

# Mitigating elastic effects of acoustic full waveform inversion for VSP data via deep learning

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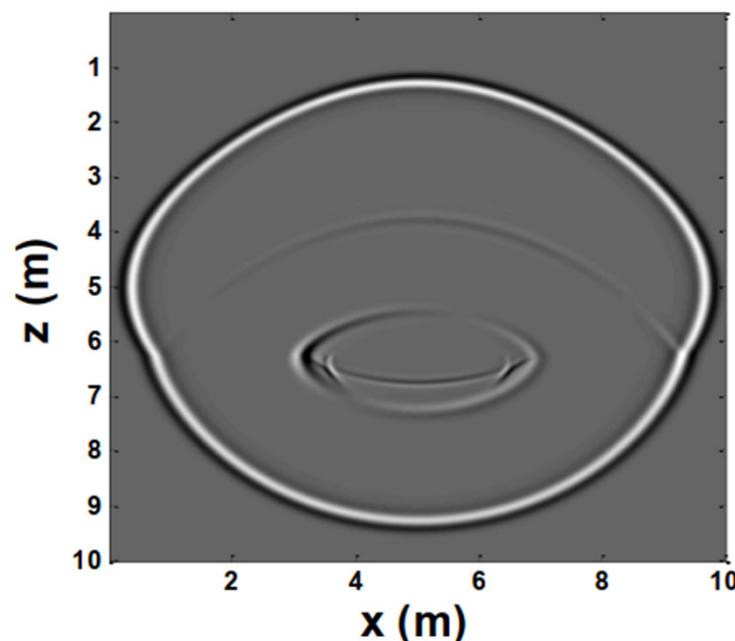


- Motivation
- Method of mitigating elastic effects
- Neural network training results
- Acoustic FWI results
- Time-lapse results
- Conclusions



## Acoustic FWI

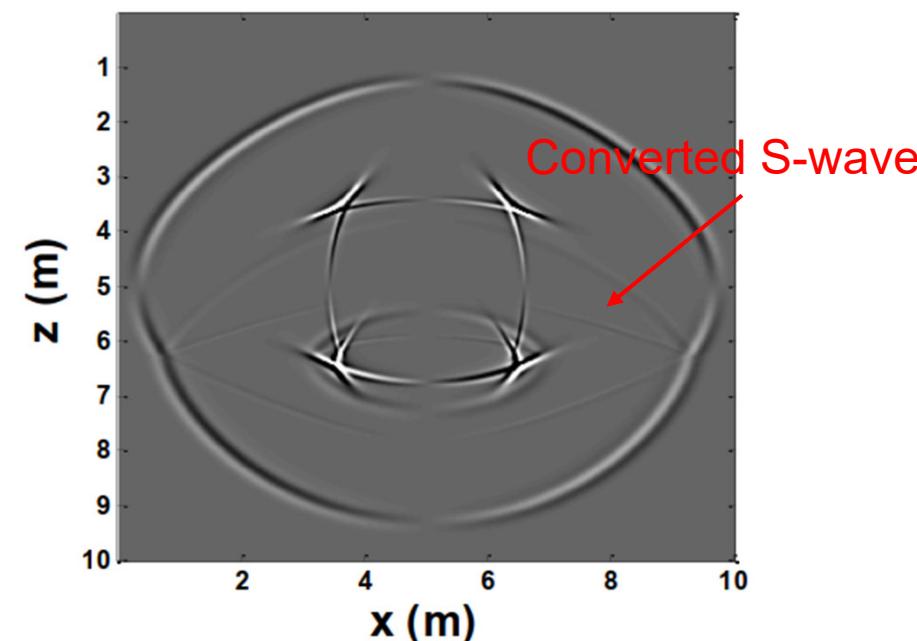
- Efficient and robust
- Less correct due to neglecting elastic effects in the recorded field data



P-wave

## Elastic FWI

- Higher computational costs
- Physically more correct since the observed data do have elastic effects resulting from PS and SP-wave conversions

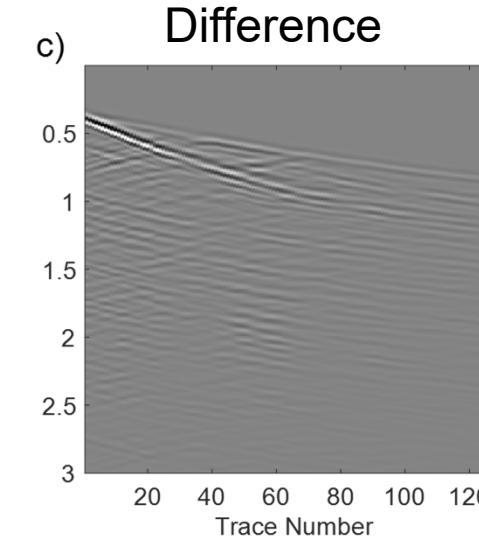
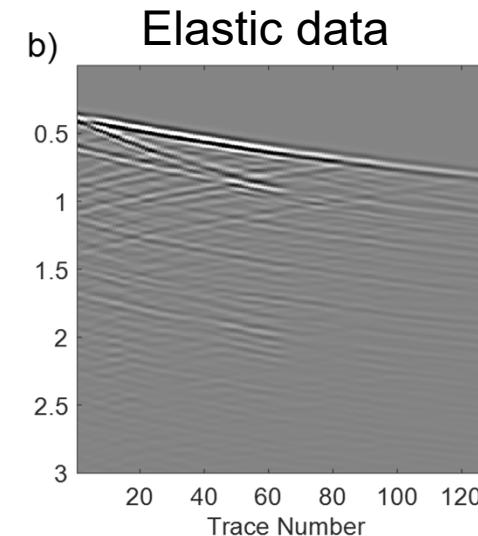
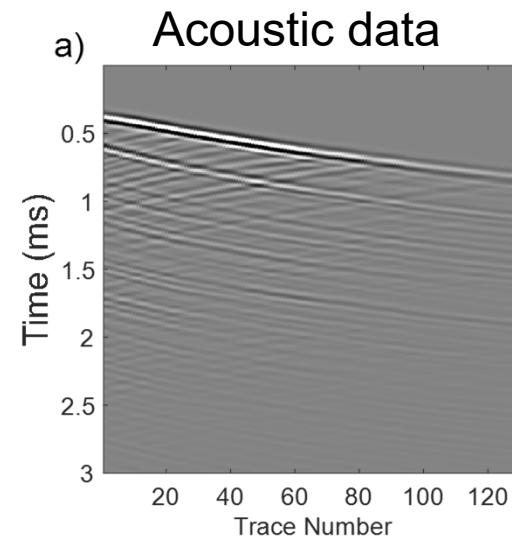


P-wave + S-wave



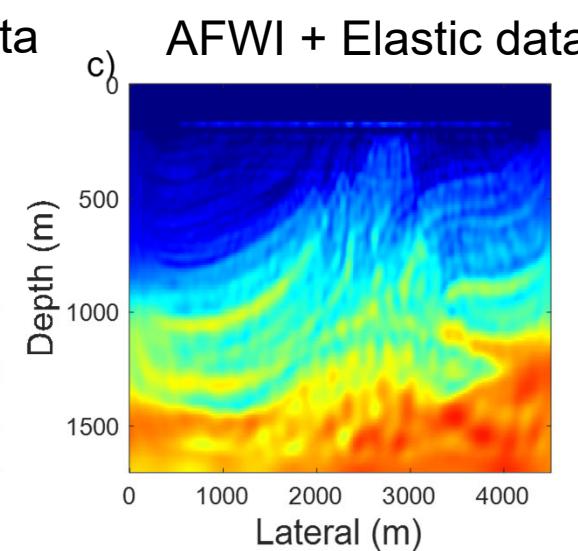
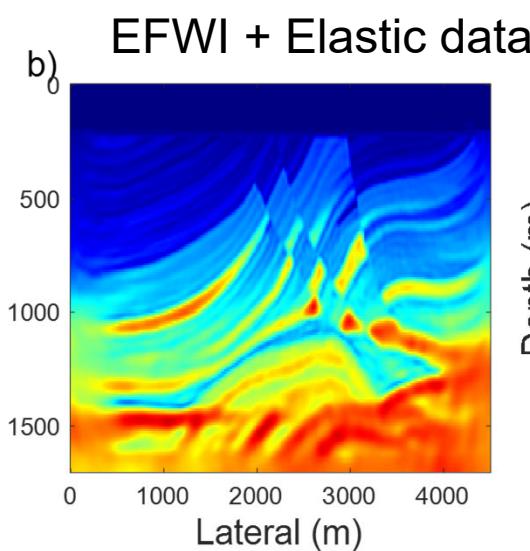
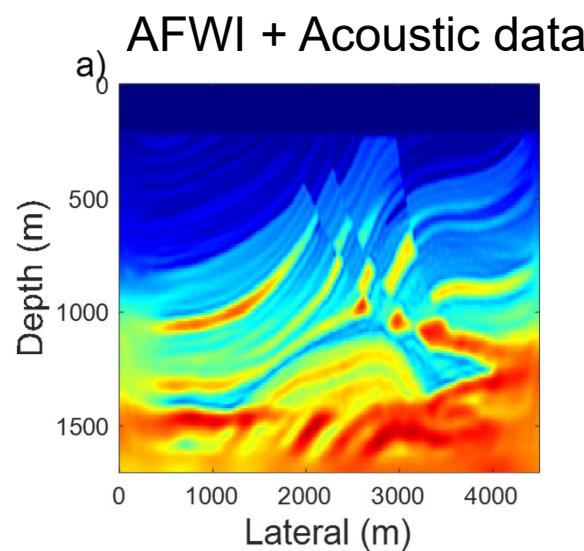
# Motivation

