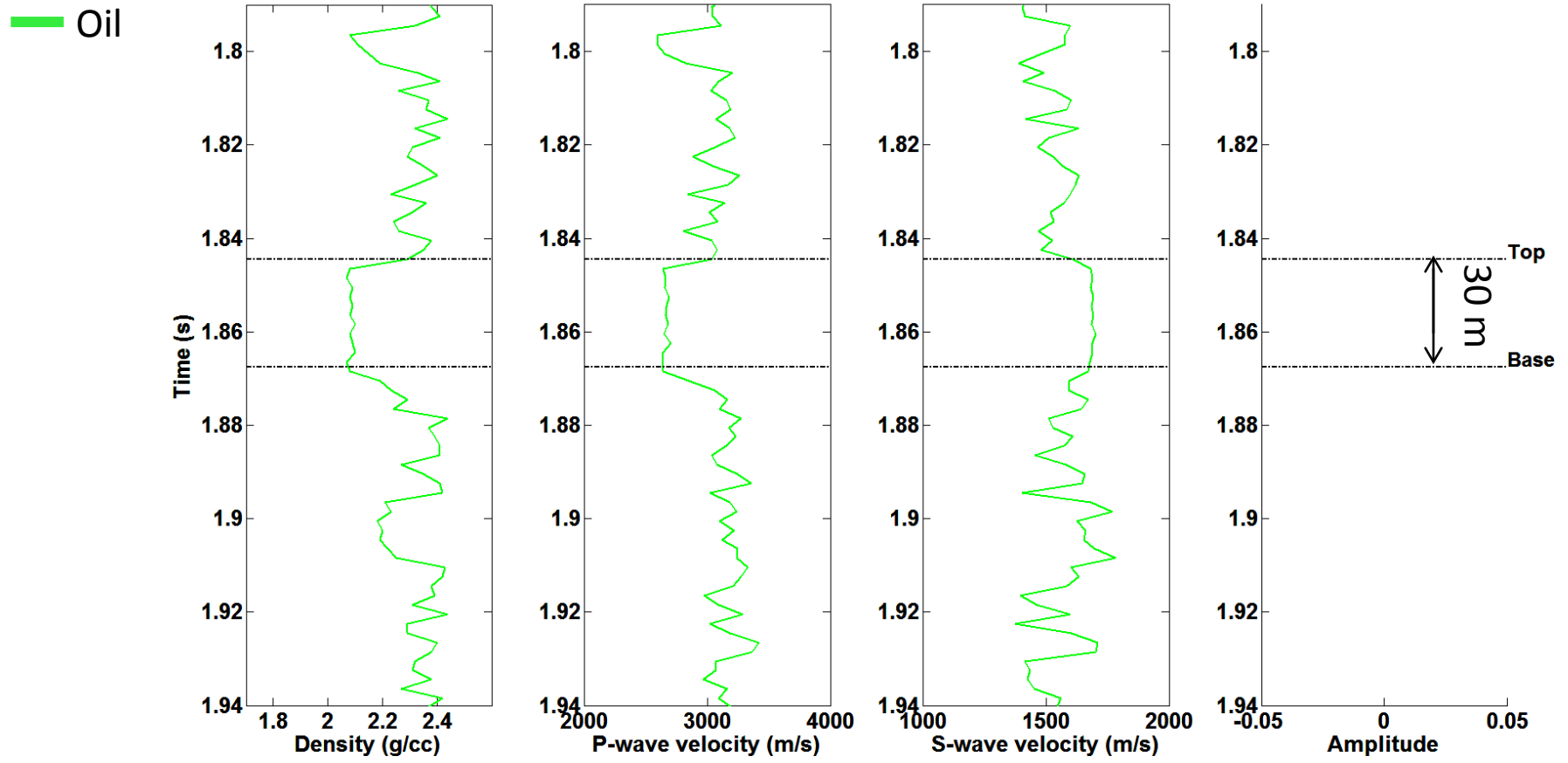


Repercussions of available long offset,
random noise and impedance contrast on
AVO analysis

- ✓ Introduction
 - Motivations
 - Geological target
 - Fluid replacement modelling
 - Vertical seismic resolution
 - AVO modelling using Zoeppritz equations
- ✓ Effect of random noise keeping maximum offset constant
- ✓ Quantifying the error
- ✓ Effect of reducing offset keeping noise constant
- ✓ Simultaneous effect of reducing offset and varying level of noise
- ✓ Conclusions and future work

Motivations

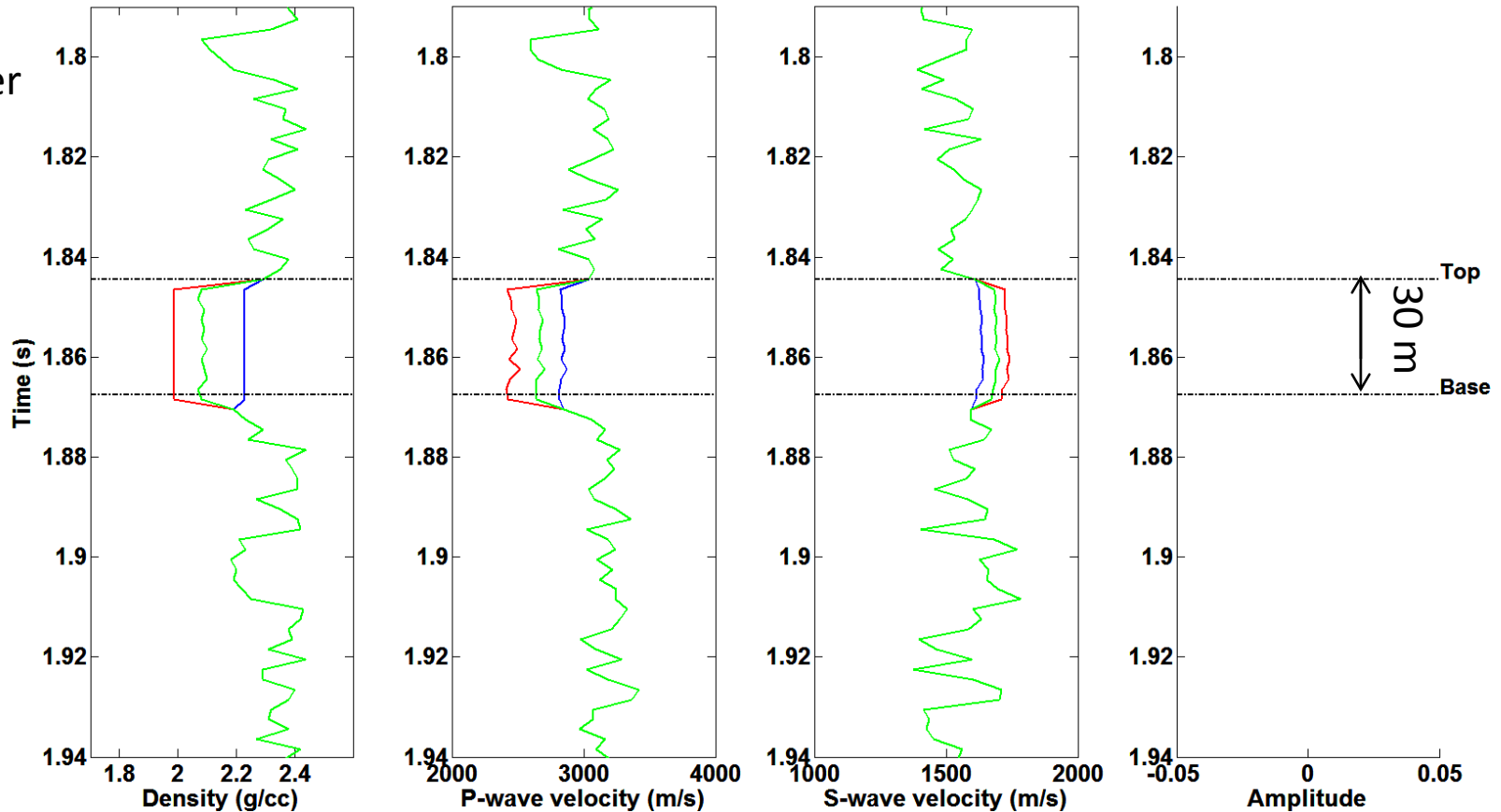
- How to meet the large offset requirement when designing a seismic survey for AVO analysis
- If we already have a seismic data set, is it suitable for AVO analysis?



Depth of reservoir = 2280 m

Light oil (38 api)

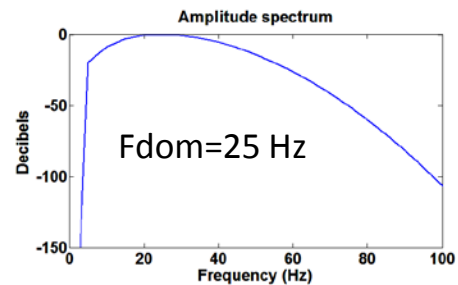
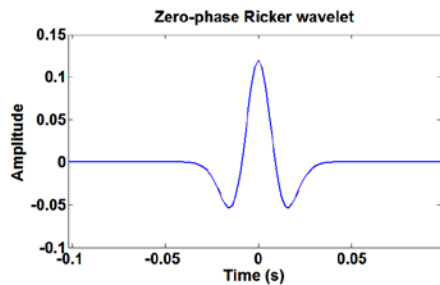
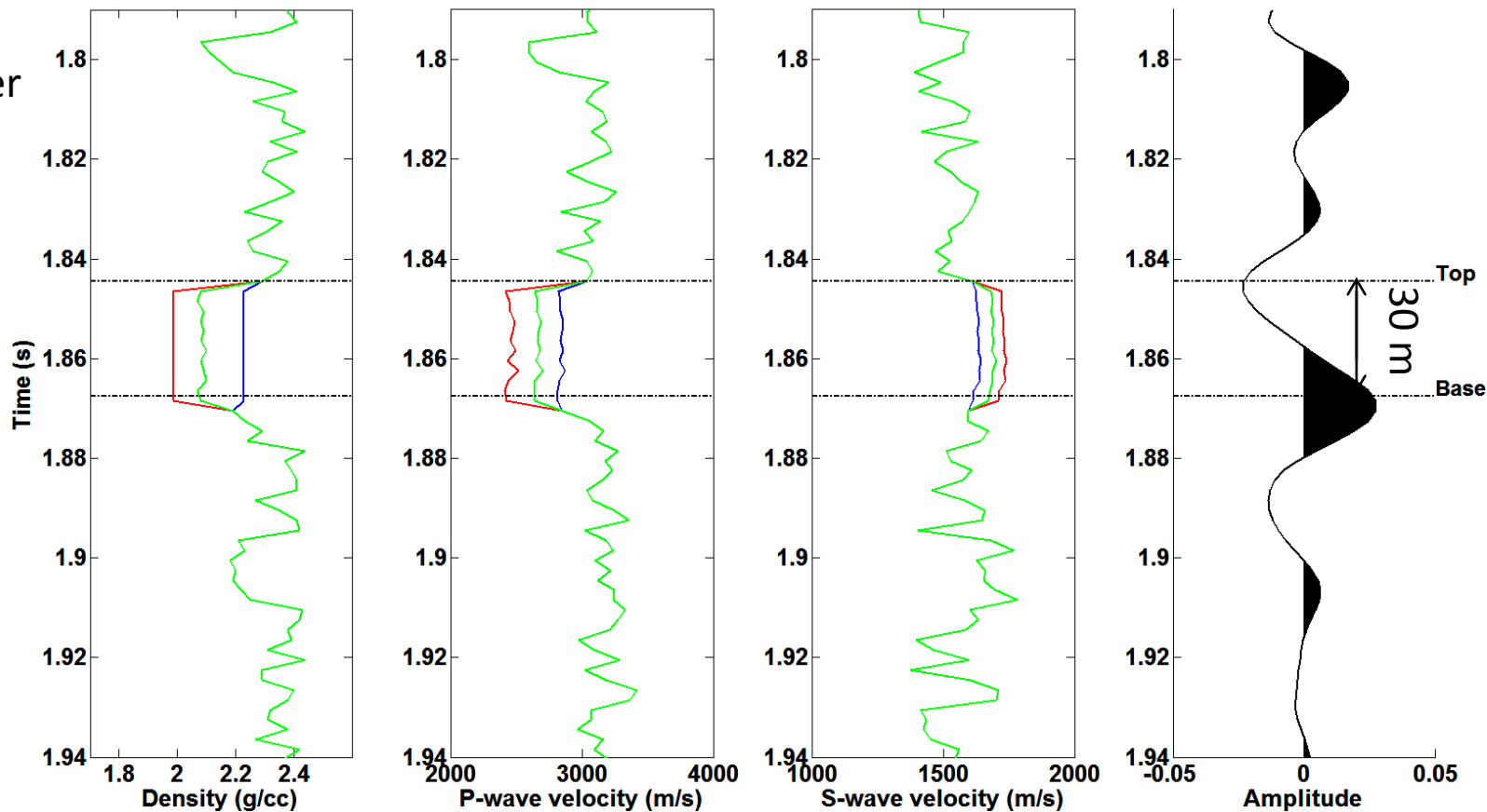
- █ Gas
- █ Oil
- █ Water



Gas produces a significant decrement of P-wave velocity and density , and a subtle increase in S-wave velocity.

Water produces the opposite change; P-wave velocity and density rise, while S-wave velocity slightly falls.

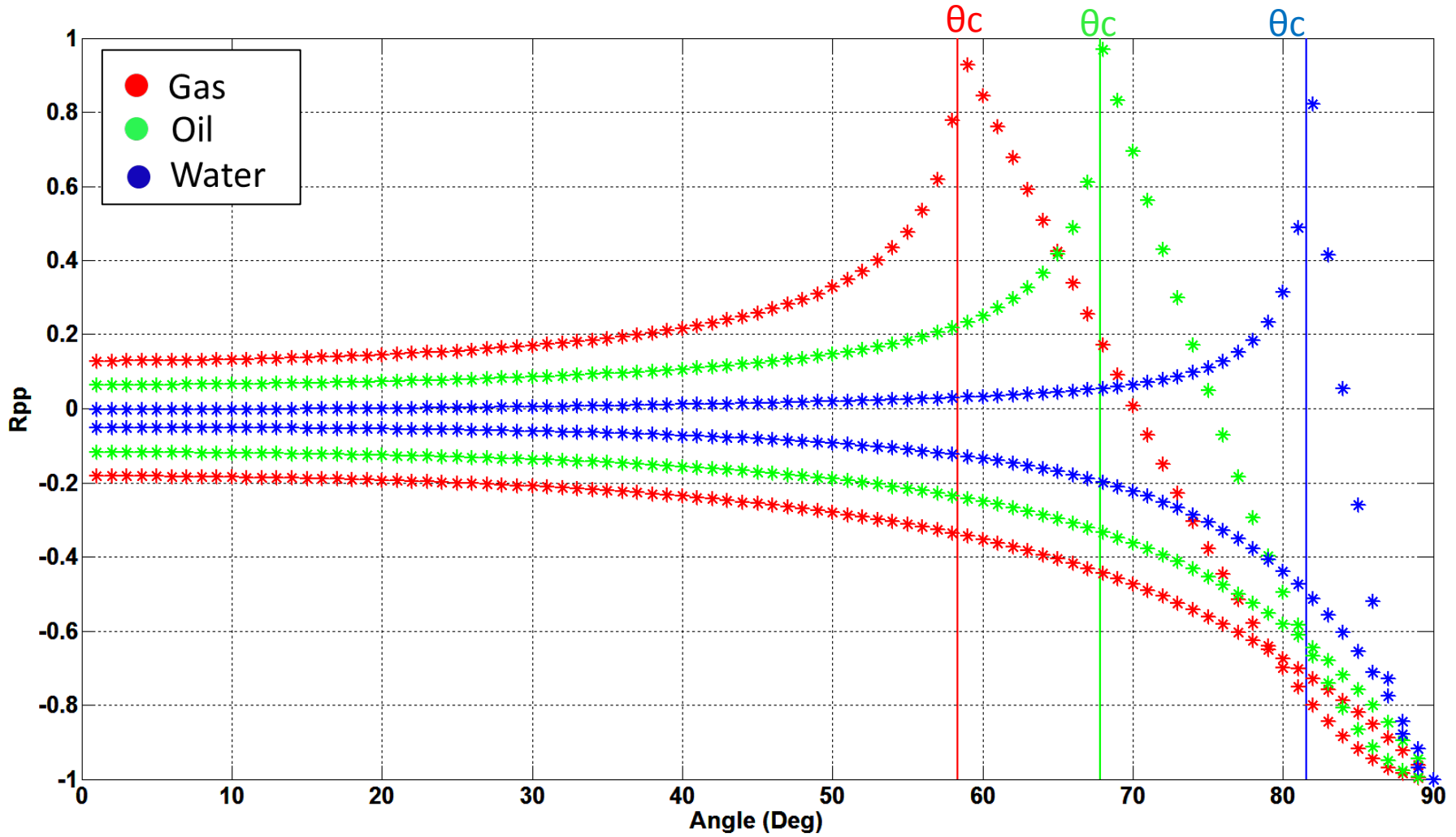
- █ Gas
- █ Oil
- █ Water



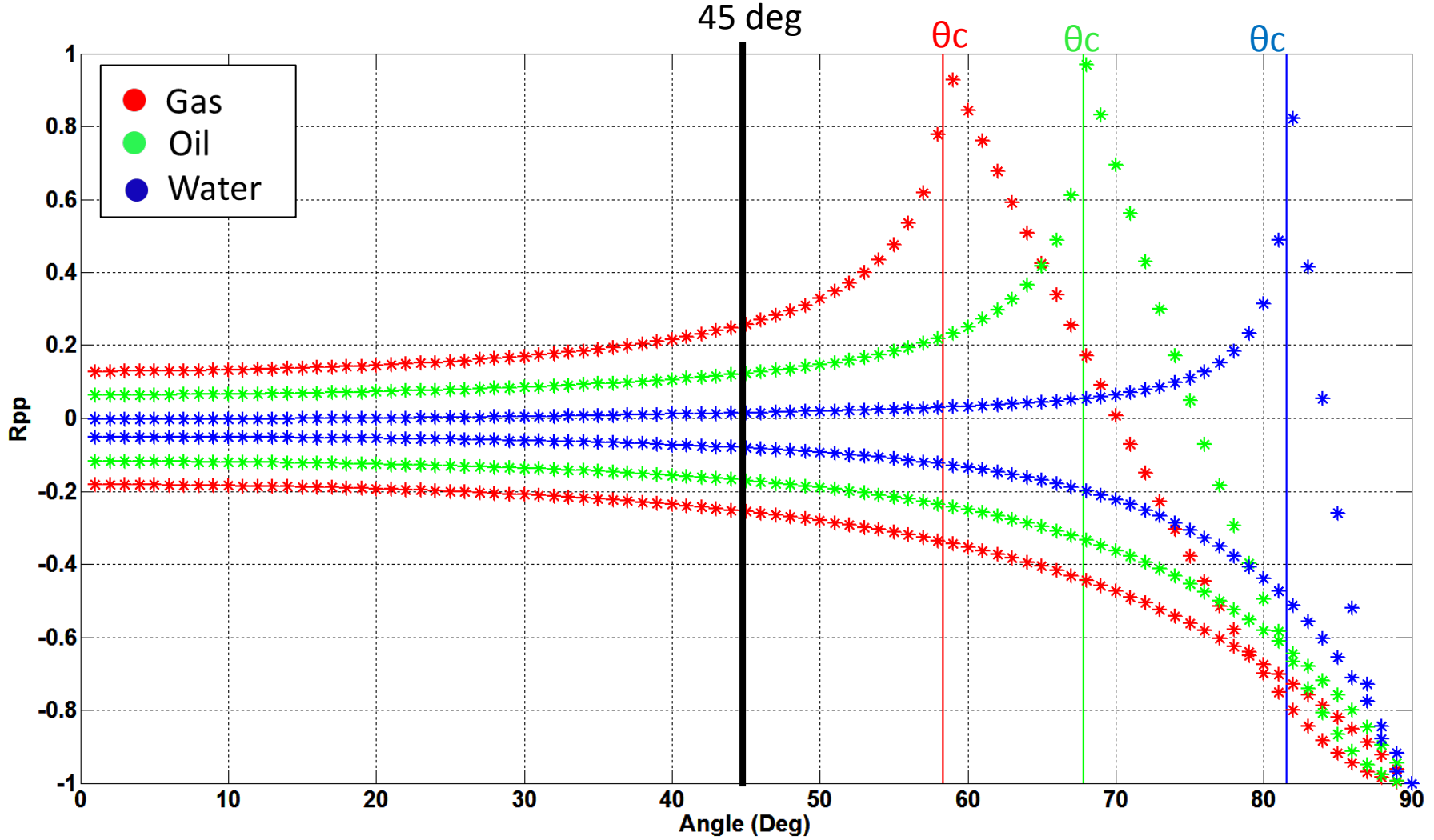
Reflection coefficient vs angle of incidence

Zoeppritz equations

Introduction



θ_c =critical angle



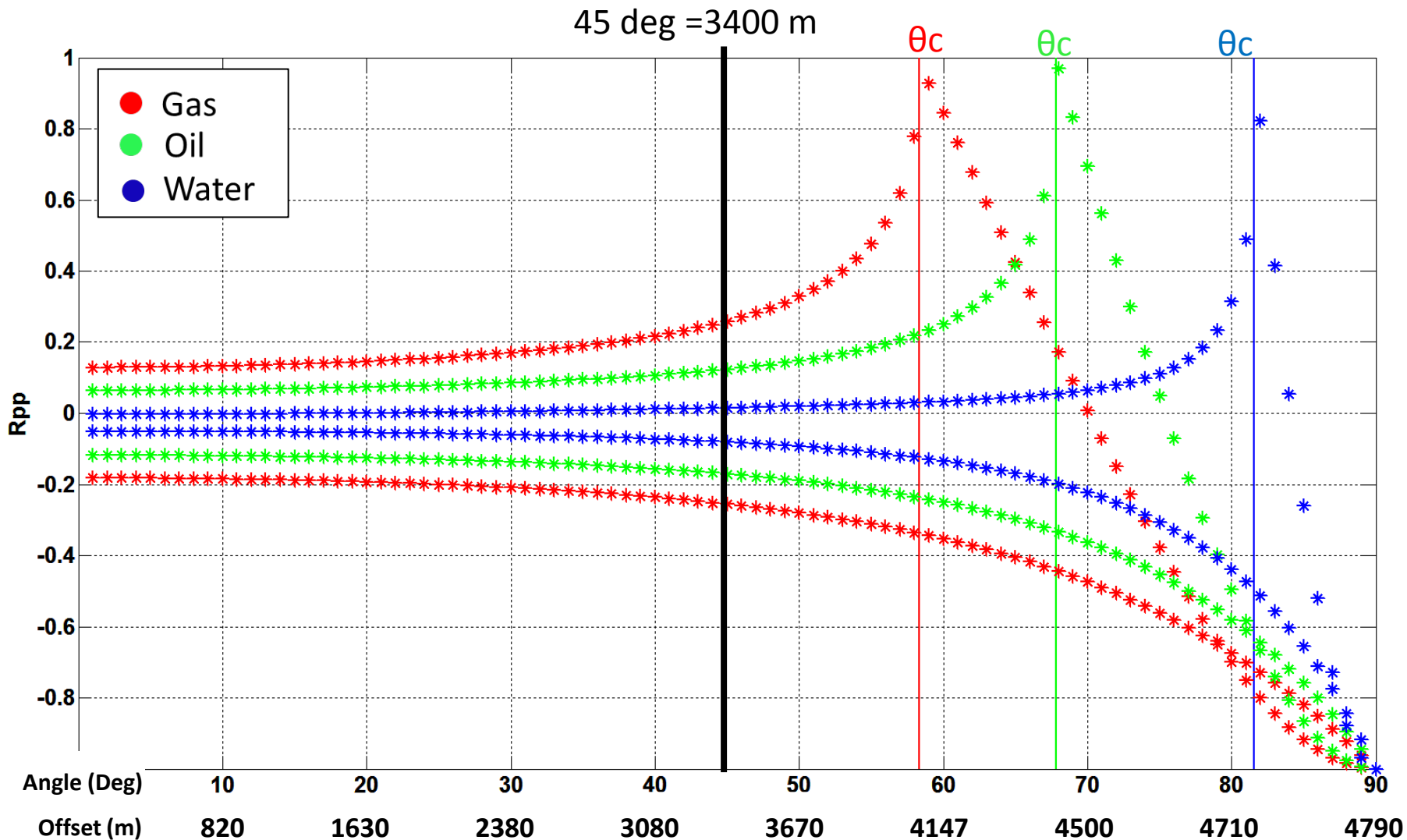
Pre-critical angles up to 45 degrees were used for this experiment

θ_c =critical angle

Reflection coefficient vs angle of incidence

Zoeppritz equations

Introduction



Top

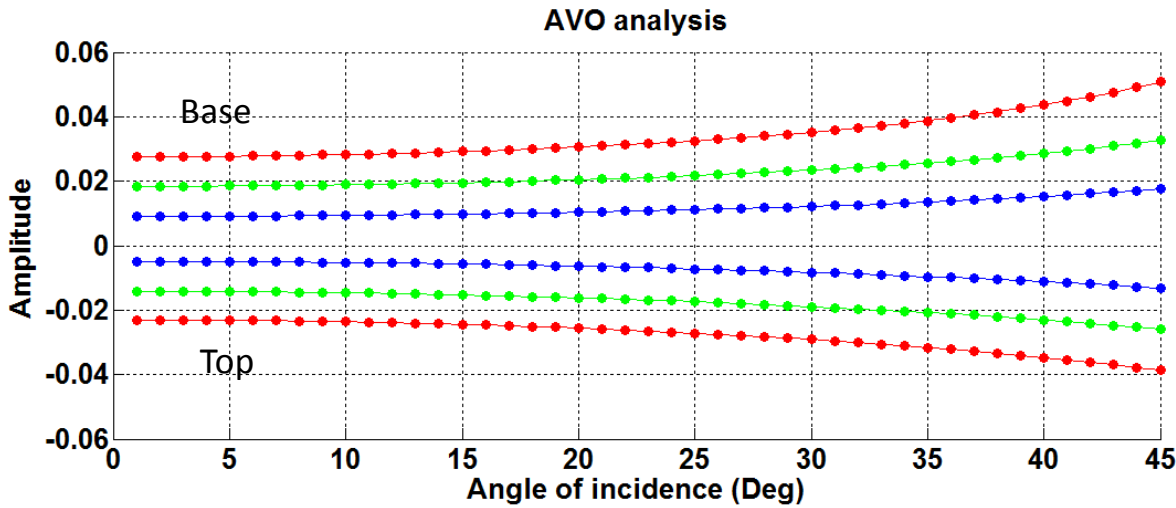
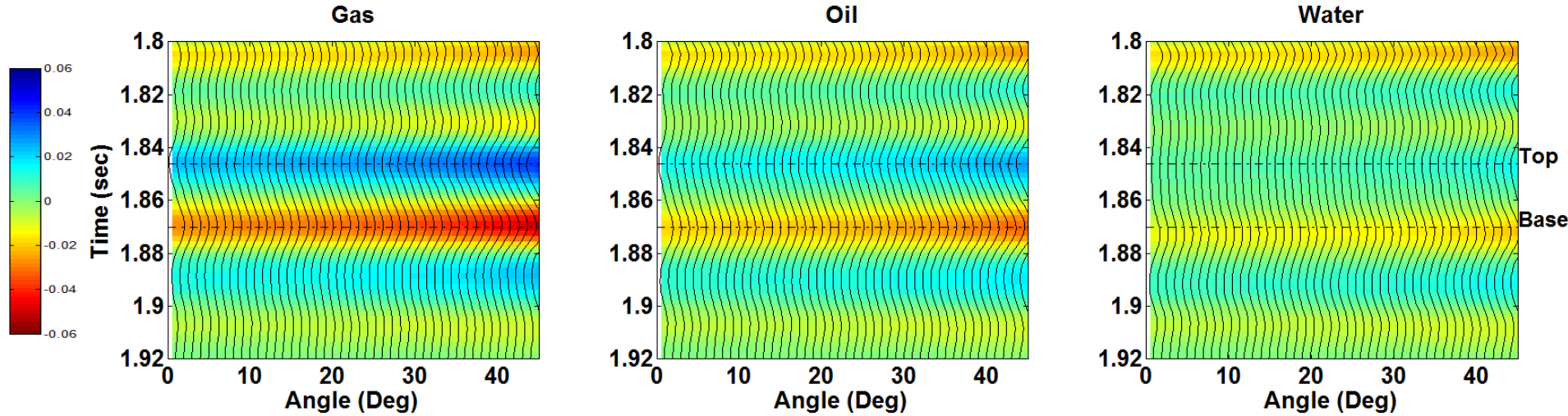
$$\sin \theta = \frac{X V_{int}}{t V_{rms}^2}$$

