

Deblending RTM in receiver domain

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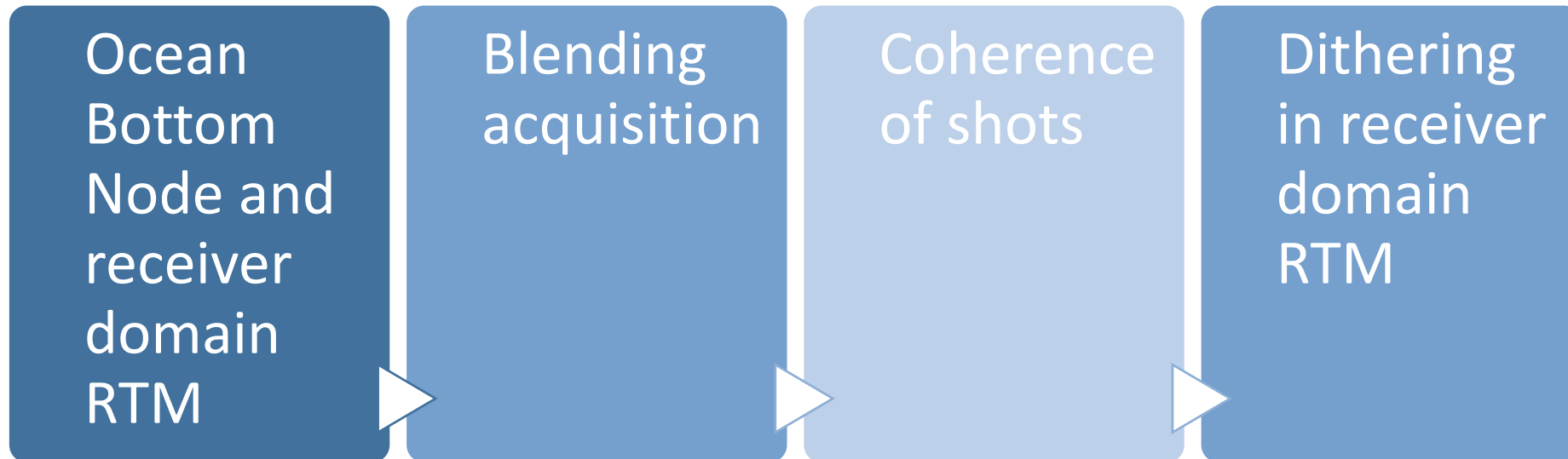
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**NSERC
CRSNG**



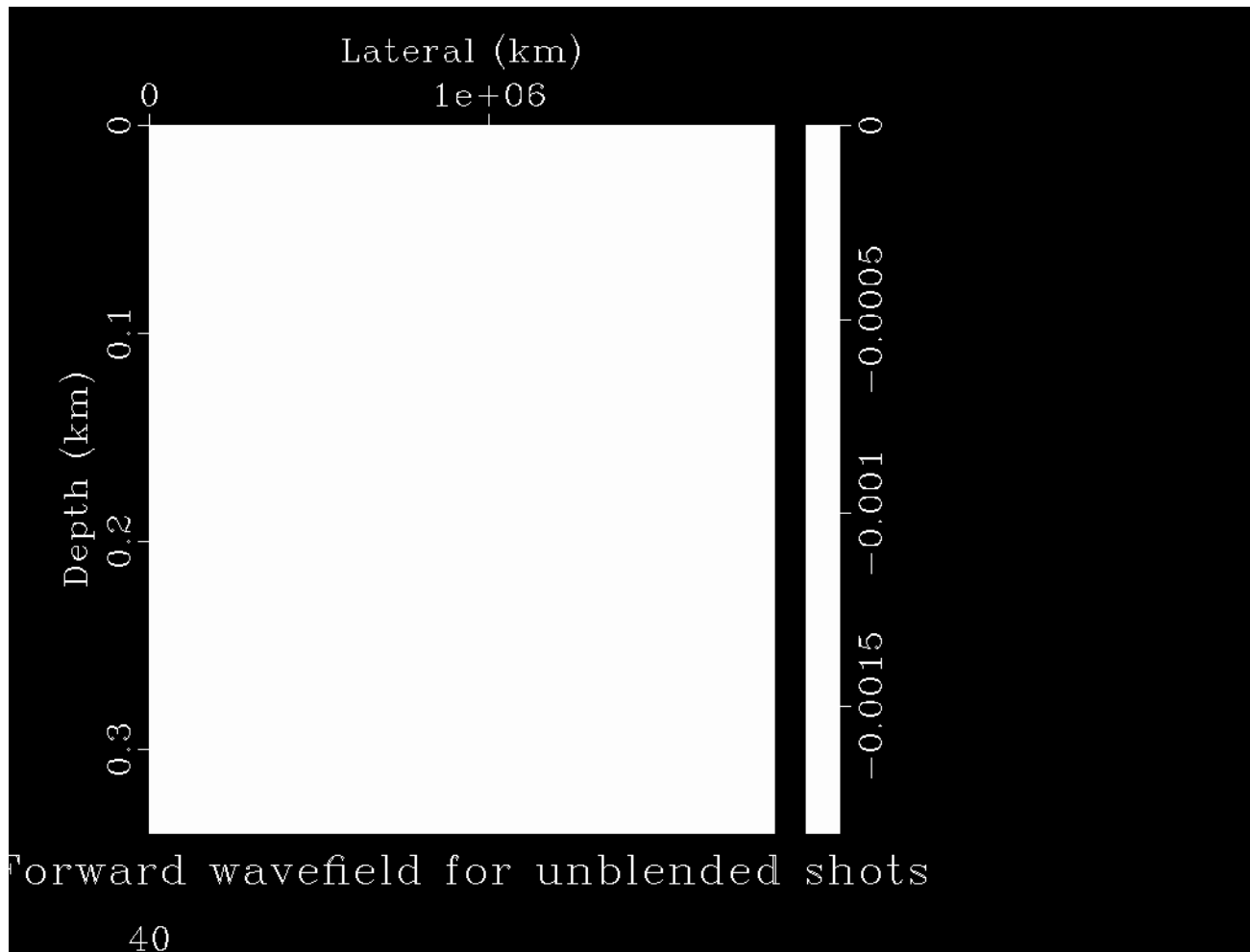
UNIVERSITY OF CALGARY
FACULTY OF SCIENCE
Department of Geoscience