## Surface survey



### Correction methods:

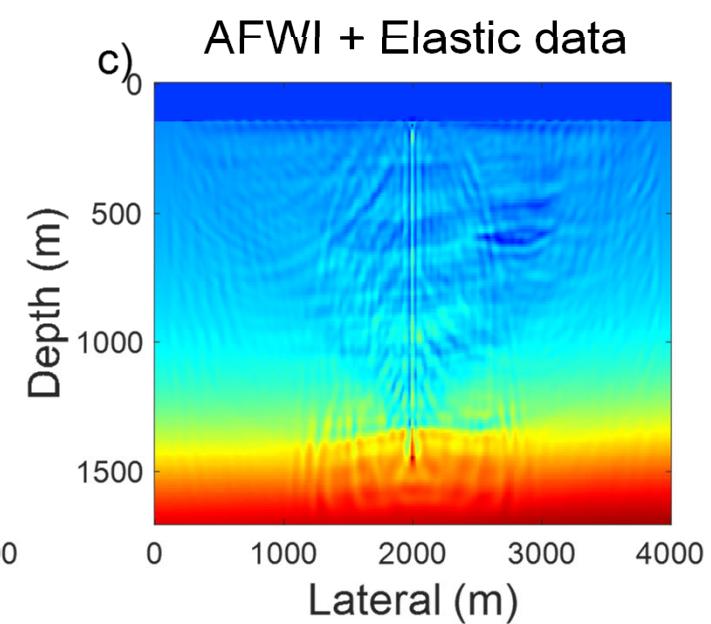
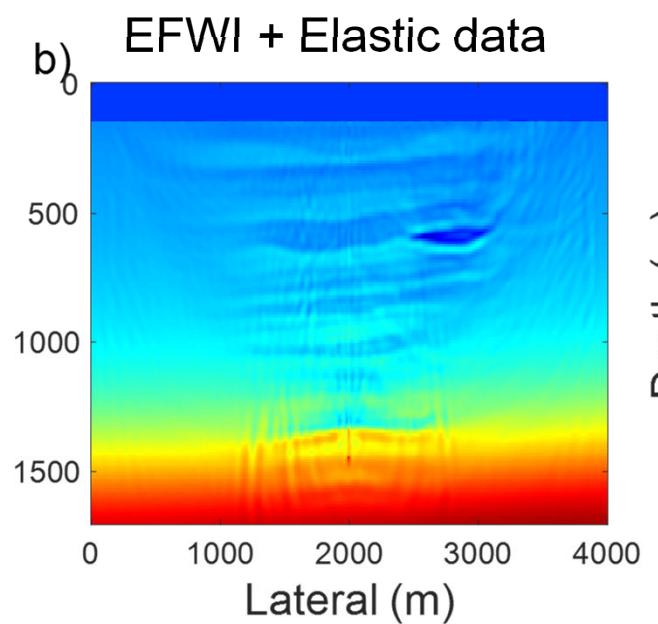
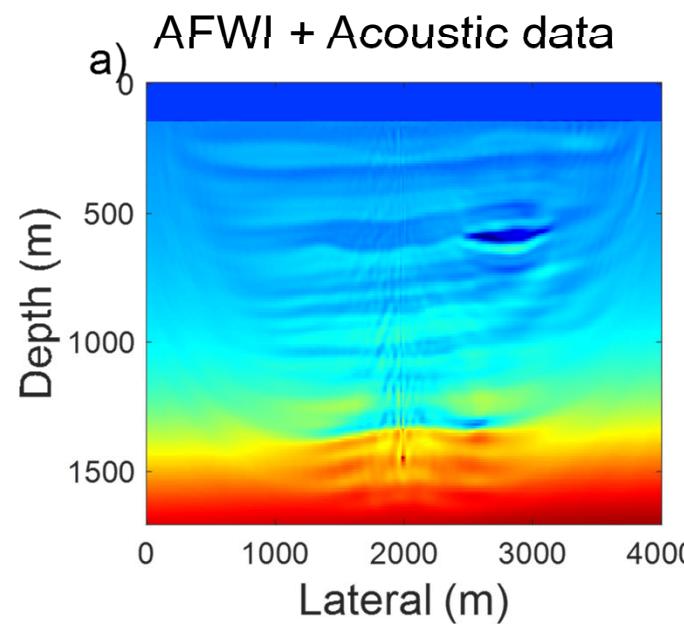
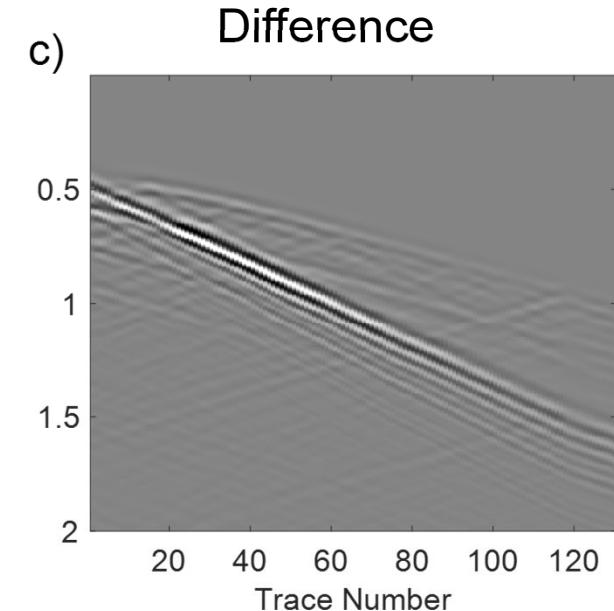
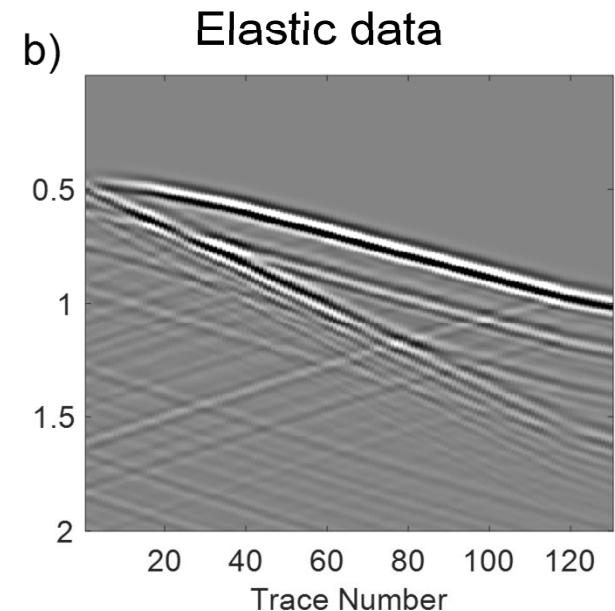
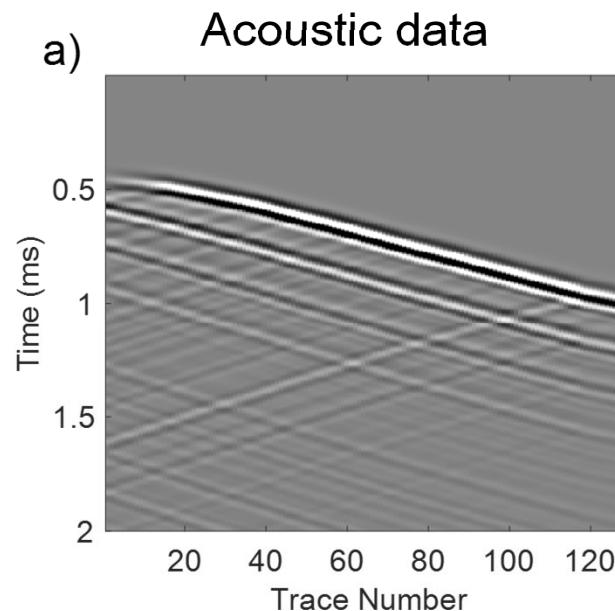
- acoustic wave equation (Chapman et al., 2014; Hobro et al., 2014)
- elastic data using matching filters (Agudo et al., 2018)
- elastic data using deep learning (Li et al., 2019; Voytan et al., 2022)
- gradient using GANs (Yao et al., 2020)





# Motivation

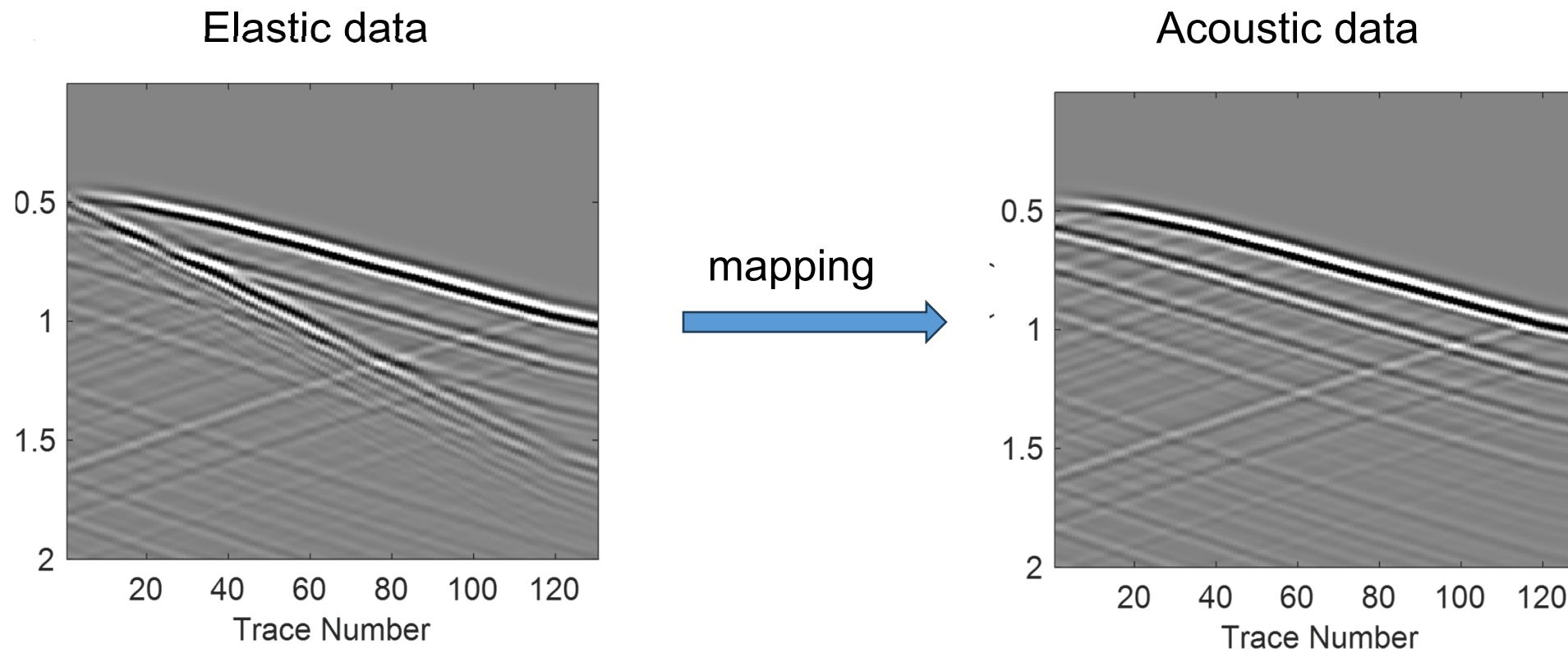
VSP survey





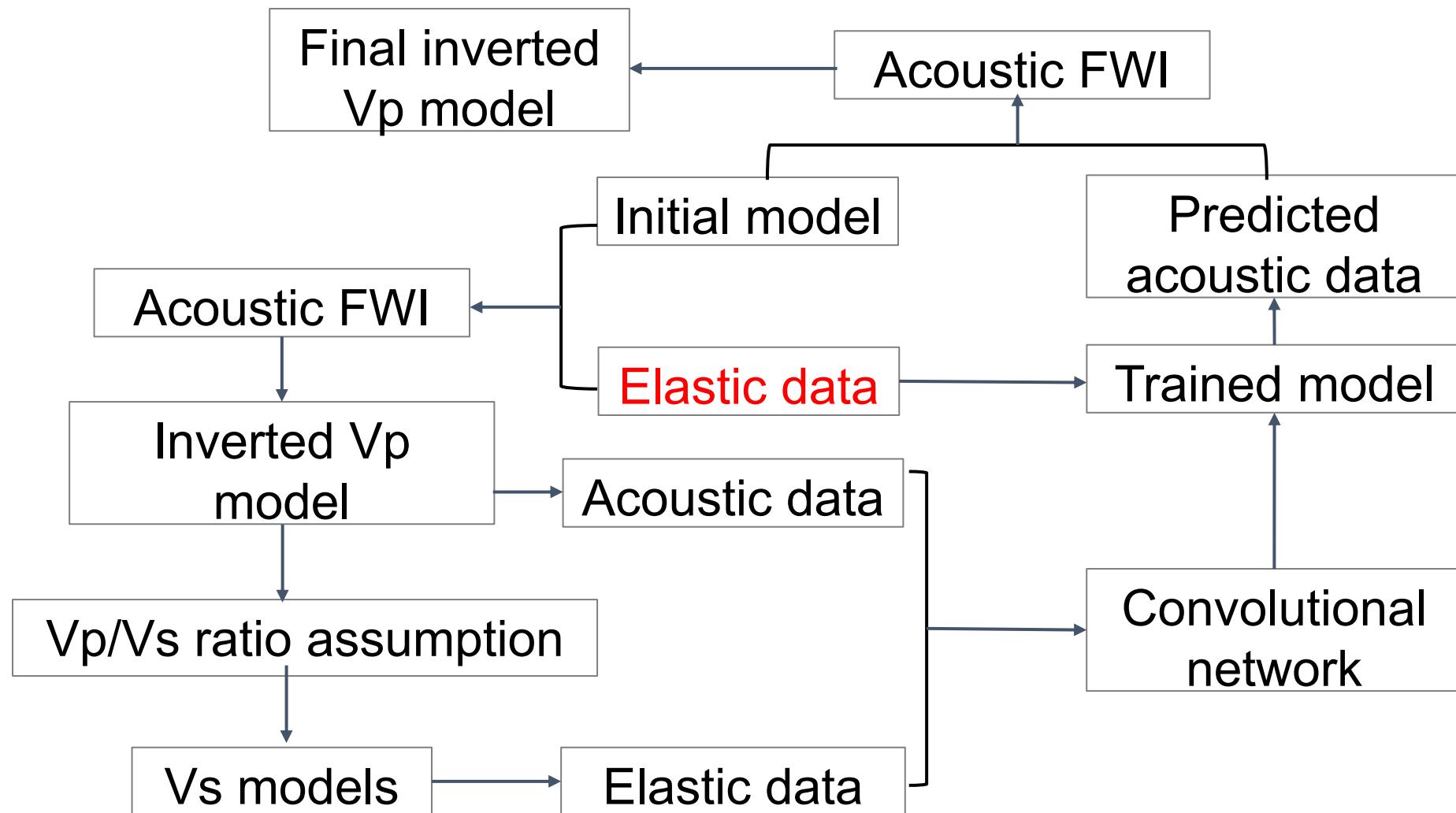
# Mitigate the elastic effects in AFWI for VSP data