θ_c =critical angle

AVO modelling

Amplitude vs angle of incidence

Introduction

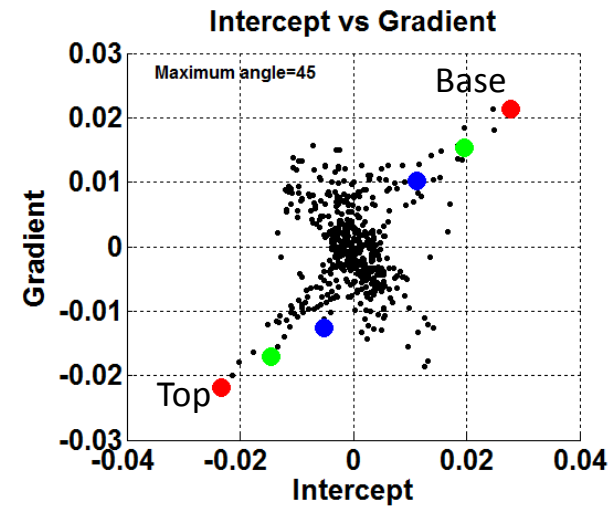
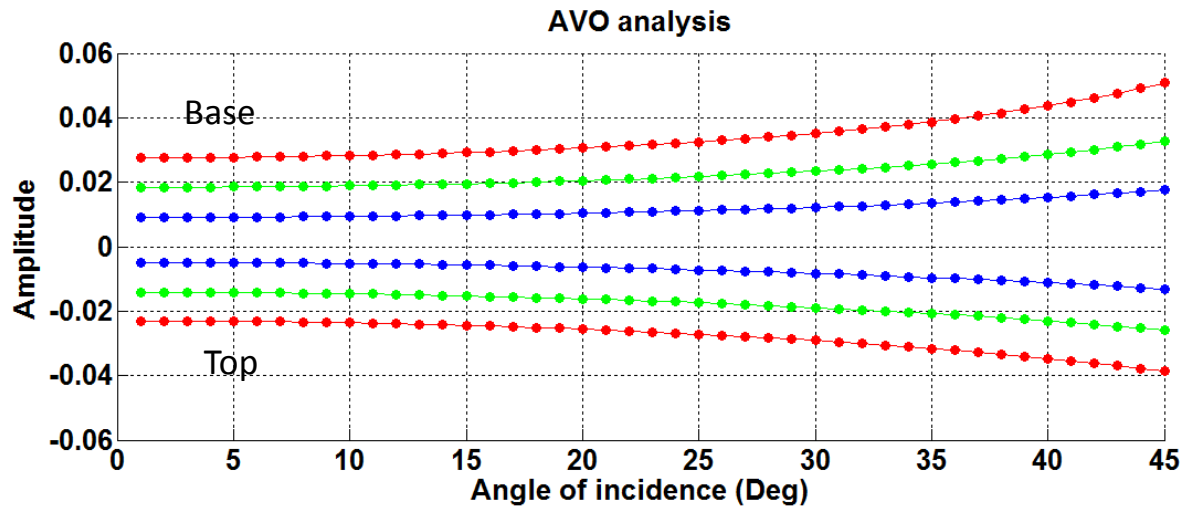
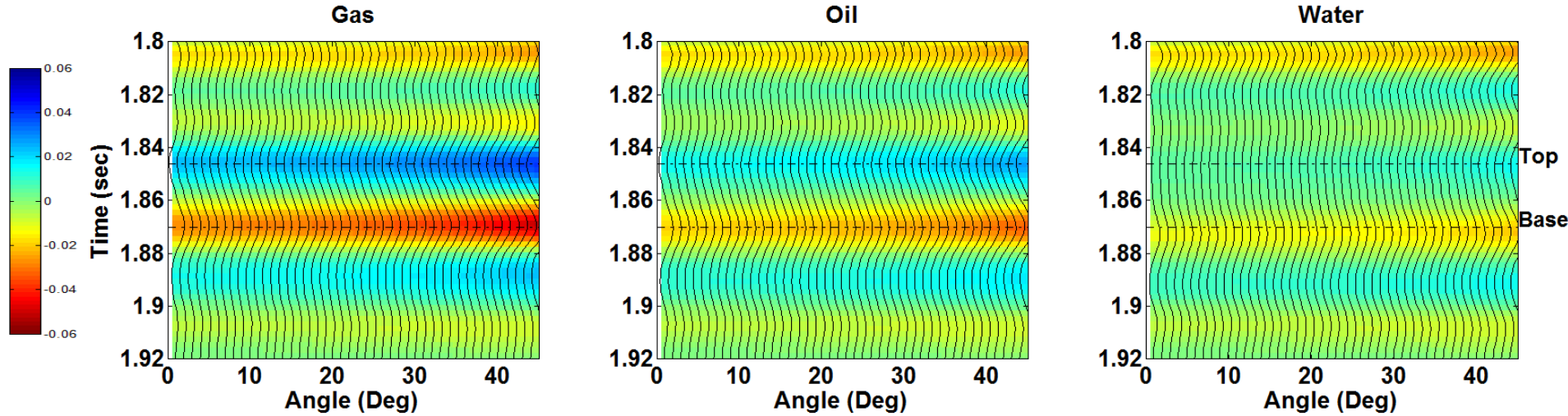


- Gas
- Oil
- Water

AVO modelling

Amplitude vs angle of incidence

Introduction



- Gas
- Oil
- Water

$$R_P(\theta) = R_{AI} + G \sin^2 \theta + R_{VP} \sin^2 \theta \tan^2 \theta$$

↖
↖
↖

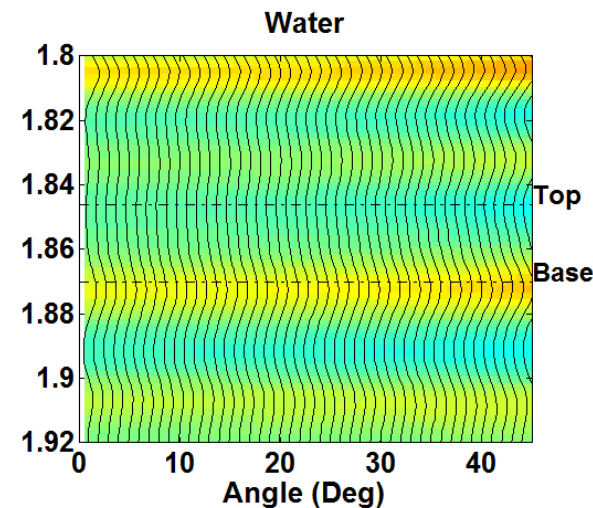
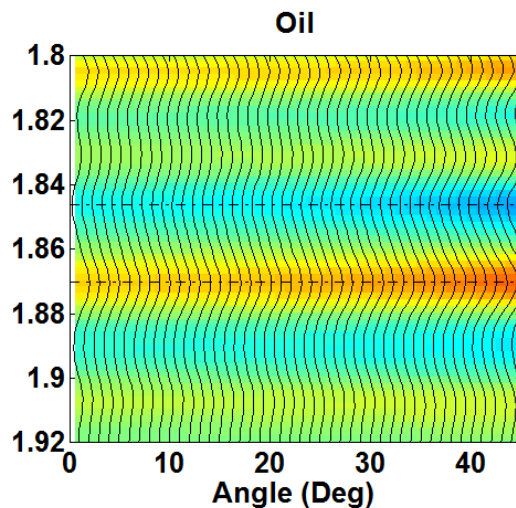
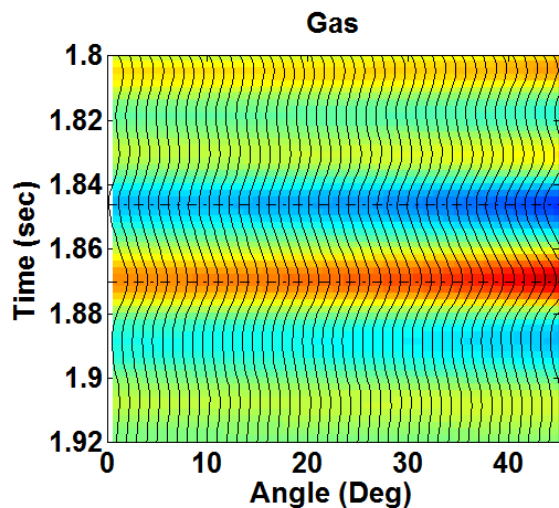
Intercept
Gradient
Curvature

Wiggins et al (1983)

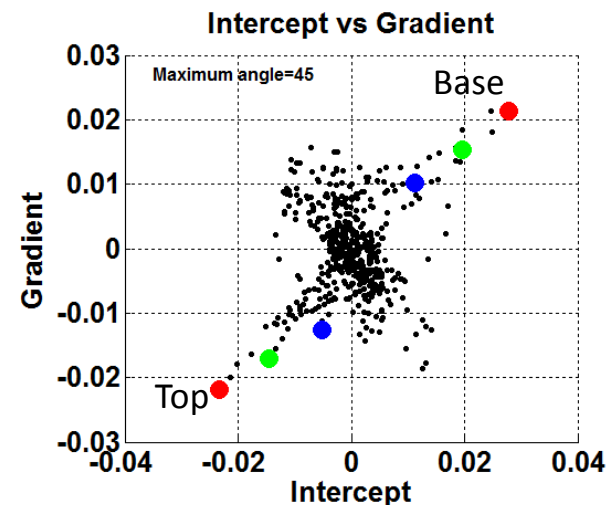
Max. Angle=45

No noise

Introduction



| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |



$$R_P(\theta) = R_{AI} + G \sin^2 \theta + R_{VP} \sin^2 \theta \tan^2 \theta$$

Intercept

Gradient

Curvature

Wiggins et al (1983)

Russell and Hampson(2006)

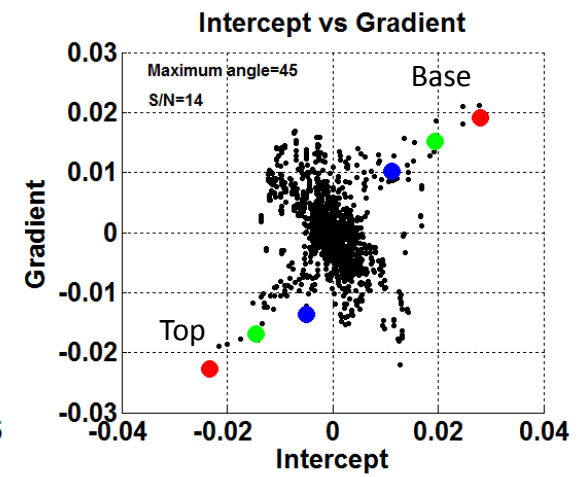
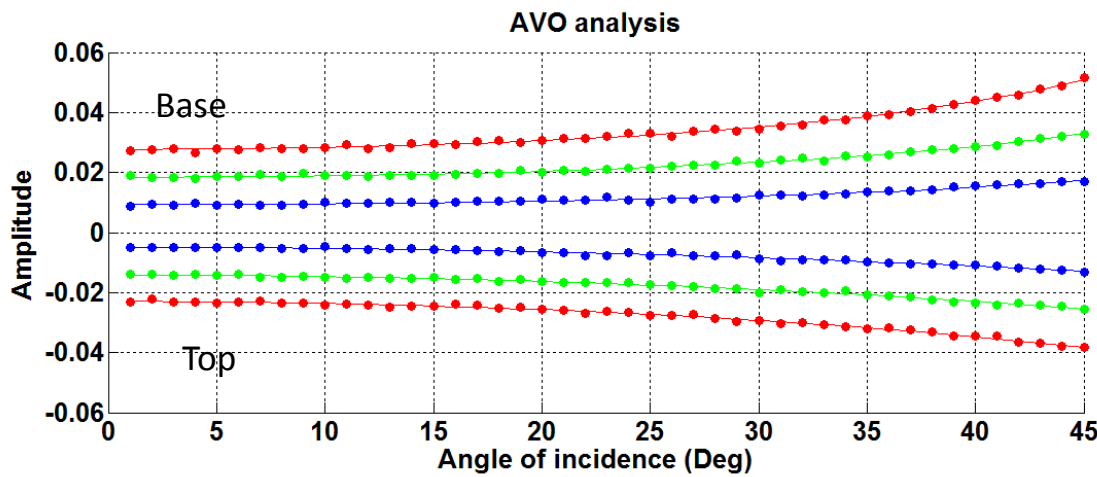
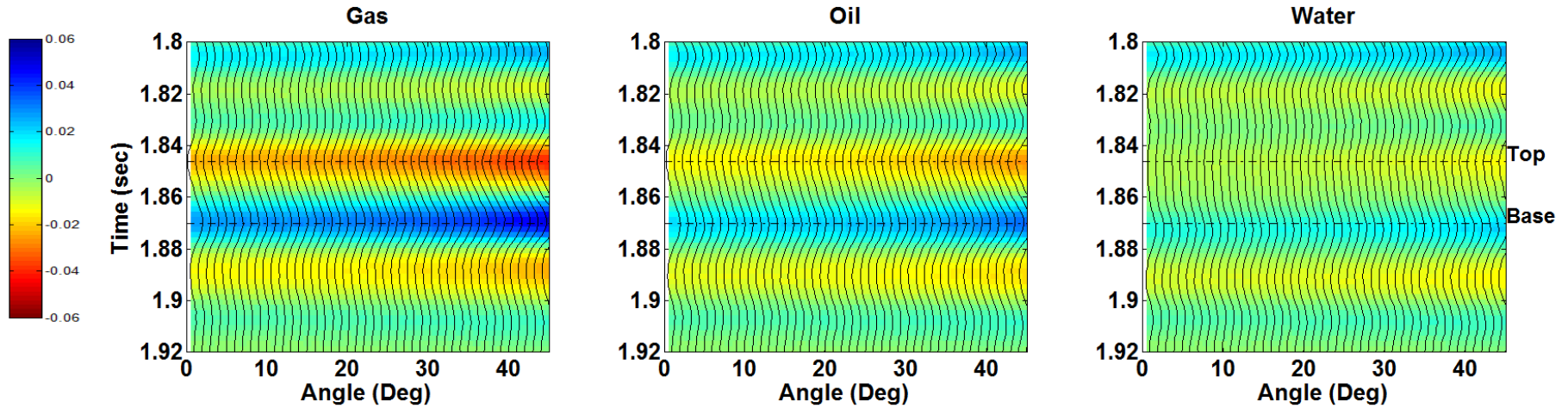
Effect of varying level of noise
keeping maximum angle constant

Max. Angle=45

S/N=14

Effect of reducing angle of incidence

Keeping maximum angle constant



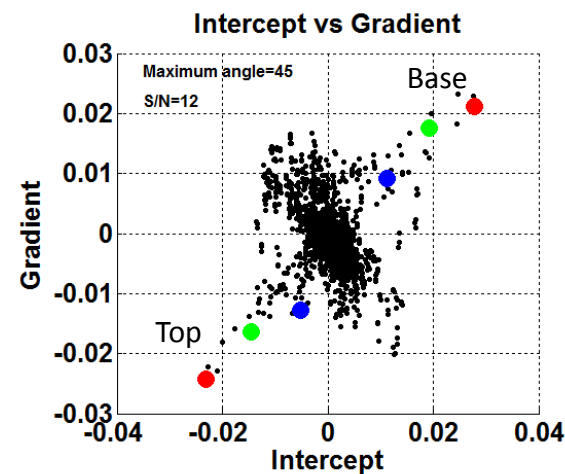
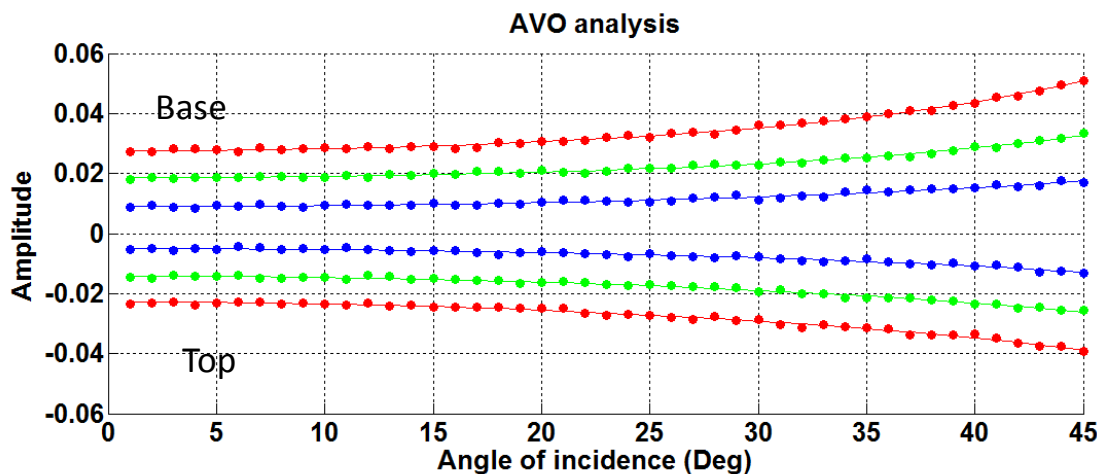
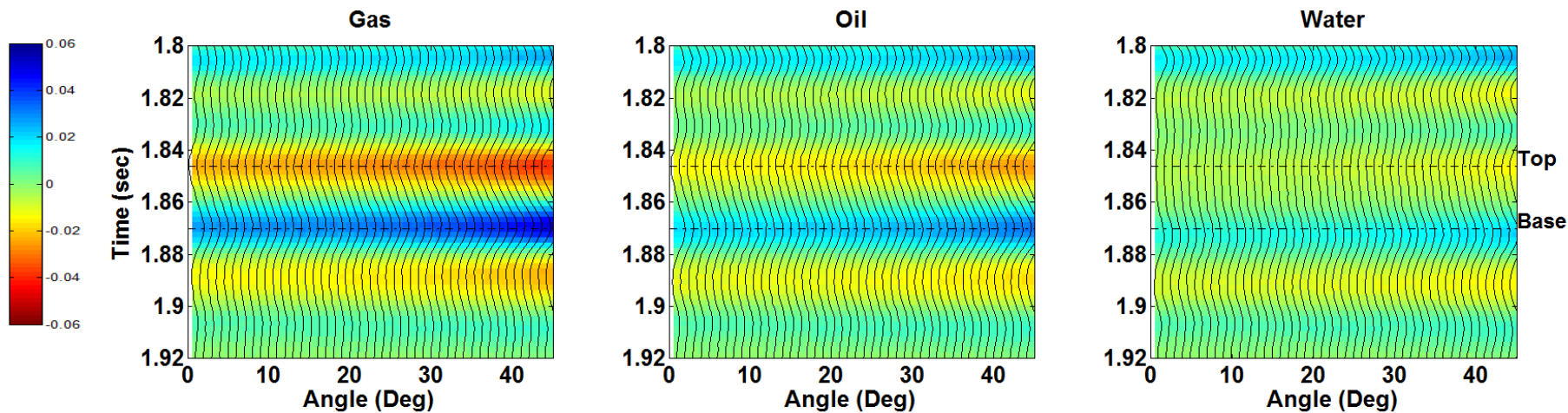
- Gas
- Oil
- Water

Max. Angle=45

S/N=12

Effect of reducing angle of incidence

Keeping maximum angle constant



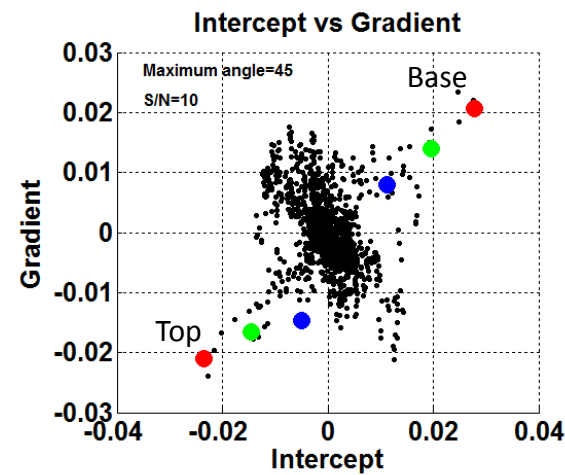
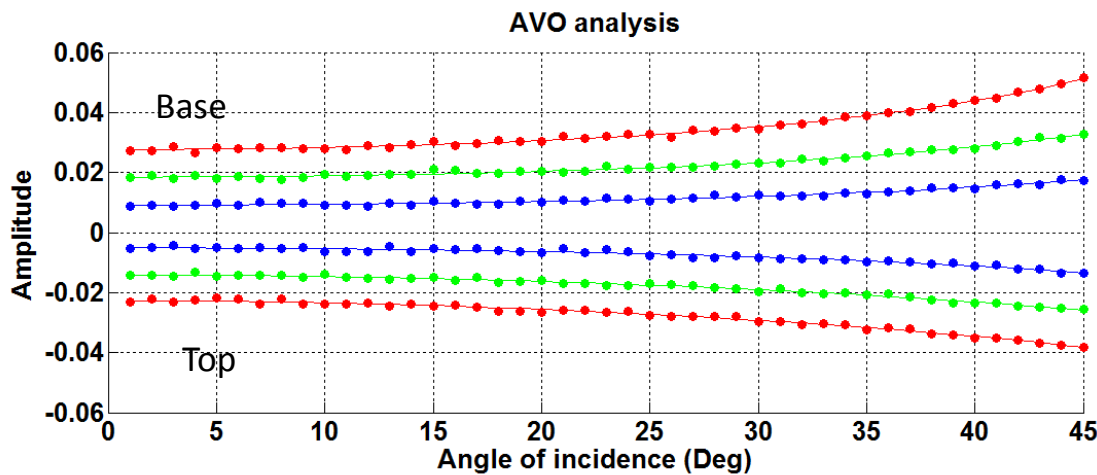
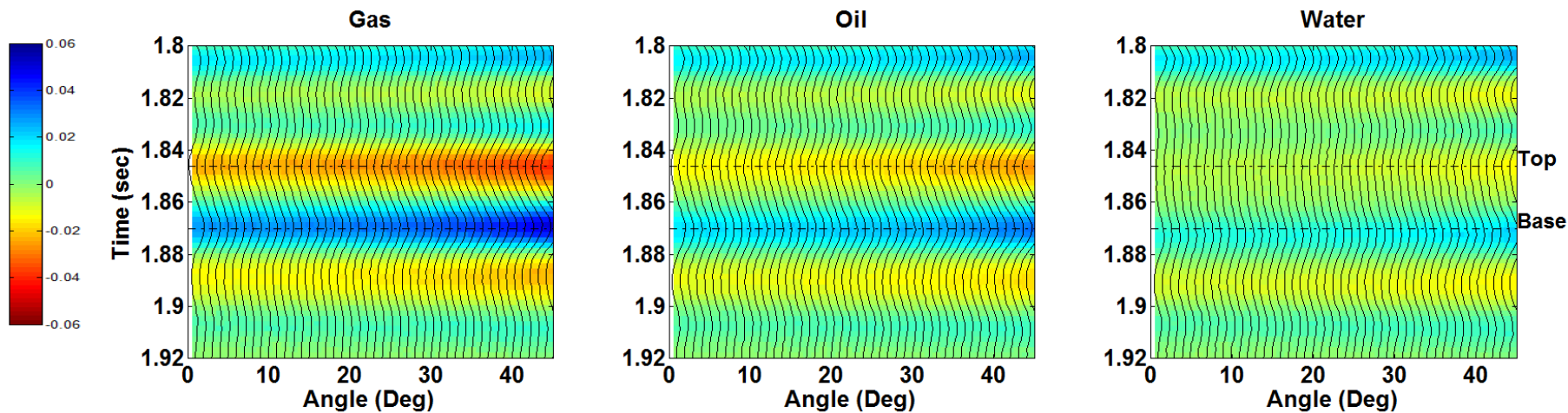
- Gas
- Oil
- Water

Max. Angle=45

S/N=10

Effect of reducing angle of incidence

Keeping maximum angle constant



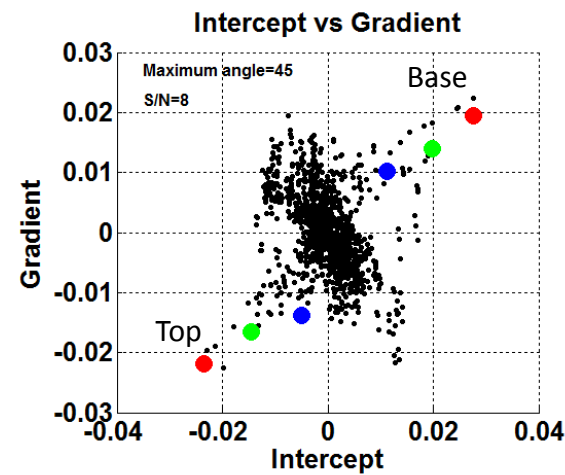
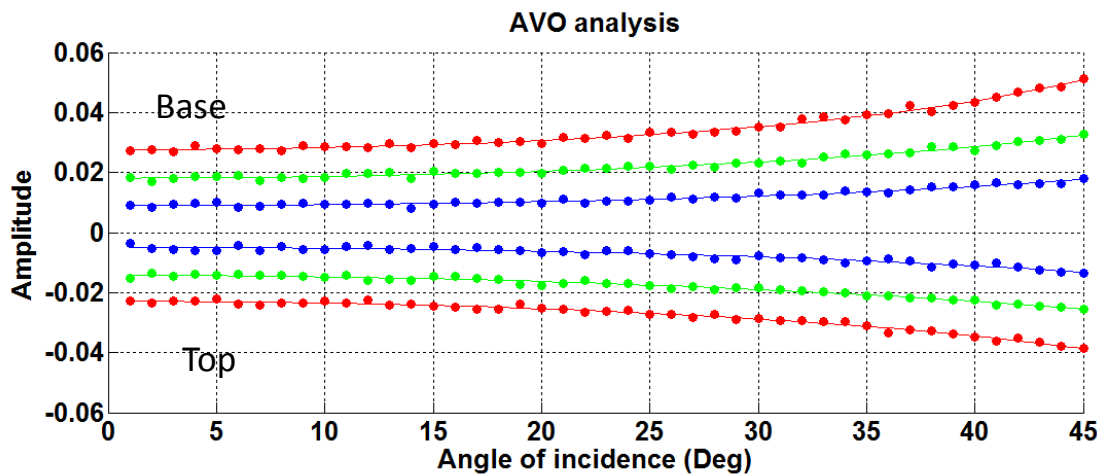
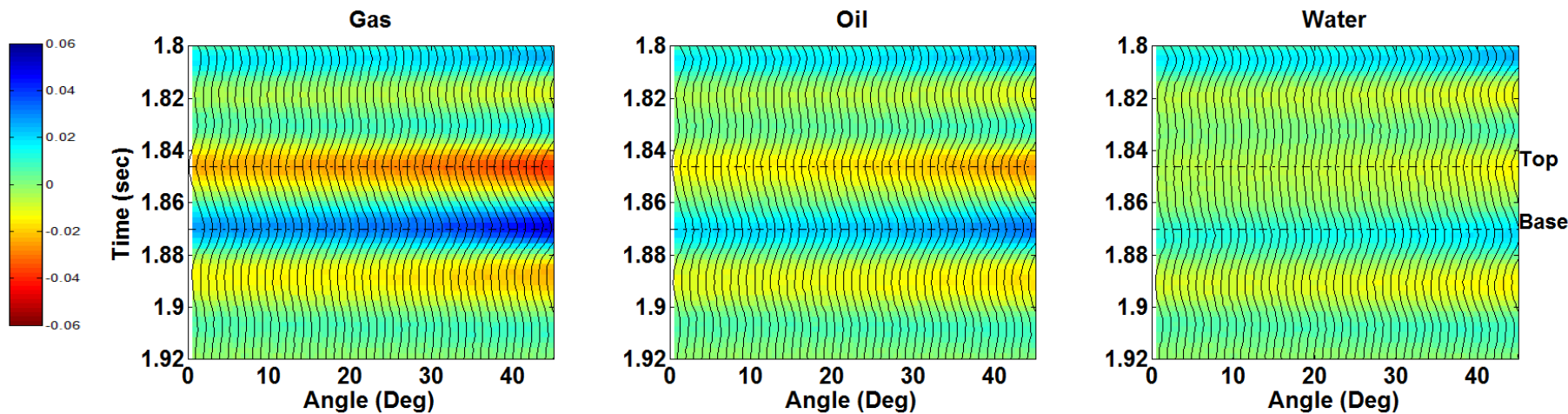
- Gas
- Oil
- Water

