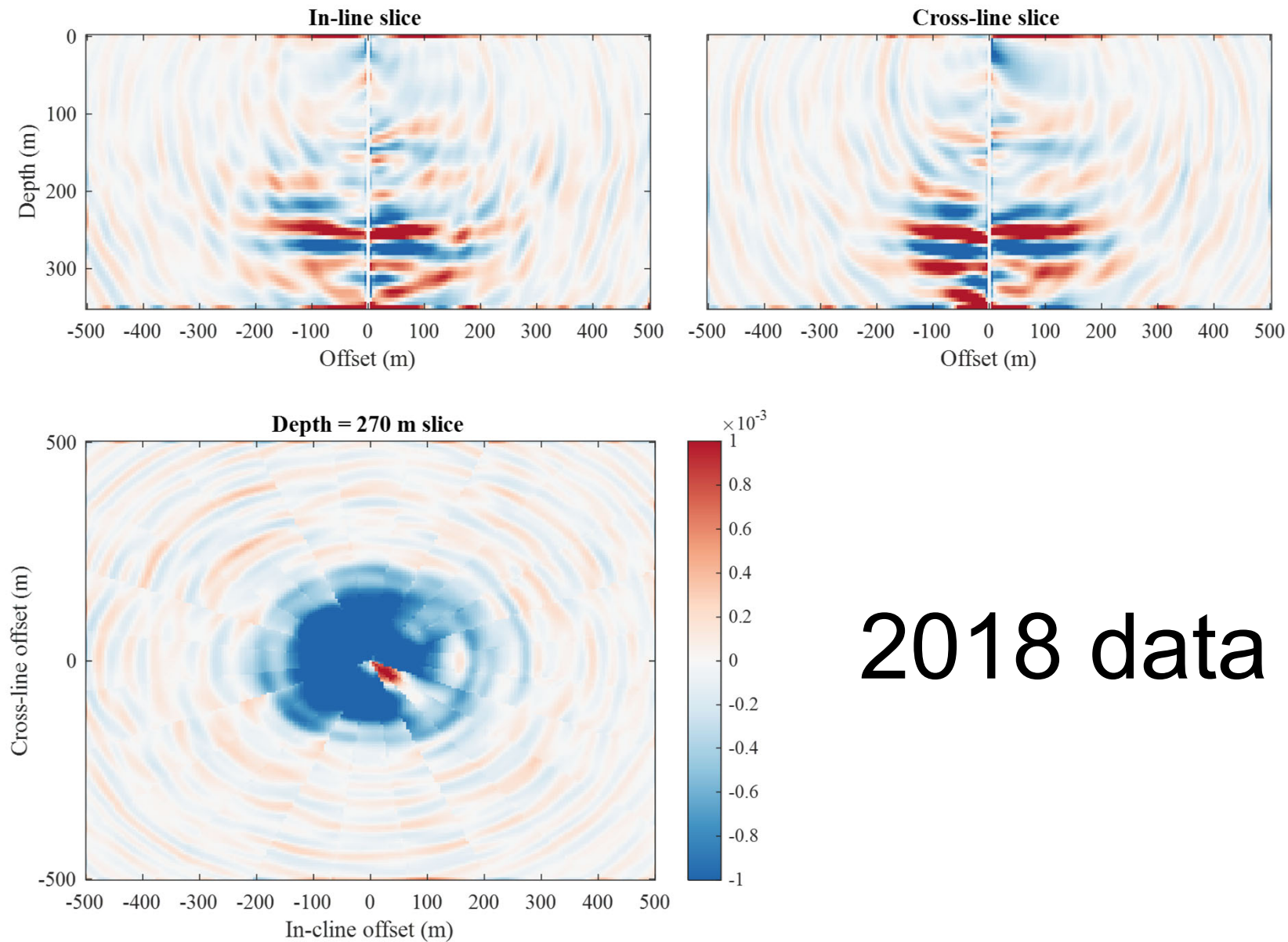


Synthetic Test—3D azimuth-dependent RTM result