## Data domain



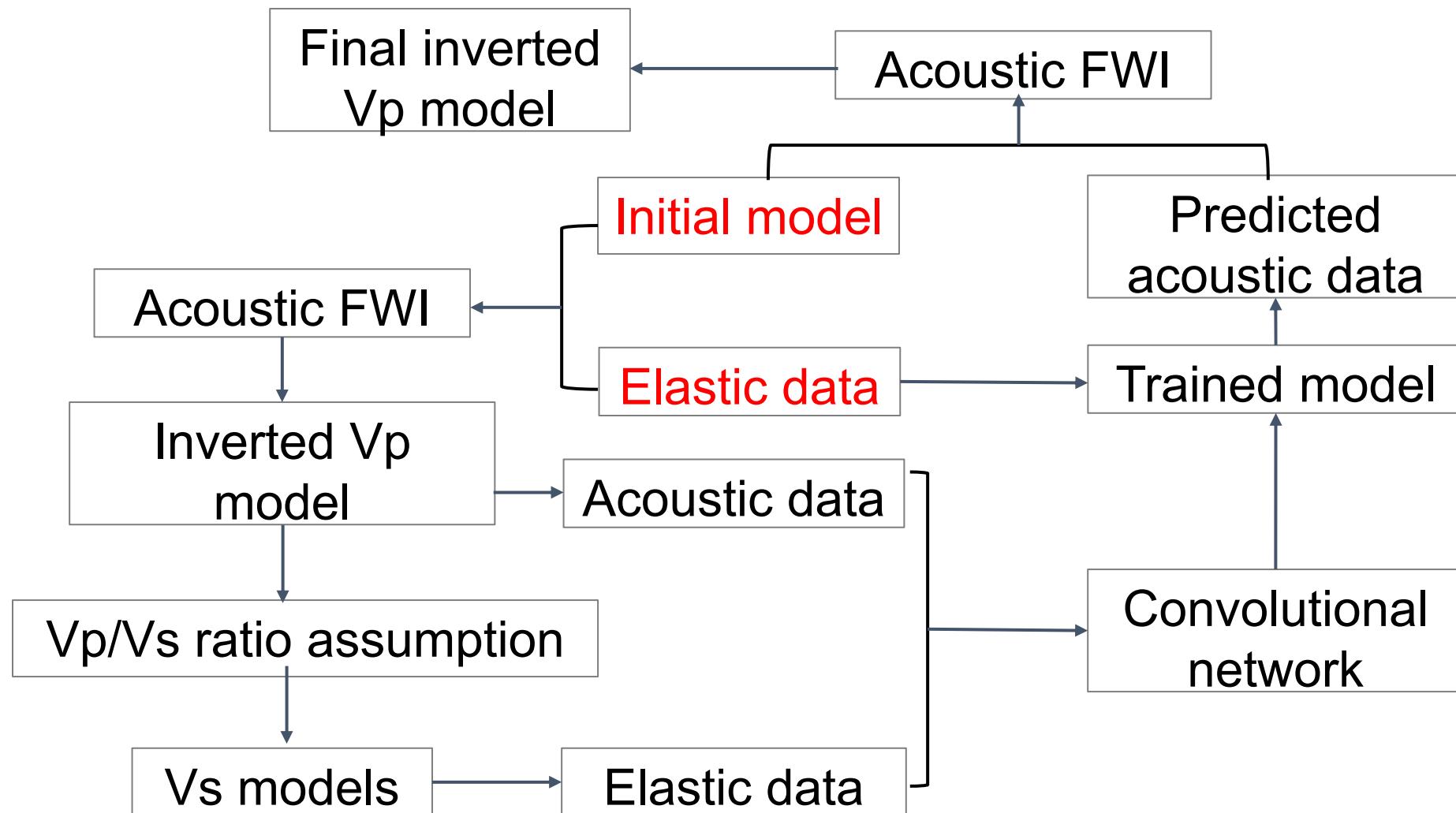


## Workflow





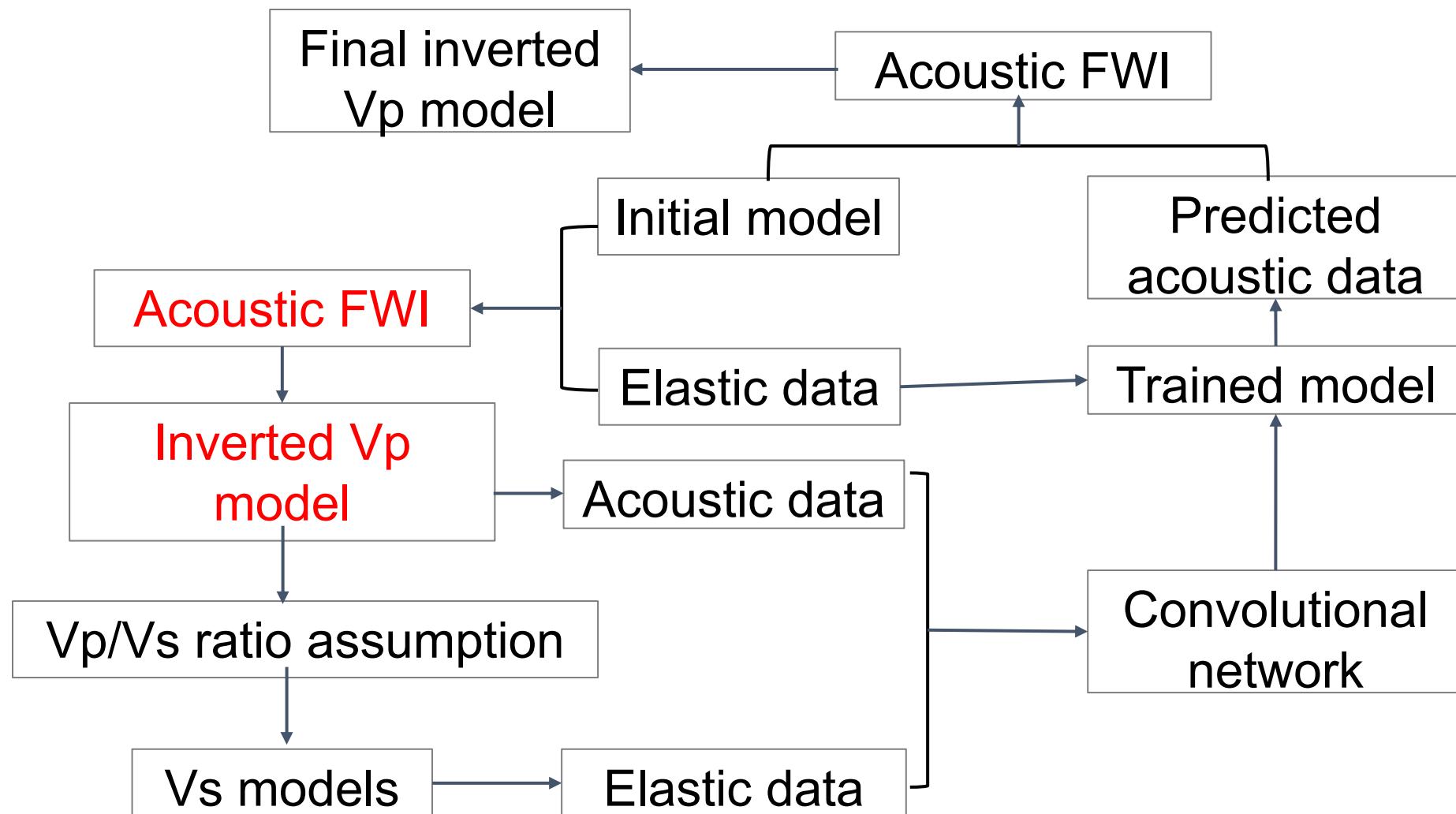
## Workflow



Step 1: assume we have access to the initial models necessary for acoustic FWI.



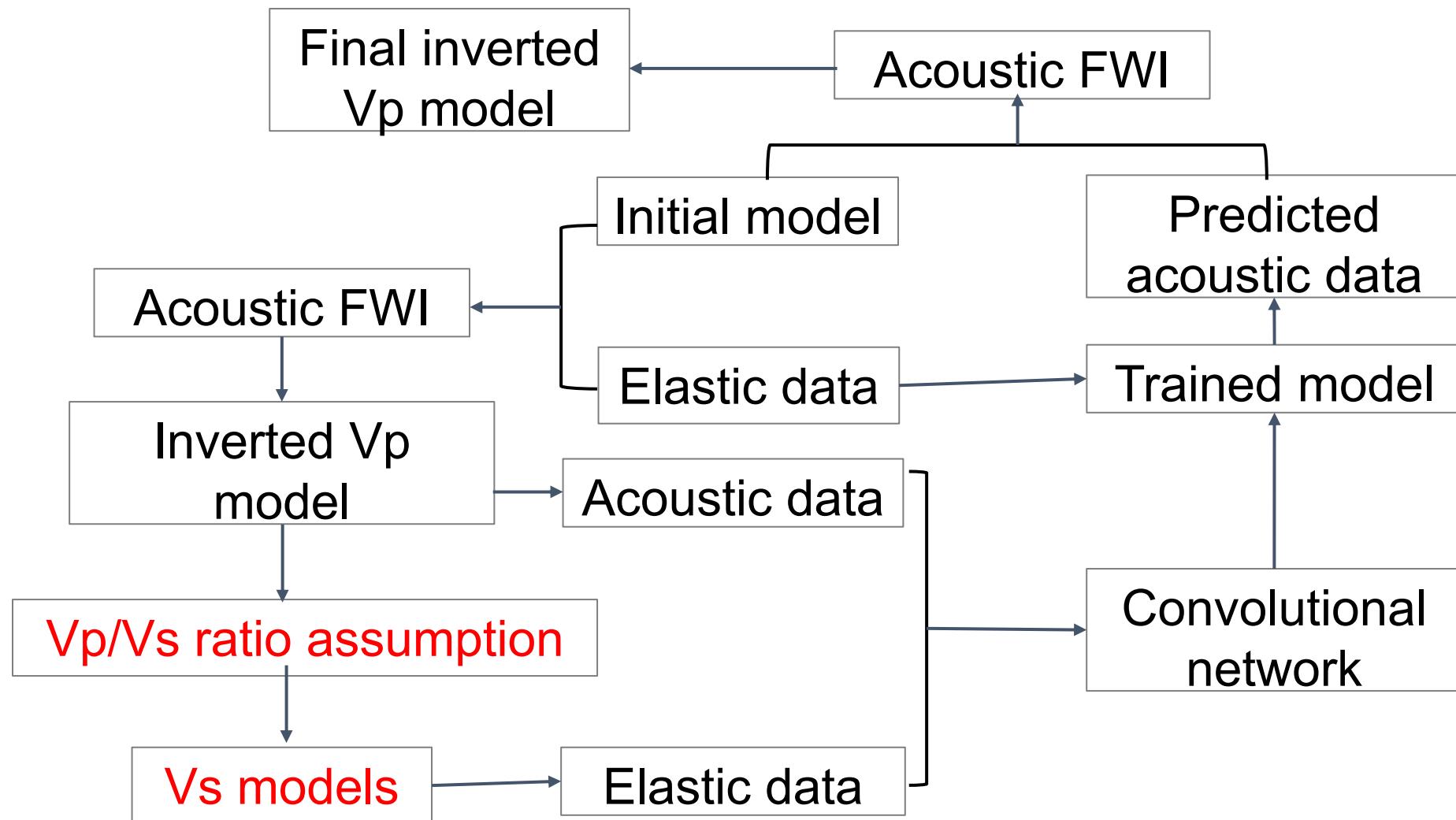
## Workflow



Step 2: perform AFWI with initial model to build an acoustic model, which better simulates the field data.