Max. Angle=45

S/N=8

Effect of reducing angle of incidence

Keeping maximum angle constant



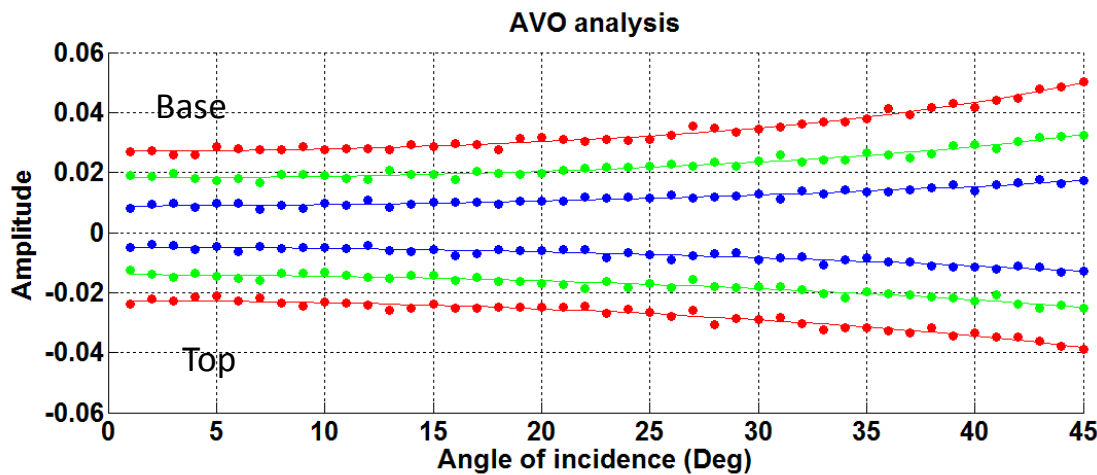
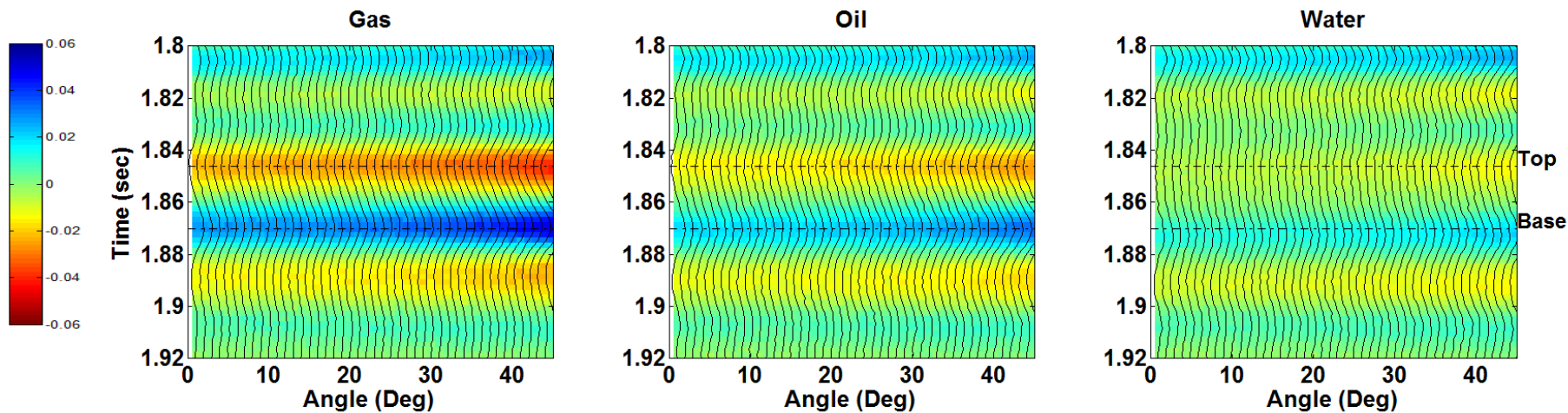
- Gas
- Oil
- Water

Max. Angle=45

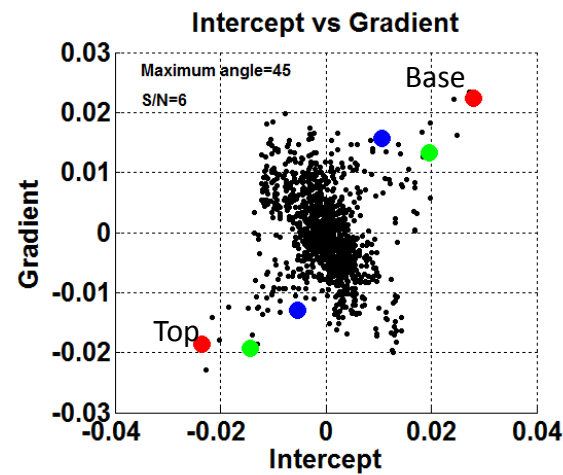
S/N=6

Effect of reducing angle of incidence

Keeping maximum angle constant



- Gas
- Oil
- Water

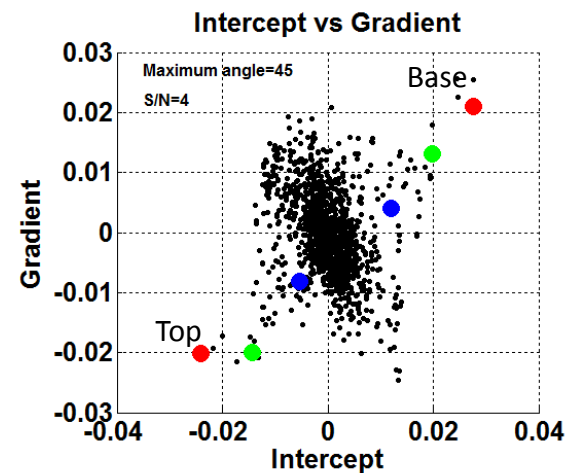
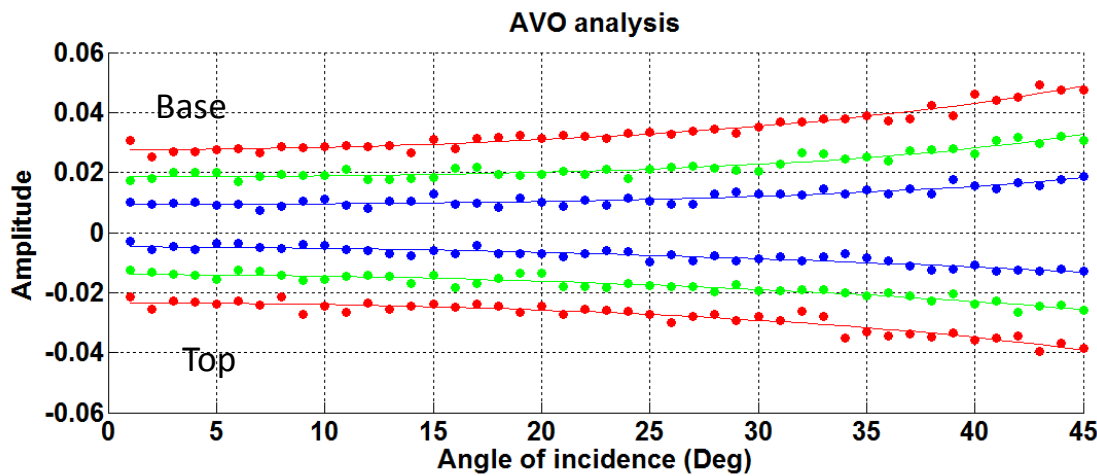
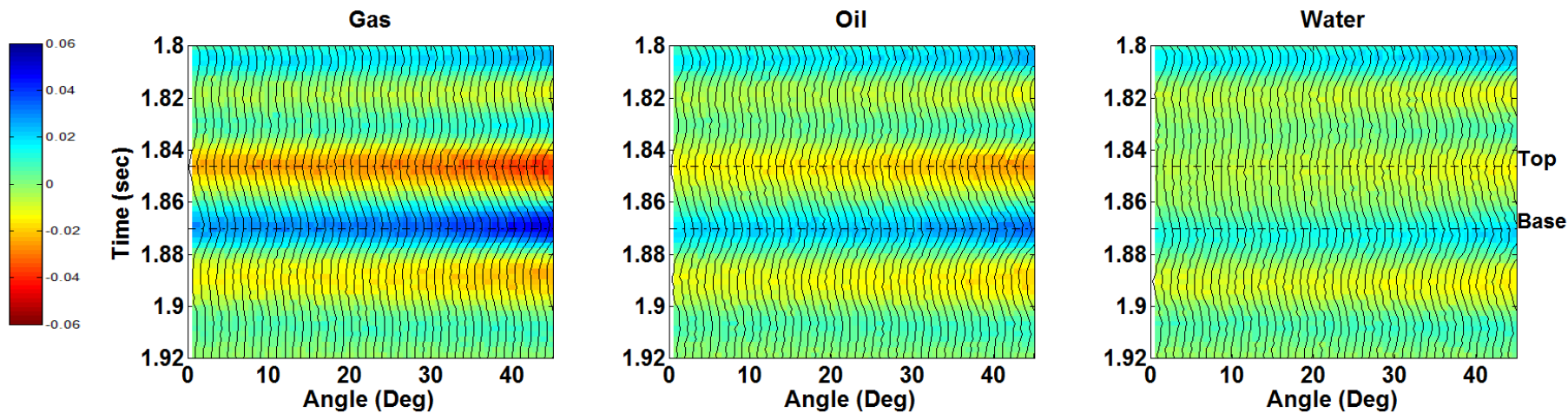


Max. Angle=45

S/N=4

Effect of reducing angle of incidence

Keeping maximum angle constant



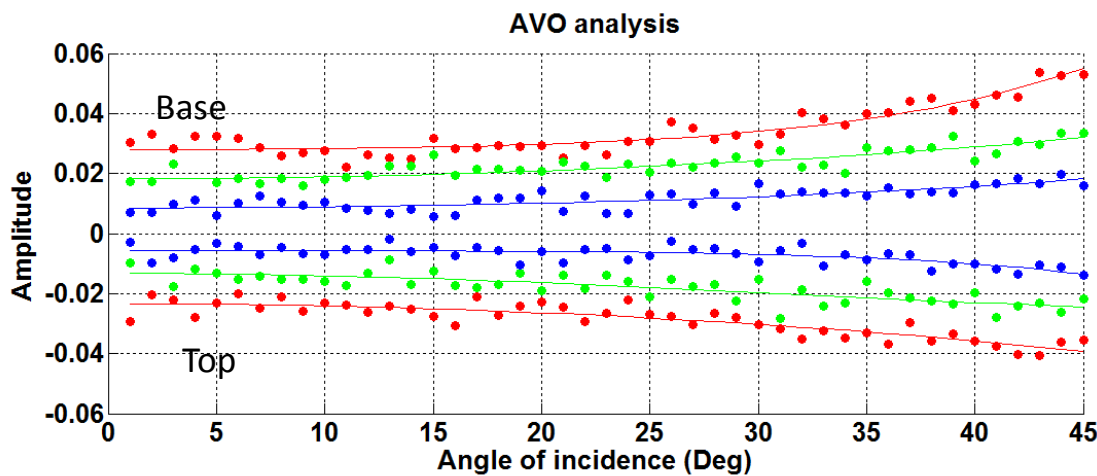
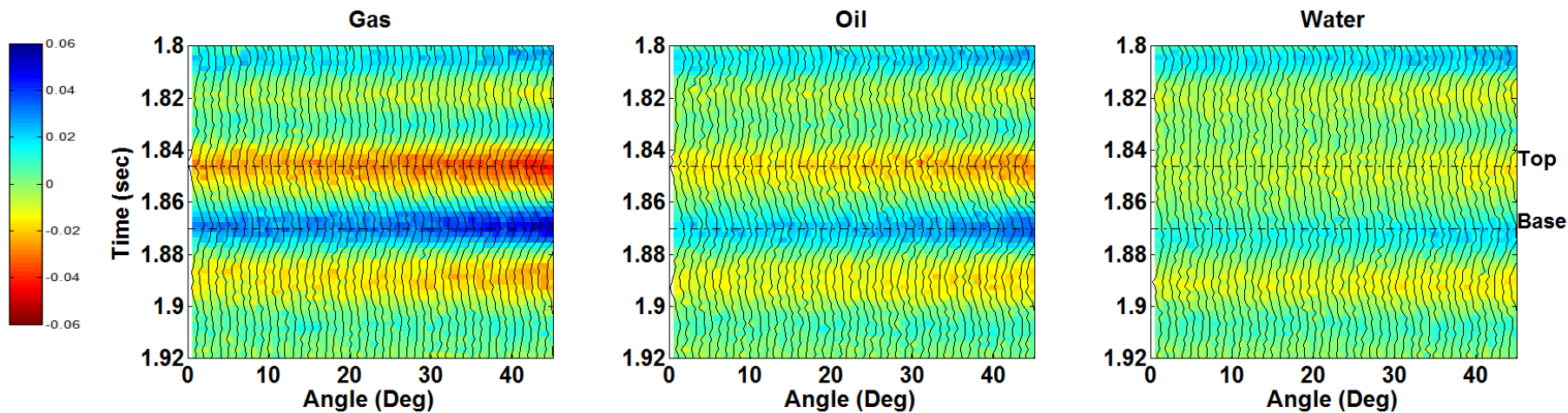
- Gas
- Oil
- Water

Max. Angle=45

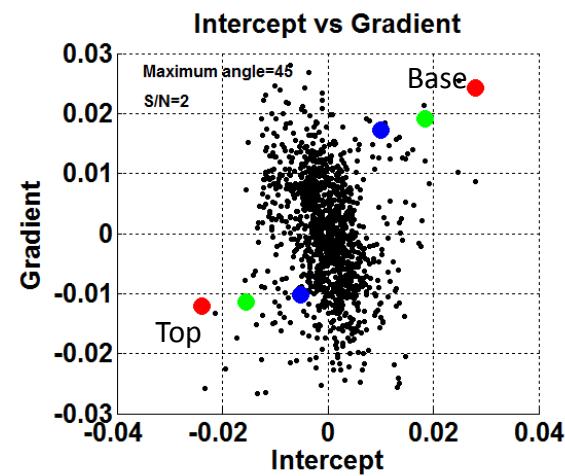
S/N=2

Effect of reducing angle of incidence

Keeping maximum angle constant



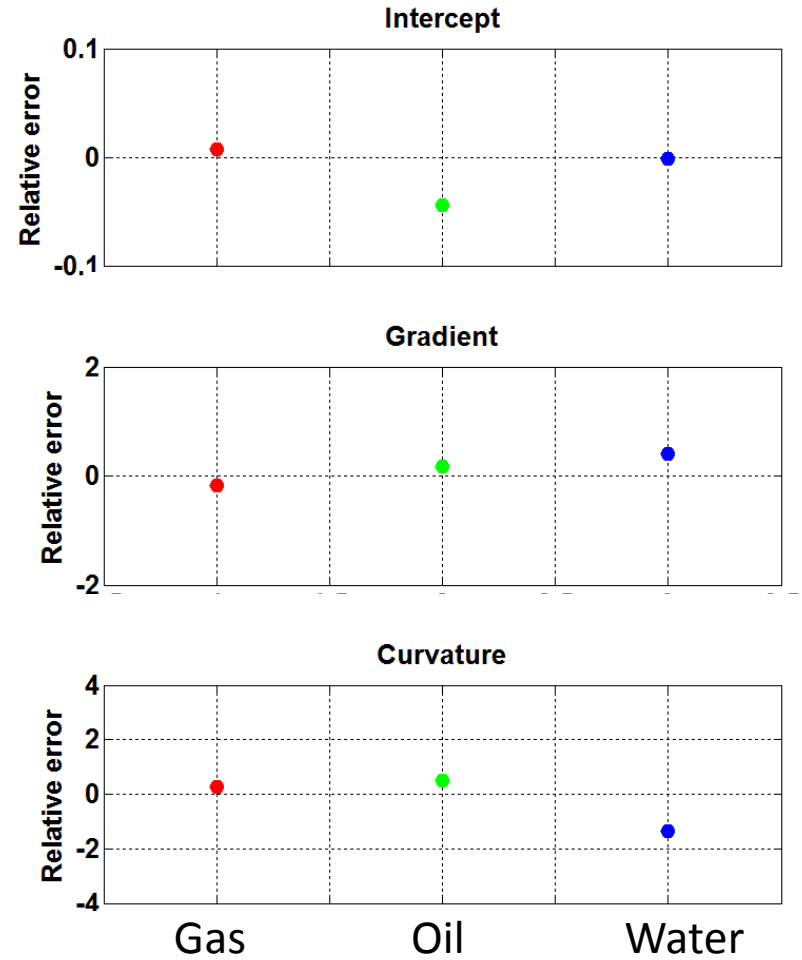
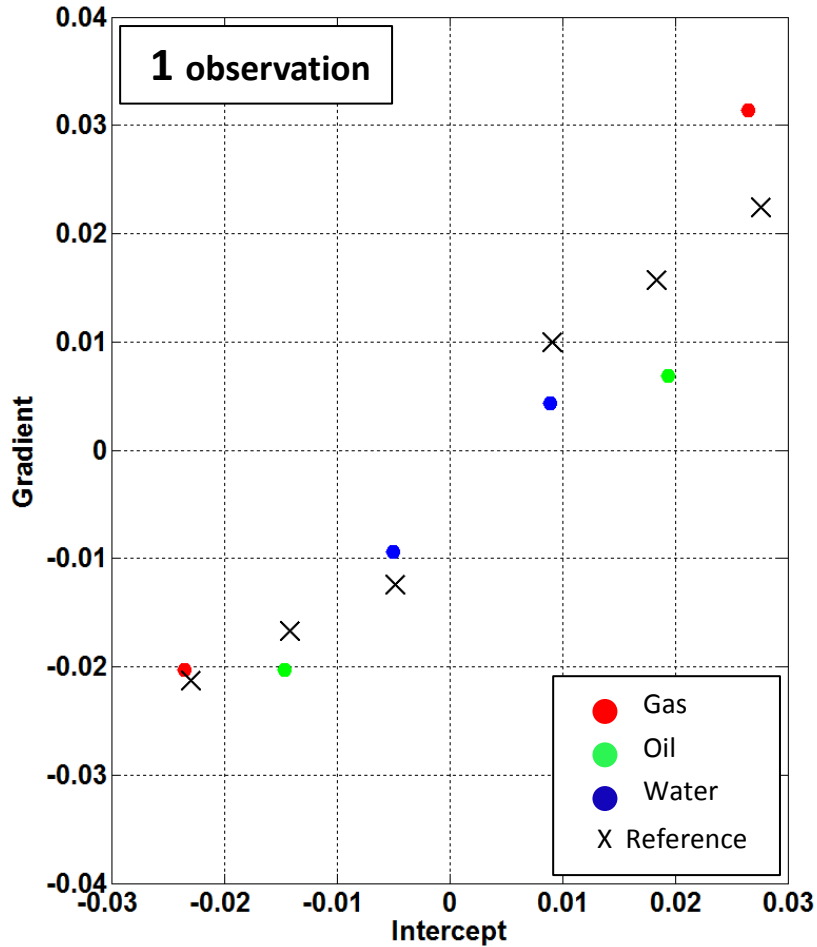
- Gas
- Oil
- Water



Measuring error and standard deviation

S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

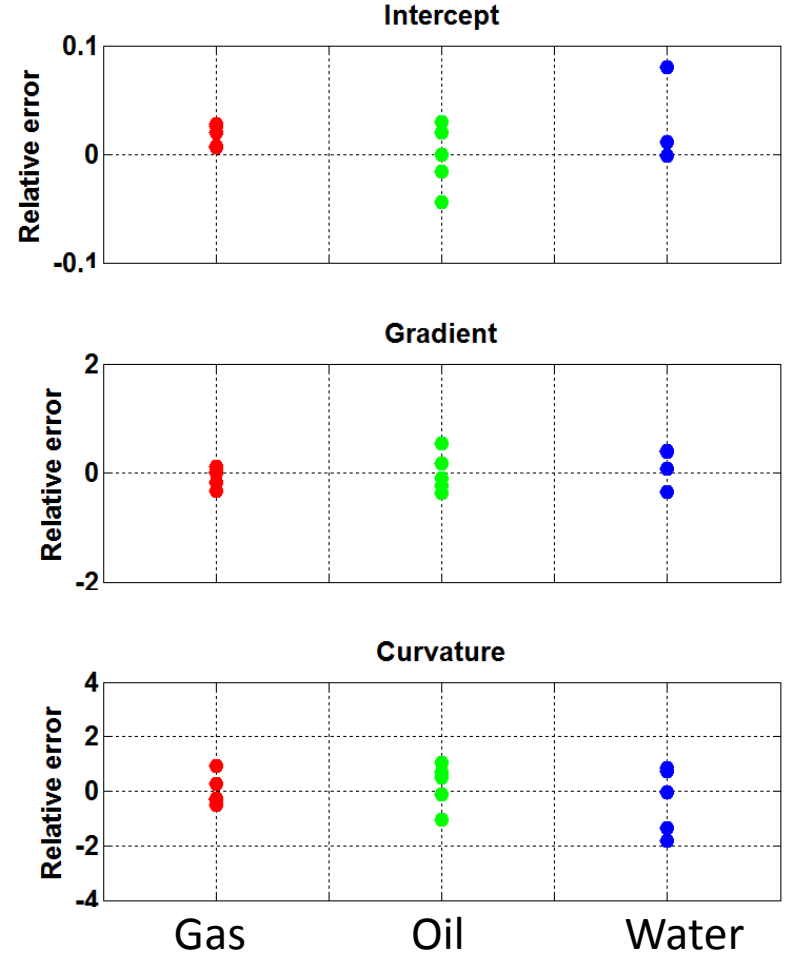
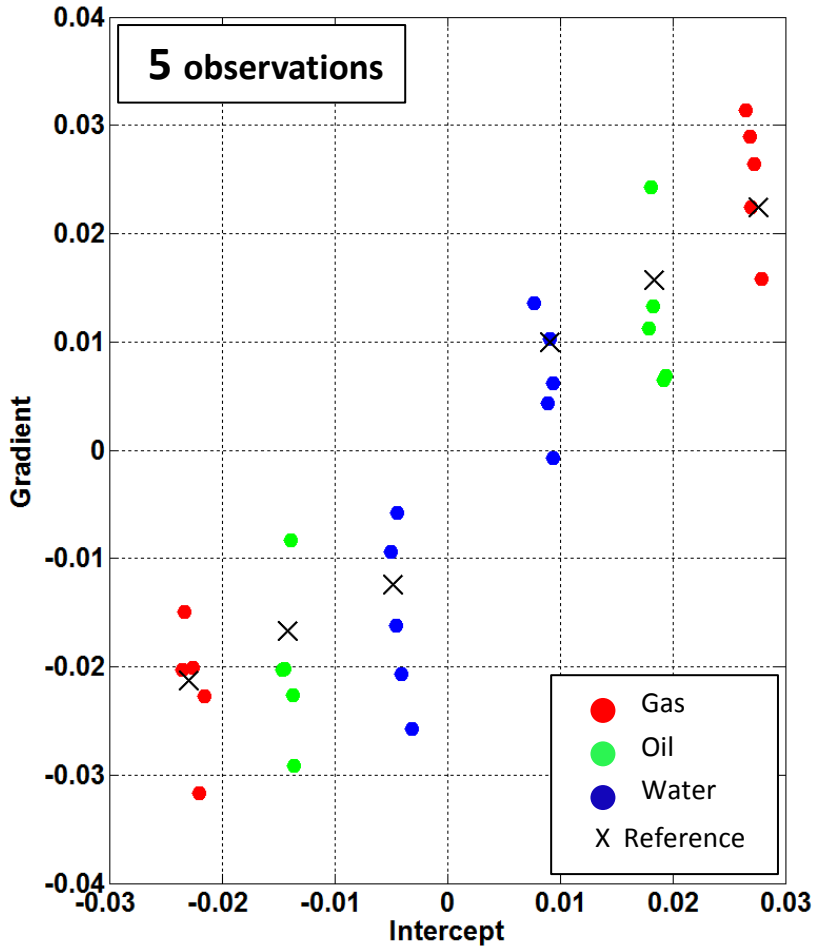
No noise

Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

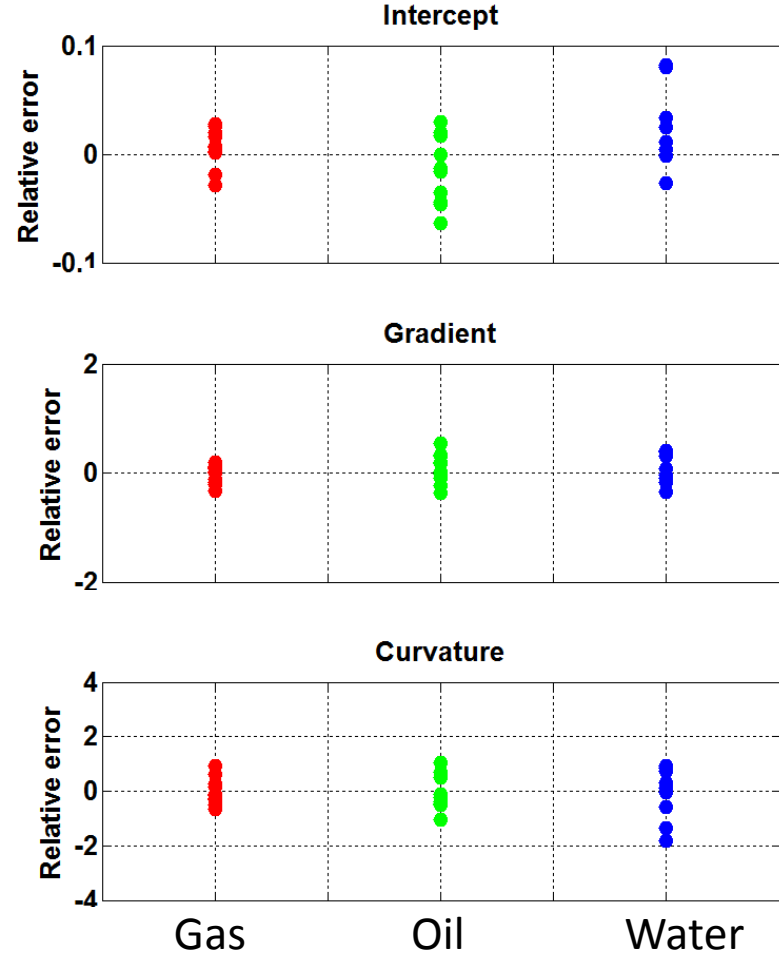
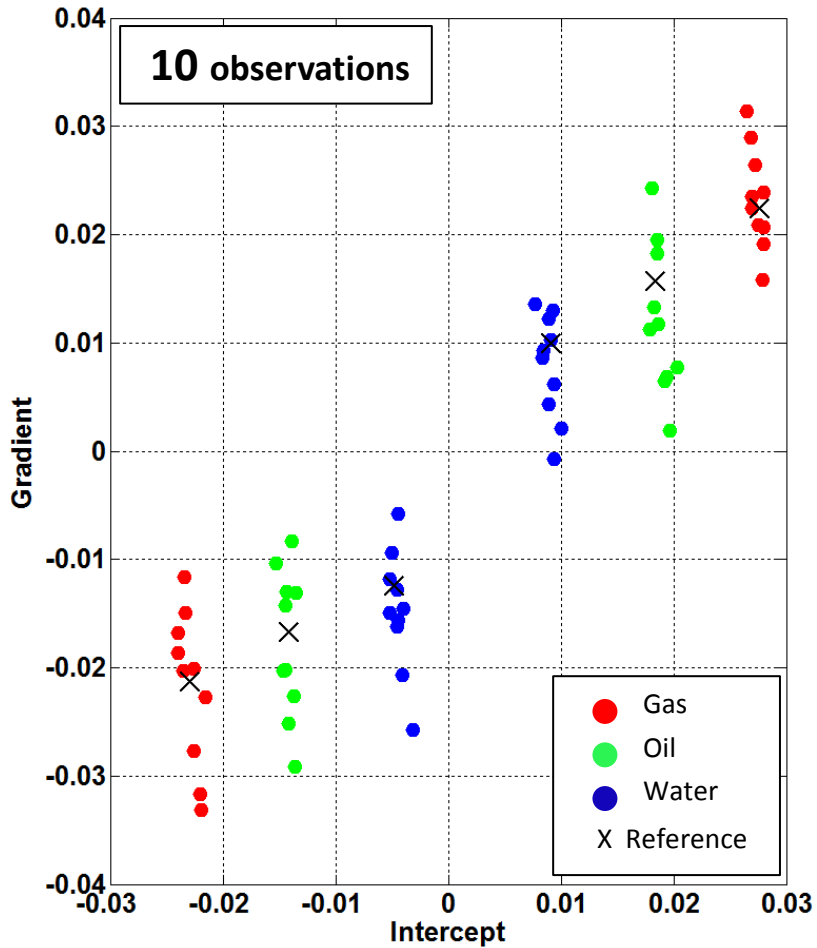
No noise

Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

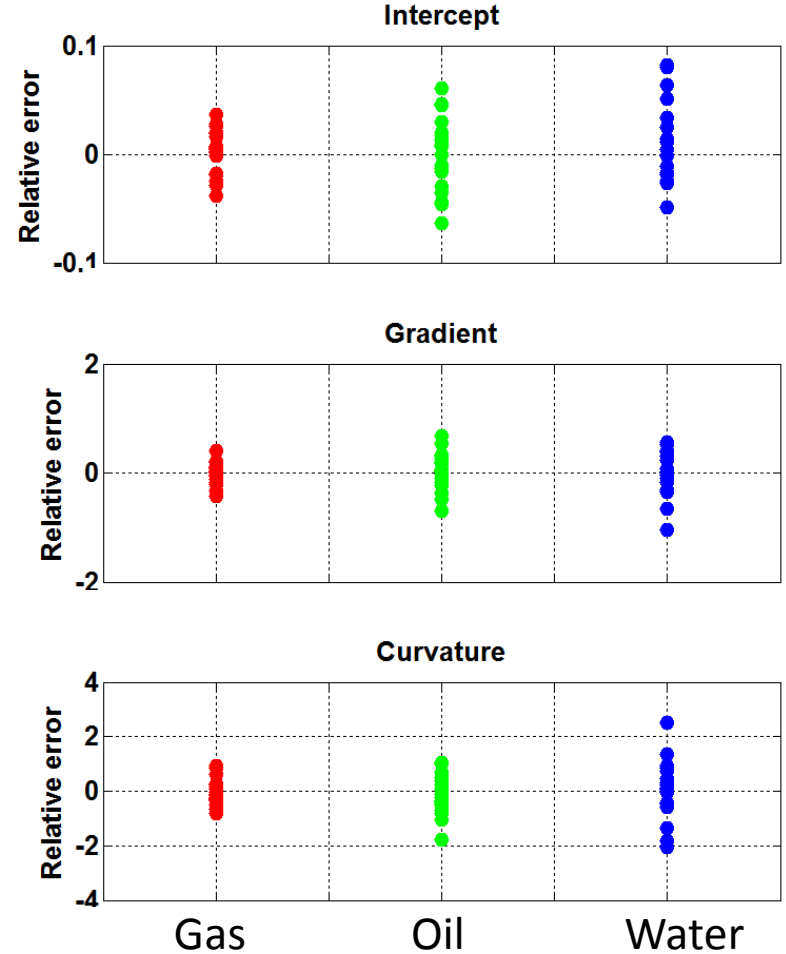
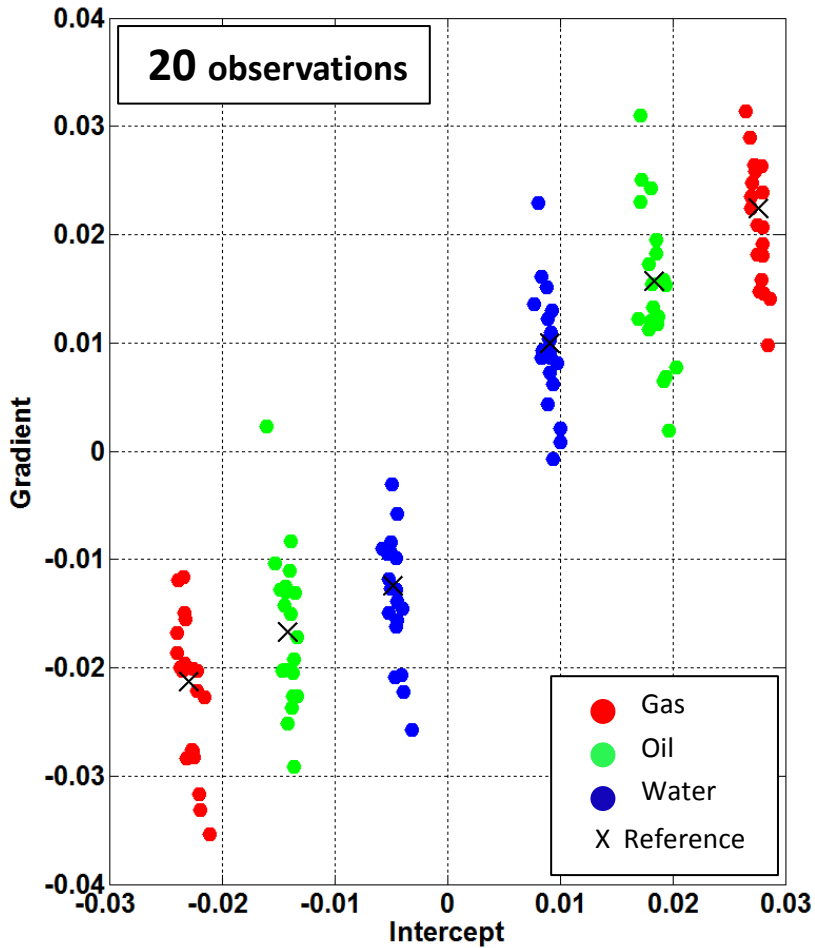
No noise

Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
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S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

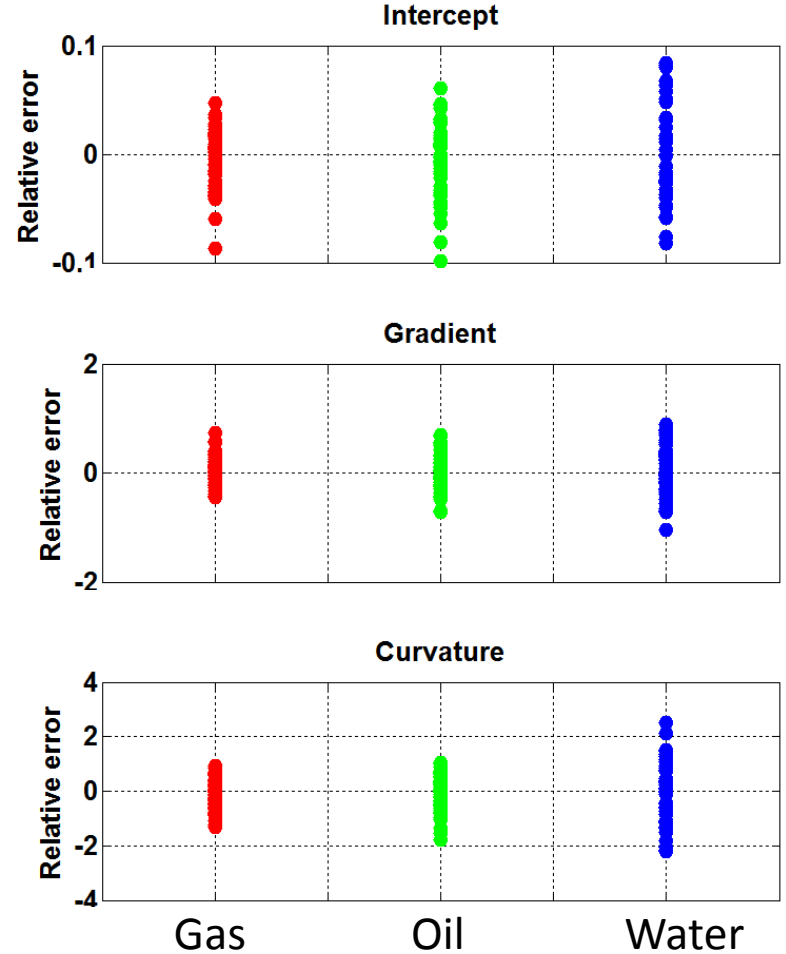
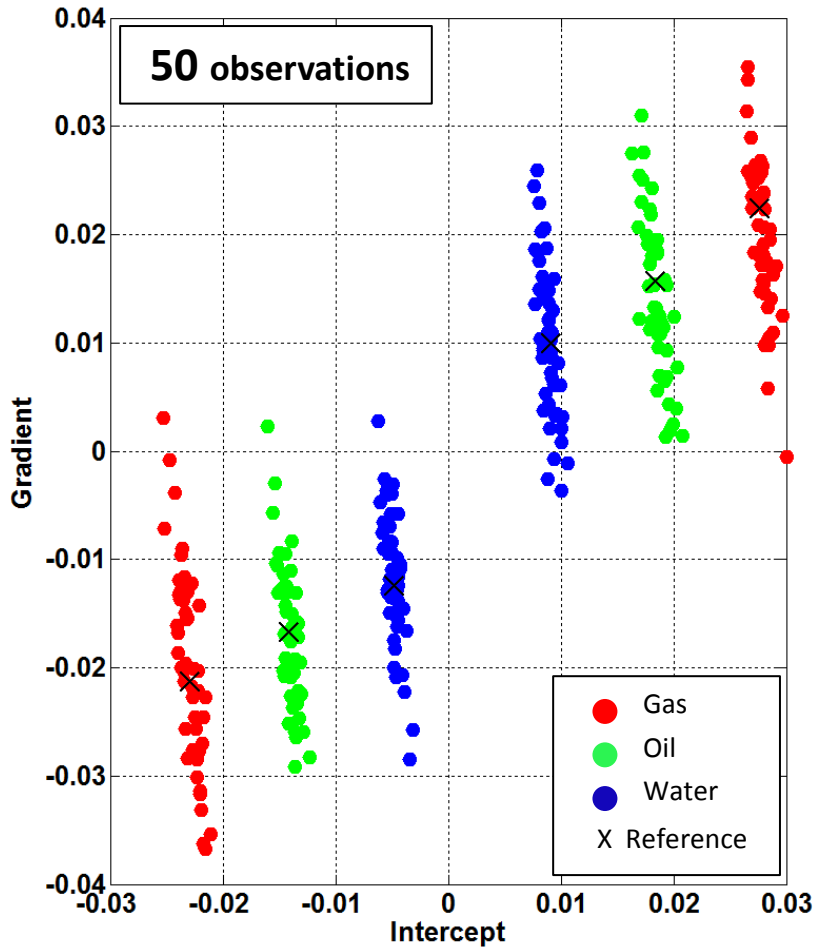
No noise

Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

No noise

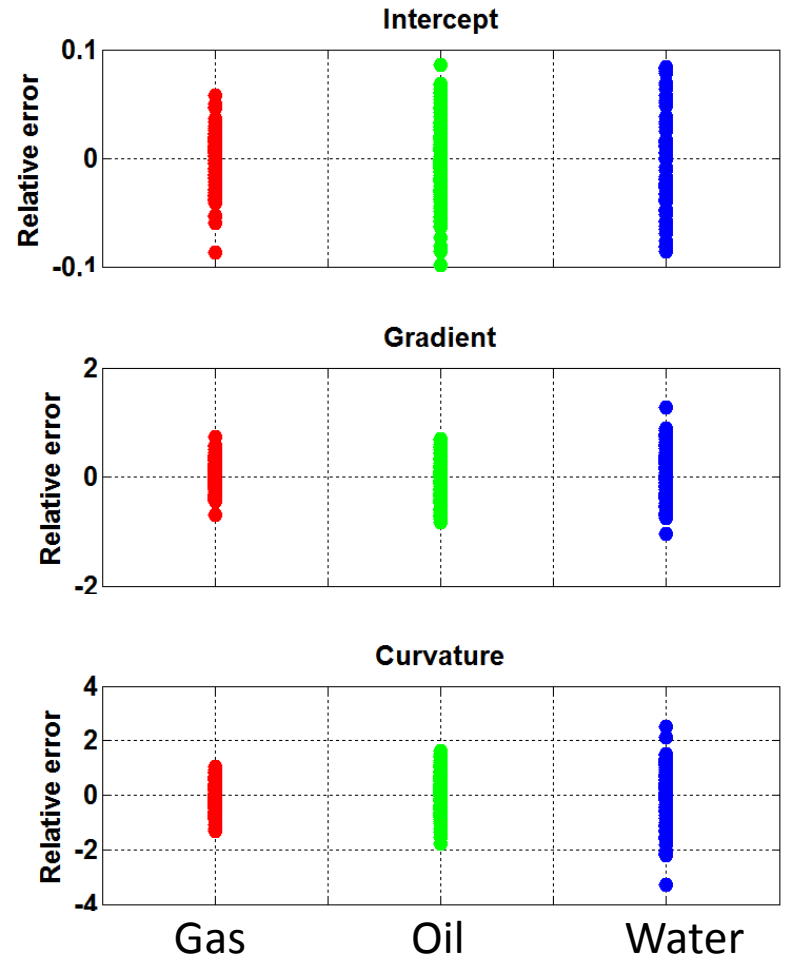
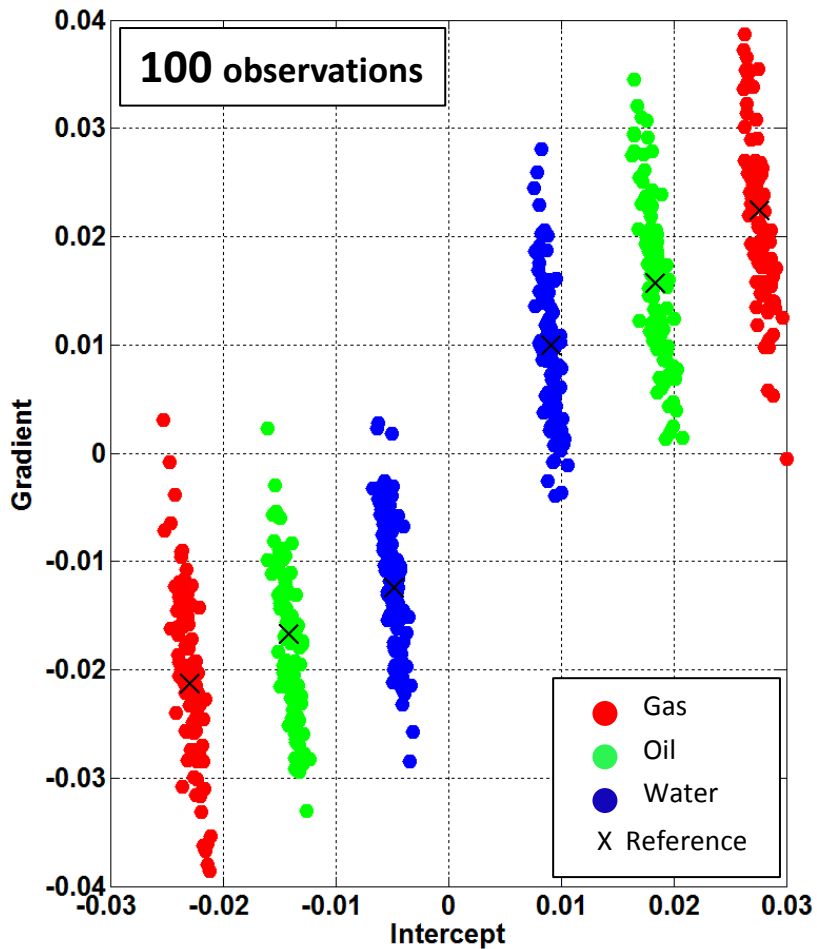
Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

S/N=2

Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

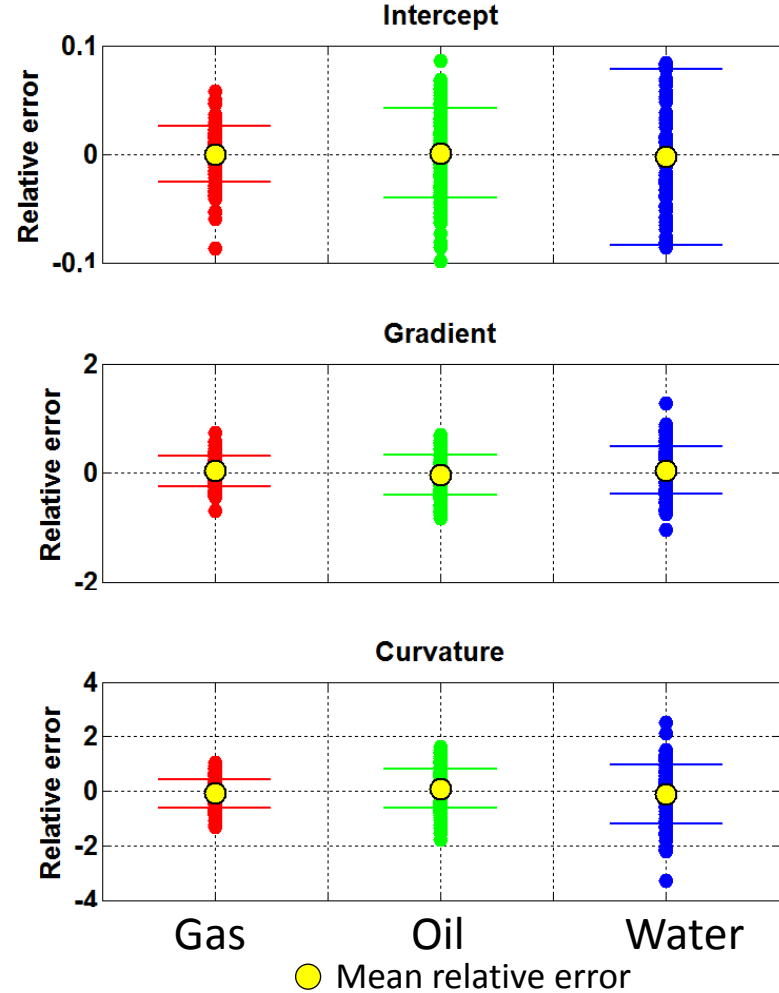
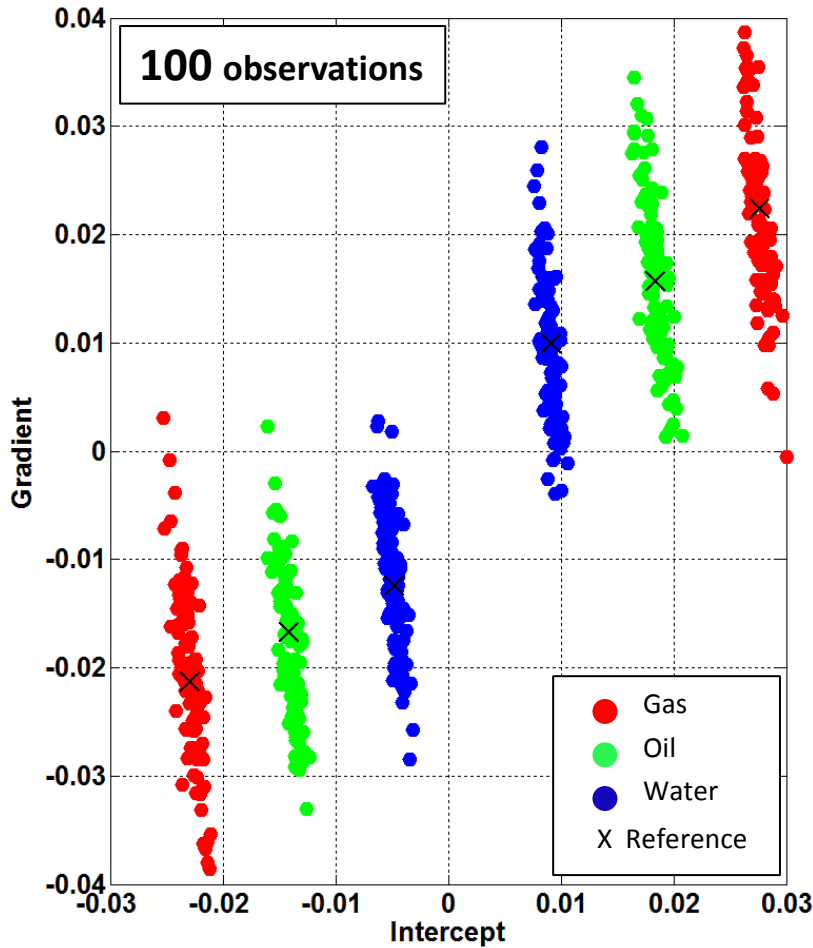
No noise

Max. angle: 45 deg

| | TOP | | | BASE | | |
|-------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

S/N=2
 Max. Angle=45 deg.

Measuring error and standard deviation



Reference to measure the error

No noise

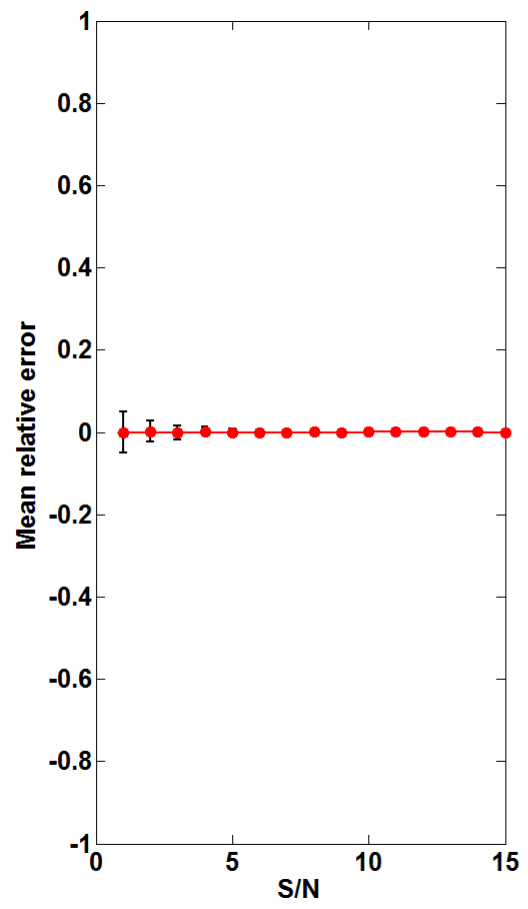
Max. angle: 45 deg

| | TOP | | | BASE | | |
|--------------|-----------|----------|-----------|-----------|----------|-----------|
| | Intercept | Gradient | Curvature | Intercept | Gradient | Curvature |
| GAS | -0.023 | -0.021 | -0.010 | 0.028 | 0.022 | 0.024 |
| OIL | -0.014 | -0.017 | -0.007 | 0.018 | 0.016 | 0.013 |
| WATER | -0.005 | -0.012 | -0.004 | 0.009 | 0.010 | 0.007 |