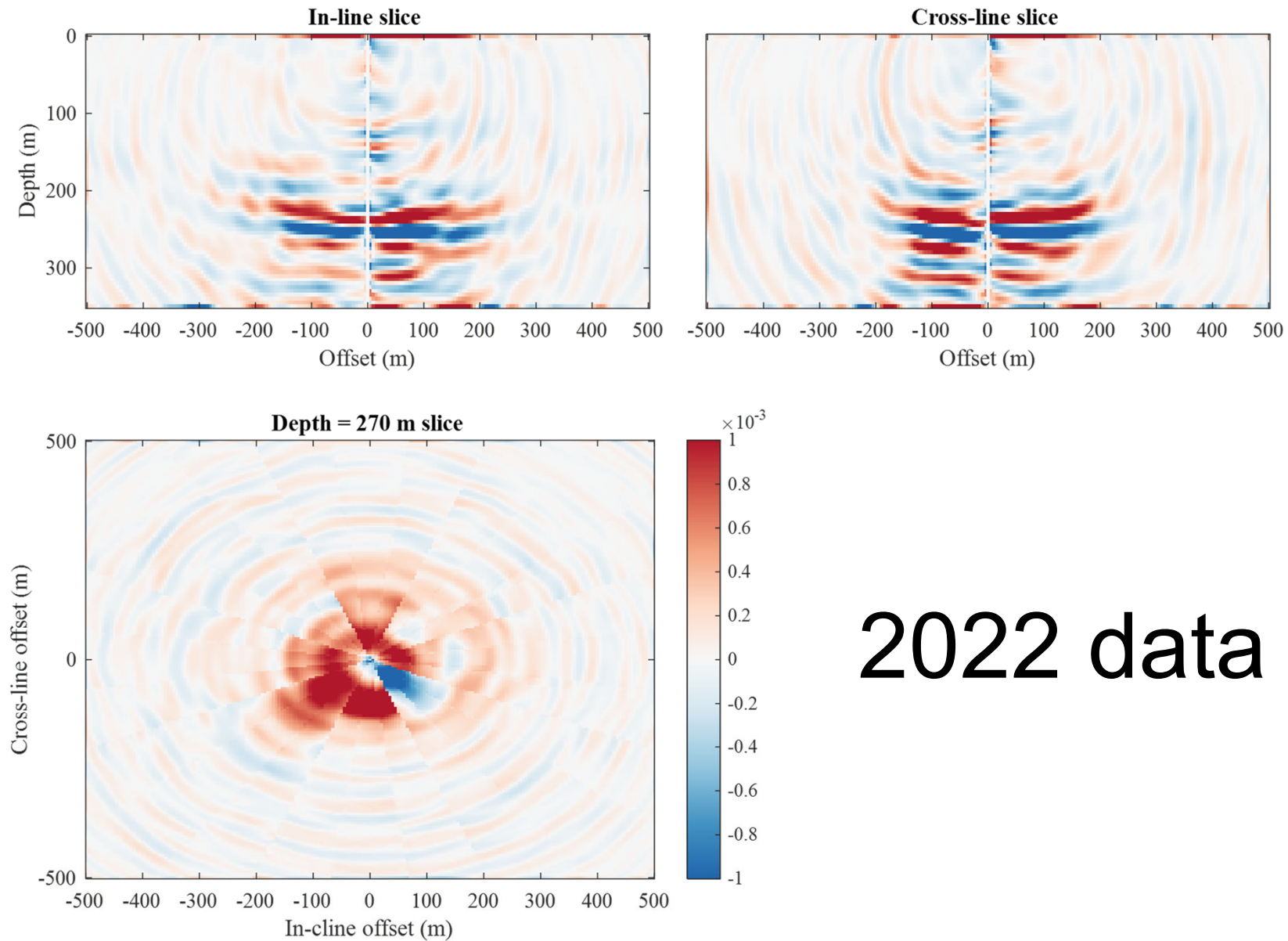
Field data—3D azimuth-dependent RTM result