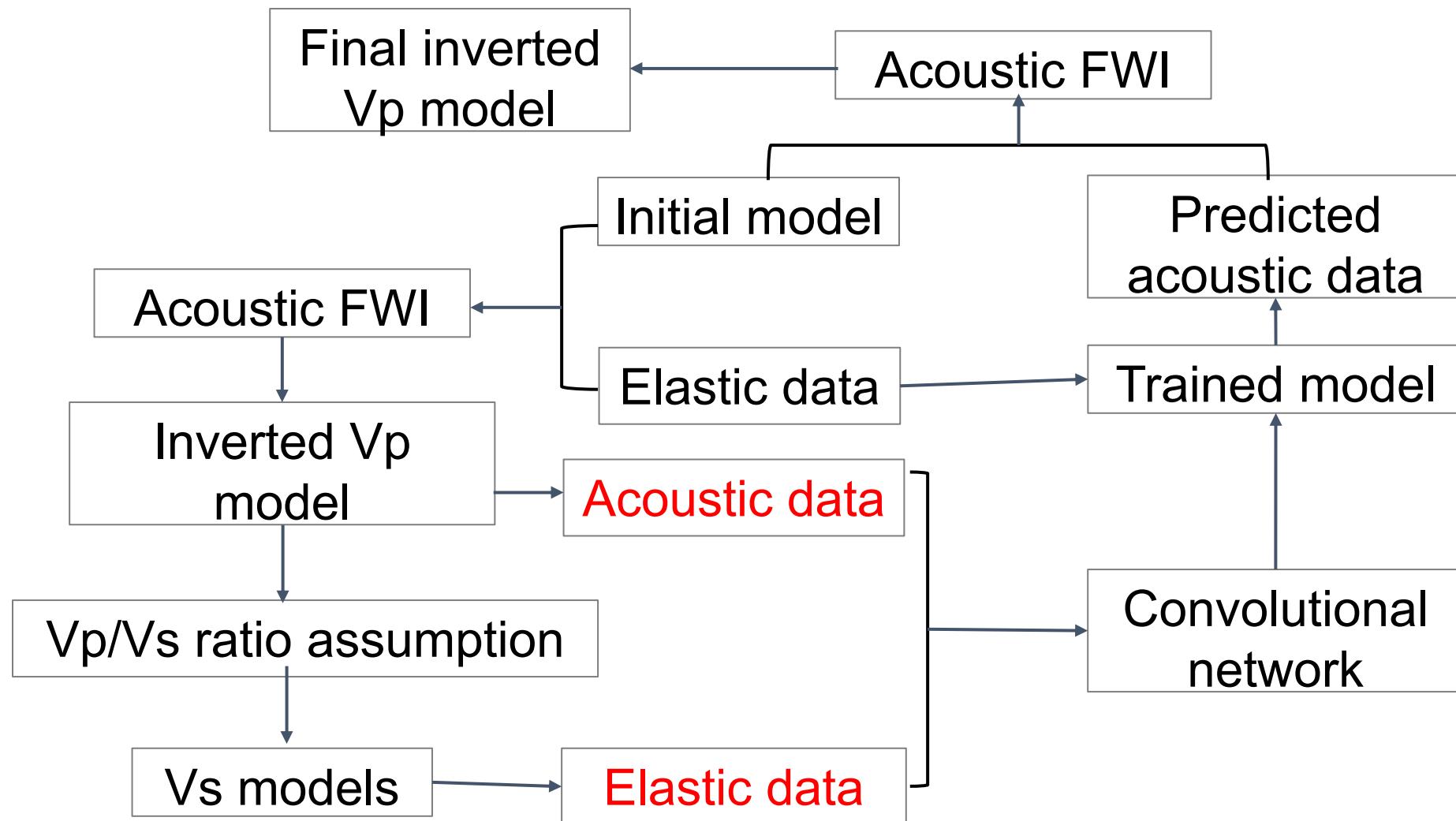
## Workflow



Step 3: estimate  $V_p/V_s$  ratios to build a series of elastic models.

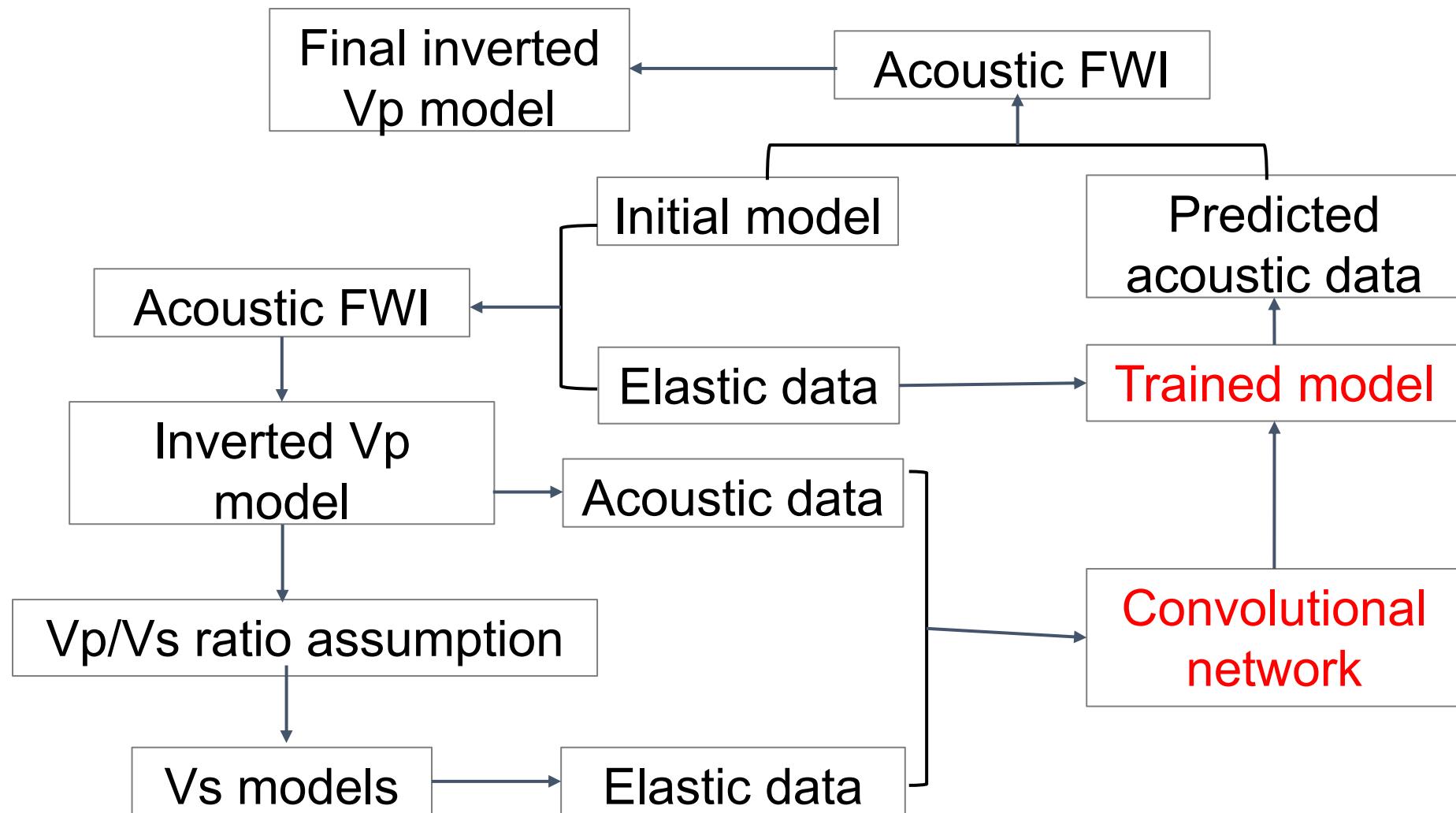


## Workflow



Step 4: generate synthetic acoustic and elastic shot gathers using the acoustic and elastic models as the training data.

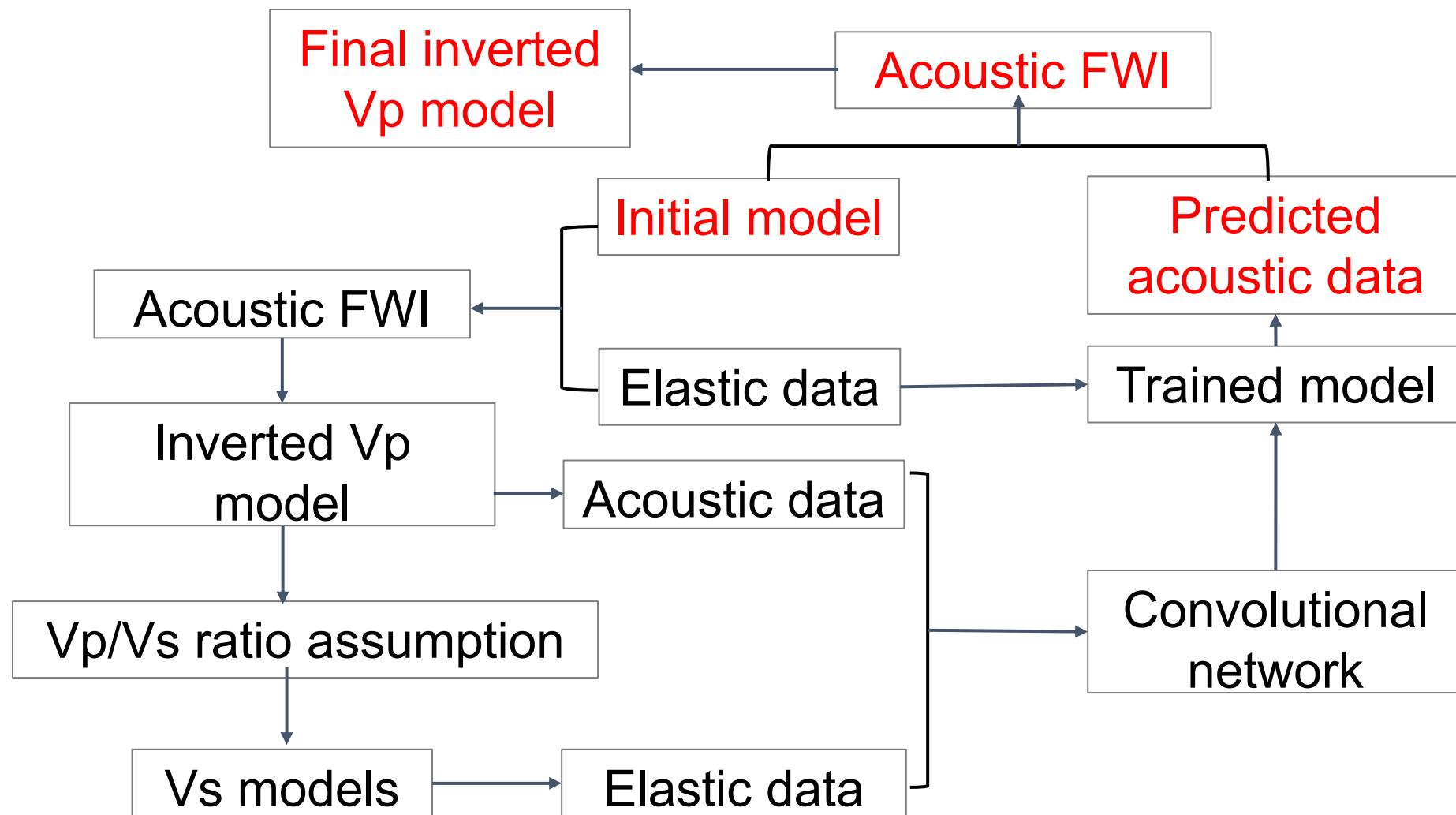
# Workflow



Step 5: train the network to learn the mapping from an elastic shot gather to its acoustic equivalent.