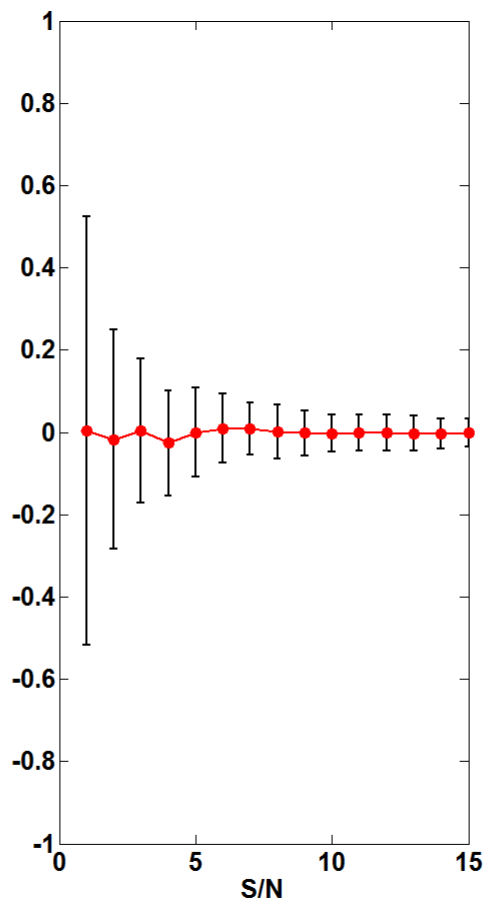
Max. Angle=45

GAS-error

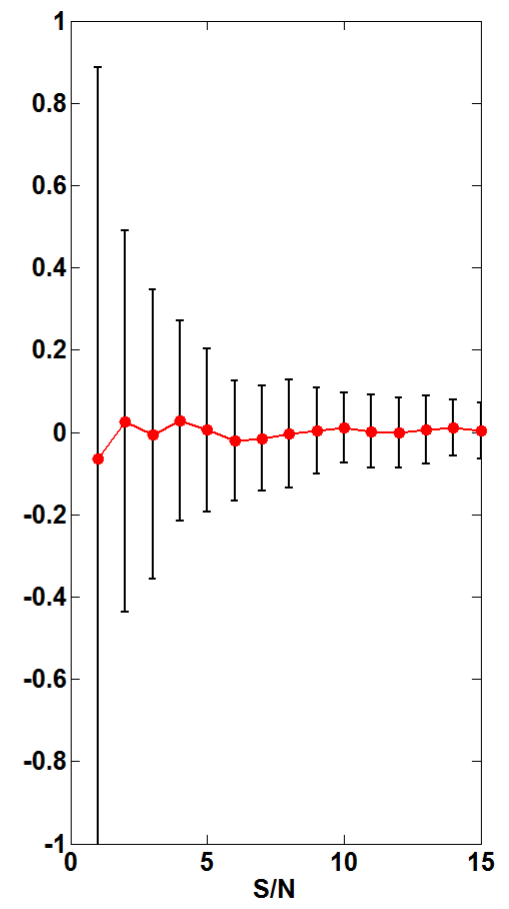
Intercept



Gradient

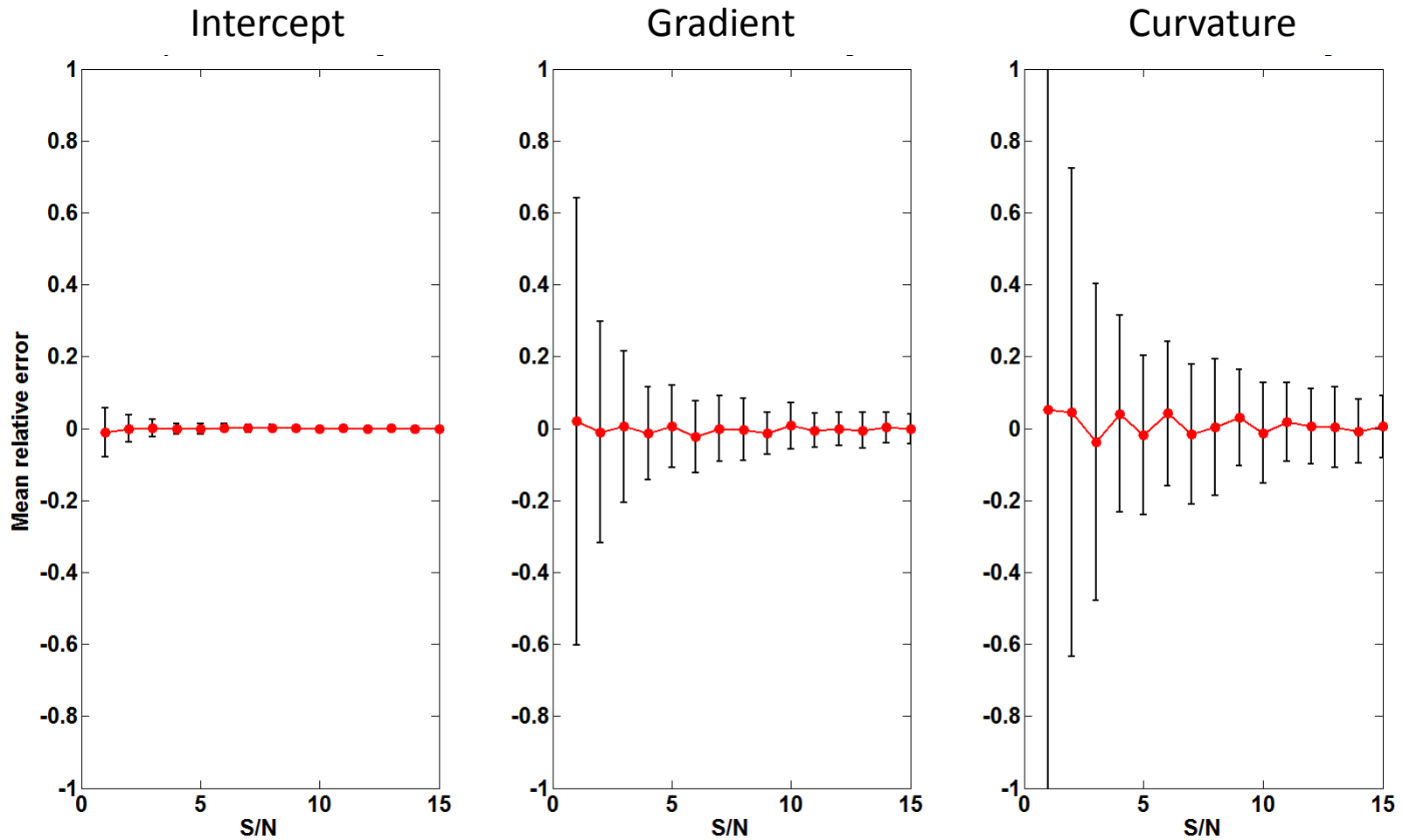


Curvature



Max. Angle=45

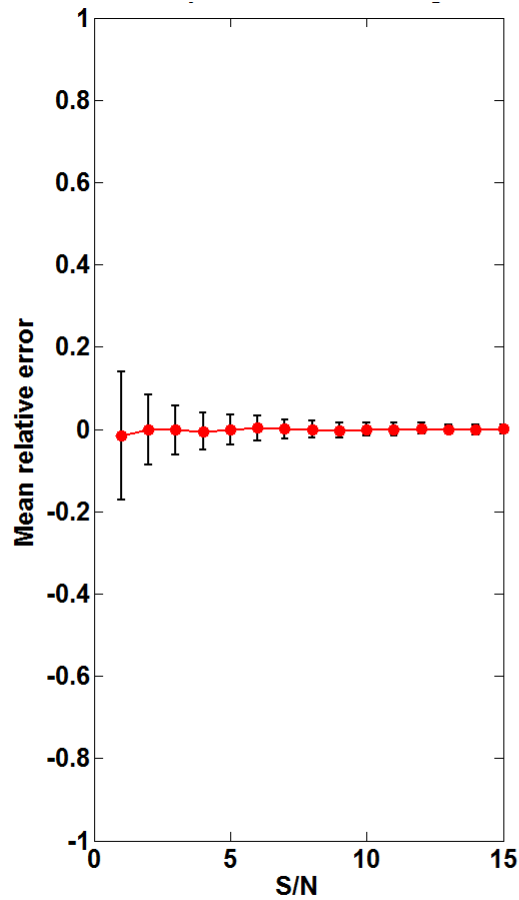
OIL-error



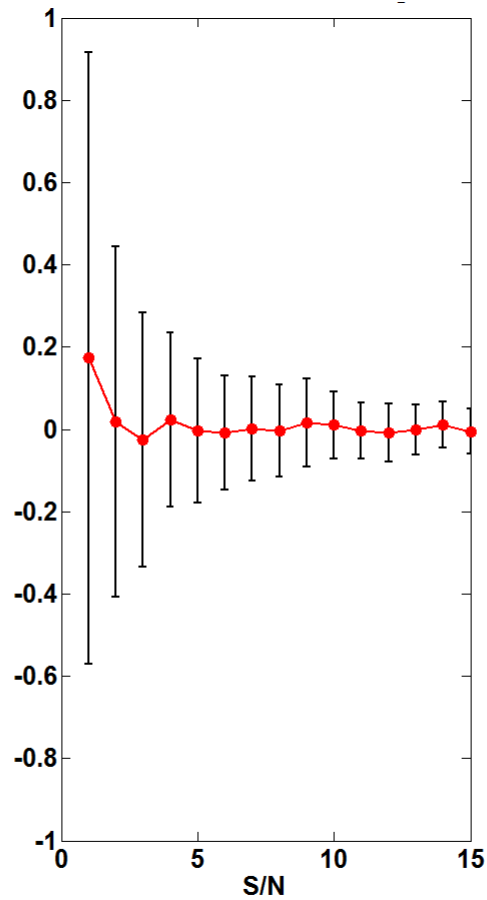
Max. Angle=45

WATER-error

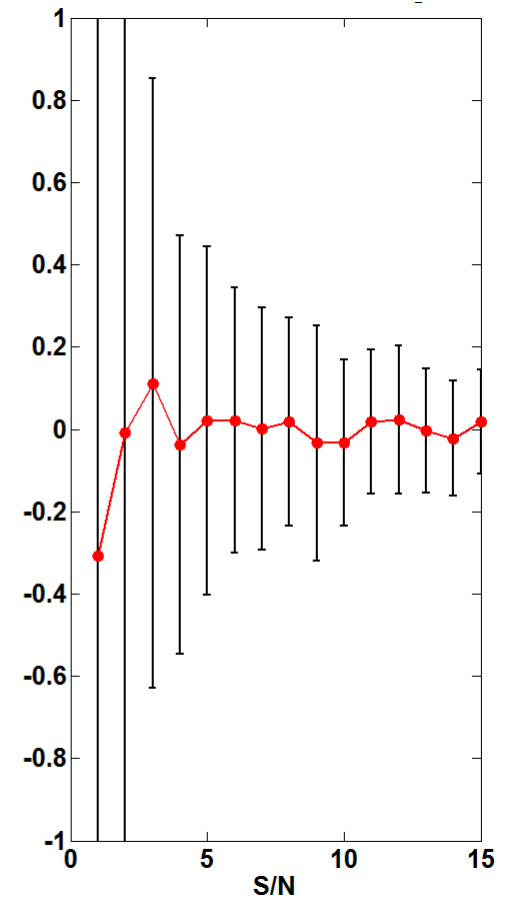
Intercept



Gradient

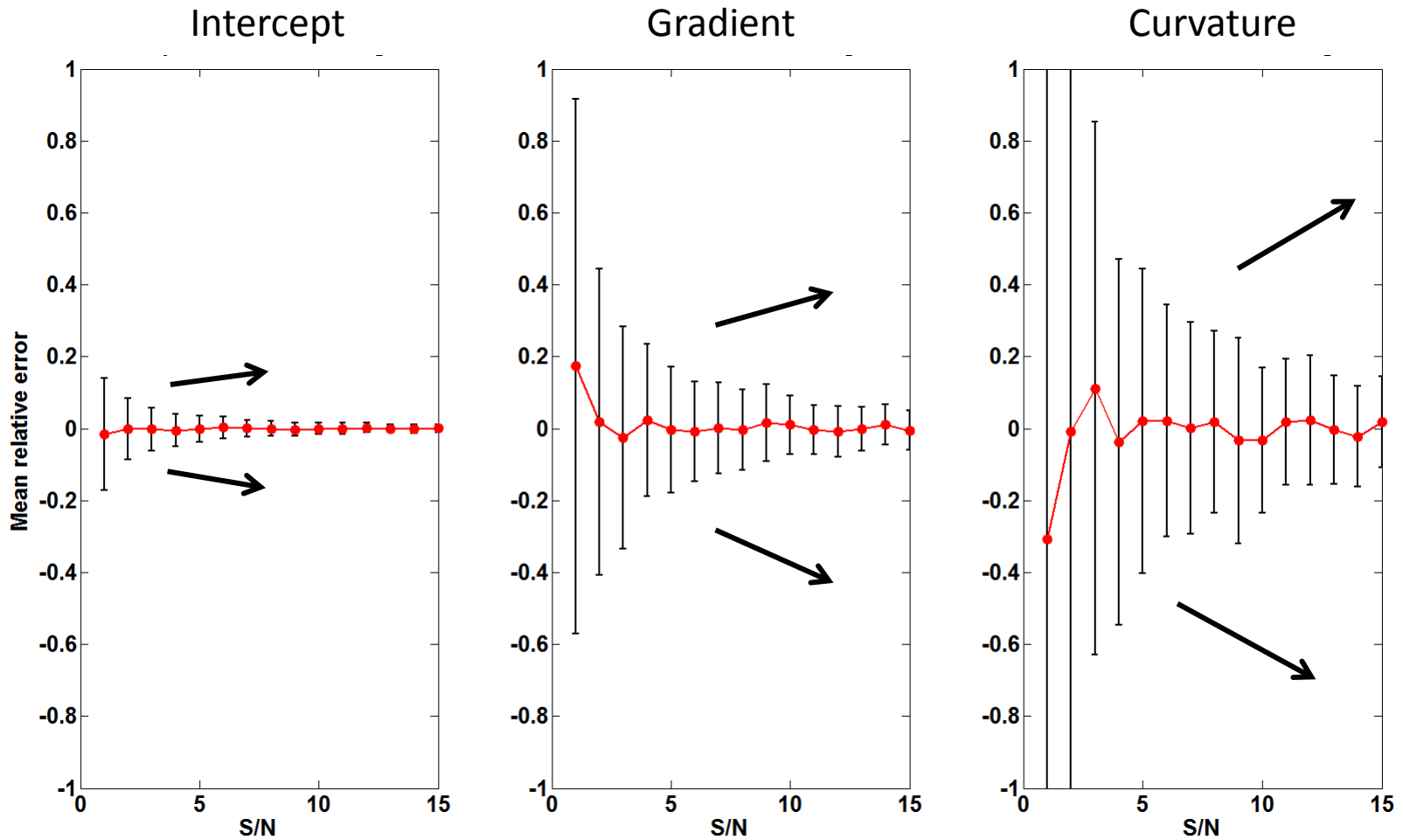


Curvature



Max. Angle=45

WATER-error



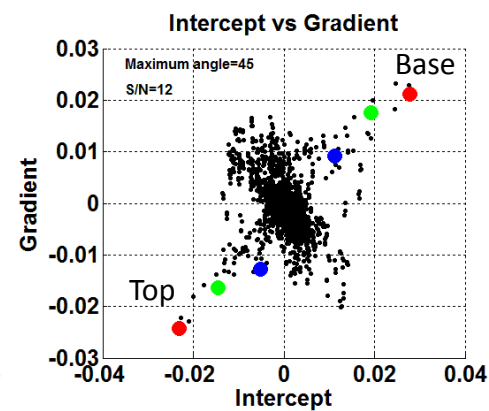
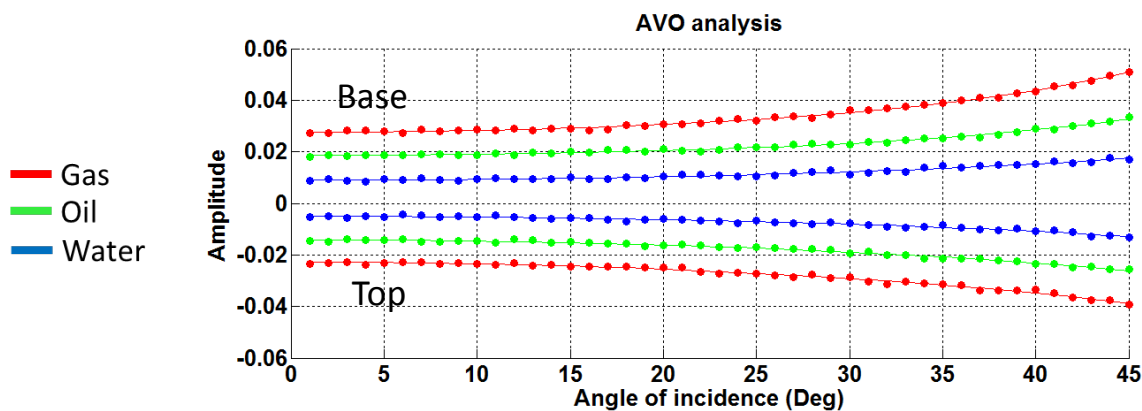
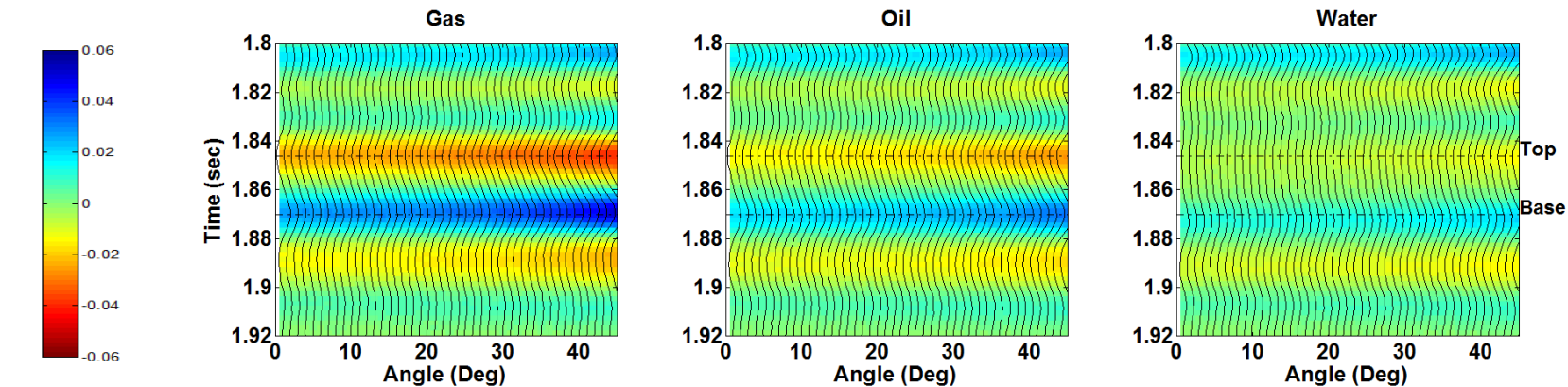
The error increases as the impedance contrast decreases

Effect of reducing angle of incidence
keeping noise constant

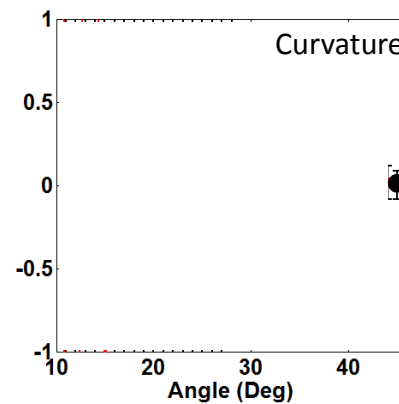
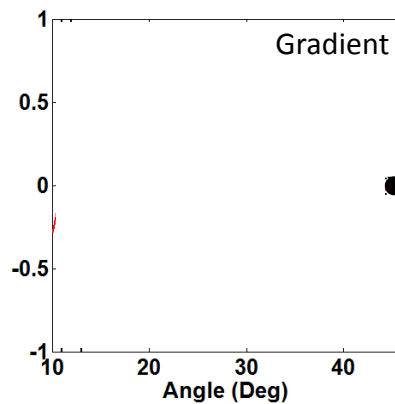
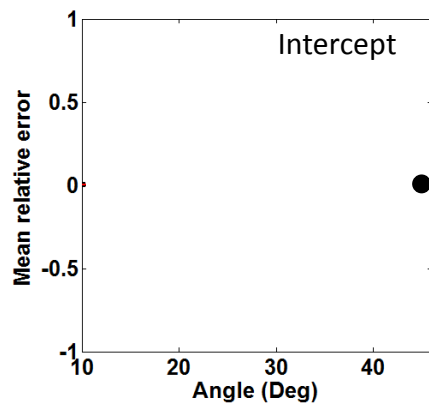
Max. Angle=45

S/N=12

Effect of reducing angle of incidence
keeping noise constant



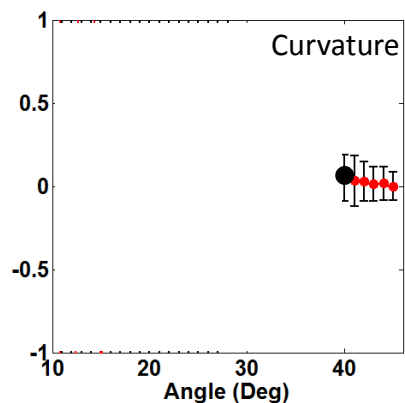
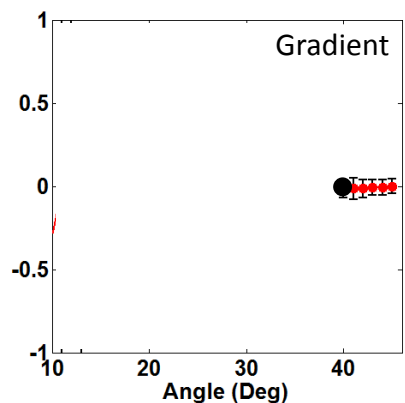
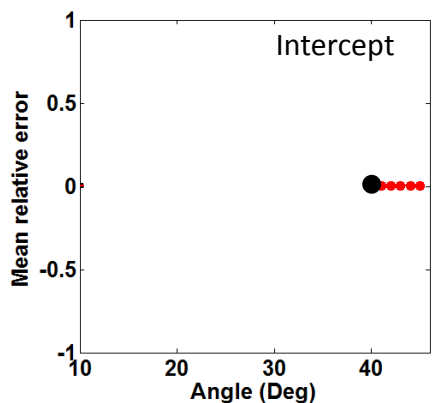
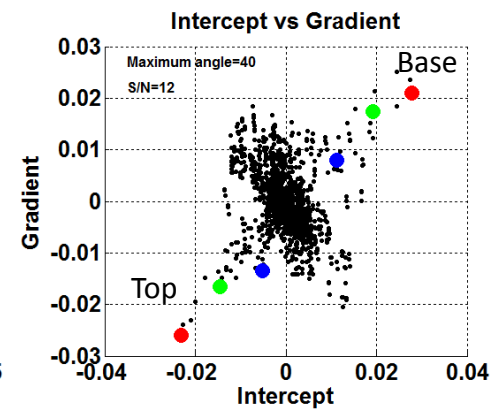
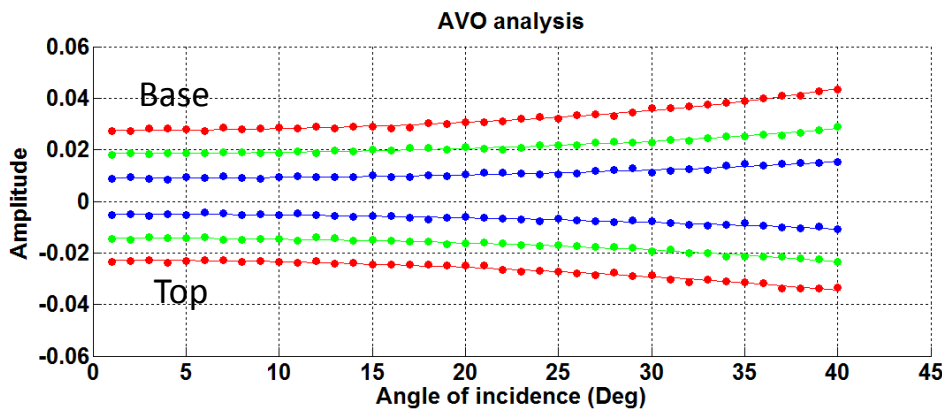
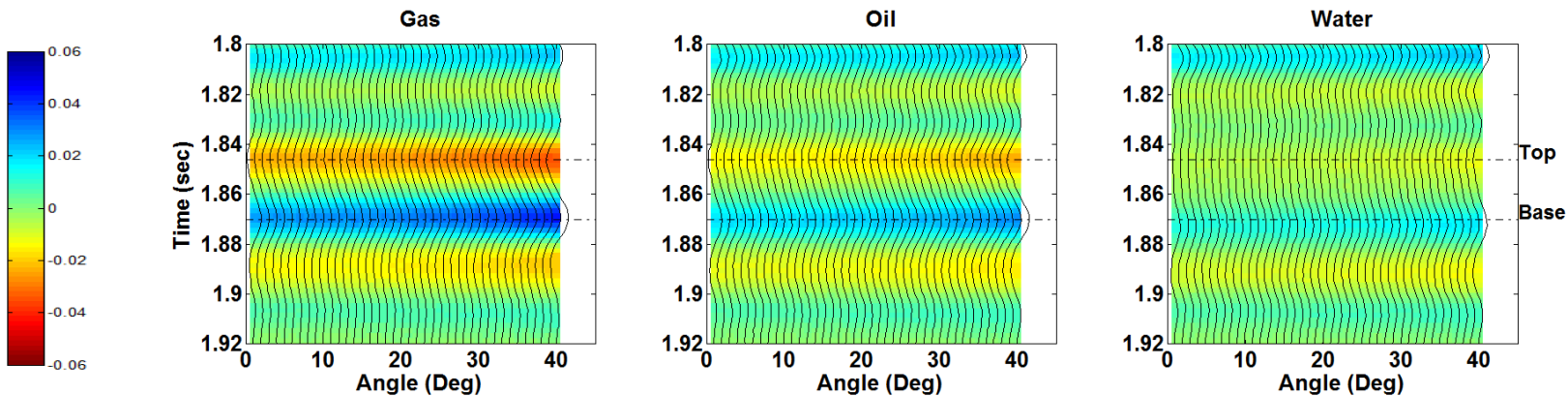
GAS error



Max. Angle=40

S/N=12

Effect of reducing angle of incidence
keeping noise constant

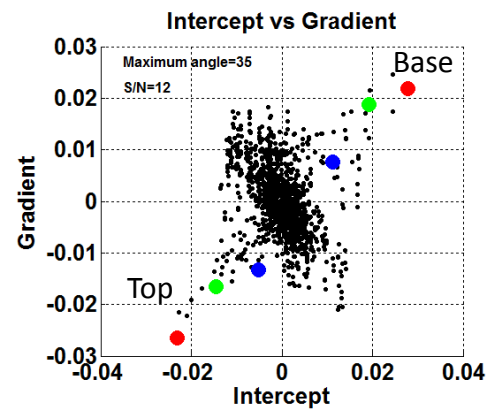
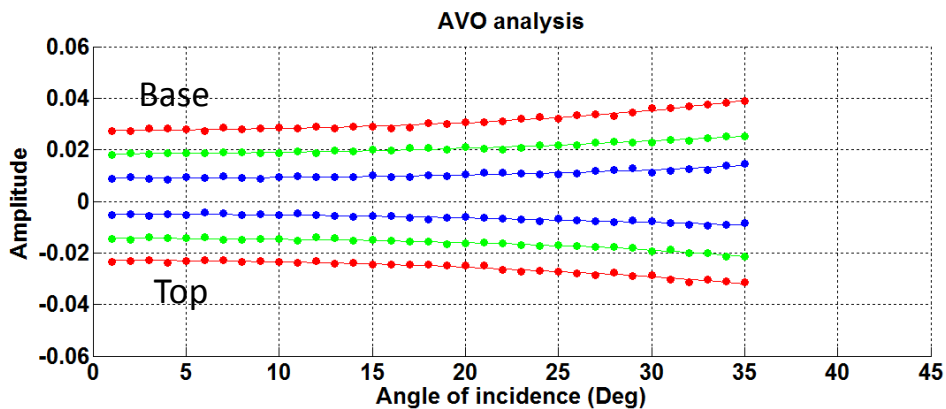
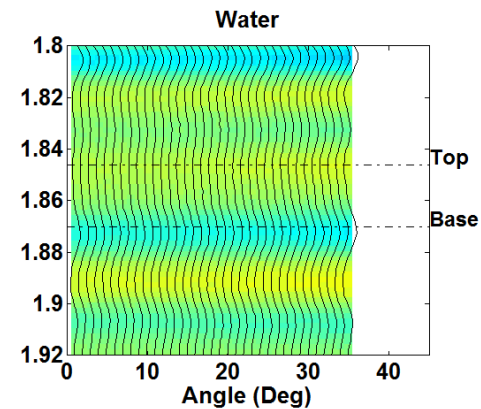
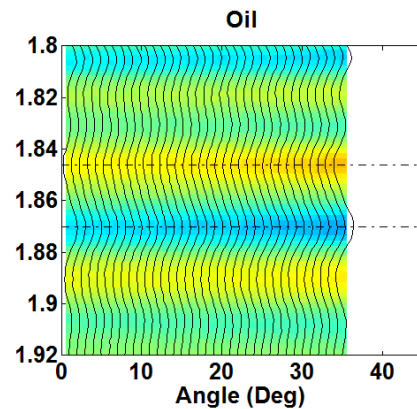
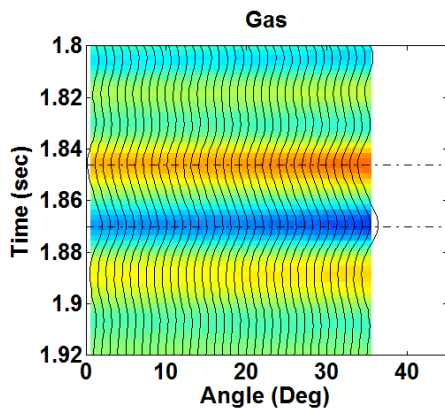
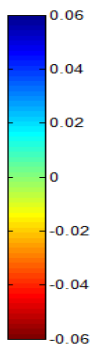


GAS error

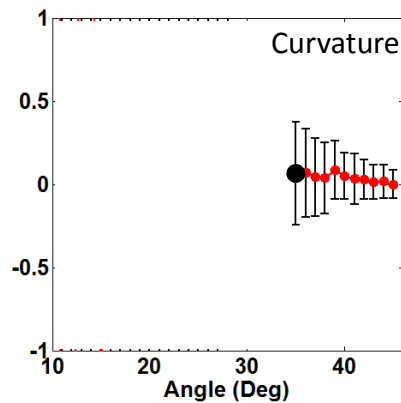
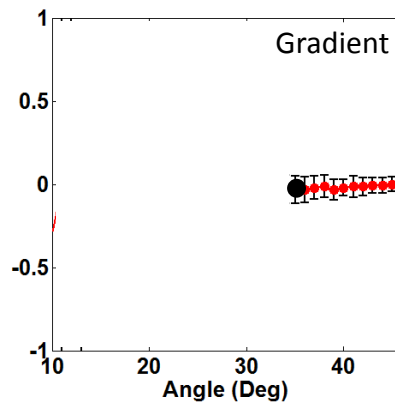
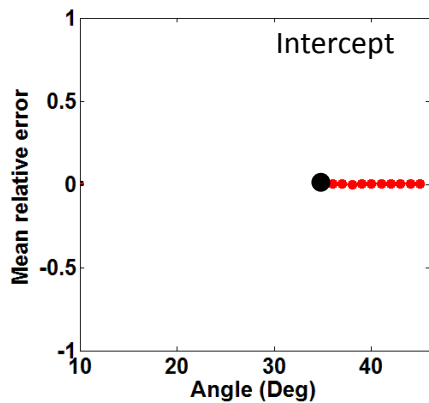
Max. Angle=35

S/N=12

Effect of reducing angle of incidence
keeping noise constant



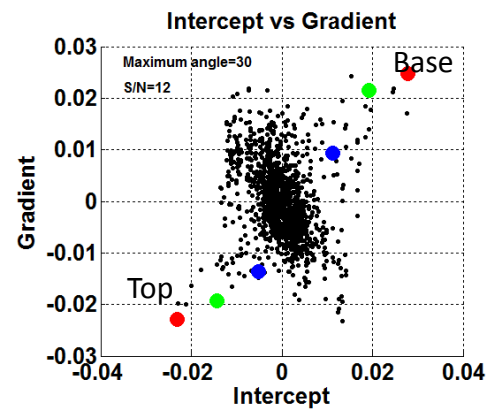
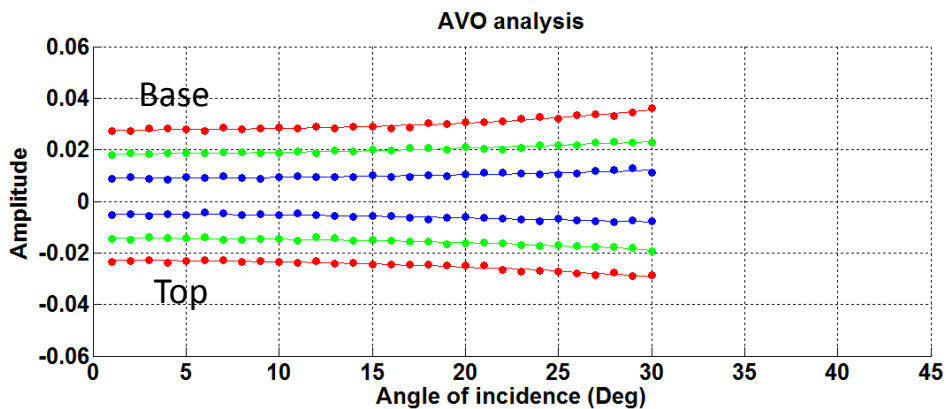
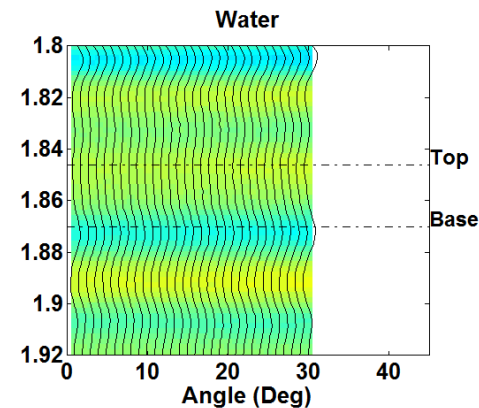
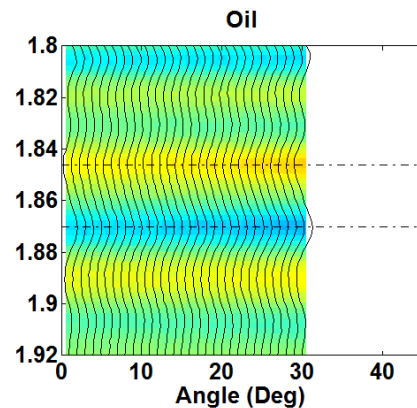
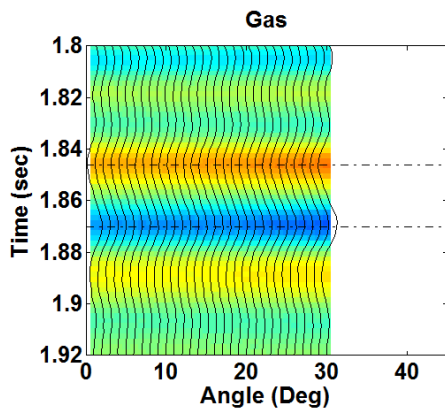
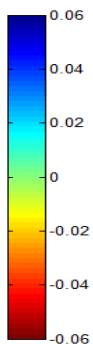
GAS error



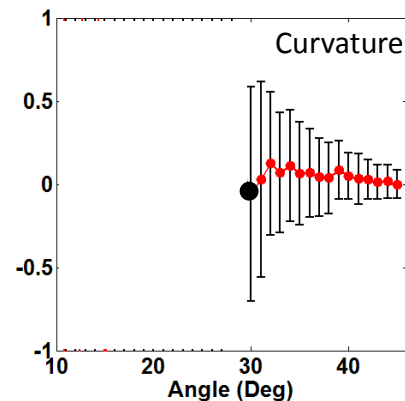
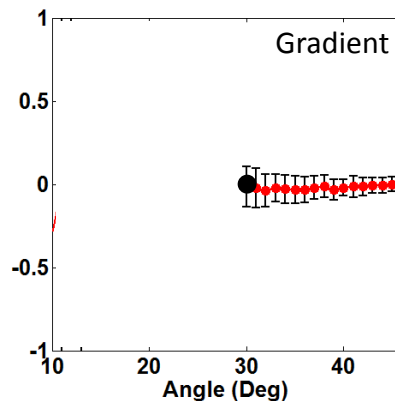
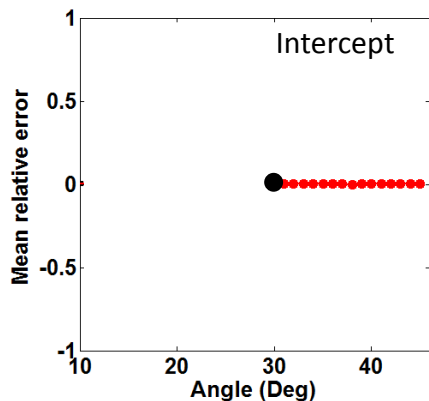
Max. Angle=30