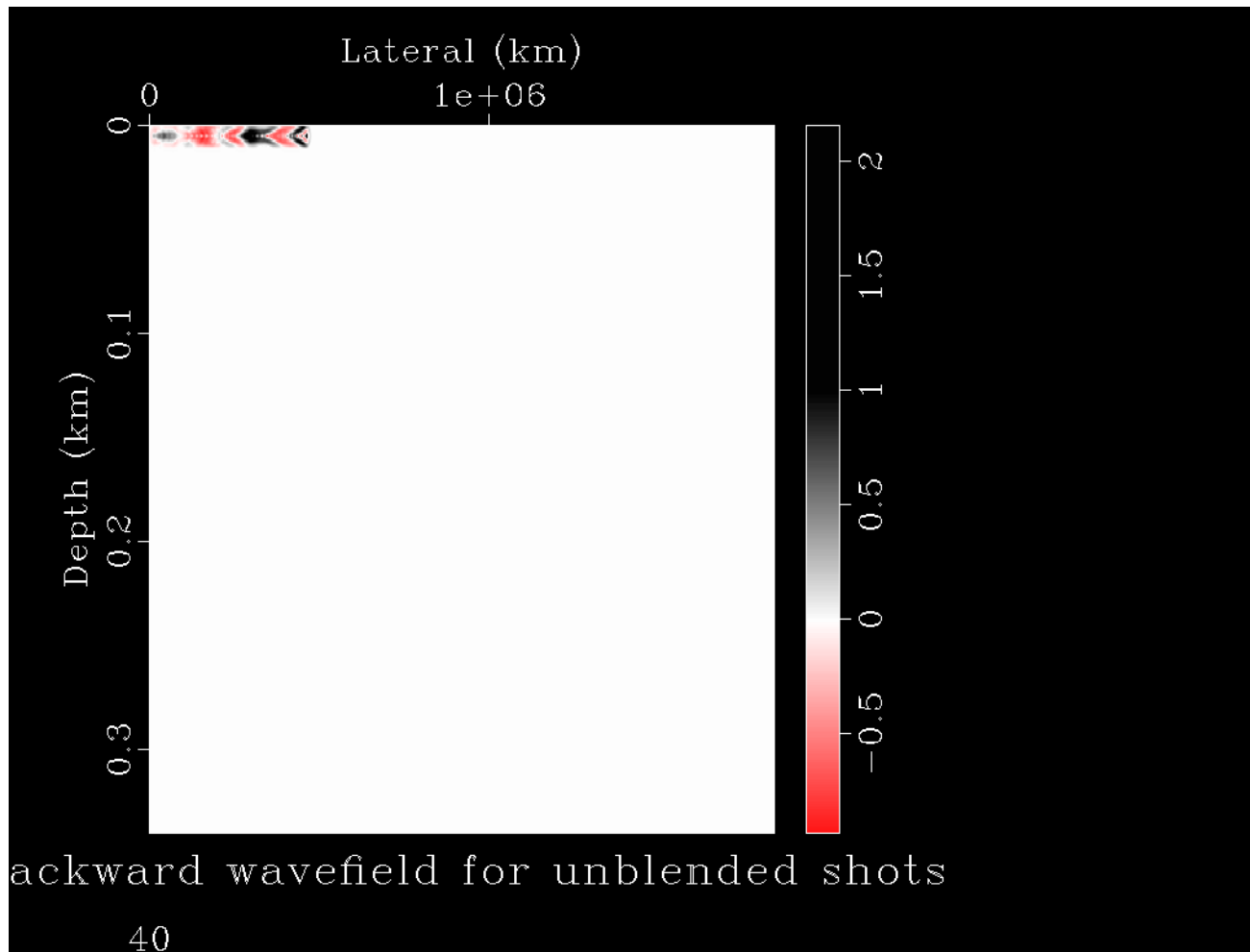
Reverse Time Migration in shot domain

1. inject source in forward wavefield





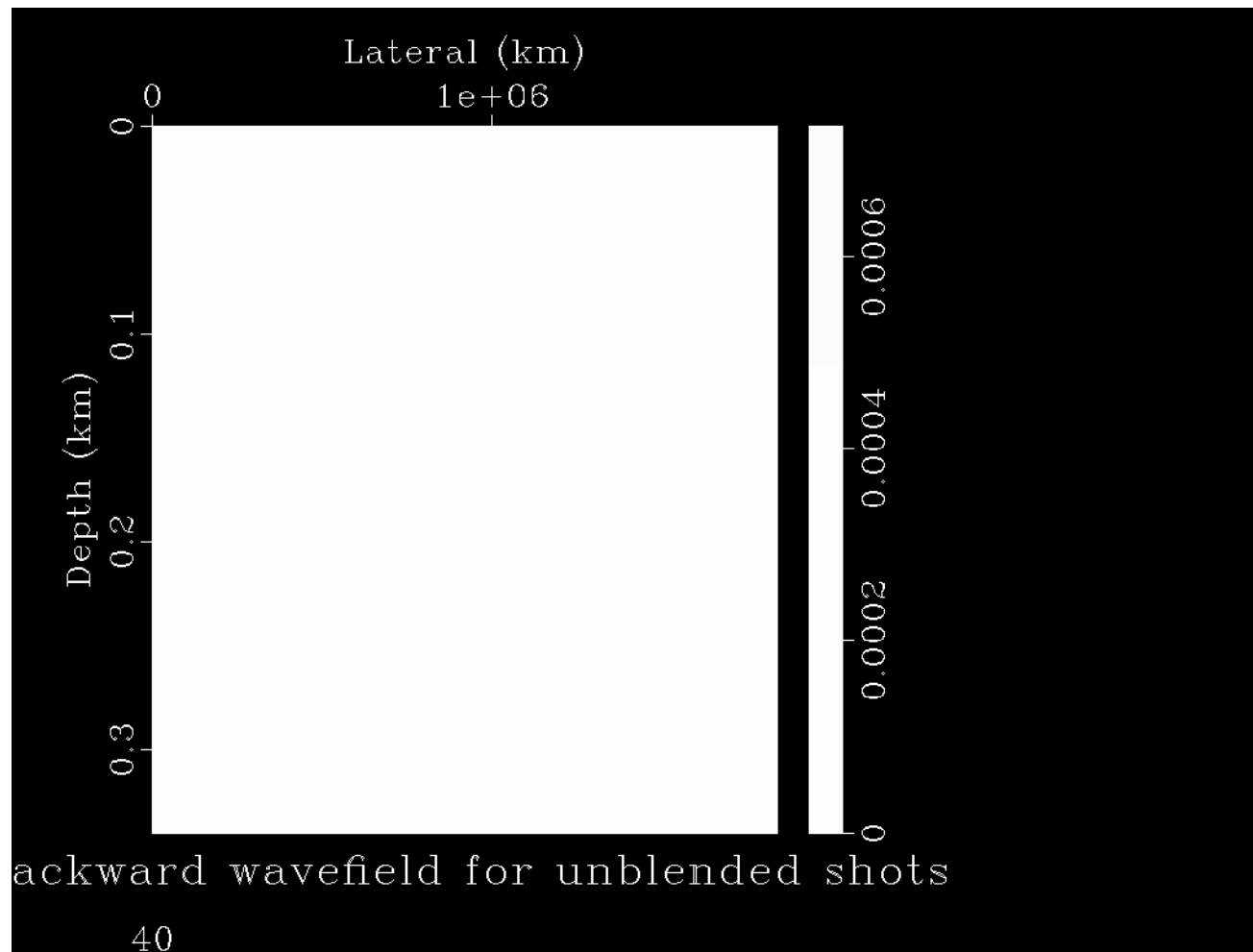
Reverse Time Migration in shot domain 2. inject data in backward wavefield





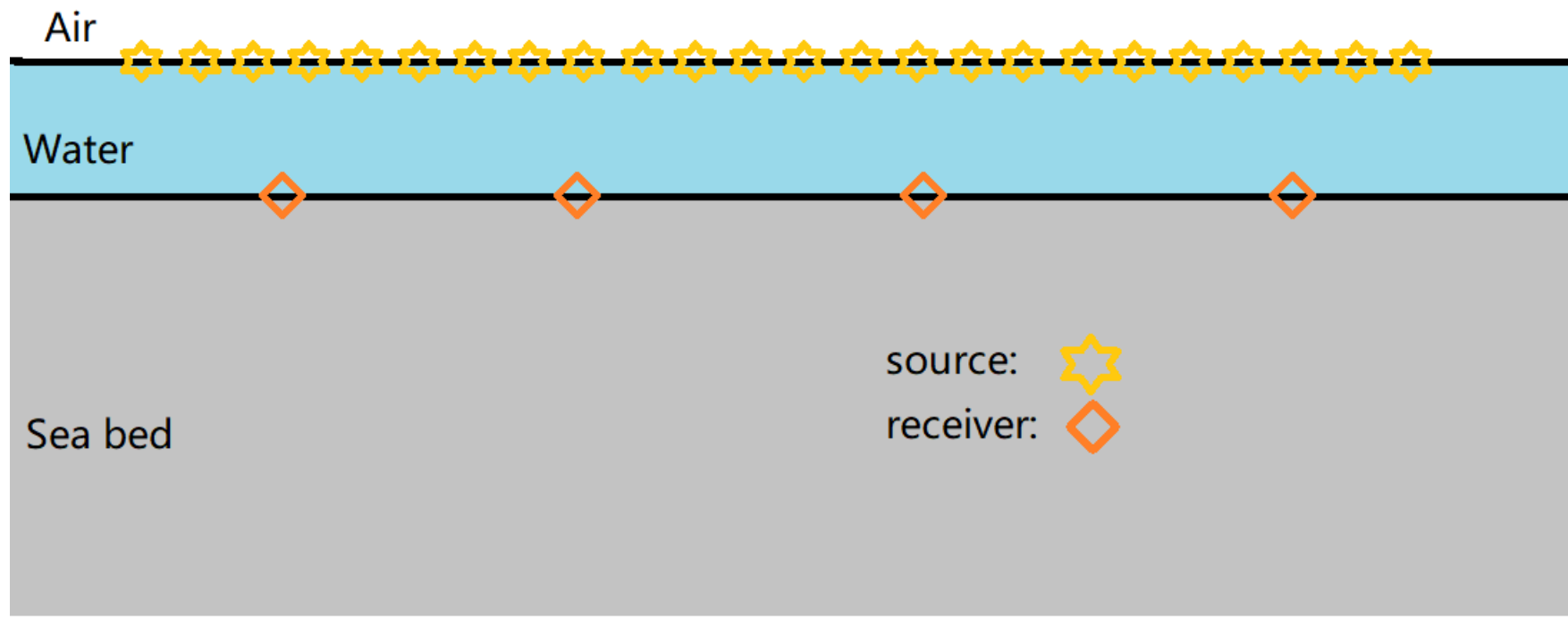
Reverse Time Migration in shot domain

3. Cross-correlation of the two wavefields





Ocean Bottom Node / OBN / Nodes





Why Ocean Bottom Node?

quieter on the seabed than water surface.

acquire wide azimuth and long offset data more cost “effectively”.

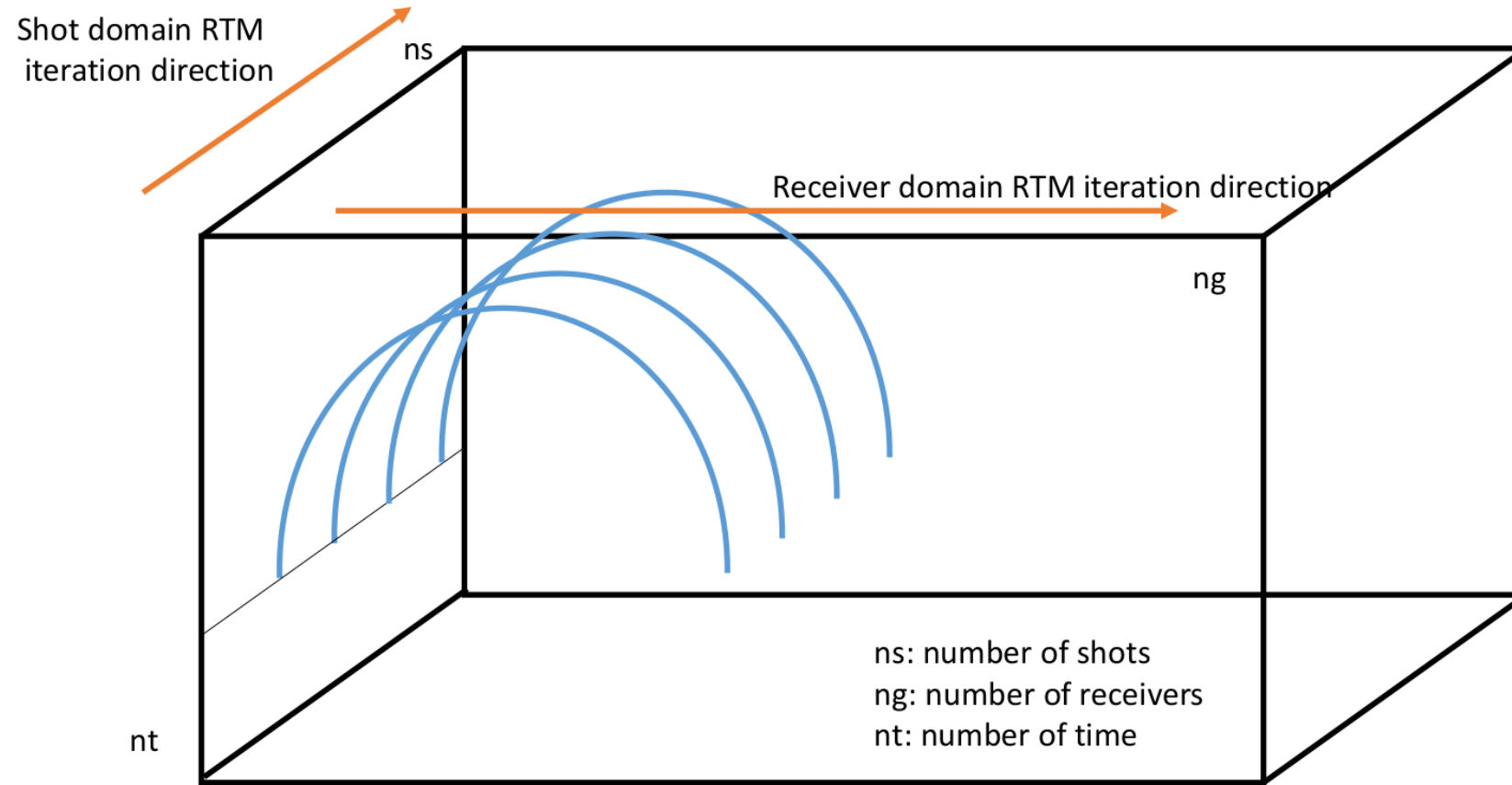
better coverage in areas around platforms.