## Workflow



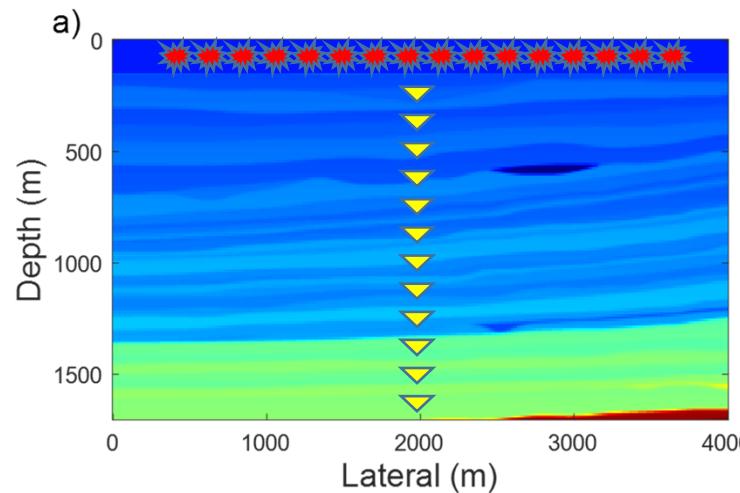
Step 6: apply the network to observed data and perform AFWI.



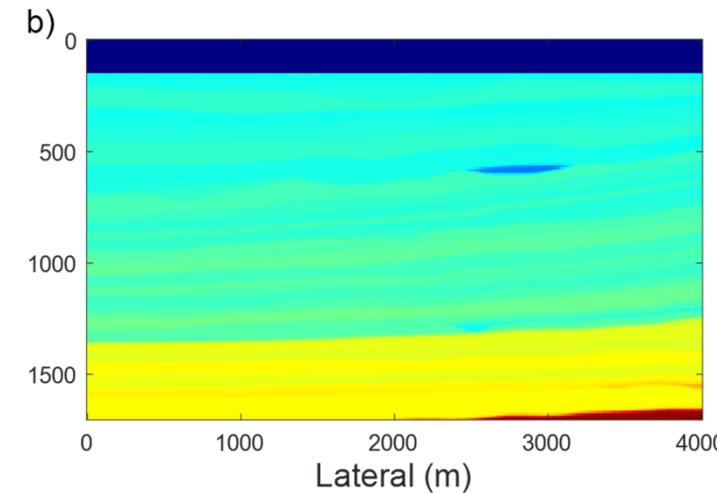
# Result

## Model and geometry

True  $V_p$

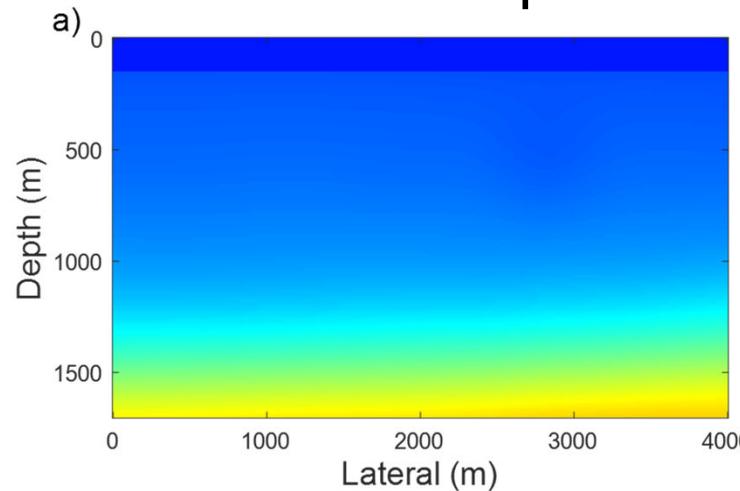


True  $V_s$

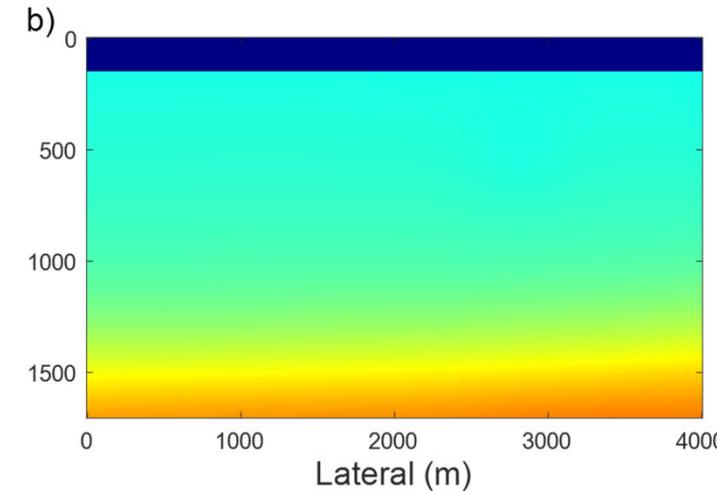


36 sources  
128 receivers

Initial  $V_p$



Initial  $V_s$





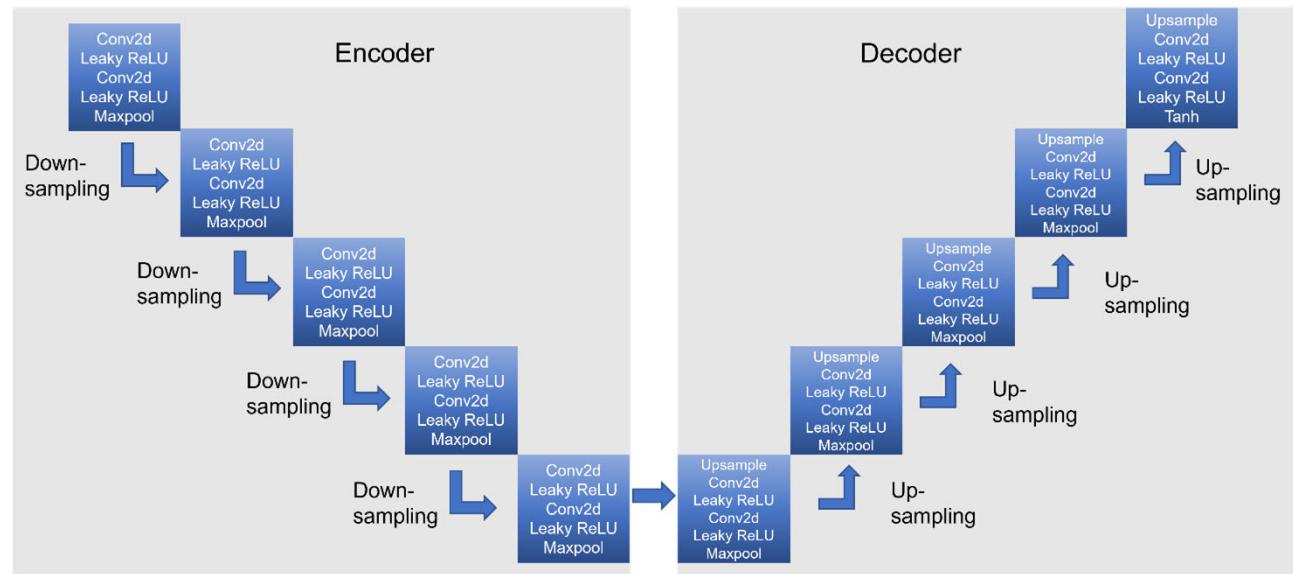
# Data preparation and training

## Data preparation

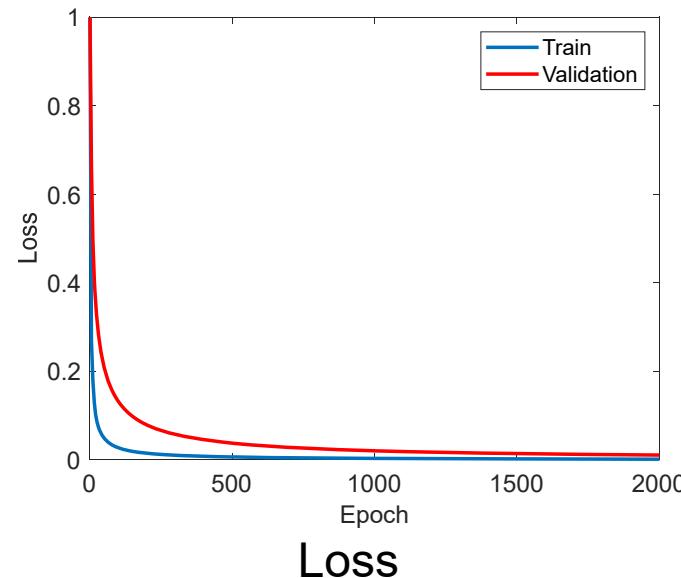
- Generate 1800 acoustic and elastic shot gather pairs.
- Training data: 2880
- Validation data: 360
- Test data: 360

## Training

Optimizer	ADAM
Software	PyTorch
Hardware	NVIDIA A100
Training time	~8 hours
Learning rate	0.0001
Loss function	MSE
Batch size	50



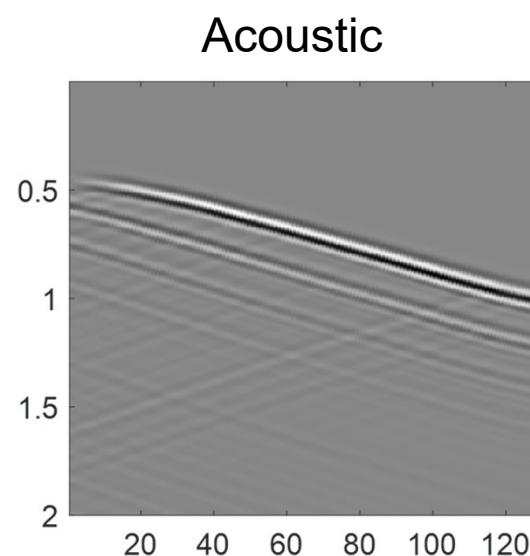
Architecture of the convolutional neural network