2018 data



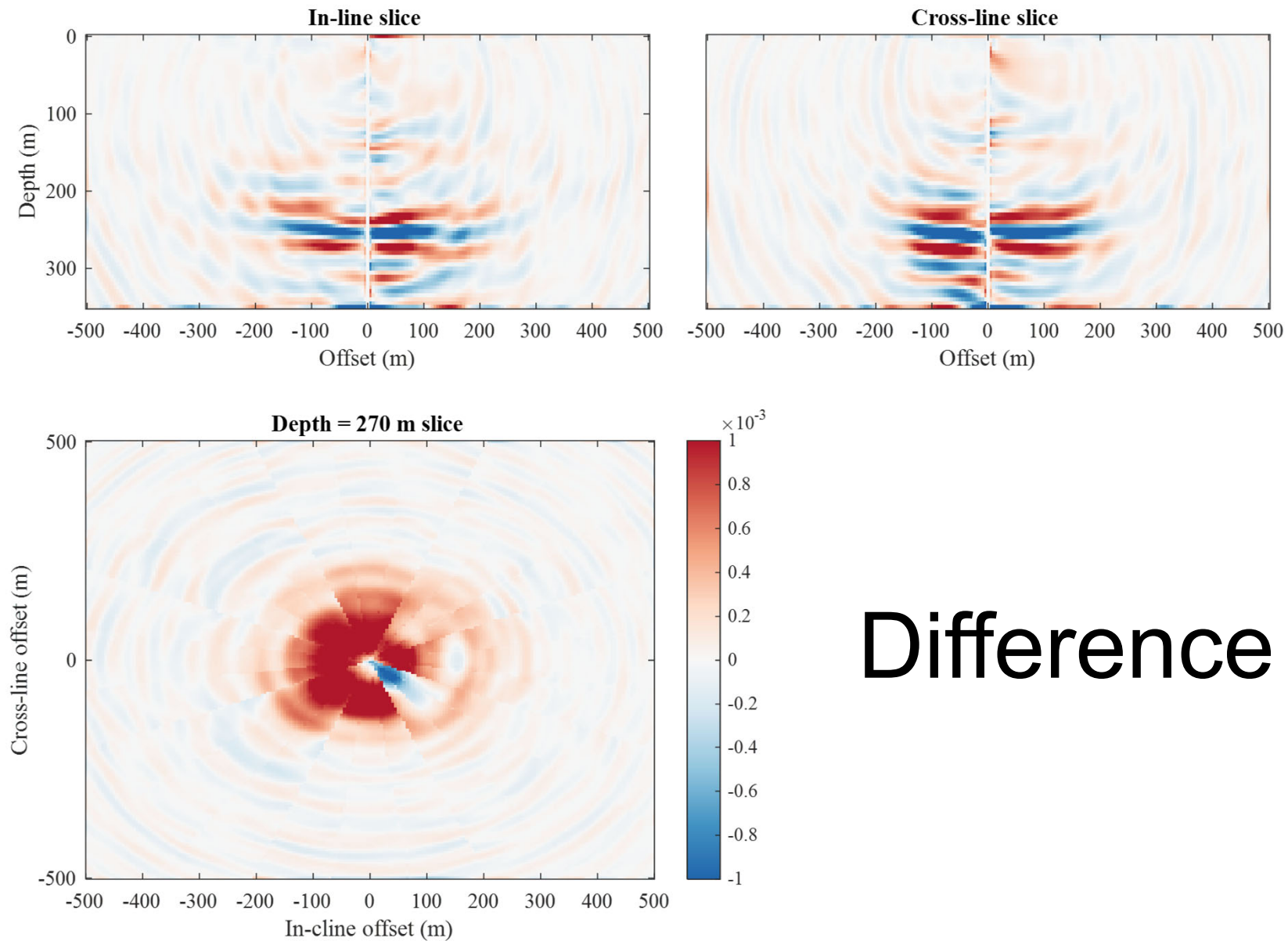
Field data—3D azimuth-dependent RTM result



2022 data



Field data—3D azimuth-dependent RTM result



- Conclusions
 - Processing of the low signal-to-ratio DAS data is crucial
 - Azimuthal geometry makes the introduction of azimuth-dependent RTM essential.
 - The 3D time-lapse imaging serve as a source of inspiration for the low-cost CO2 monitoring: DAS, VSP
- Next steps
 - Reflection angle-dependent RTM
 - 3D Elastic LSRTM, FWI



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