record shear-waves.

multiple attenuation by separating upcoming and down-going wave-fields

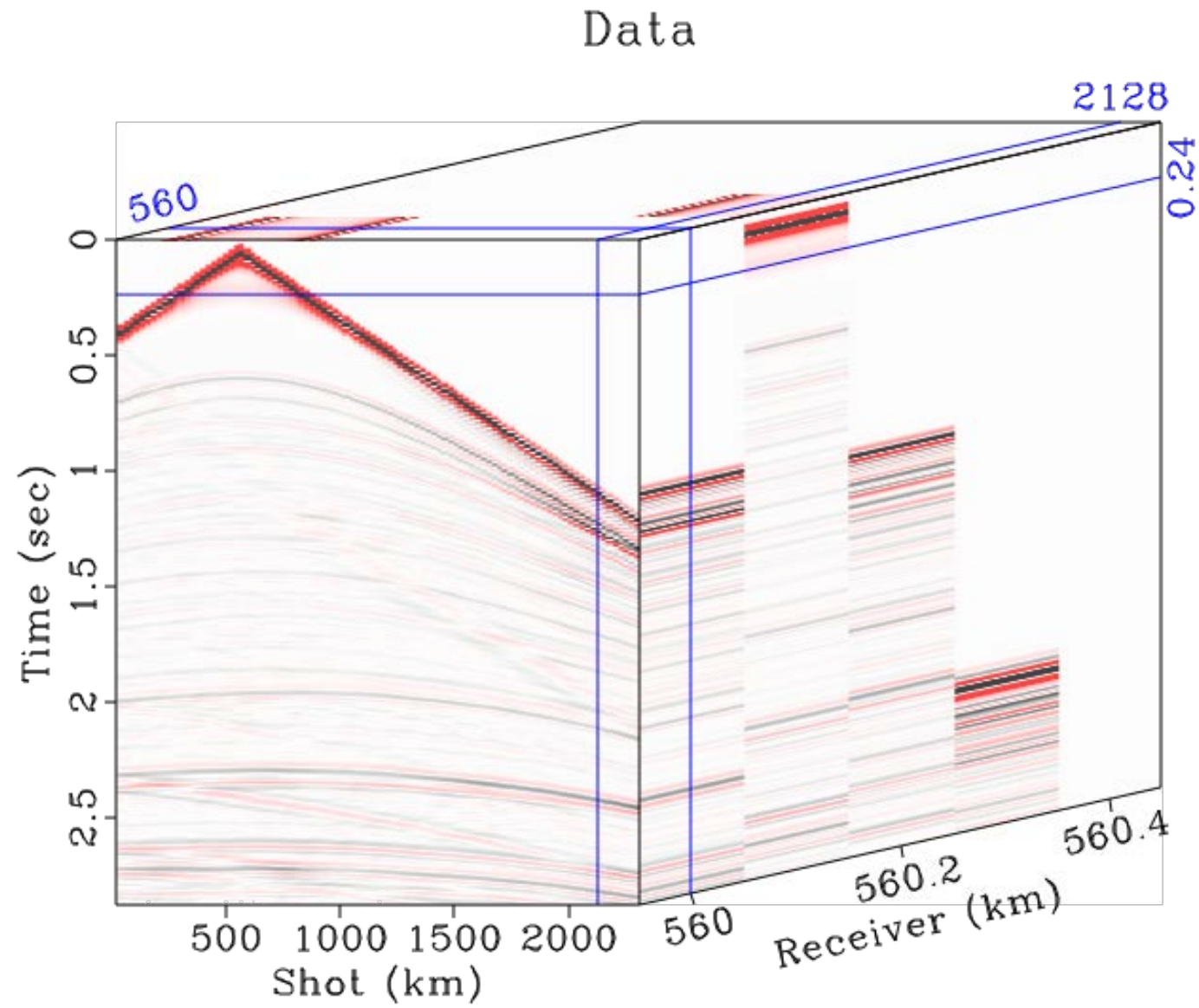


Receiver domain RTM



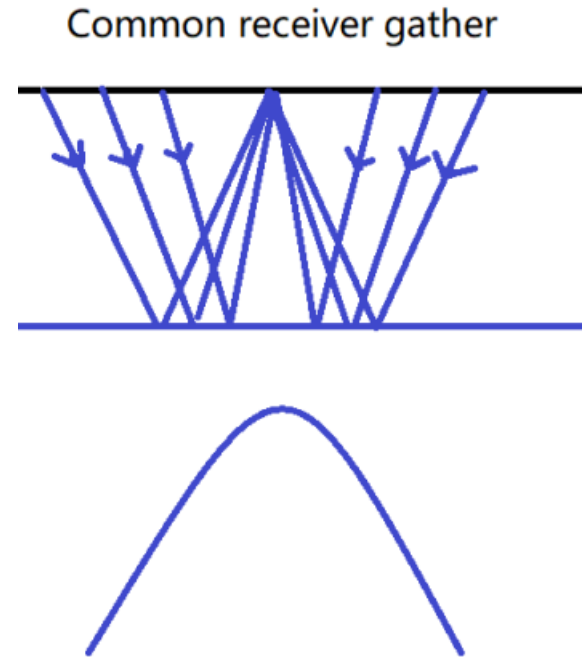


Ocean Bottom Node and receiver domain RTM



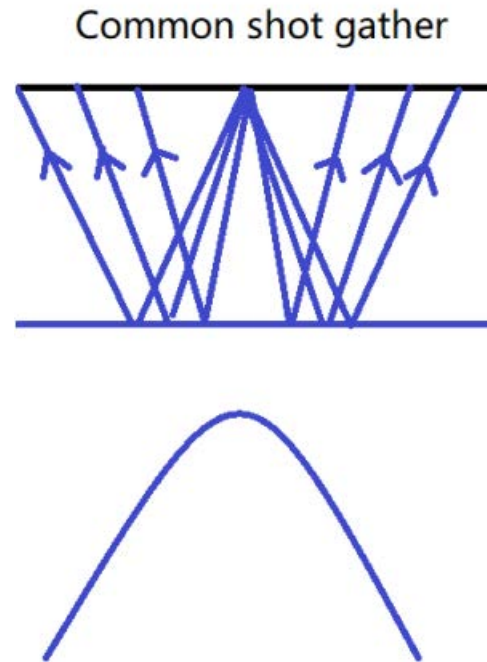


Common receiver gather is the data gathered from one receiver.



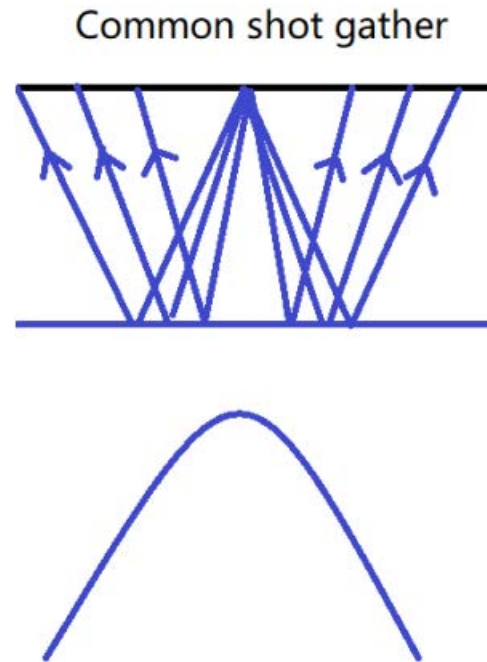


Utilizing the principle of reciprocity, the locations of shots and receiver are exchanged in the Common Receiver Gather.





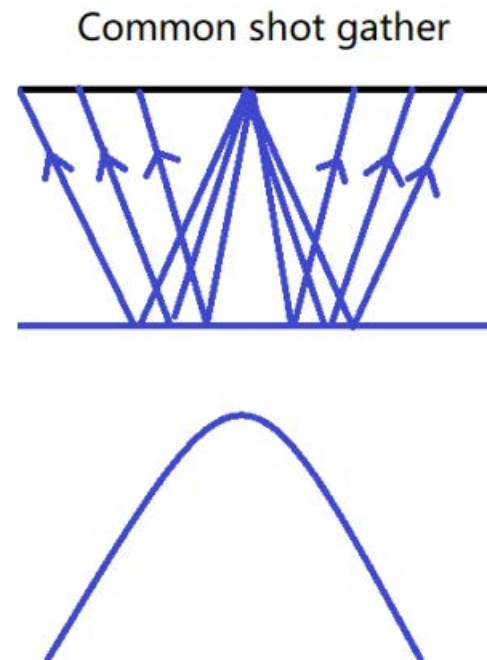
The seismic traces acquired from the one receiver corresponding to each shot are assigned to the location of the shots. In the receiver domain RTM, the traces are injected in the backward propagation.





In the receiver domain RTM, the cross-correlation of forward and backward wavefield is computed for every receivers.