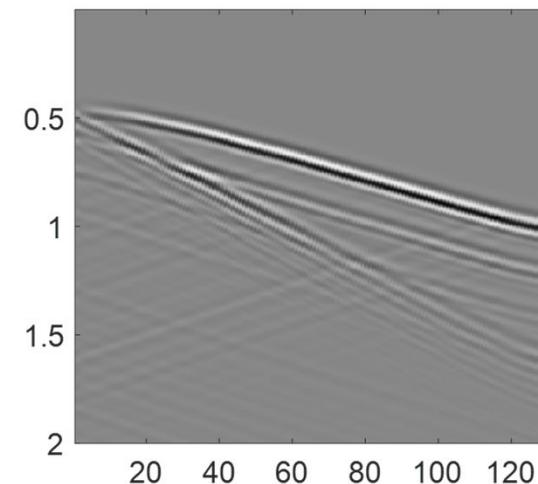


# Predicted test data

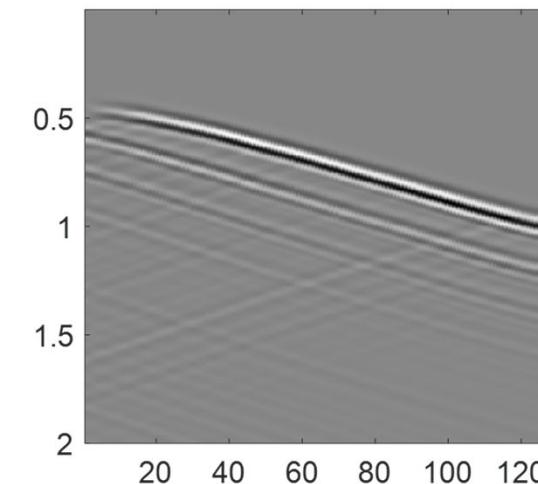
Near offset



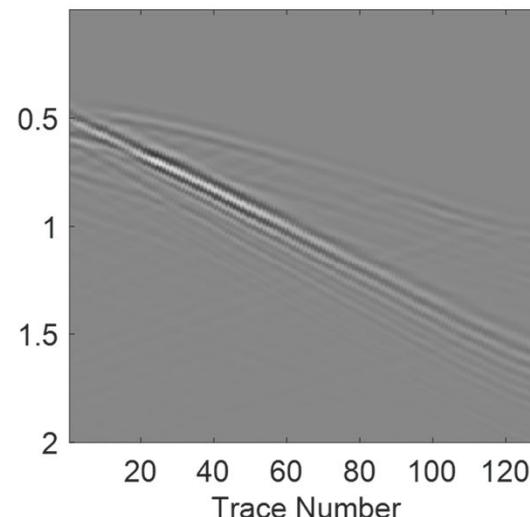
Elastic



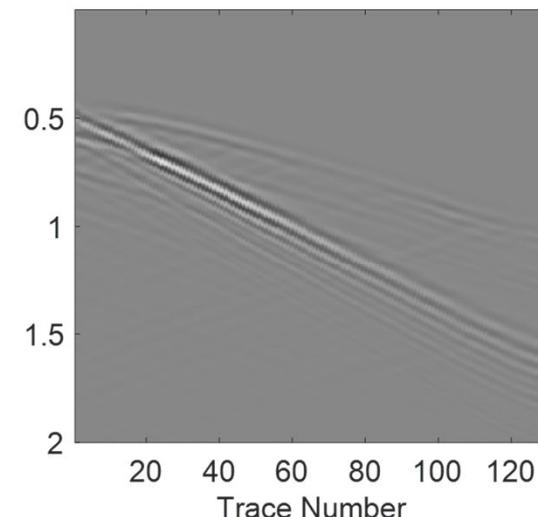
Predicted acoustic



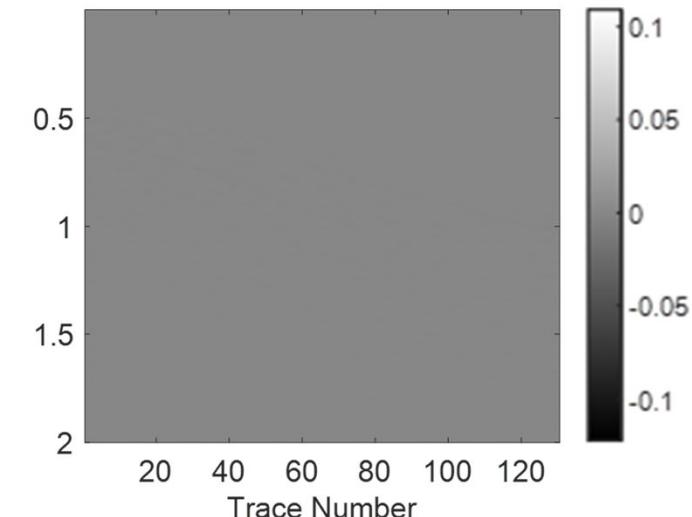
Acoustic-Elastic



Predicted Acoustic-Elastic



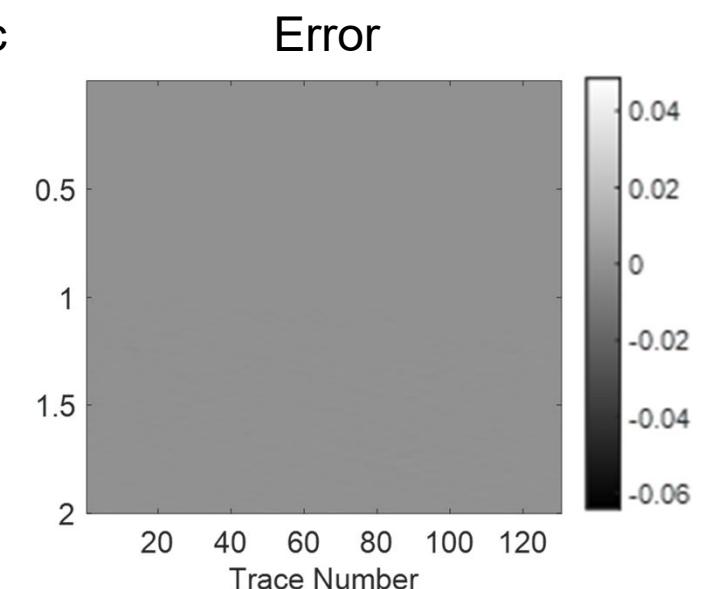
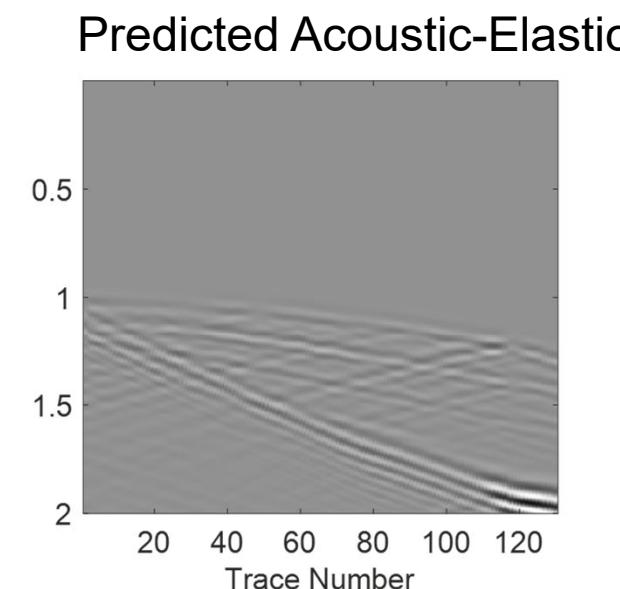
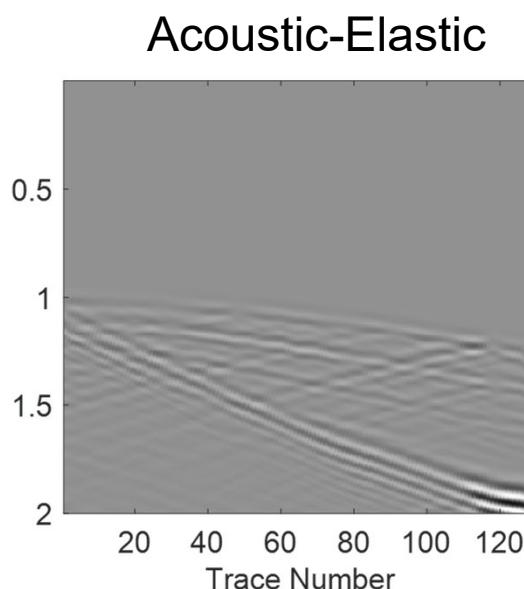
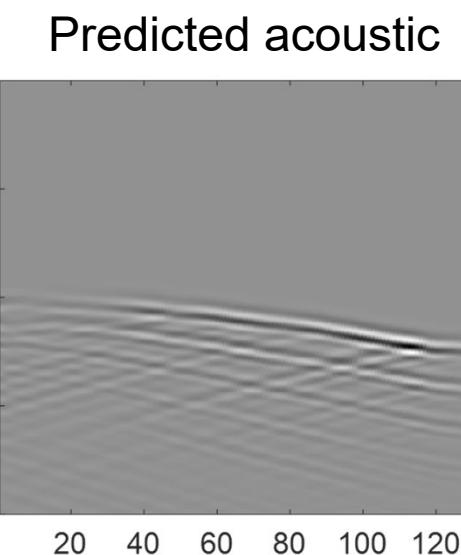
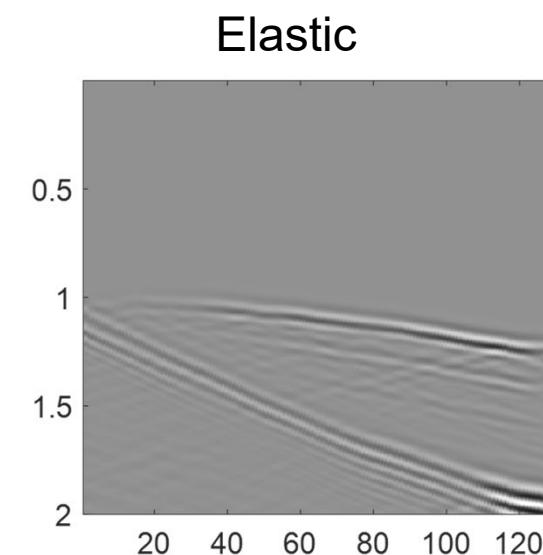
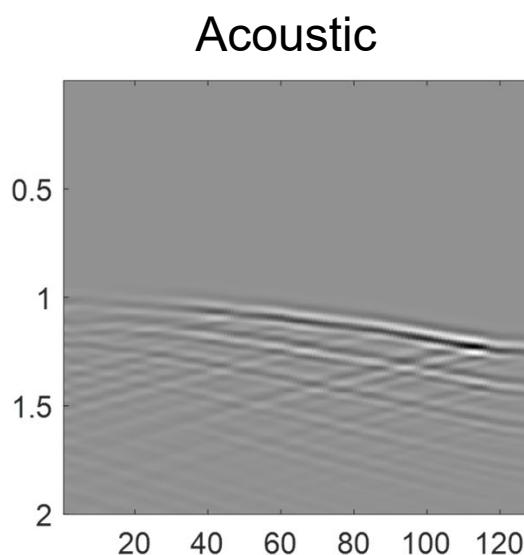
Error