S/N=12

Effect of reducing angle of incidence
keeping noise constant



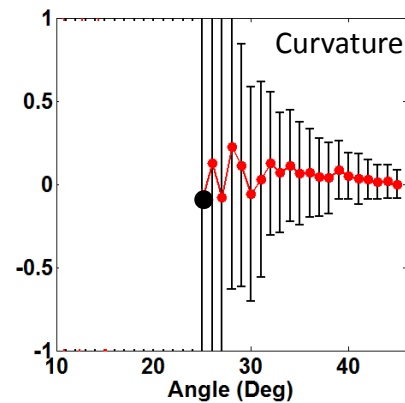
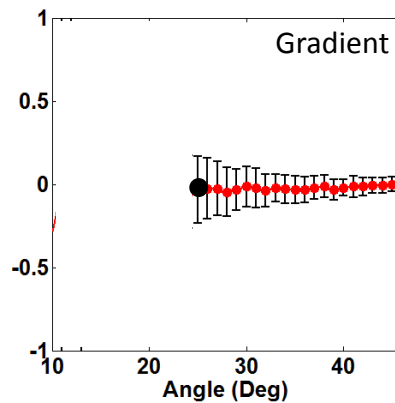
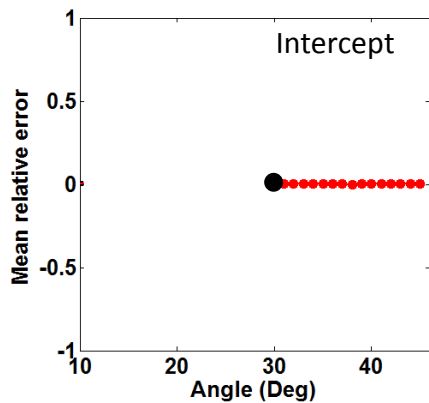
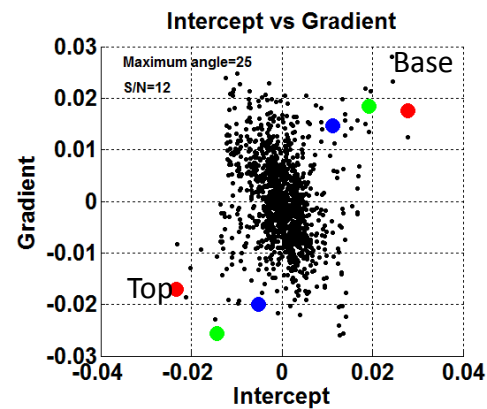
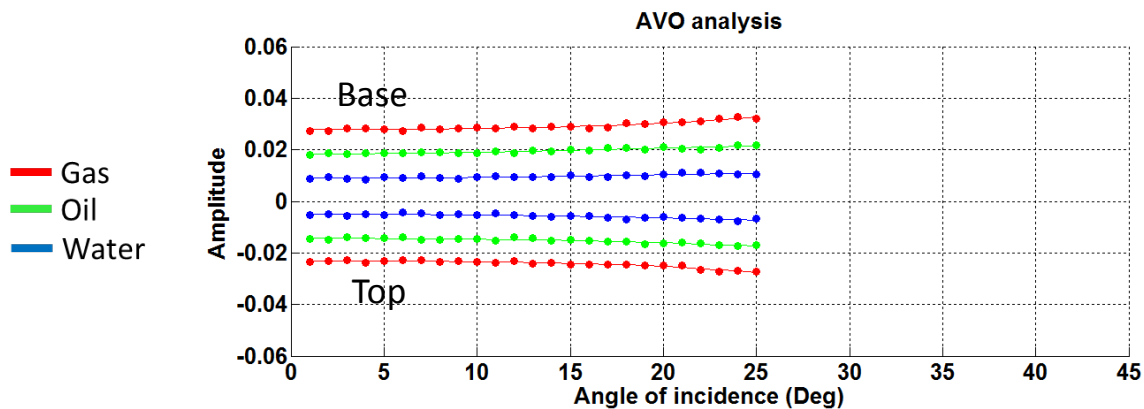
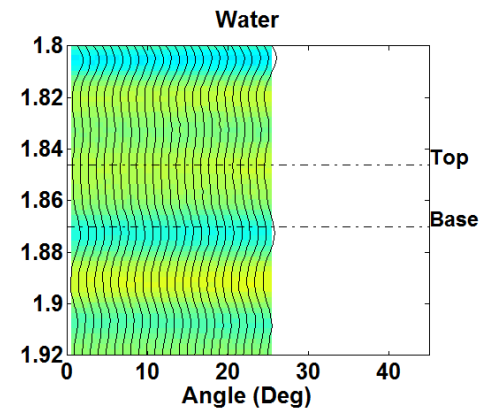
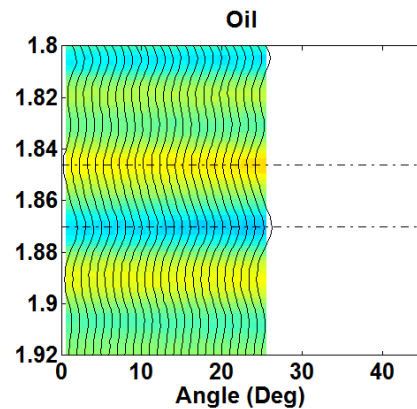
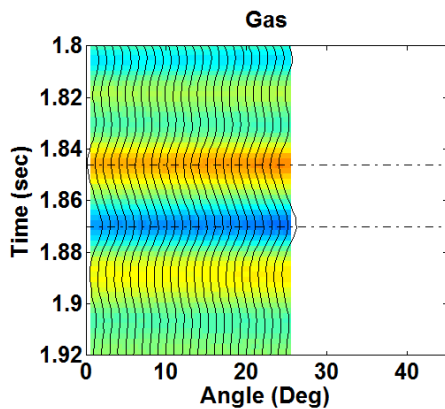
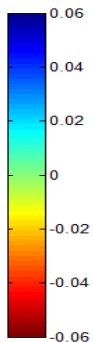
GAS error



Max. Angle=25

S/N=12

Effect of reducing angle of incidence
keeping noise constant

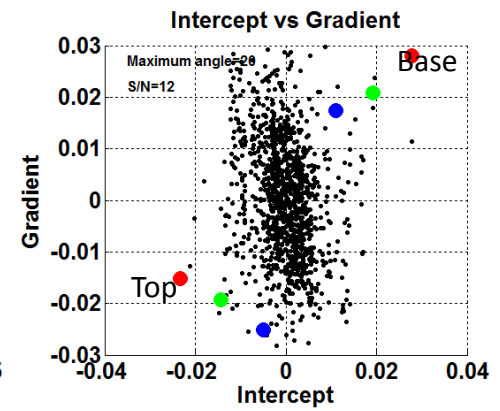
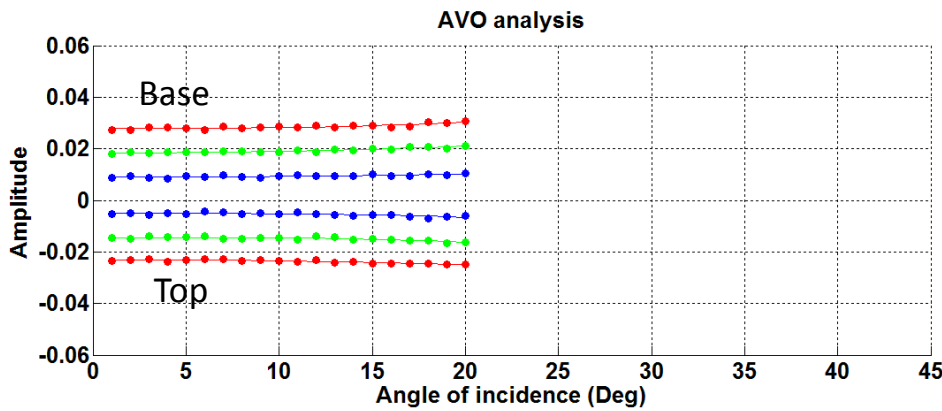
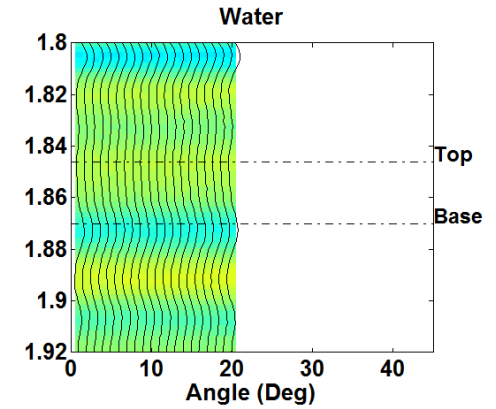
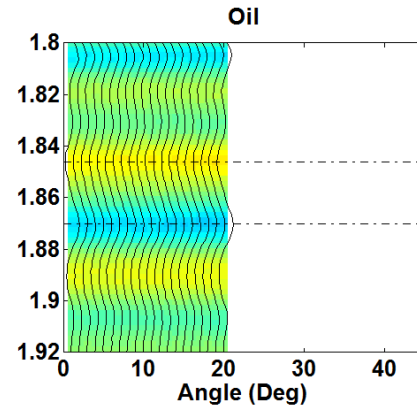
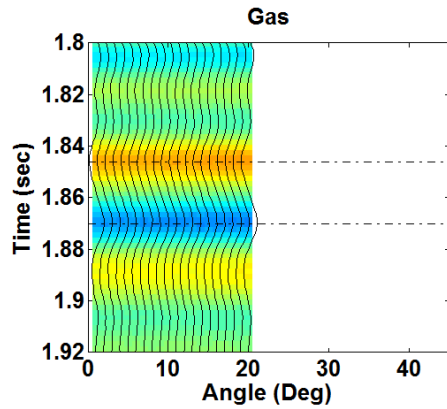
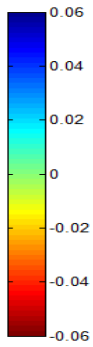


GAS error

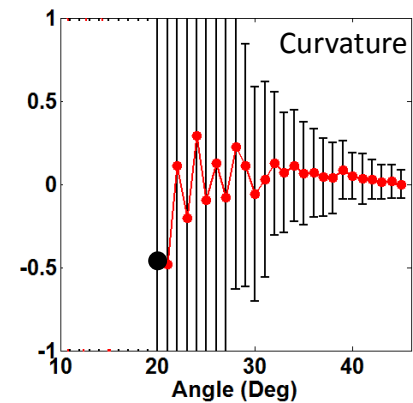
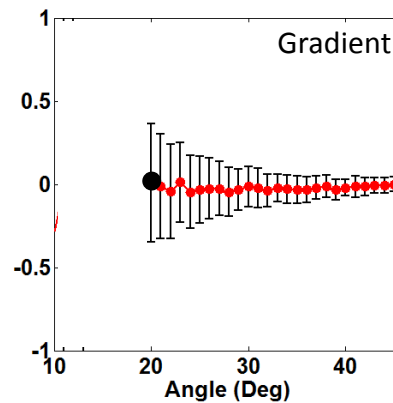
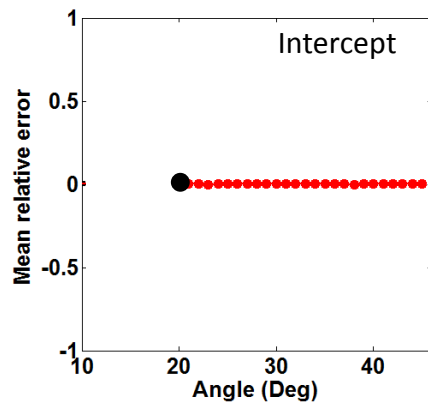
Max. Angle=20

S/N=12

Effect of reducing angle of incidence
keeping noise constant



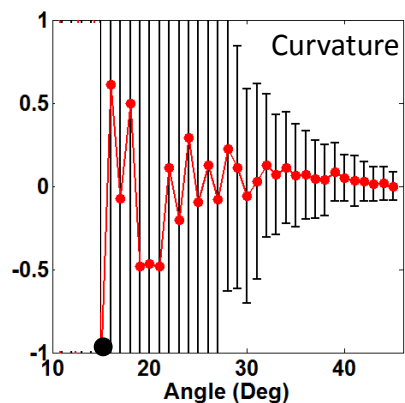
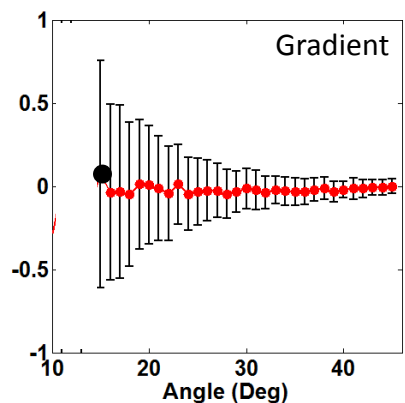
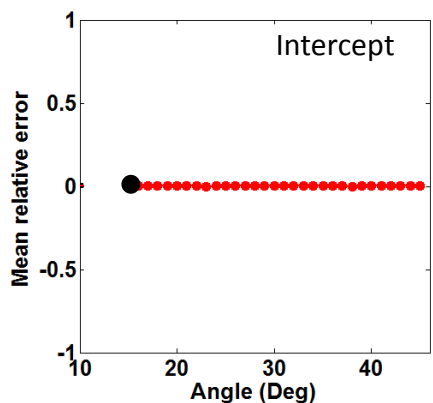
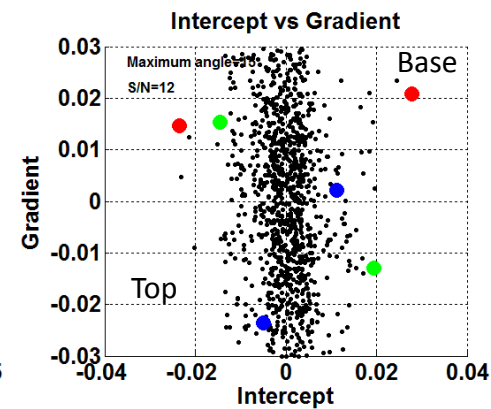
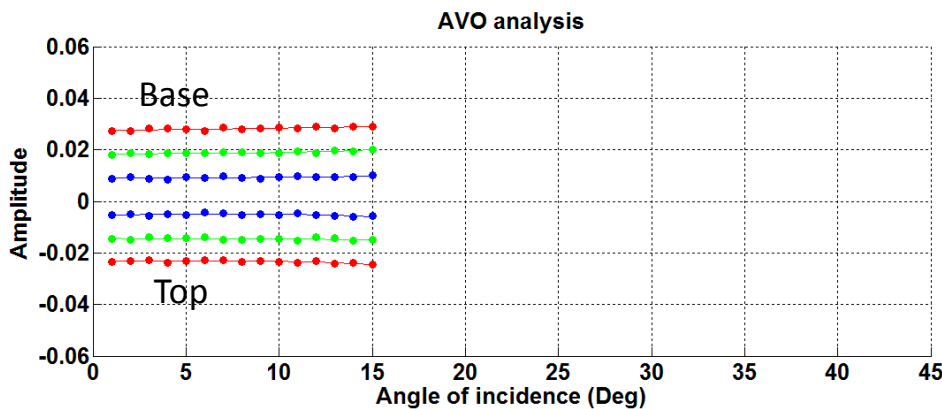
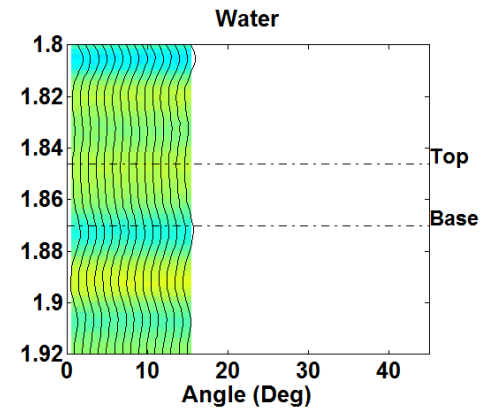
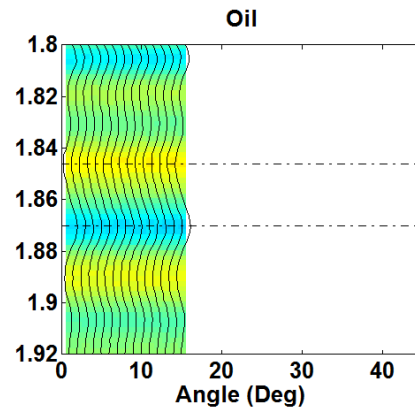
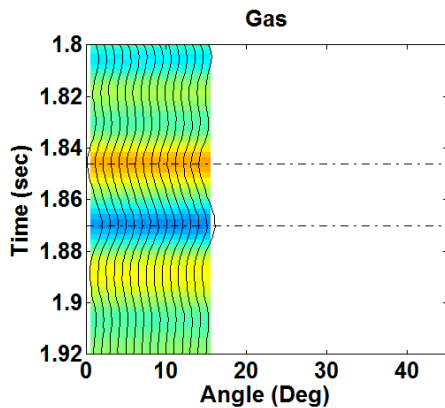
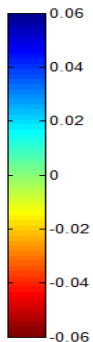
GAS error