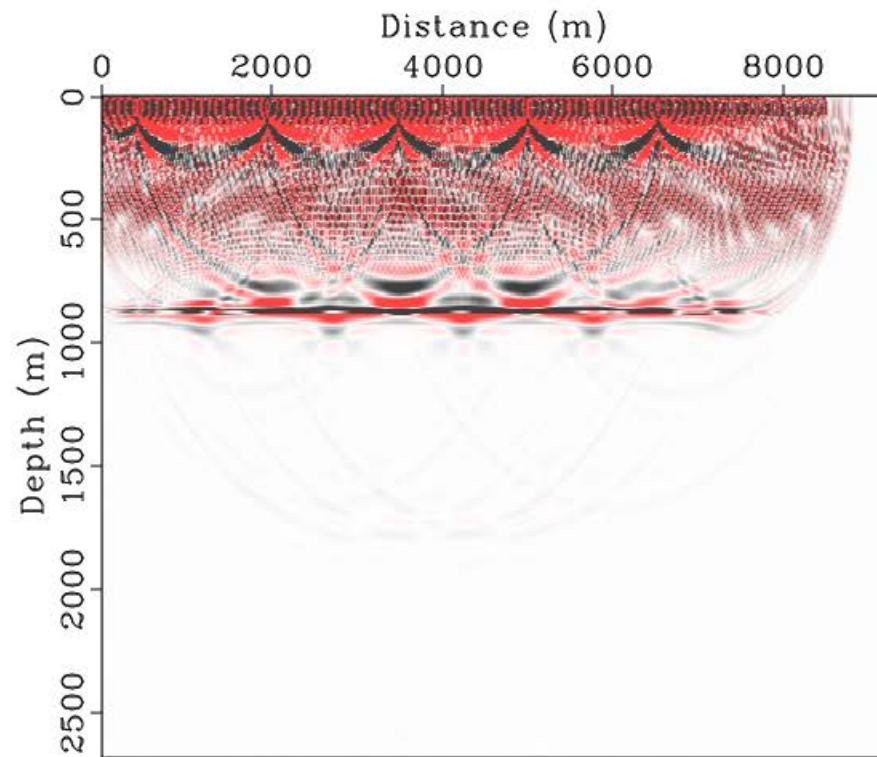
The traces from one receiver are injected in the backward wavefield propagation in in iteration.



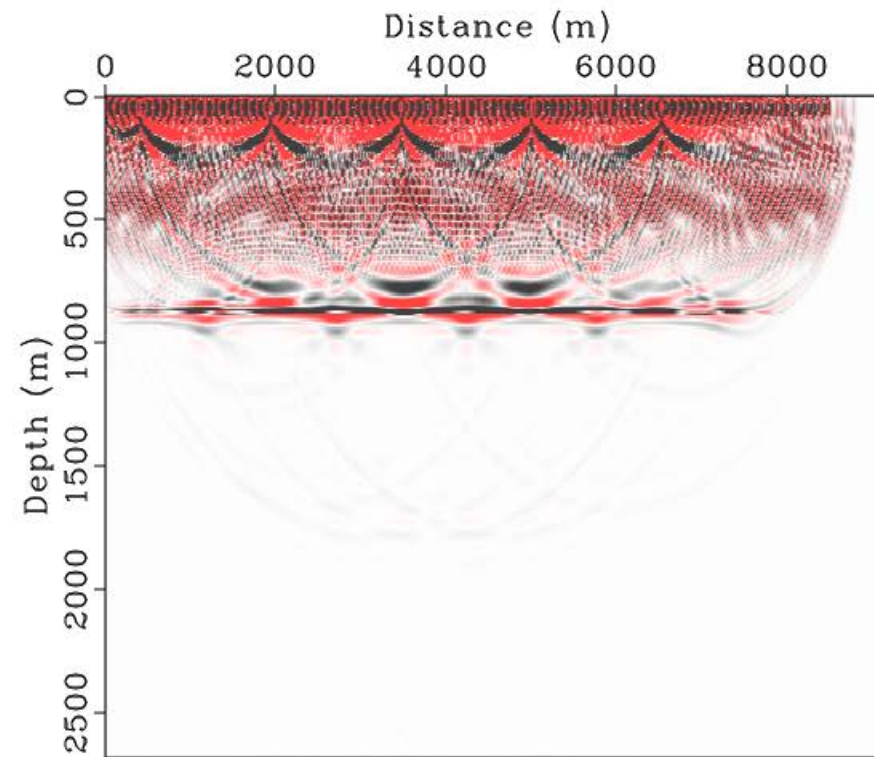


RTM in shot and receiver domain?

Two-layer model, unblended data



Shot domain RTM

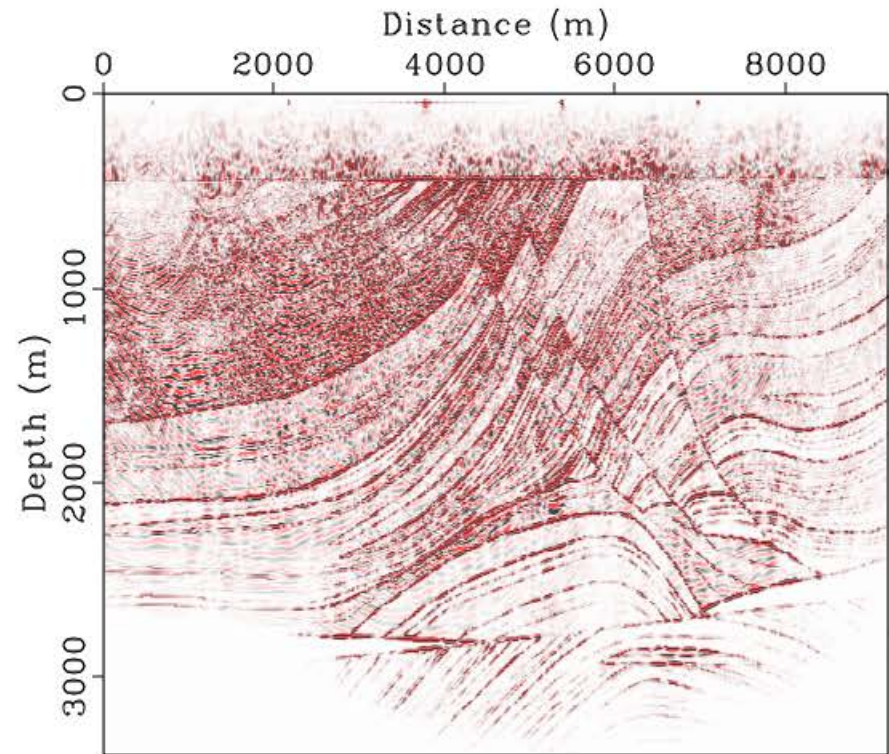
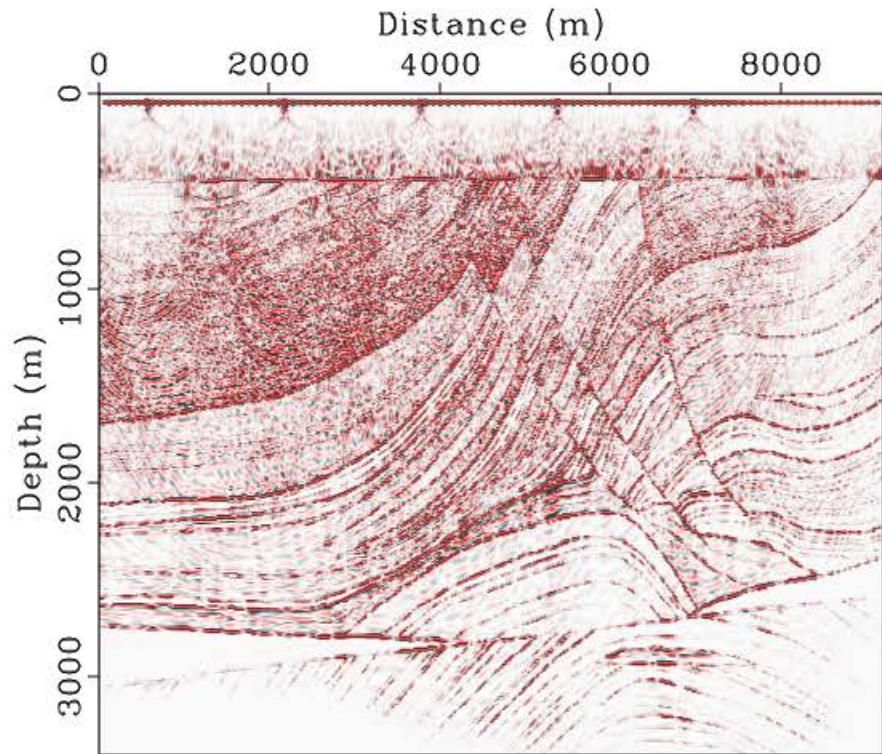


Receiver domain RTM



RTM in shot and receiver domain?

Two-layer model, marmousi data



Blended shot domain RTM for marmousi model

Blended receiver domain RTM for marmousi model



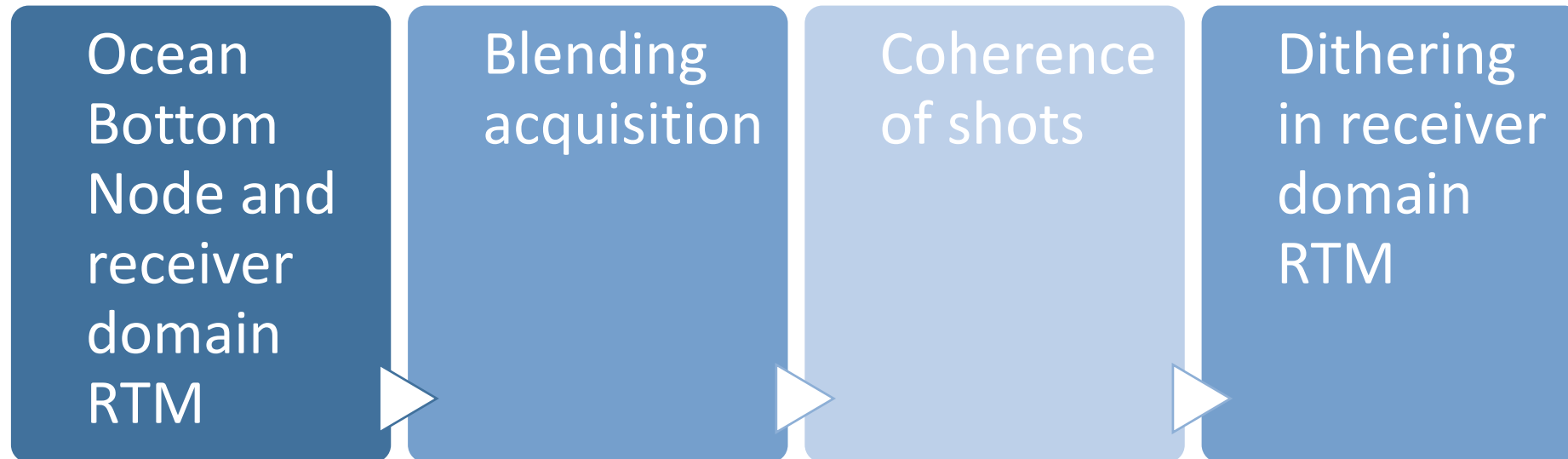
Receiver domain RTM

Computation of Shot domain RTM is proportional to #sources.