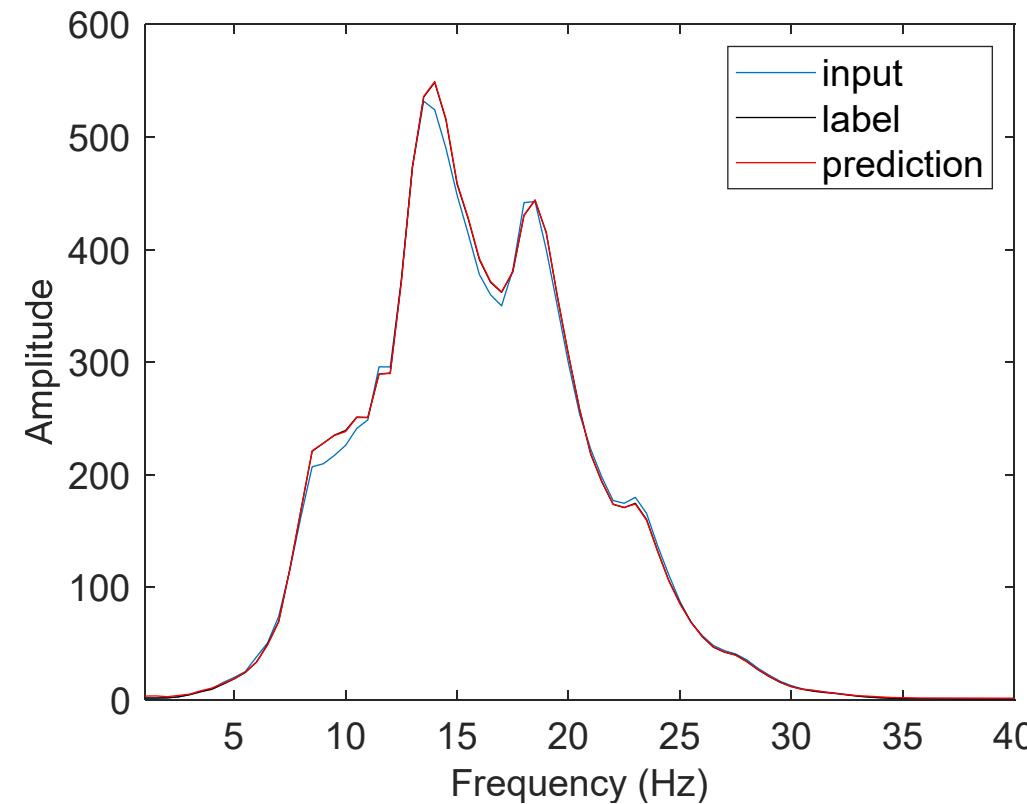
# Predicted test data

Far offset

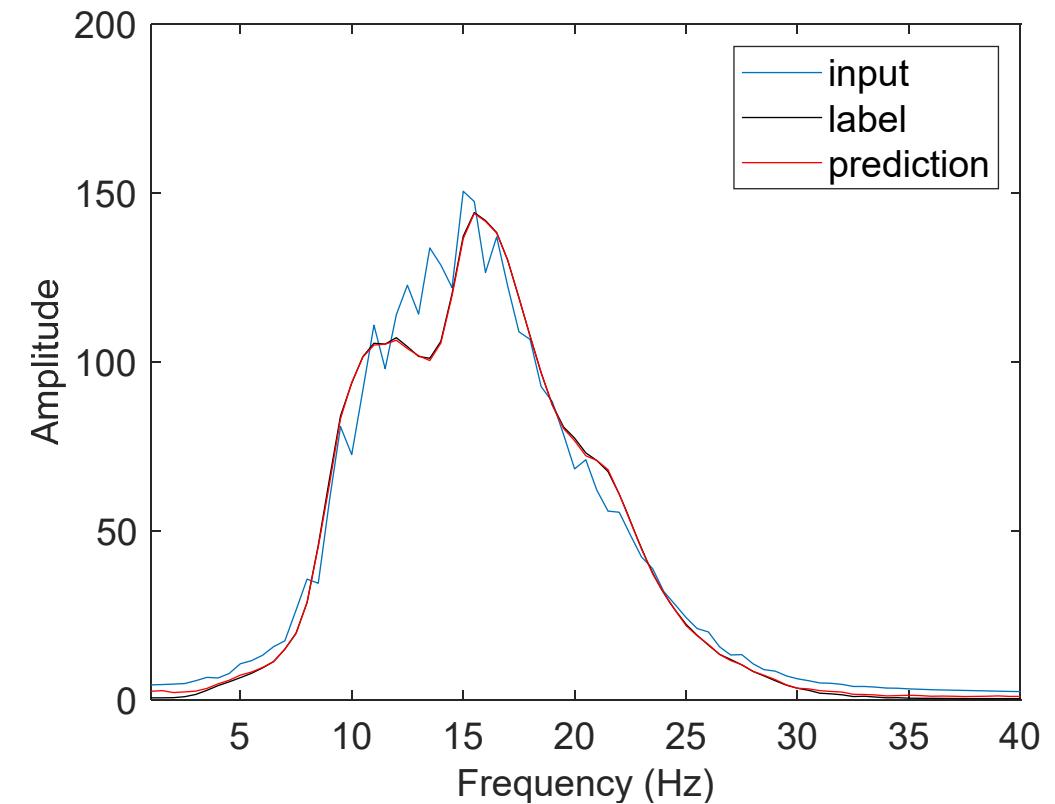




## Spectra comparison



Near offset

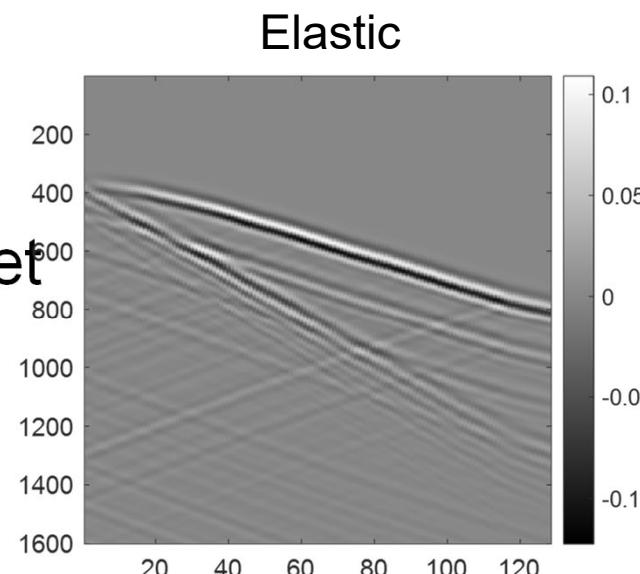


Far offset

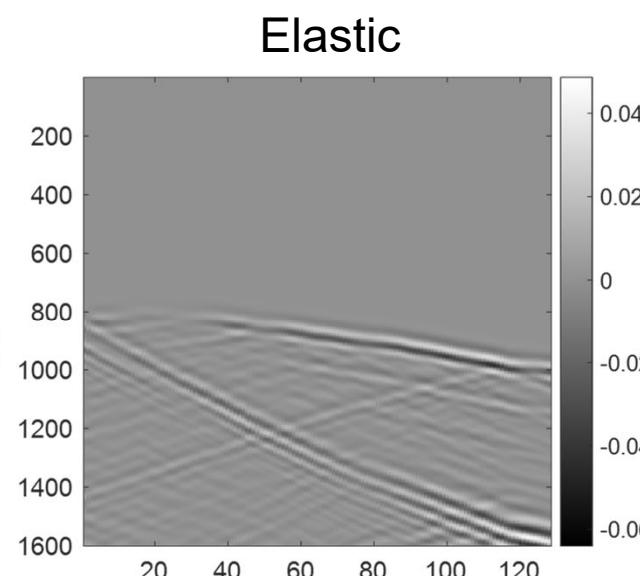


# Predicted observed data

Near offset



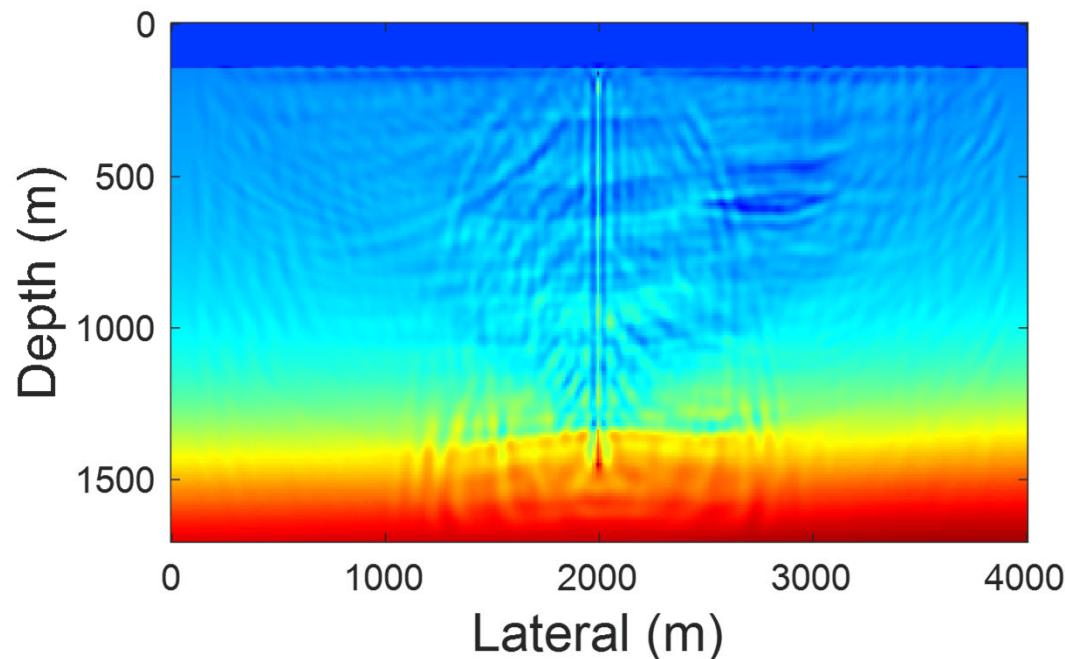
Far offset



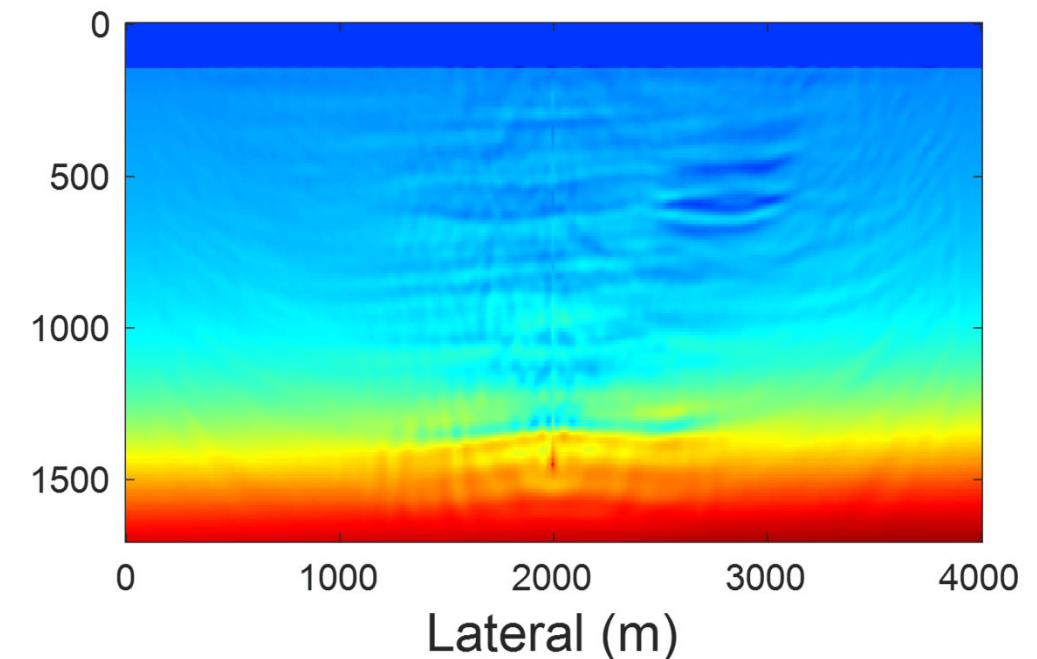


# Baseline inversion result

## AFWI results



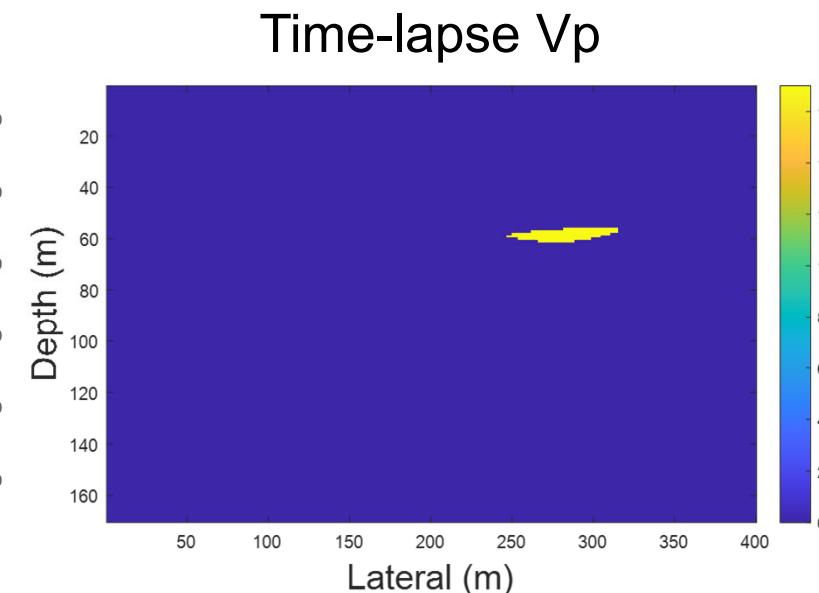
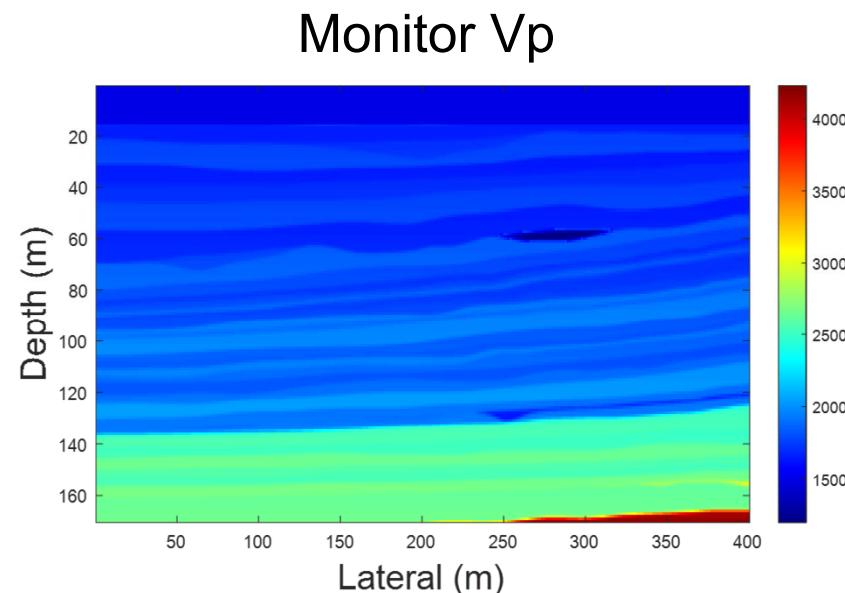
AFWI + Elastic data