Max. Angle=15

S/N=12

Effect of reducing angle of incidence
keeping noise constant

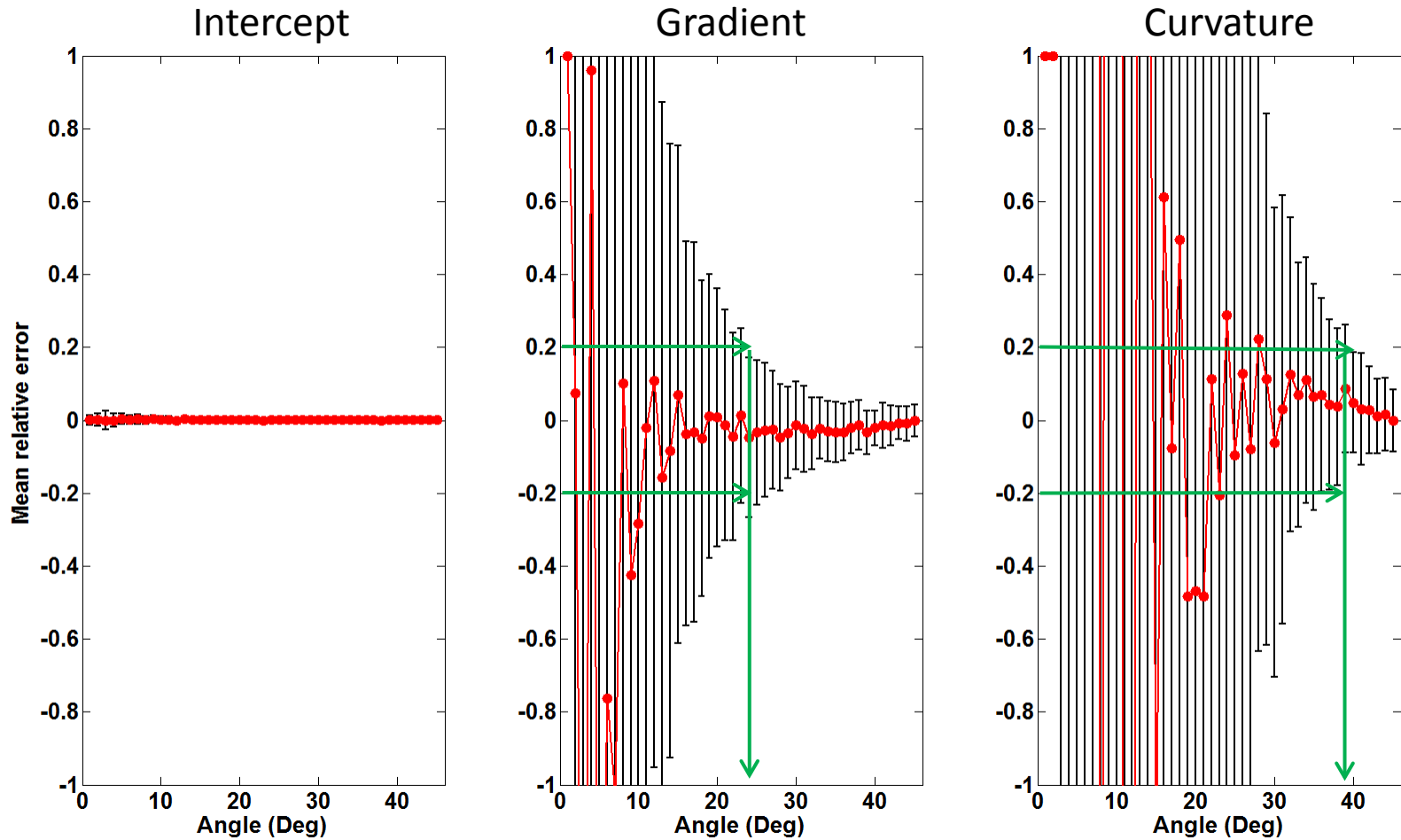


GAS error

S/N=12

Effect of reducing angle of incidence
keeping noise constant

GAS-error

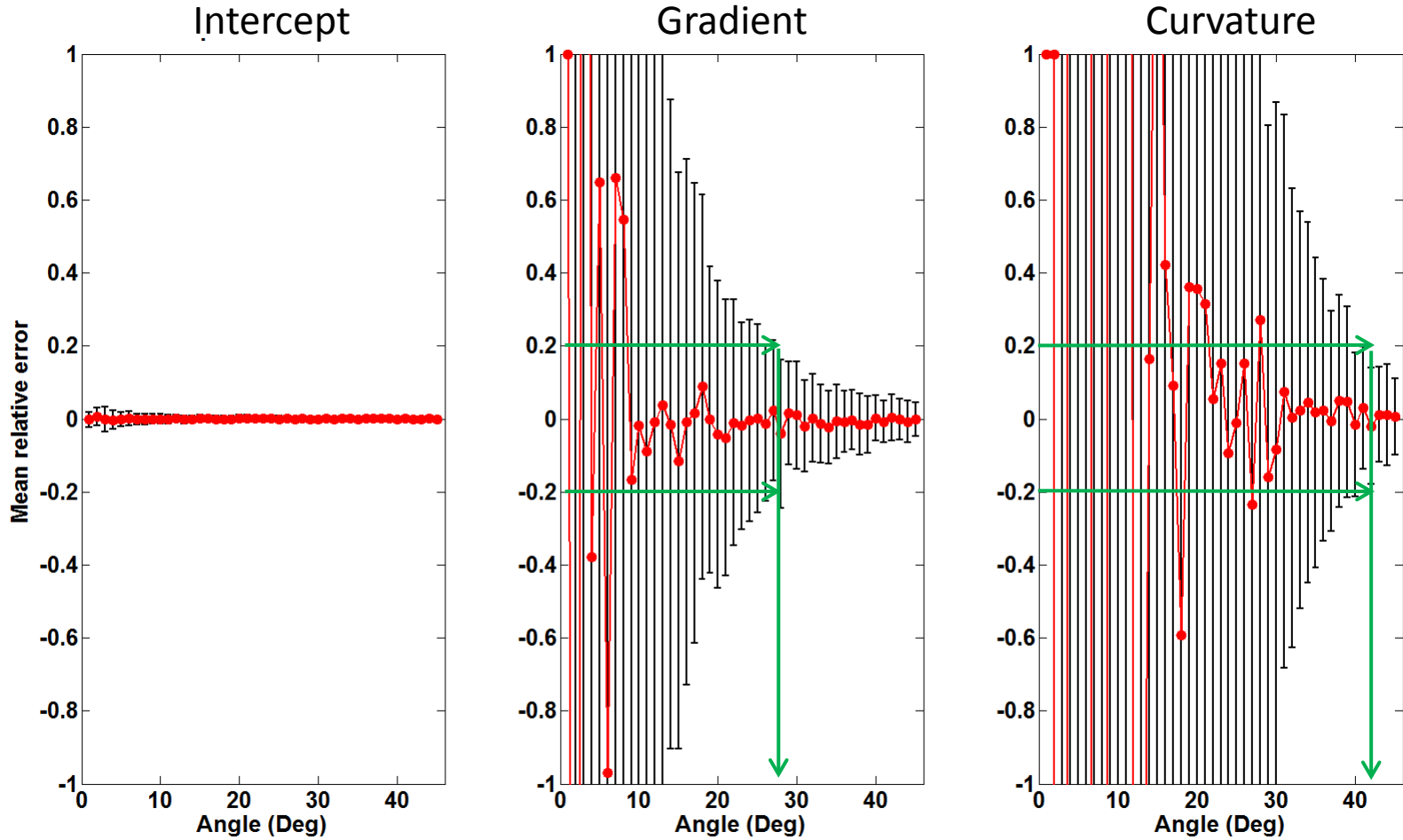


The parameter estimation becomes unstable with errors higher than 20%

S/N=12

Effect of reducing angle of incidence
keeping noise constant

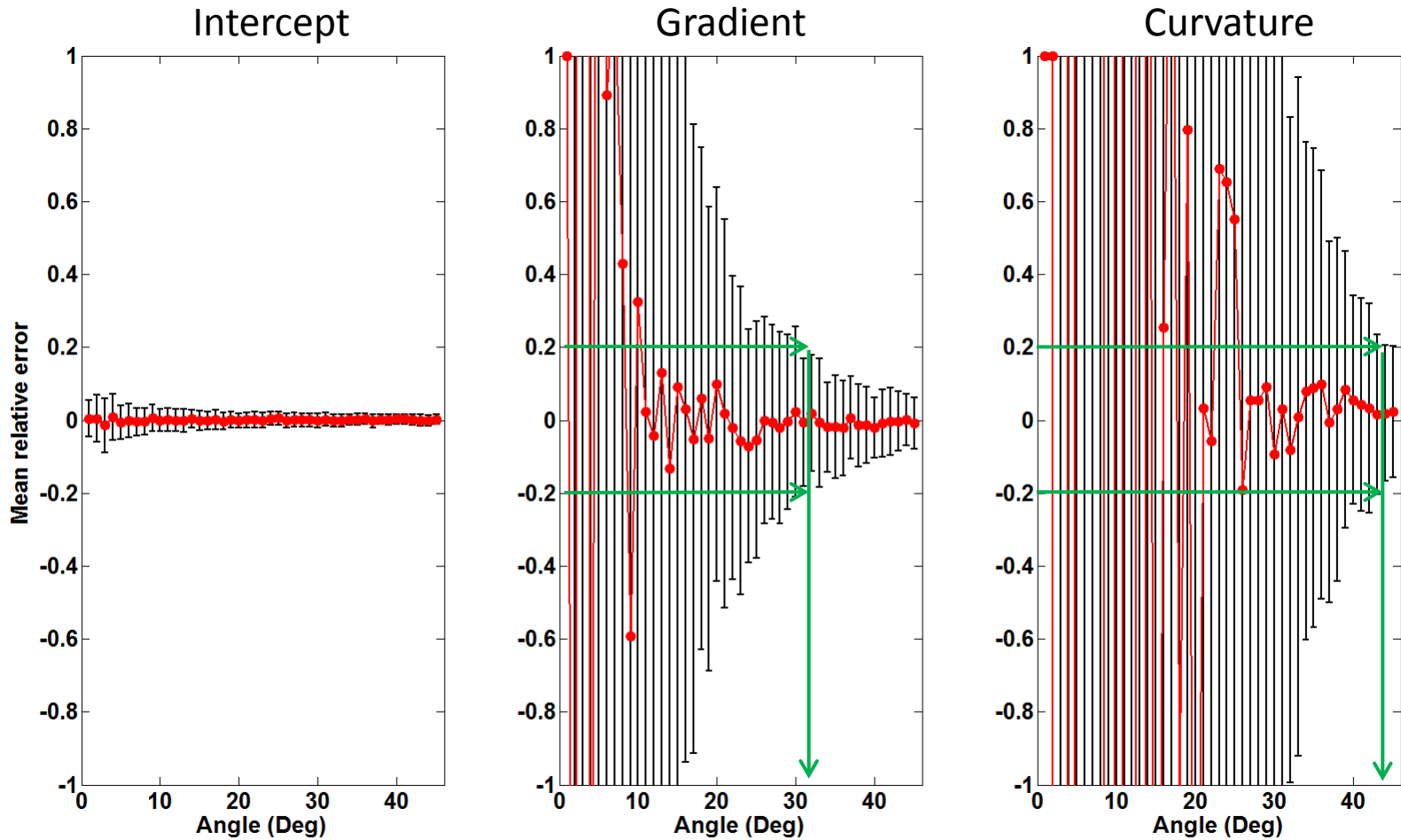
OIL-error



S/N=12

Effect of reducing angle of incidence
keeping noise constant

WATER-error

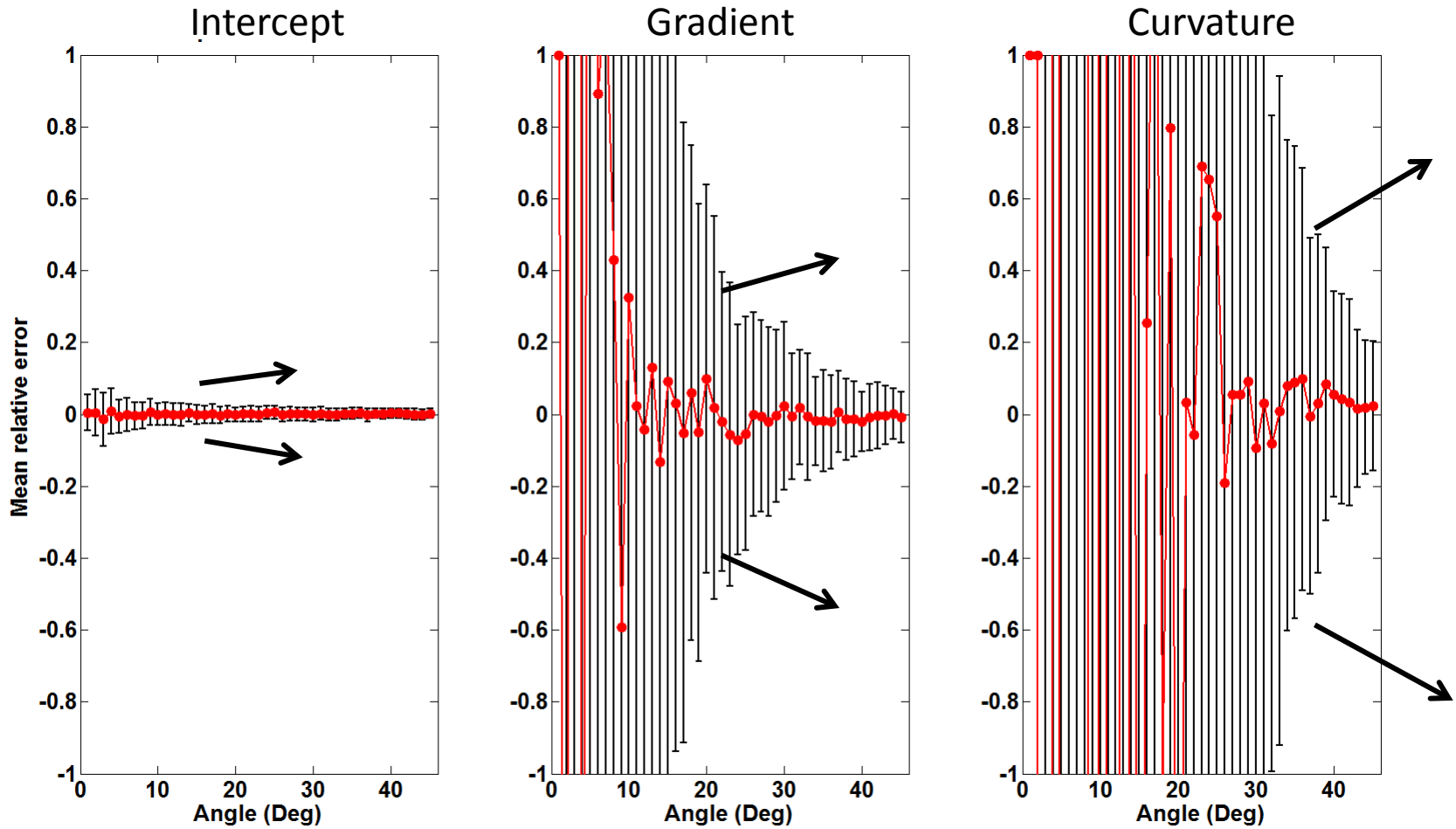


The parameter estimation becomes unstable with errors higher than 20%

S/N=12

Effect of reducing angle of incidence
keeping noise constant

WATER-error

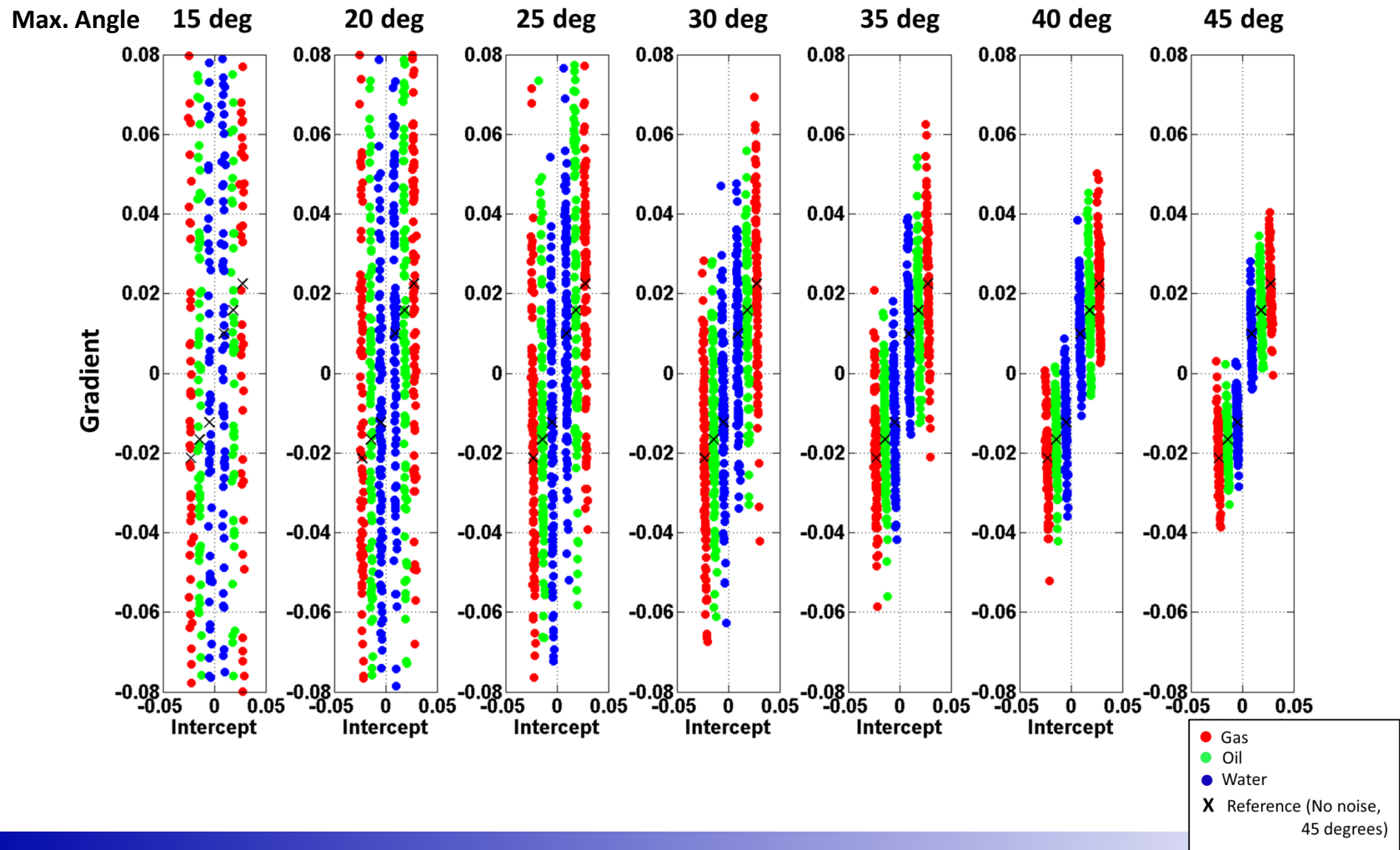


The error increases as the impedance contrast decreases

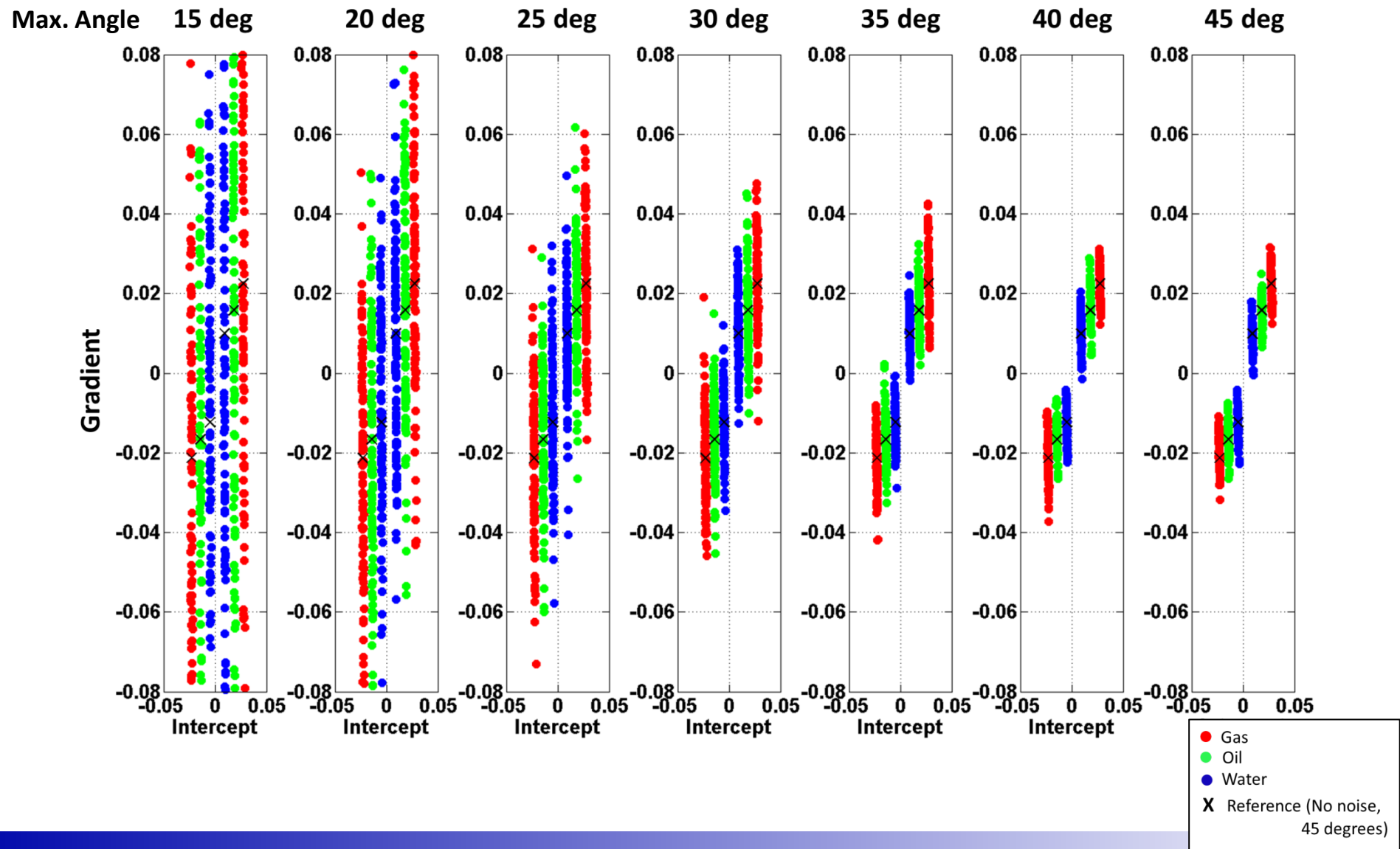
Simultaneous effect of reducing angle of incidence and varying level of noise