Computation of Receiver domain RTM is proportional to #receivers.

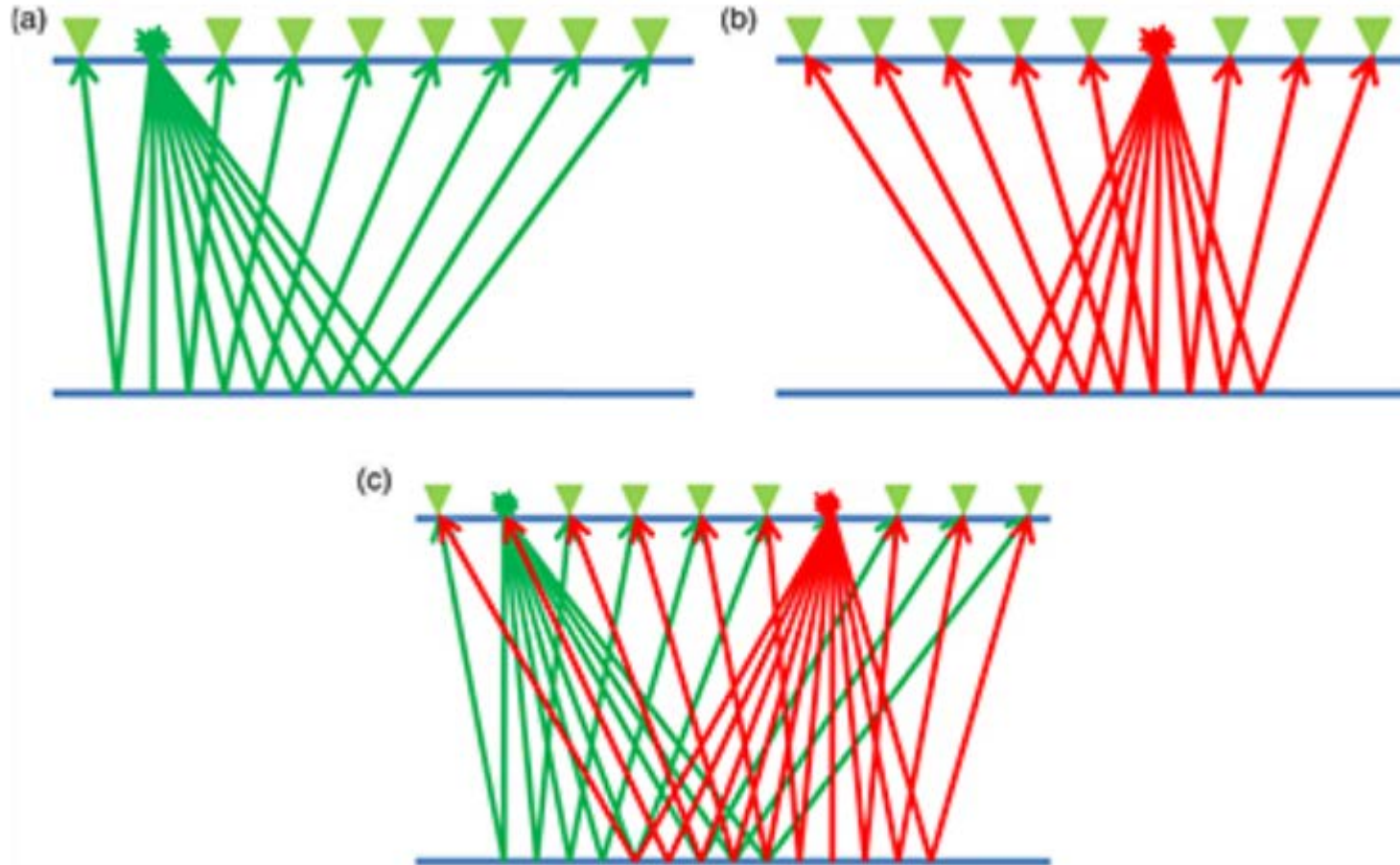
OBN has many sources and few receivers->

Receiver domain RTM saves computation in OBN.





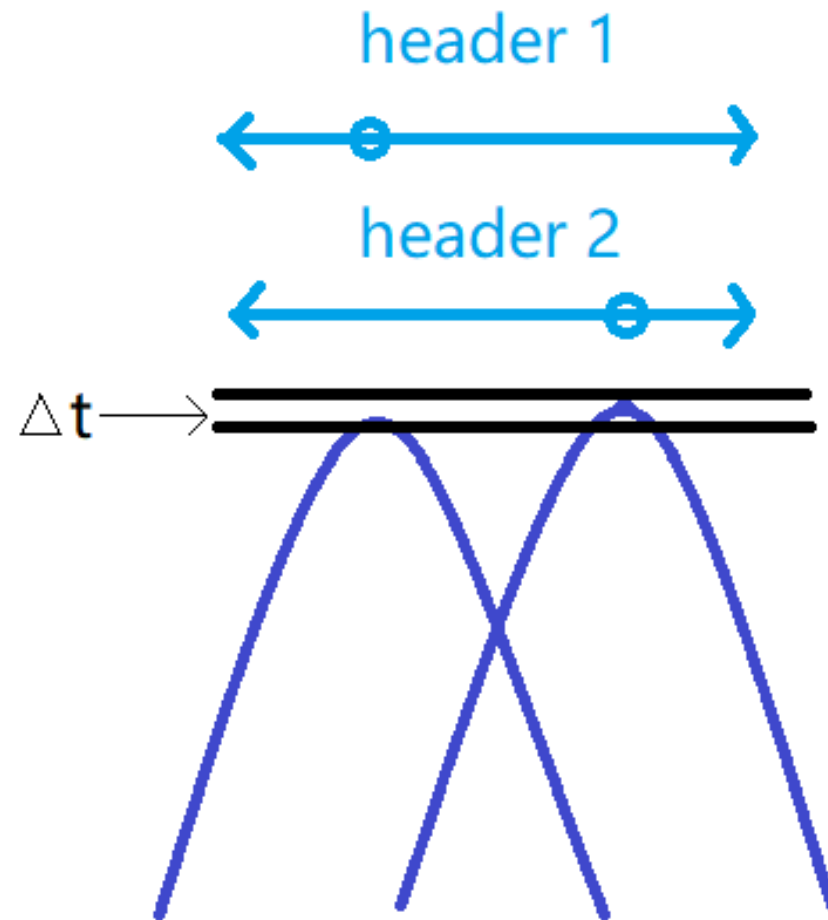
Blending acquisition: simultaneous shooting





Blending acquisition

Information we get that can distinguish them are multiple sets of headers and the time delay between sources.





Why blending acquisition?

0. Data acquisition is by far the most expensive part of seismic methods.

1. acquire more data without increasing the acquisition cost

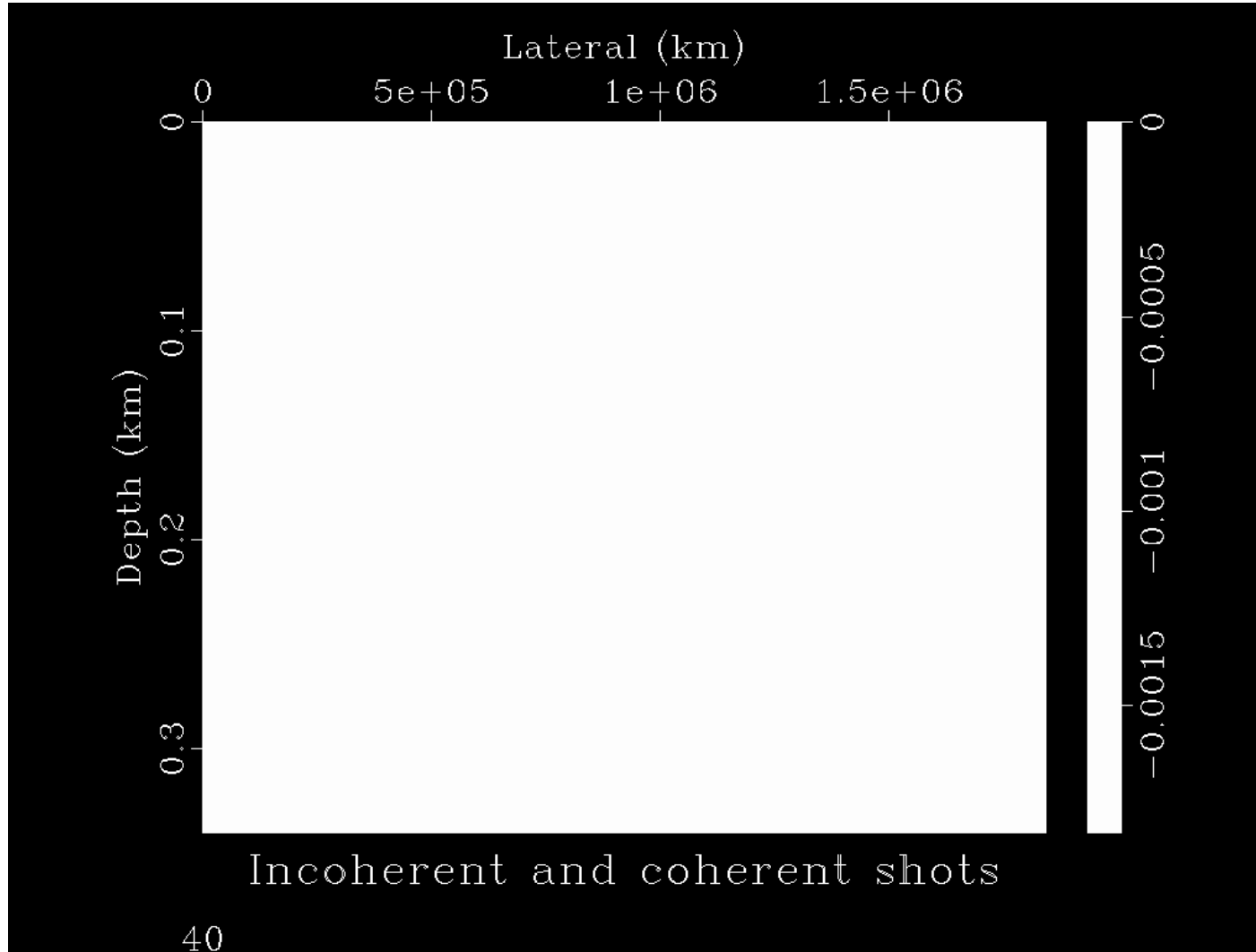
2. decrease the acquisition time and therefore greatly reduce the cost of information



Blending acquisition

Blended RTM in shot domain.