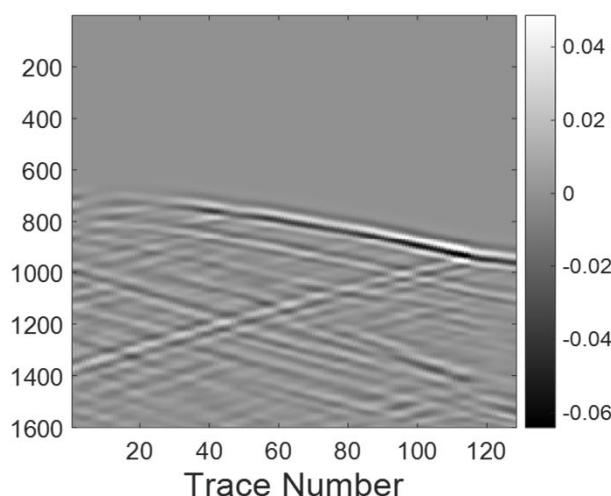
AFWI + predicted acoustic data



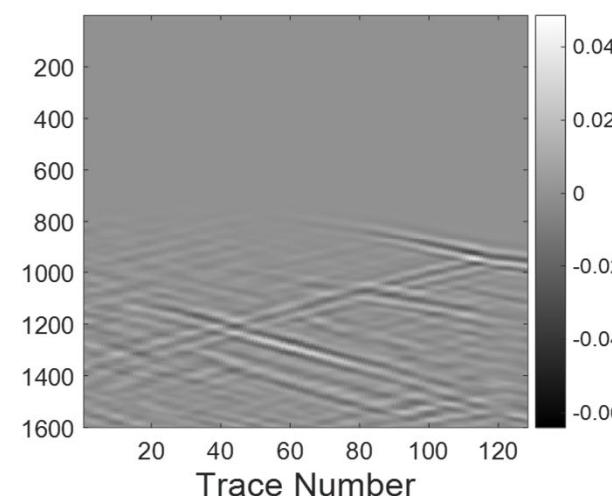
# Time-lapse inversion results



**Predicted monitor data**

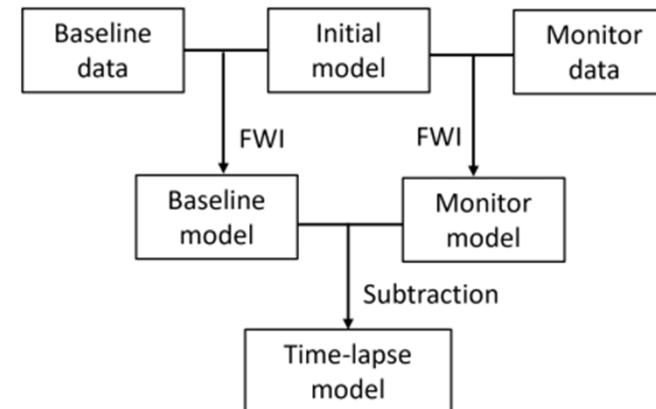


**Time-lapse difference**

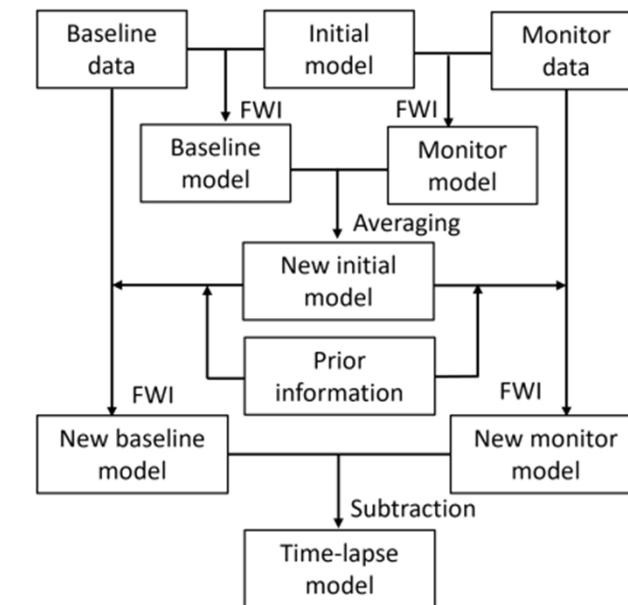
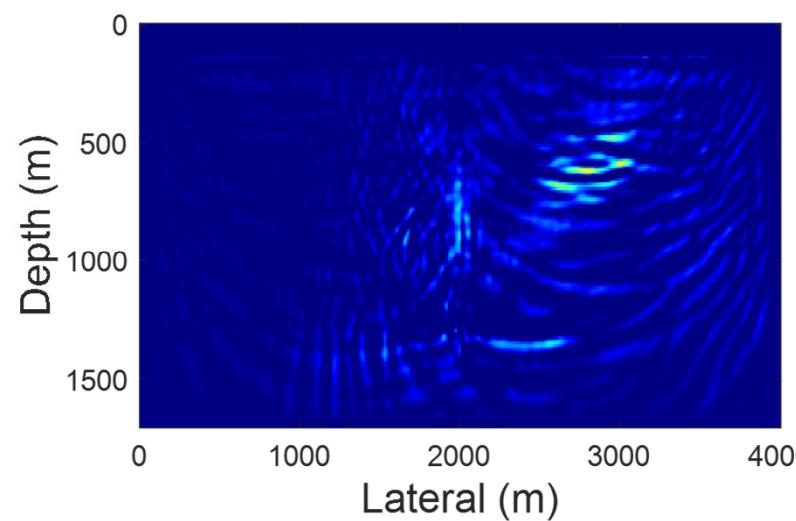




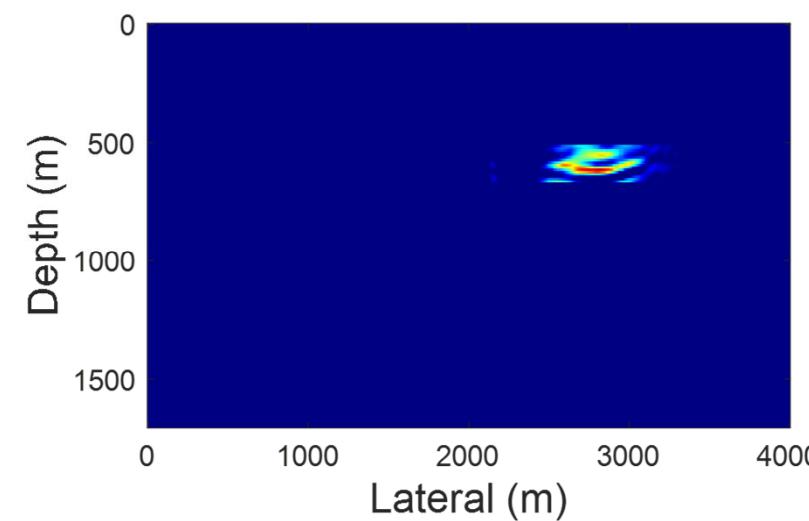
# Time-lapse inversion results



Parallel strategy



Target-oriented common model strategy





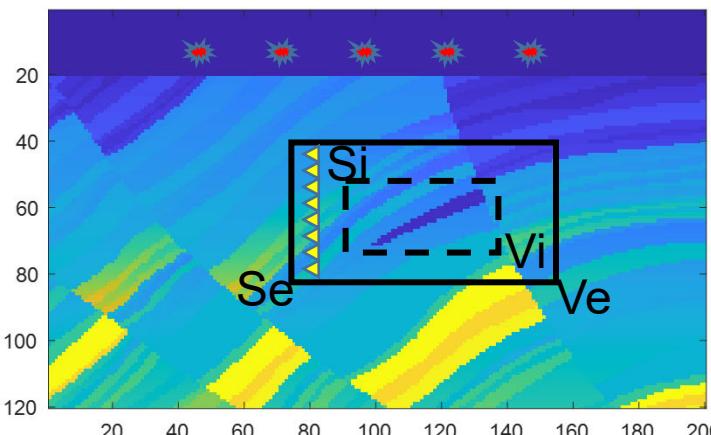
# Conclusions

- We develop a deep convolutional network to correct VSP seismic data to mitigate elastic artifacts in acoustic FWI.
- Predicted data show that elastic wave phenomena can be effectively mitigated by the deep learning approach.
- The image quality of inverted model by acoustic FWI can be improved after the elastic data are transformed into their acoustic counterparts.
- We have conducted time-lapse acoustic FWI using acoustic baseline and monitor data predicted by this deep learning approach, the inversion results show this approach can be applied into monitoring velocity changes.
- This approach can decrease the computational cost and improve the monitoring efficiency.

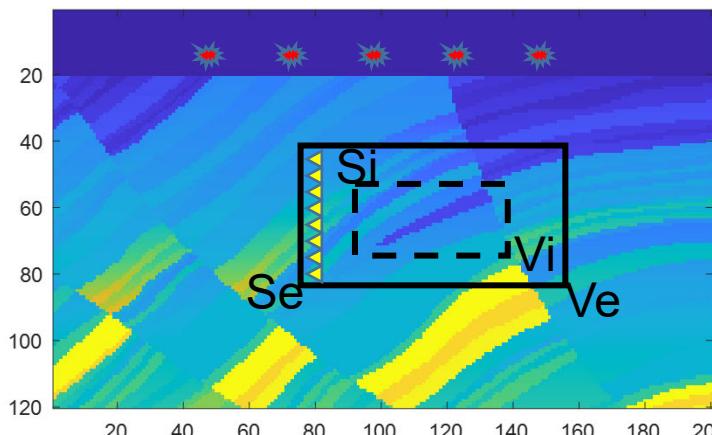


## Future work

Incorporate a local solver like the FD-injection method (Robertsson and Chapman, 2000)

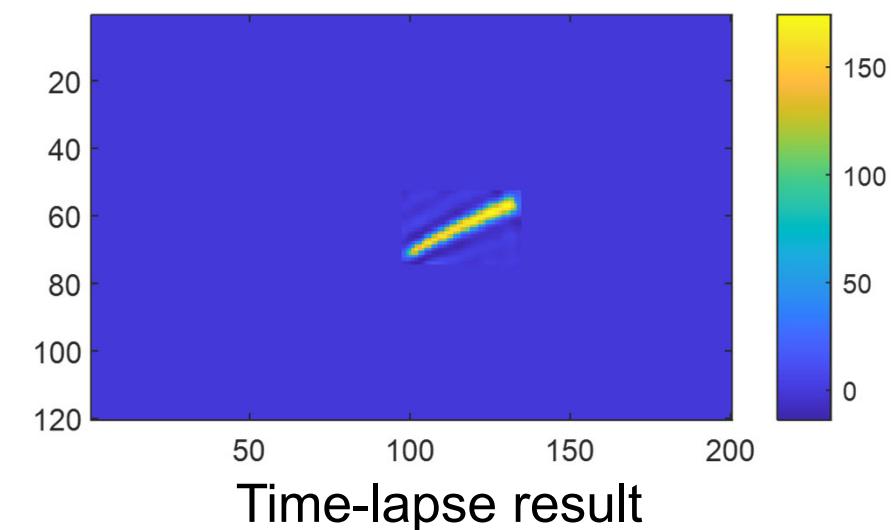


Baseline model



Monitor model

- $Si$  and  $Vi$  are the injection surface and subvolume.
- $Ve$  is an FD submesh for the second simulation and  $Se$  acts like an AB.



- Based on the baseline model, calculate the wavefields at certain surface as effective sources.
- Choose receivers lies in the area and use the baseline and monitor data difference as observed data.



## Acknowledgements

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