Effect of angle of incidence and noise

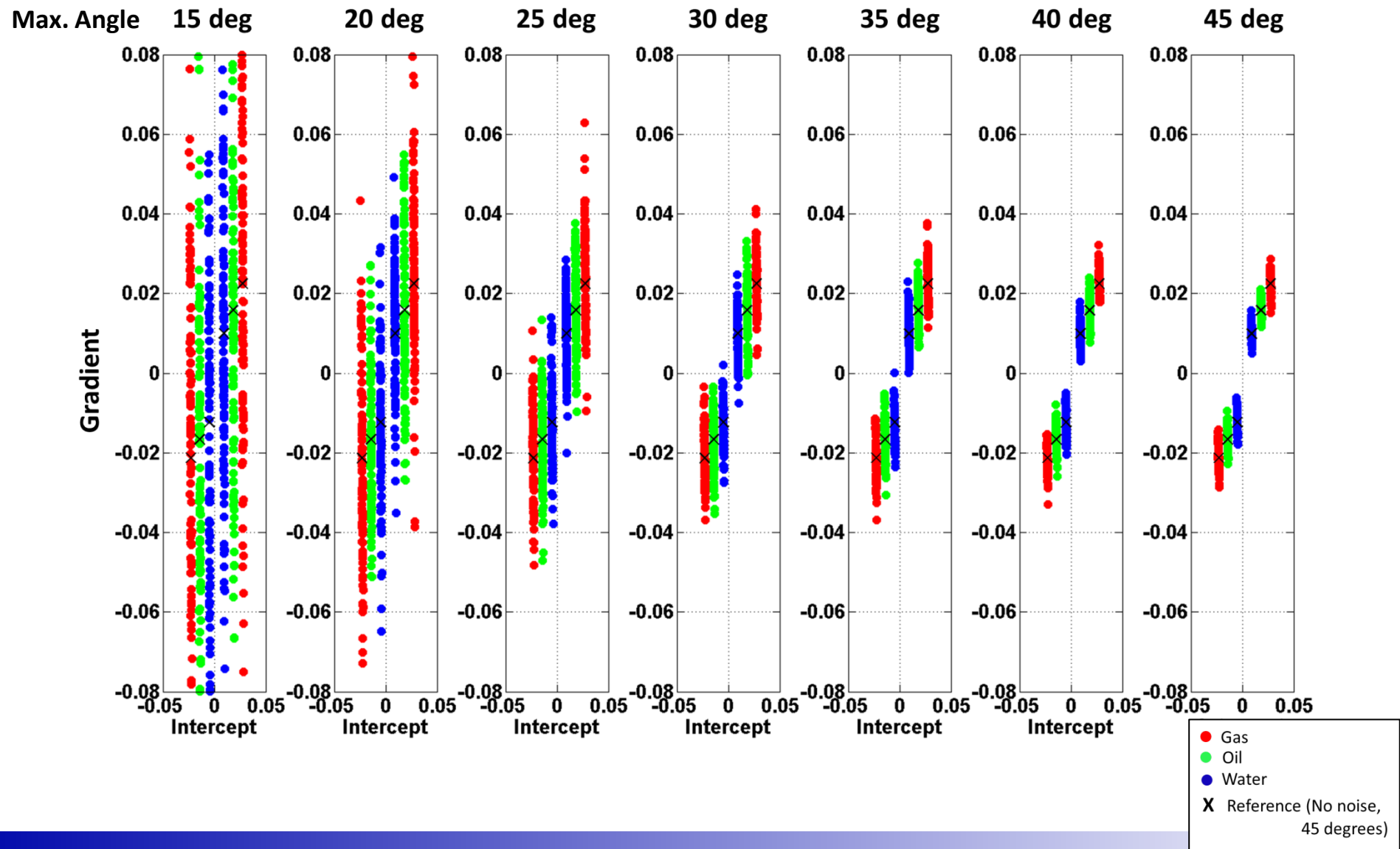
$S/N=2$



$S/N=4$

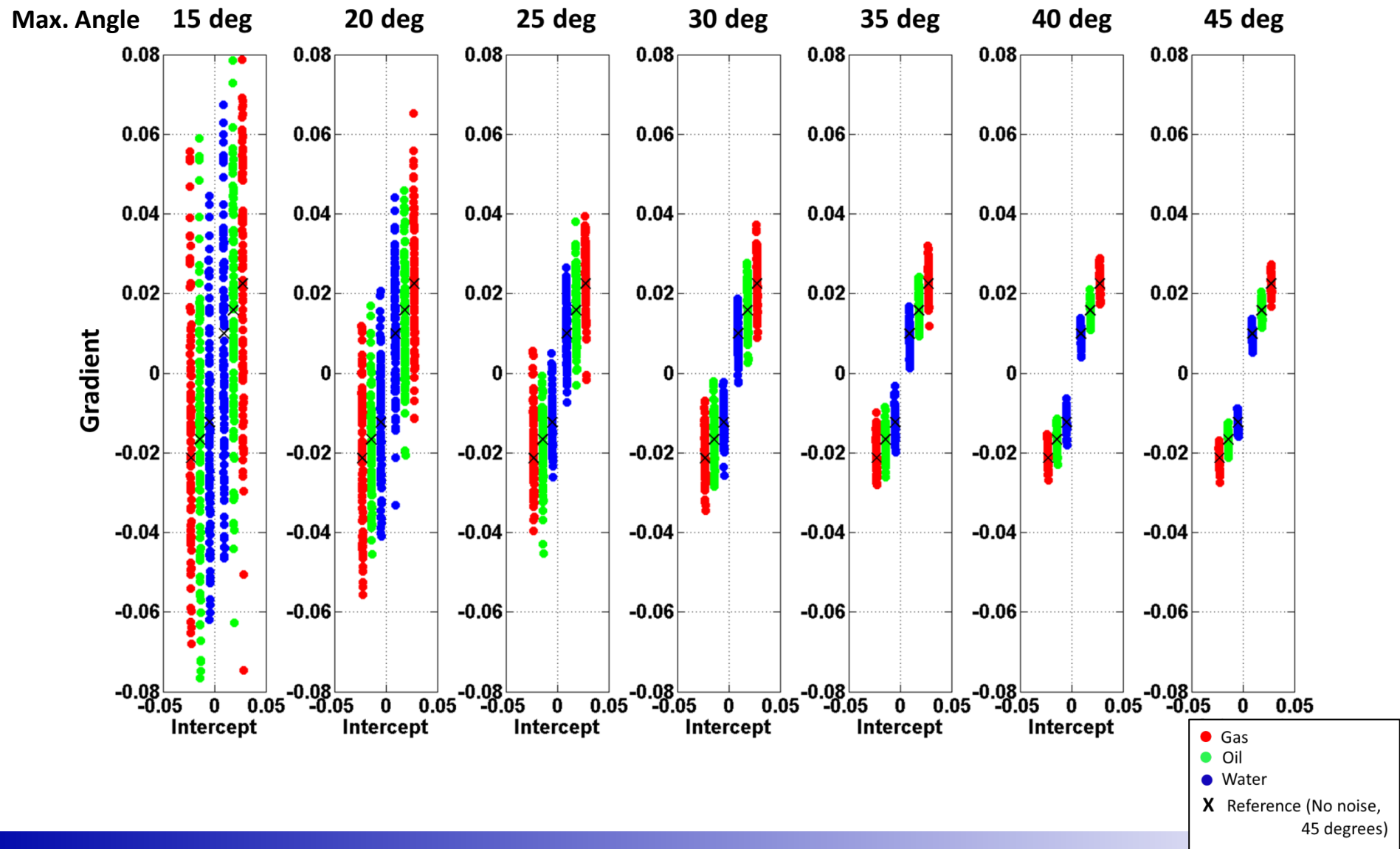


S/N=6



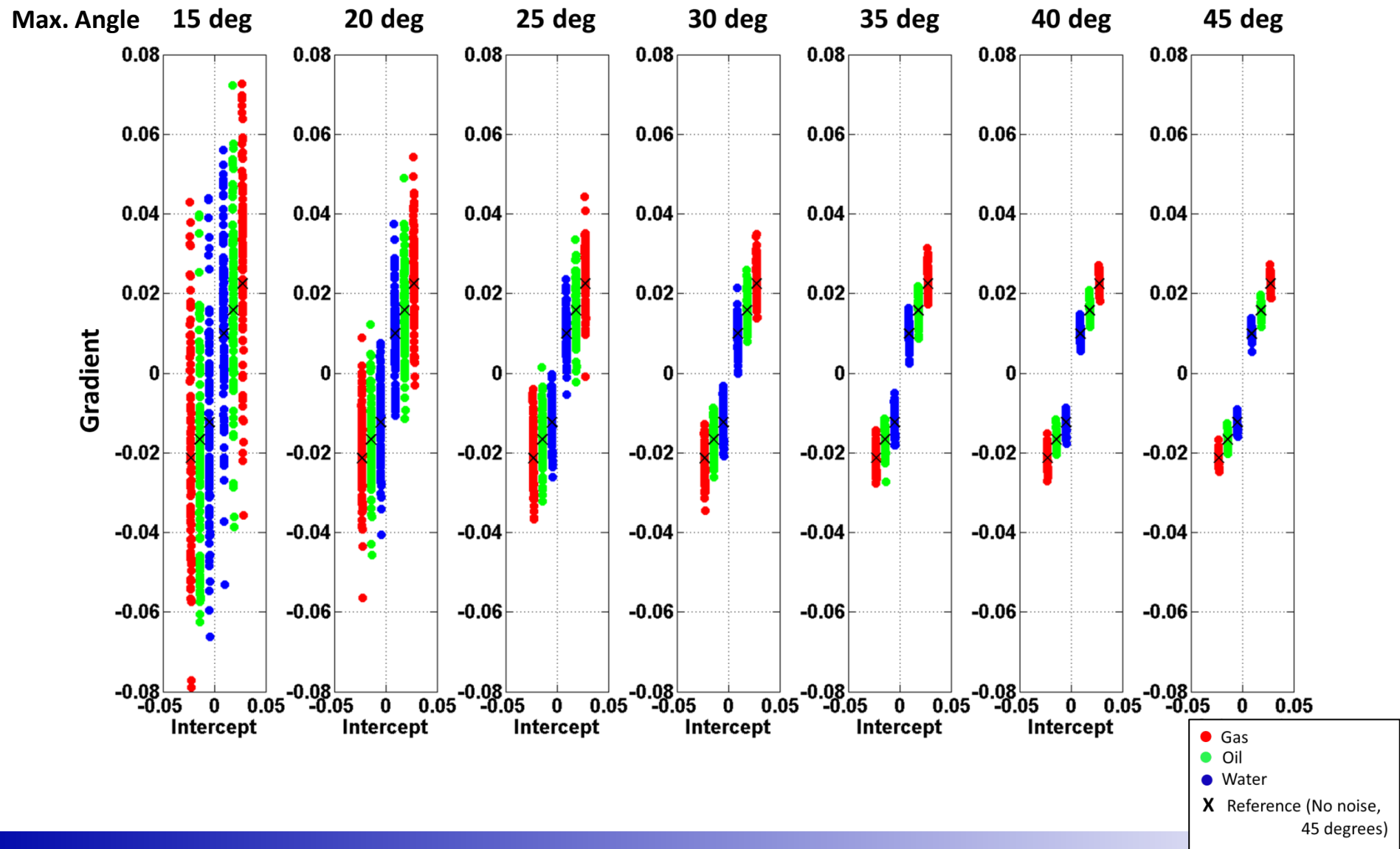
Effect of angle of incidence and noise

S/N=8



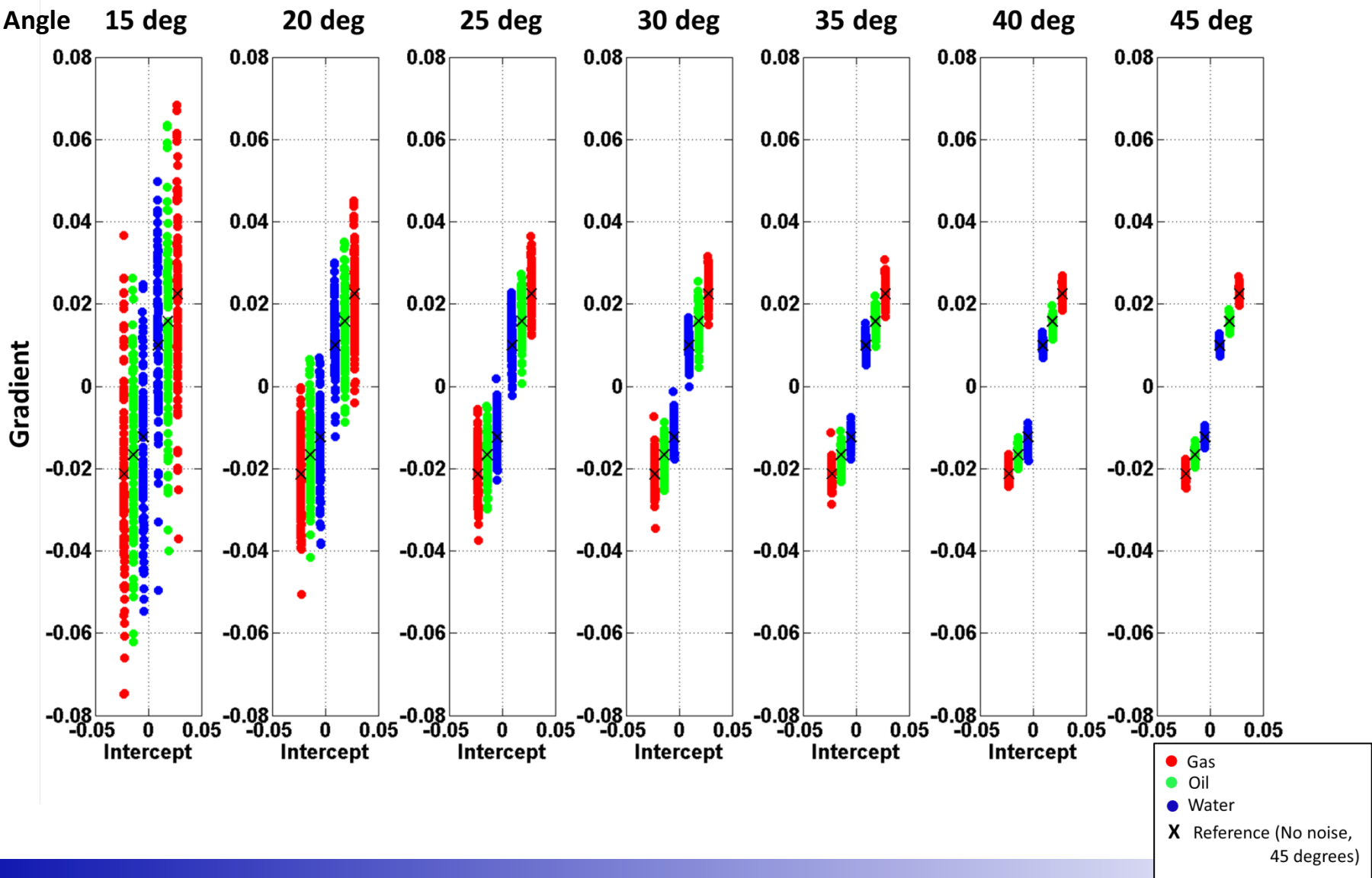
Effect of angle of incidence and noise

S/N=10



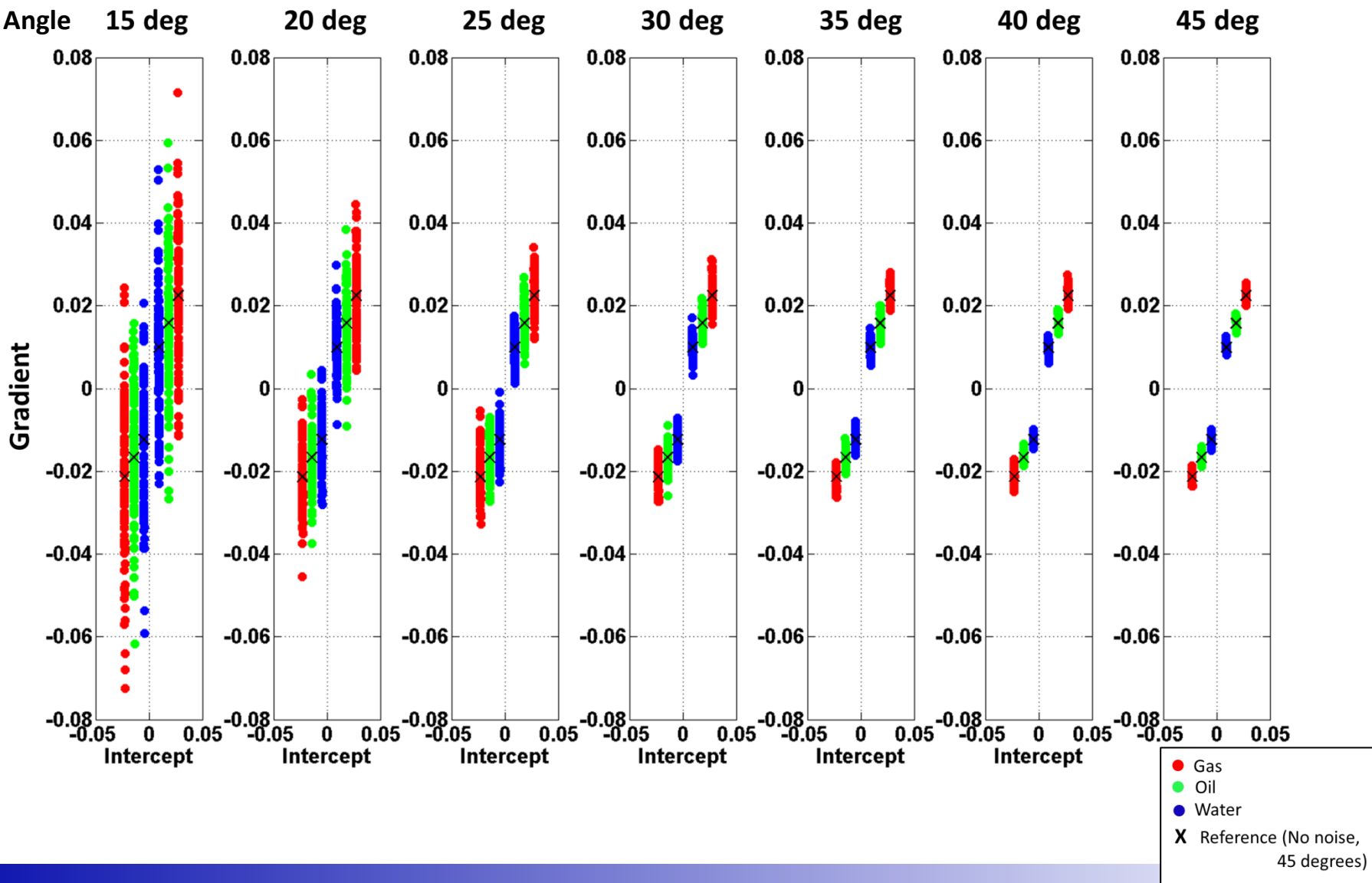
Effect of angle of incidence and noise

S/N=12

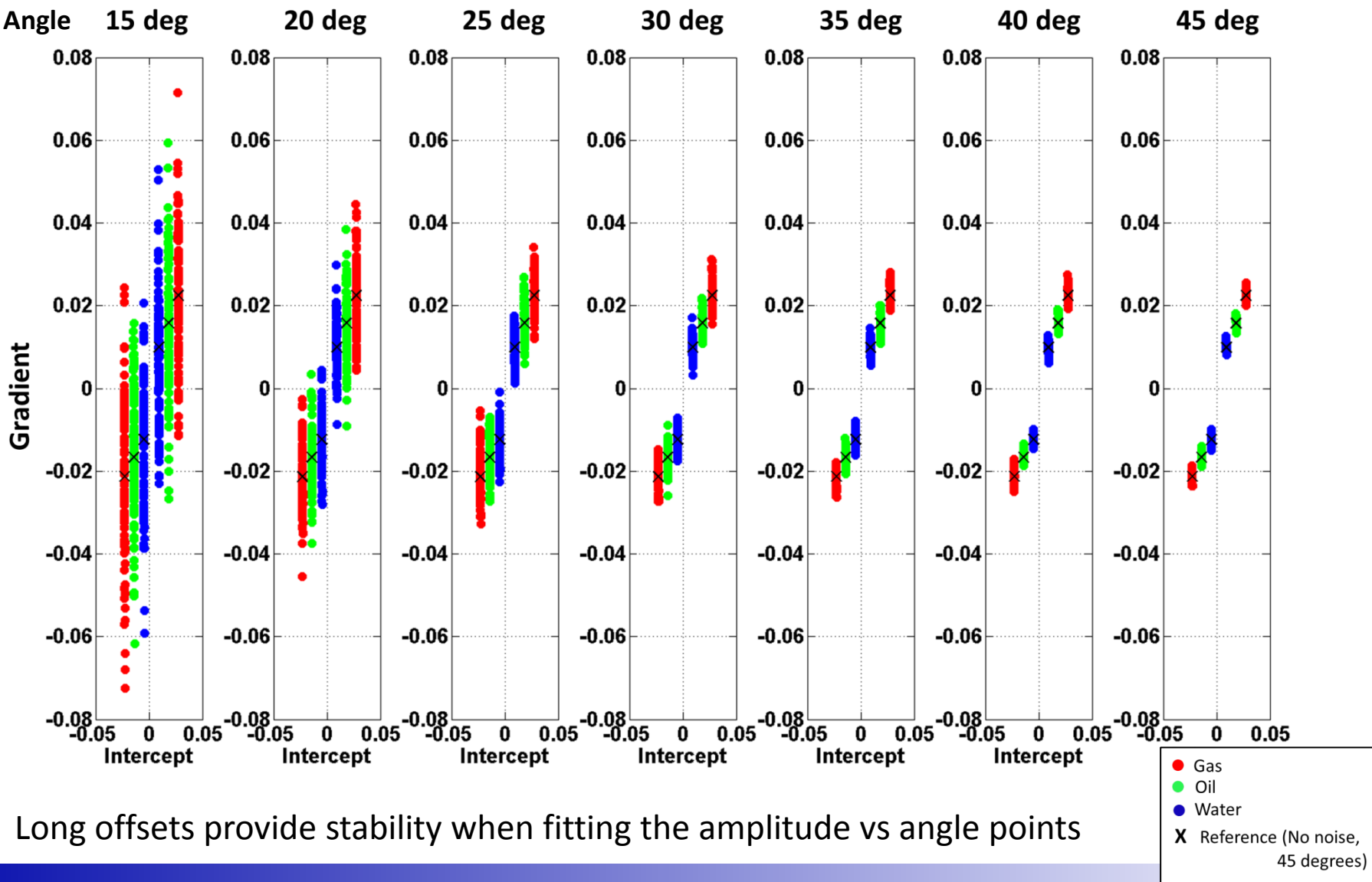


Effect of angle of incidence and noise

S/N=15

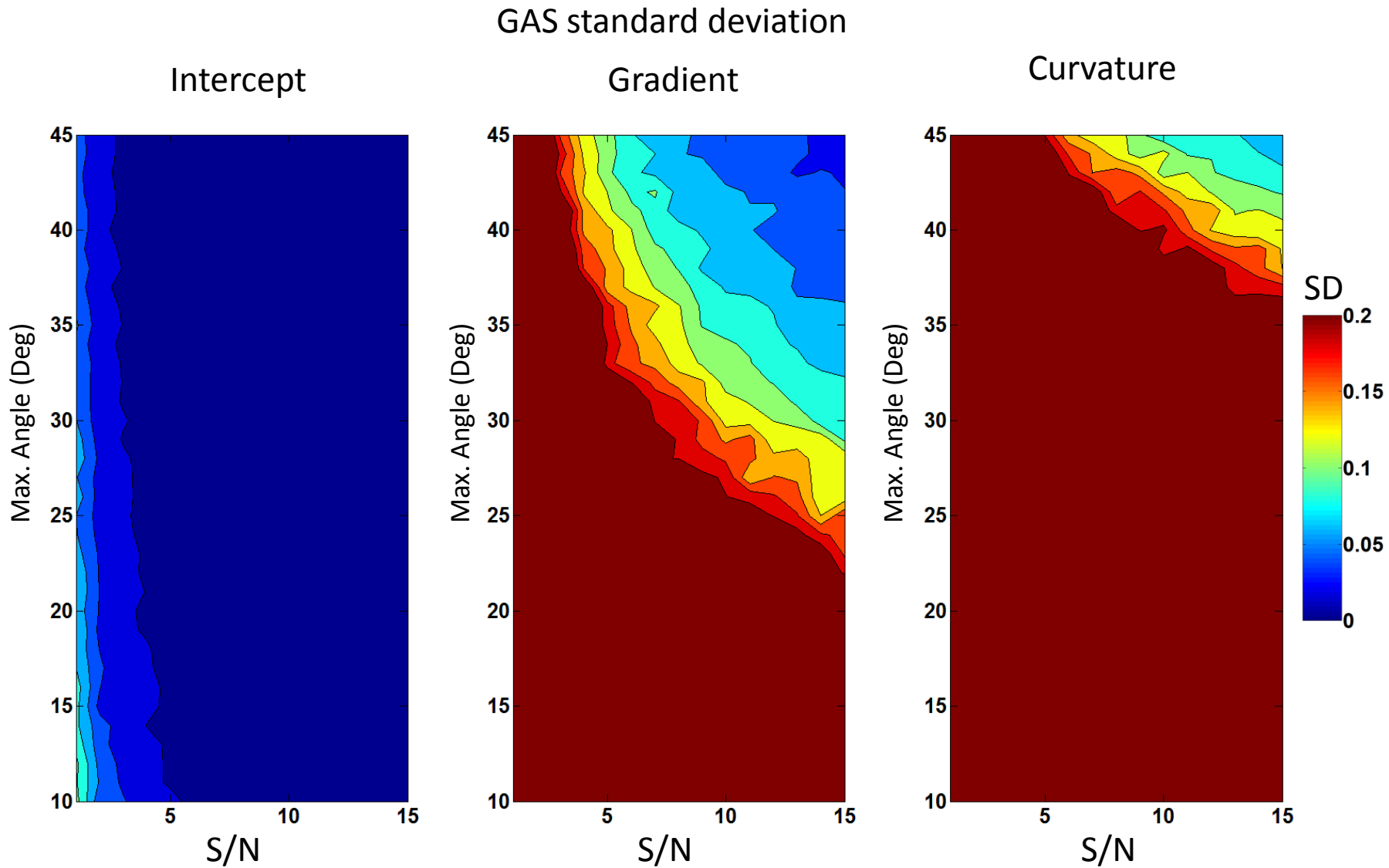


S/N=15

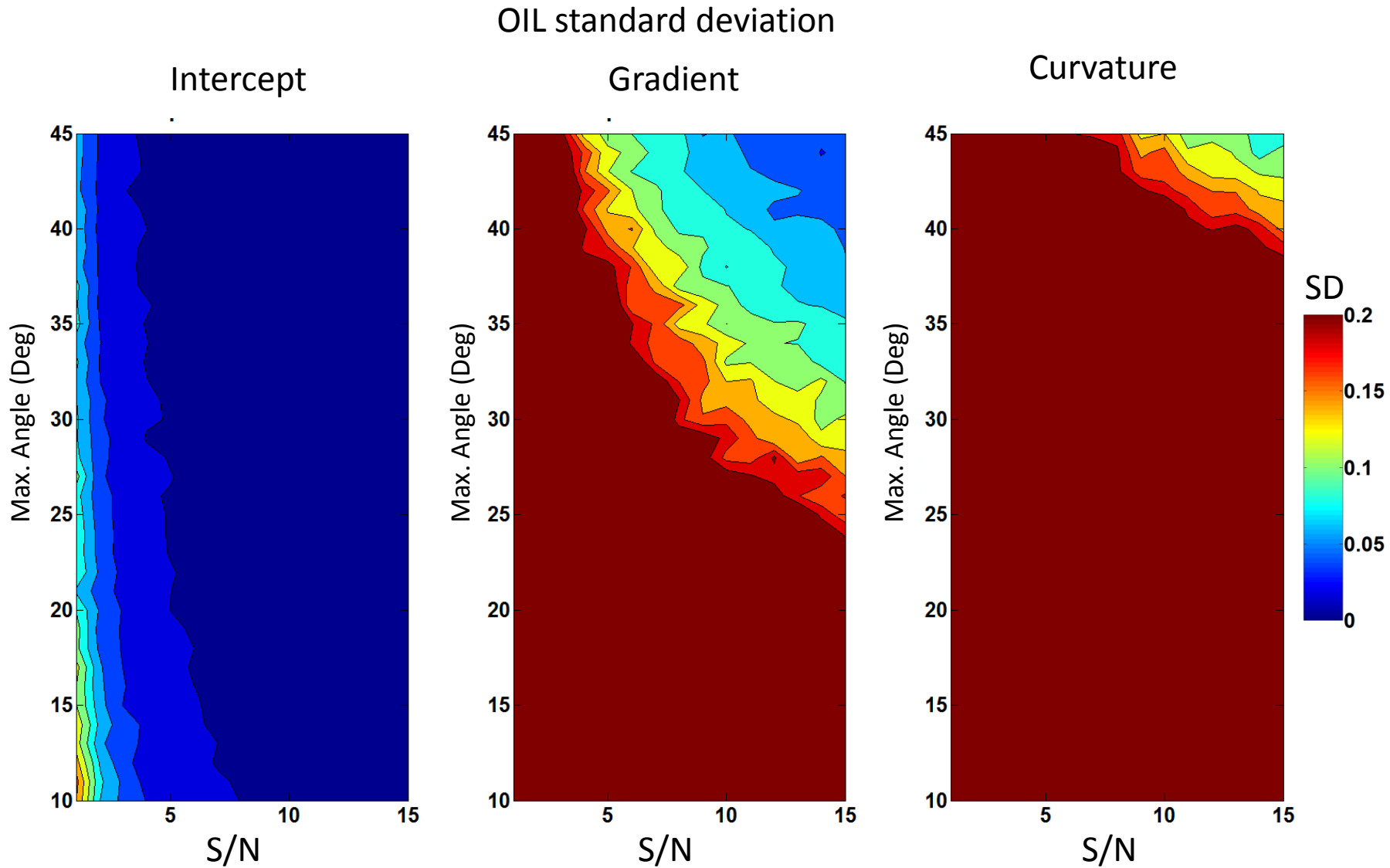


Long offsets provide stability when fitting the amplitude vs angle points

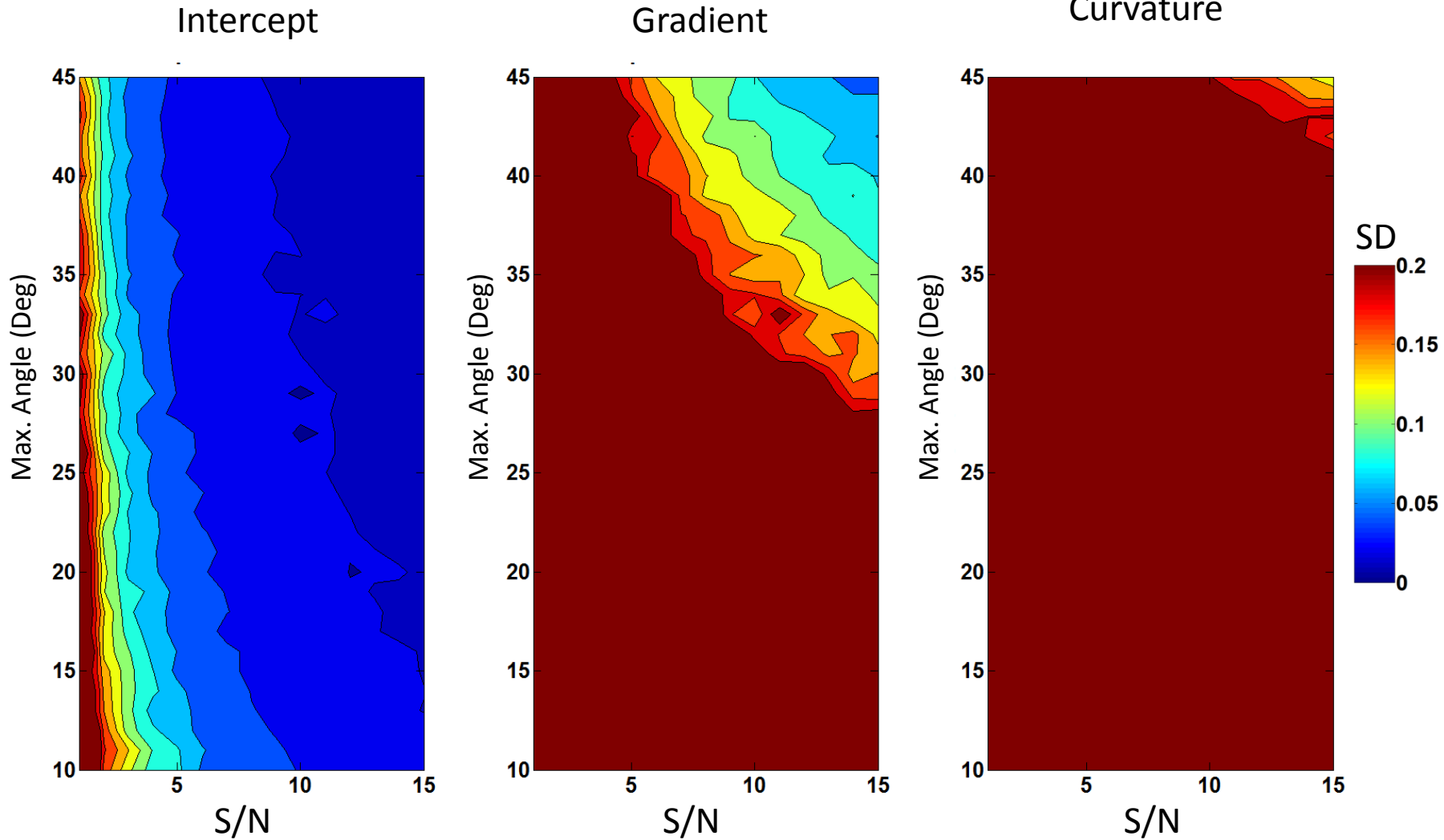
Effect of angle of incidence and noise



Effect of angle of incidence and noise



WATER standard deviation

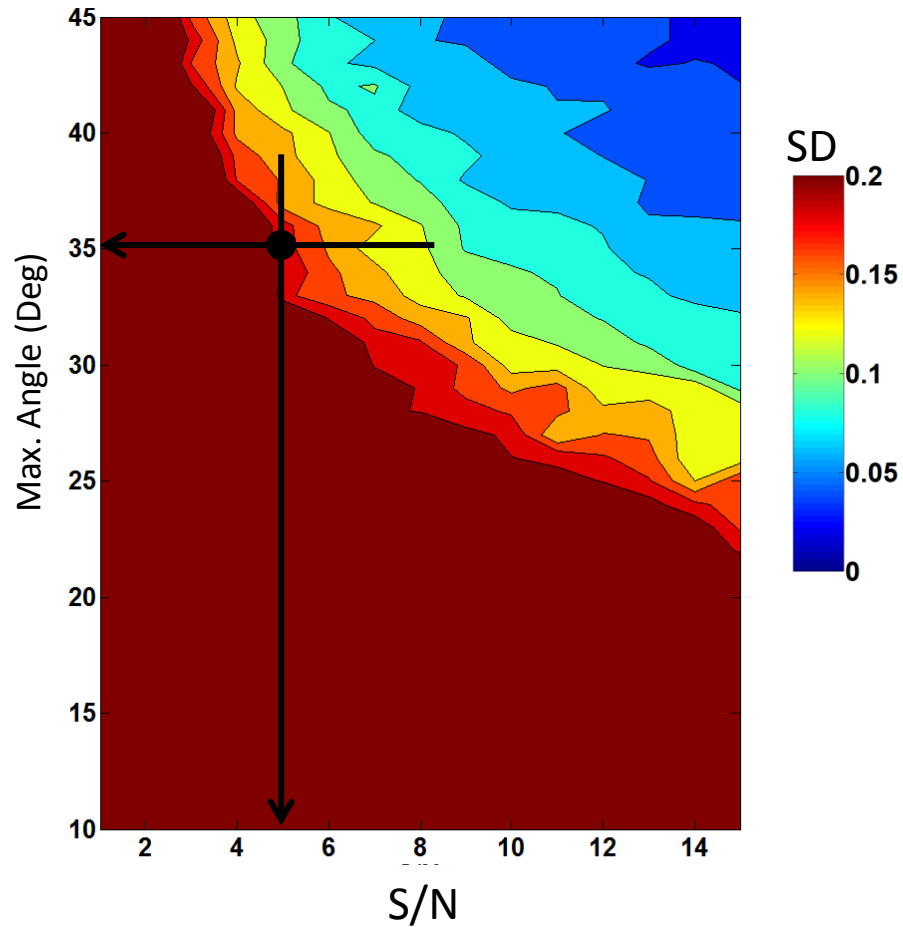


GAS standard deviation

Target depth=2280 m

Gradient

Offset=2600 m

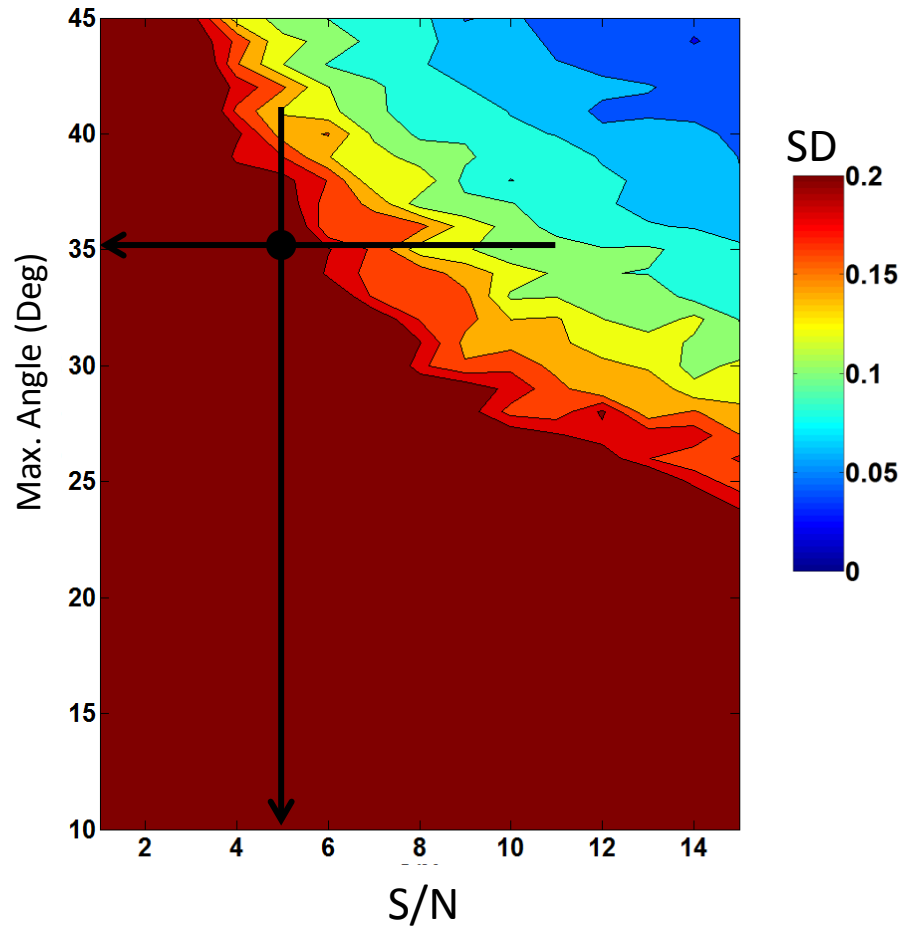


OIL standard deviation

Target depth=2280 m

Gradient

Offset=2600 m



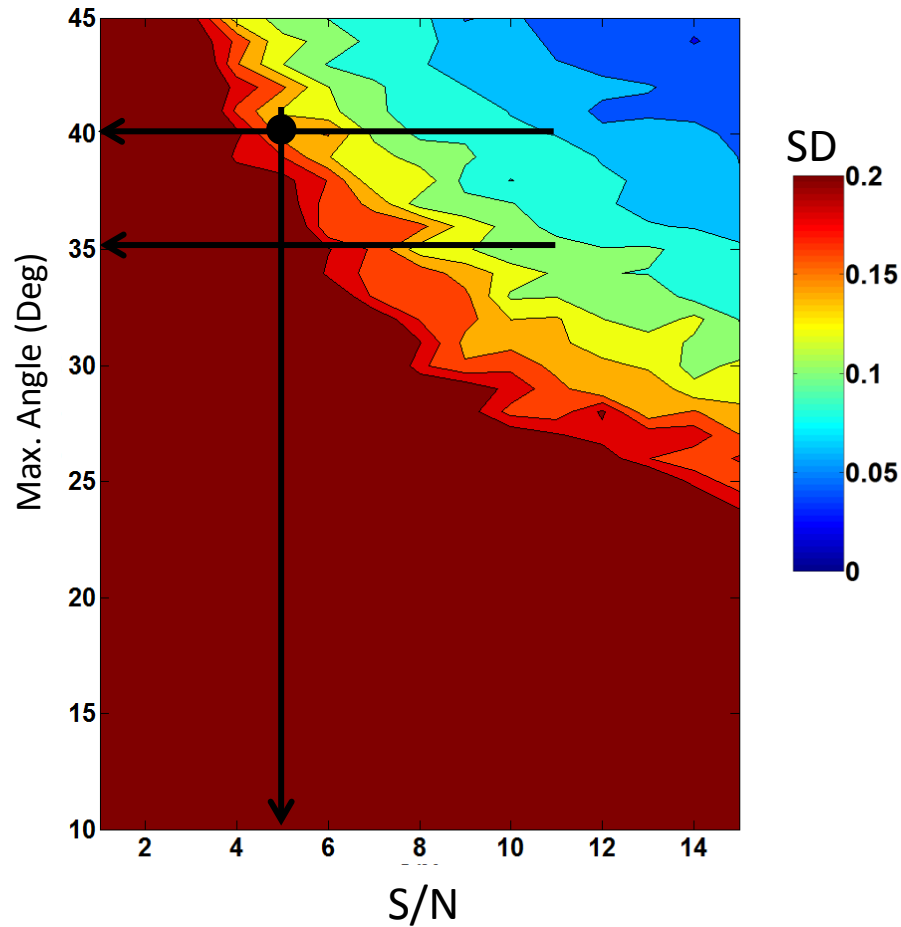
1) Design larger offsets before acquiring the data

Offset=3100 m

Offset=2600 m

OIL standard deviation

Gradient



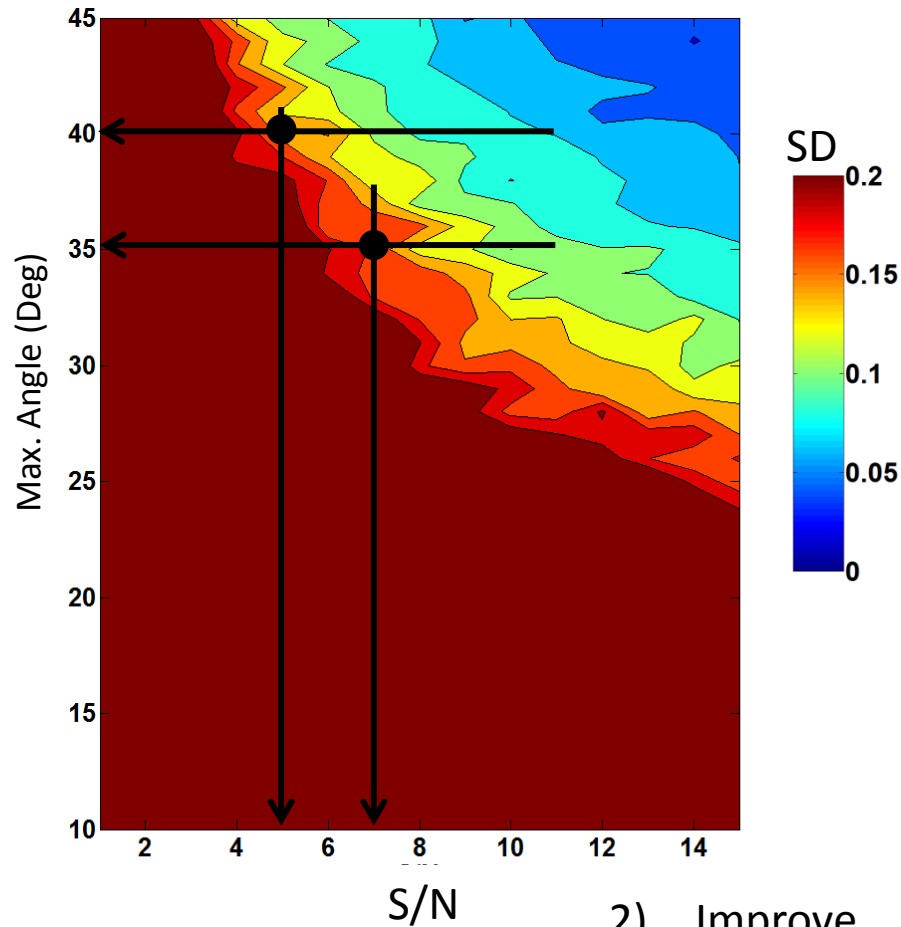
1) Design larger offsets before acquiring the data

Offset=3100 m

Offset=2600 m

OIL standard deviation

Gradient




2) Improve the S/N when processing the data

Conclusions

- Random noise and available long offset are variables that affect the estimation of AVO-parameters.
- The intercept is practically not affected by reducing offset and slightly affected by random noise.
- The gradient and curvature are strongly impacted by both noise and maximum available offset.
- The error tends to be higher if the target has low impedance contrast.
- Long offsets provide stability when fitting the amplitude vs angle points in the presence of noise
- This methodology can be used to check the feasibility of applying AVO analysis with old seismic data or for deciding the maximum offset in new seismic surveys . This information may be useful when designing a seismic survey for monitoring changes of fluids in time-lapse studies.

Future work

- Investigate the effect of other factors such as: different noise distributions, changing the thickness of the reservoir and attenuation
 - Incorporate AVO information in full waveform inversion
- 

Acknowledgements

Kris Inannen
CREWES sponsors
CREWES staff and students
PEMEX

END