1. inject sources in forward wavefield

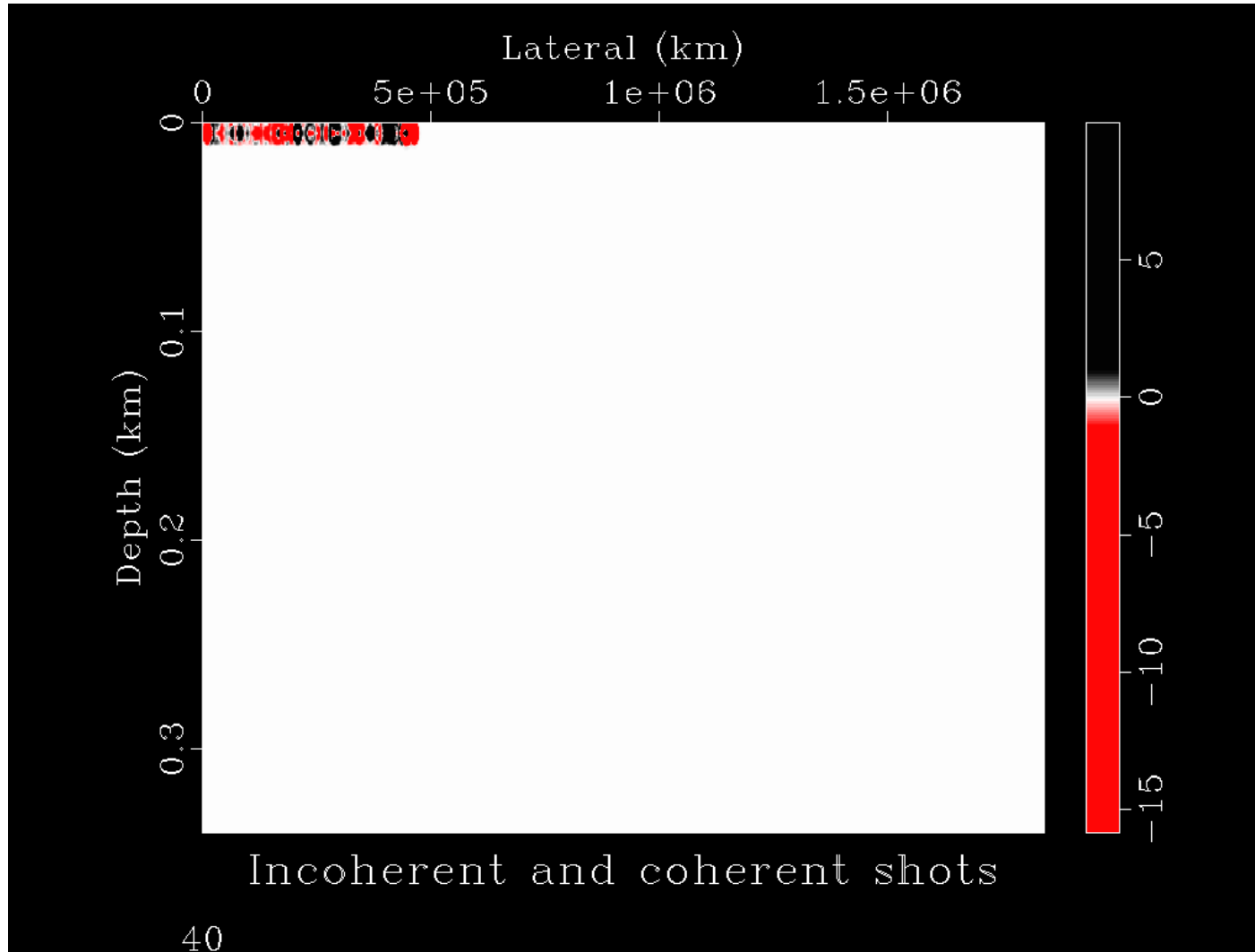




Blending acquisition

Blended RTM in shot domain.

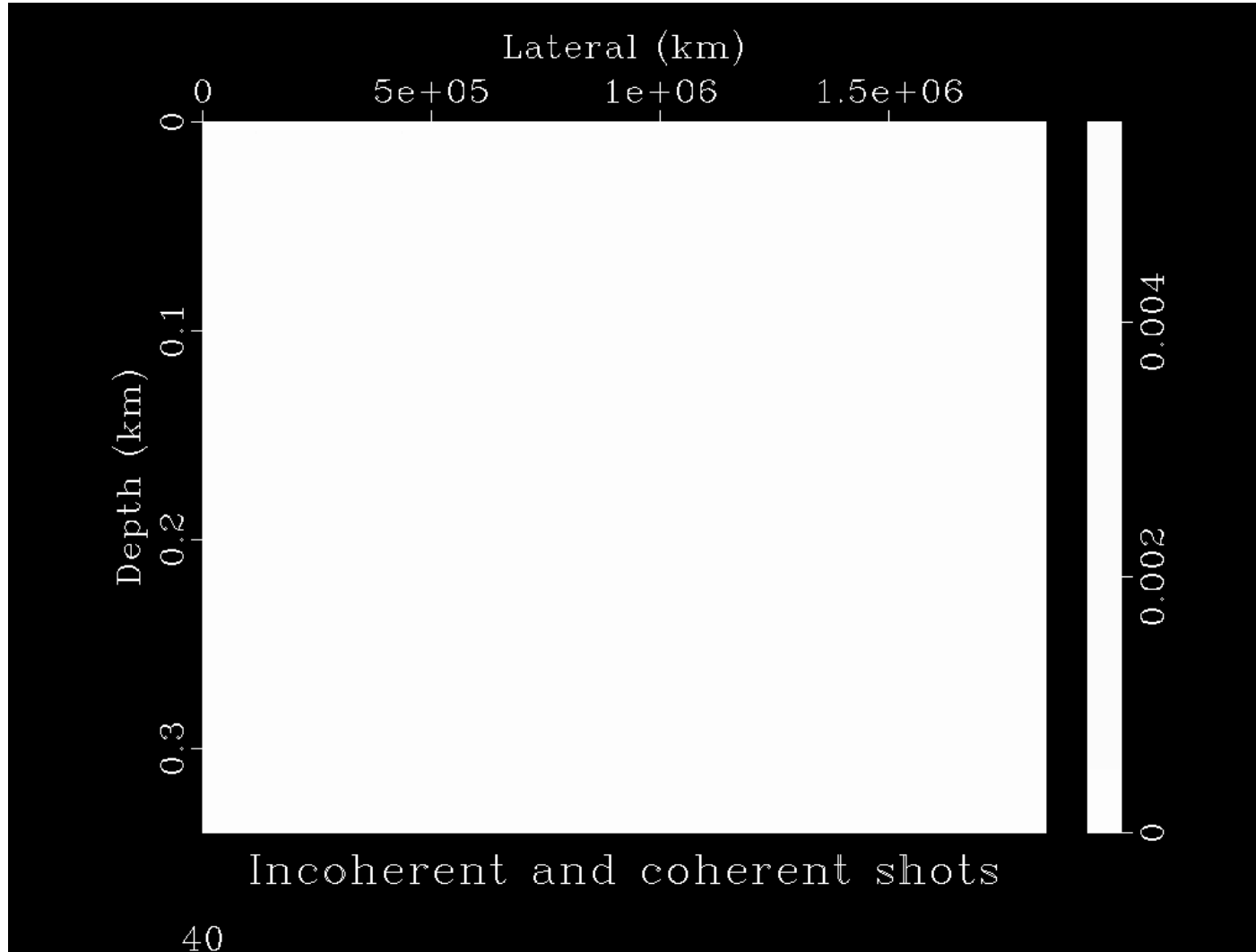
2. inject data in backward wavefield





Blended RTM in shot domain.

