

### **Looking under and above the surface using DAS** Results from the PIMS Industrial Problem Solving Workshop 2018

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#### Under the surface:

- Surface-wave dispersion
- Traveltime interferometry
- Computing dispersion curves using DAS

#### Above the surface:

- Traffic signals recorded with DAS
- Attributes extraction for traffic monitoring





# Surface-wave propagation



Surface waves are very energetic and they are confined in the near-surface (<100 m depth). They are very useful for studying the conditions of the sediments (consolidation, fluids saturation, etc)

#### Dispersive character of surface waves



The dispersion spectrum shows at what velocity is traveling each frequency. Each frequency is related to a different wavelength and penetration depth in the near-surface

### **Traveltime interferometry**



#### Near-surface characterization using DAS data

- Create virtual source gathers using interferometric principles
- Compute dispersion spectrum
- Use dispersion curve to invert for Vs

• Monitor soil conditions through time

Iterate Daily?/hourly?



































# Ctrain DAS Data





Δ





# **Data After Filtering**



# **Windowed** $\tau$ – p transform













# **Traffic Attributes**





- Using continuous DAS measurements and relatively low-energy sources it is feasible to create virtual source gathers for dispersion curves extraction.
- This process could be performed in a hourly basis for monitoring S-wave velocity changes in the near-surface.
- From an existing communication optical fibre we extracted three basic parameters to understand traffic flows: vehicles density, average velocity, and travel time.
- Calibration with other sources of data is needed to validate these results.
- Traffic monitoring data can be used for understanding traffic patterns and helping with roads management and law enforcement.
- This type of real-time DAS data could complement the data recorded by onboard sensors (limited detection range, weather sensitive) installed in vehicles to improve autonomous driving systems.



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