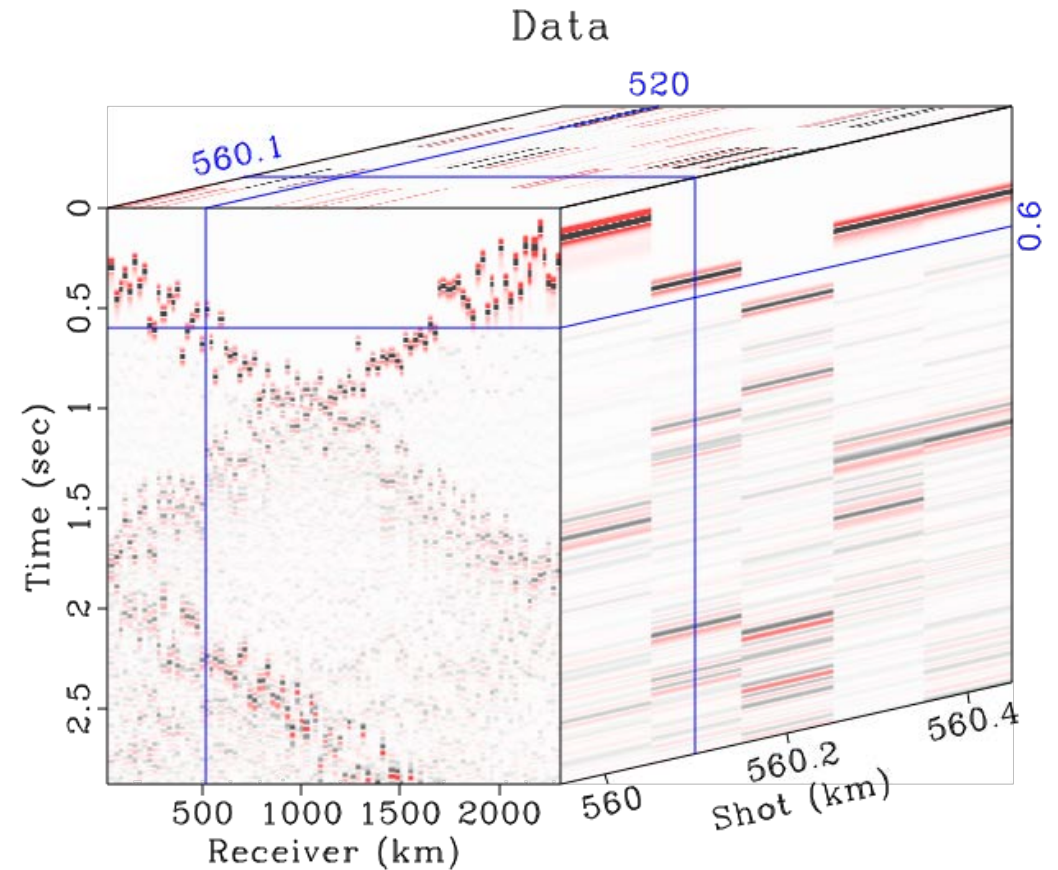
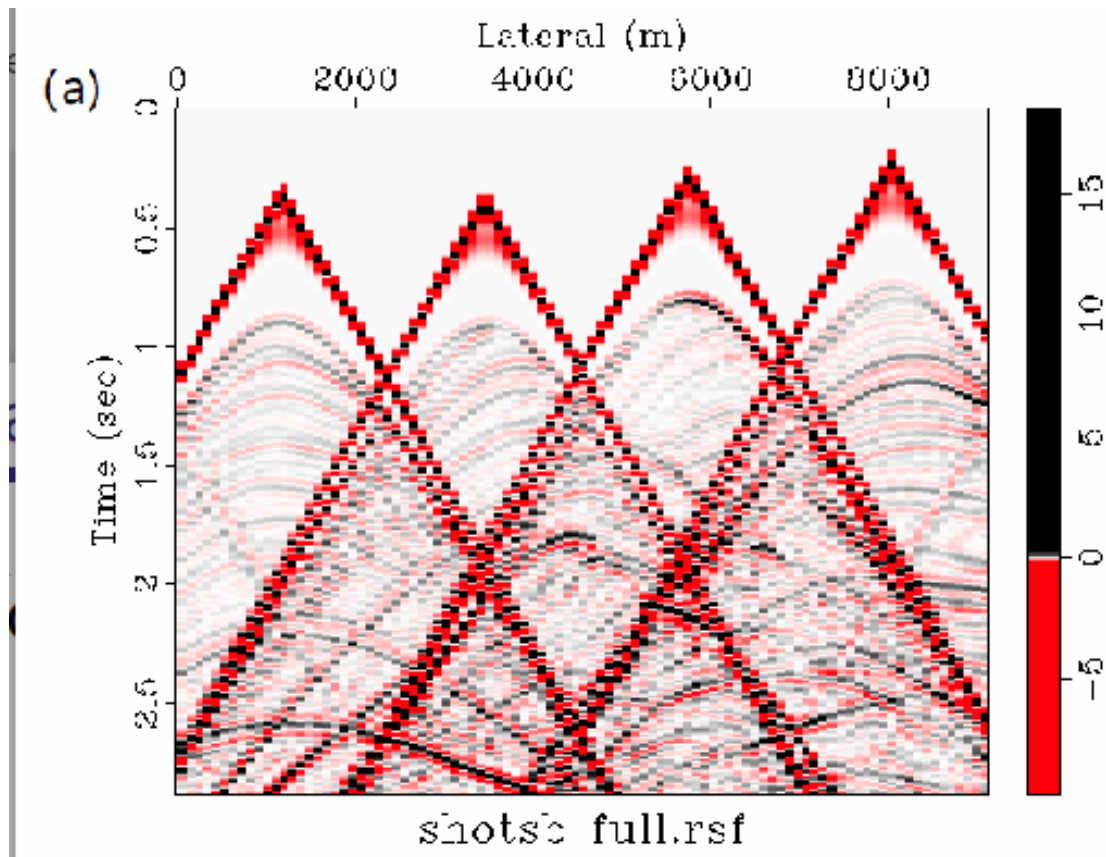
3. Cross-correlation of the two wavefields





What is deblending?

Each single shot in every “Supershot” has its own delay time.



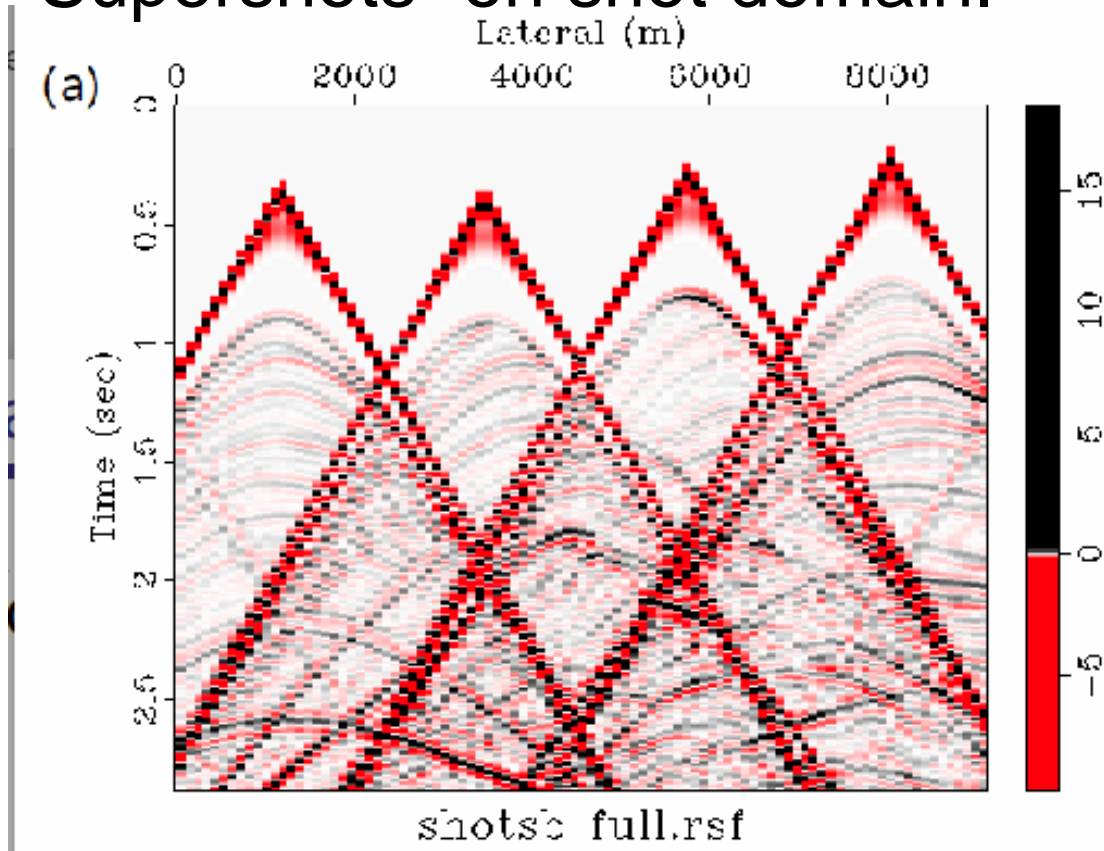


What is deblending?

Blended RTM in shot domain.

Pseudo-deblending

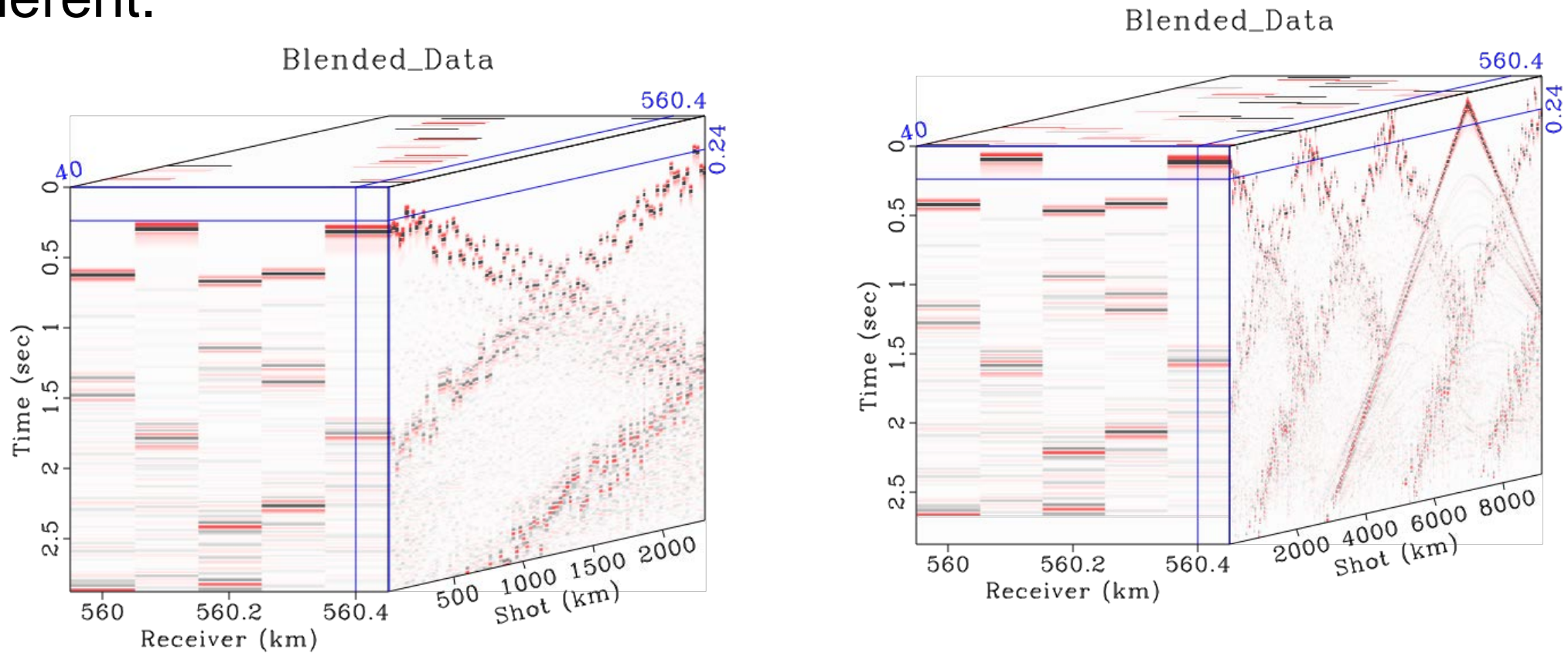
Shift target shot's delay time as zero for each shot inside
"Supershots" on shot domain.





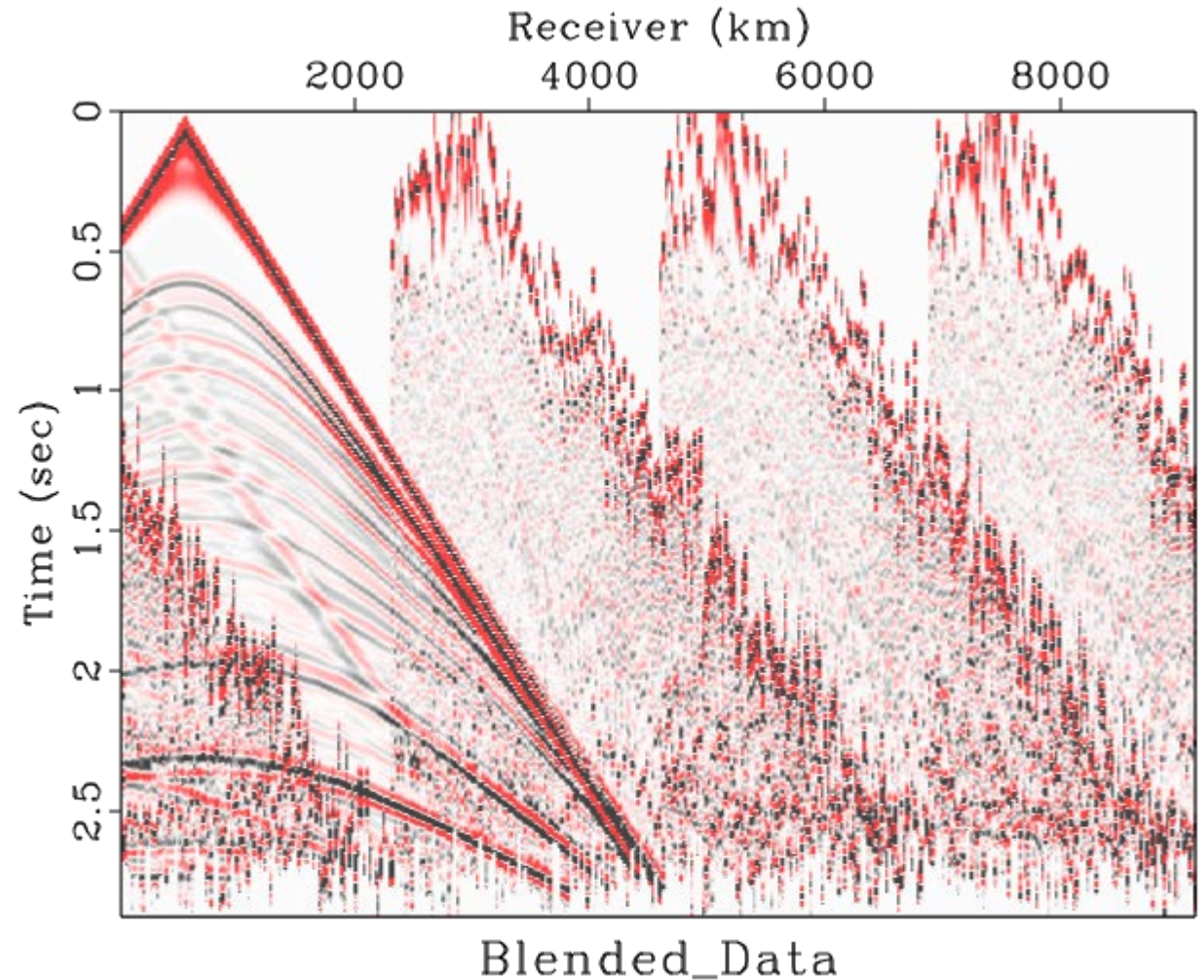
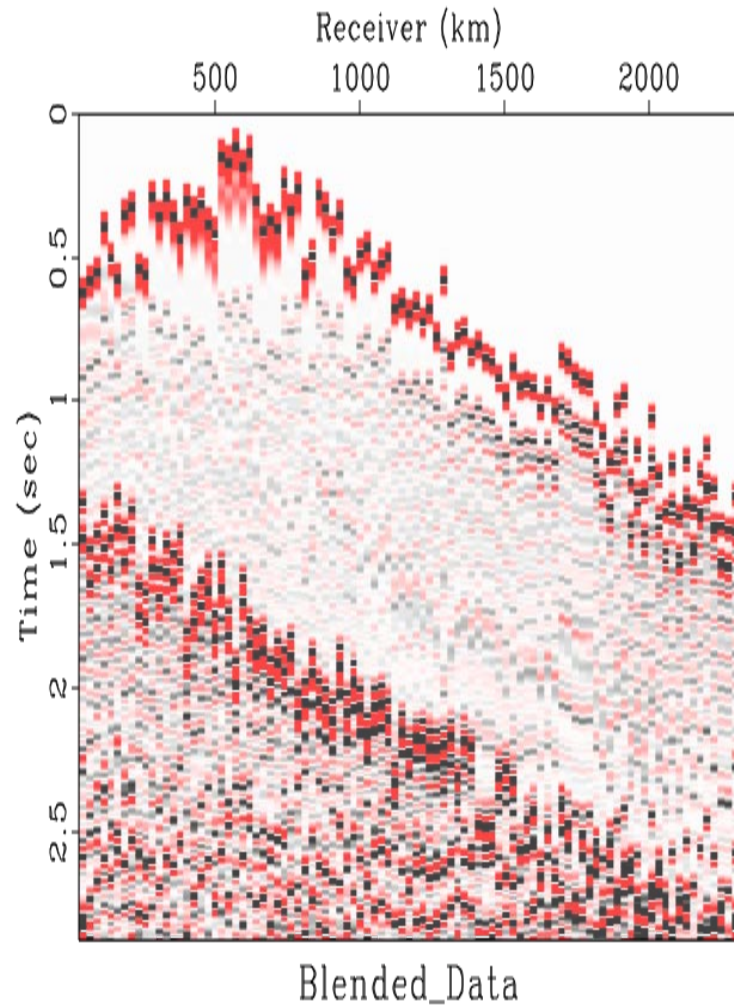
Blending acquisition

Pseudo deblending extents the data size *nblended* times, where *nblended* is the number of simultaneous shots in each supershot. After shifting, the target shot becomes coherent and other shots remain incoherent.





Extending and shifting/dithering:



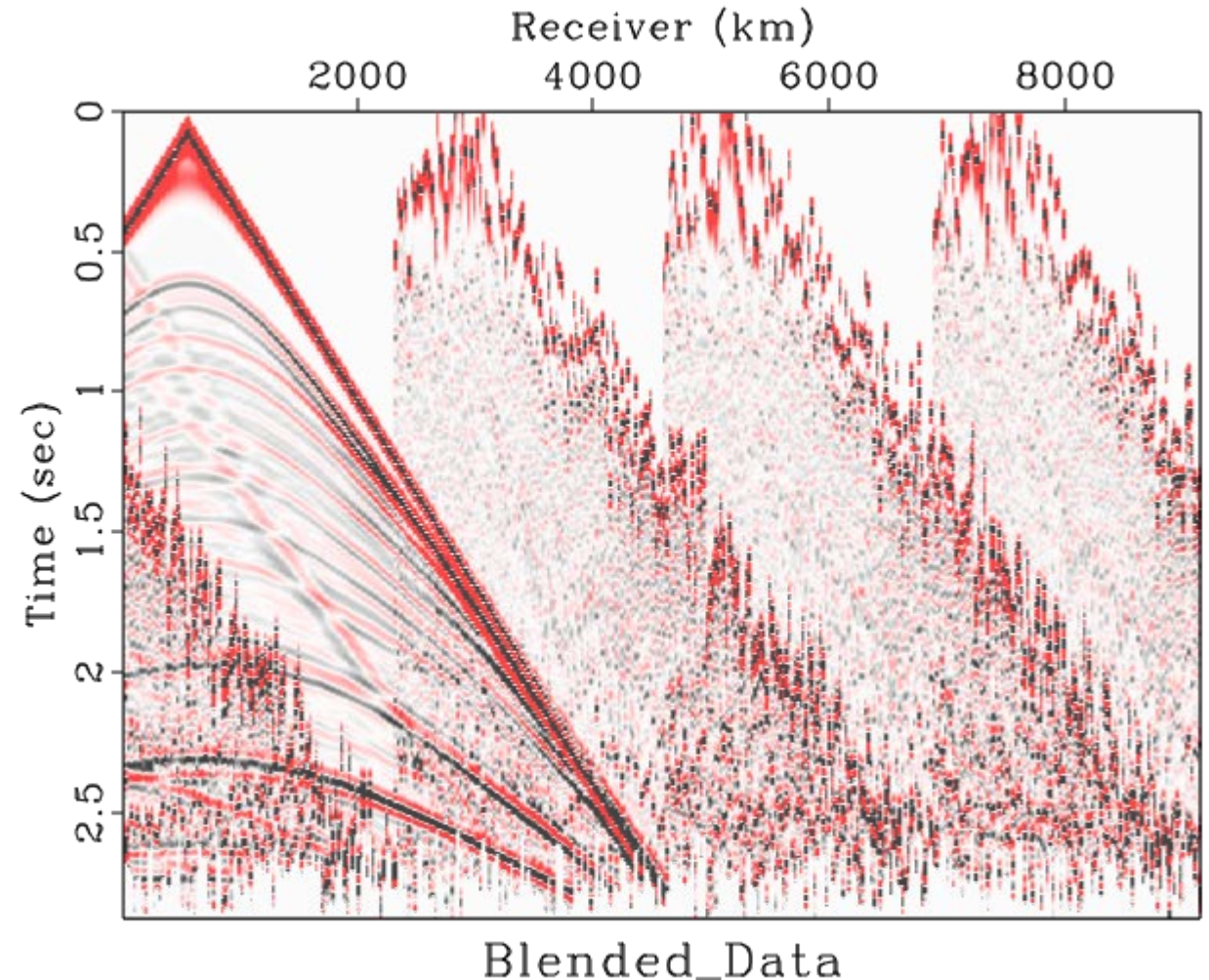
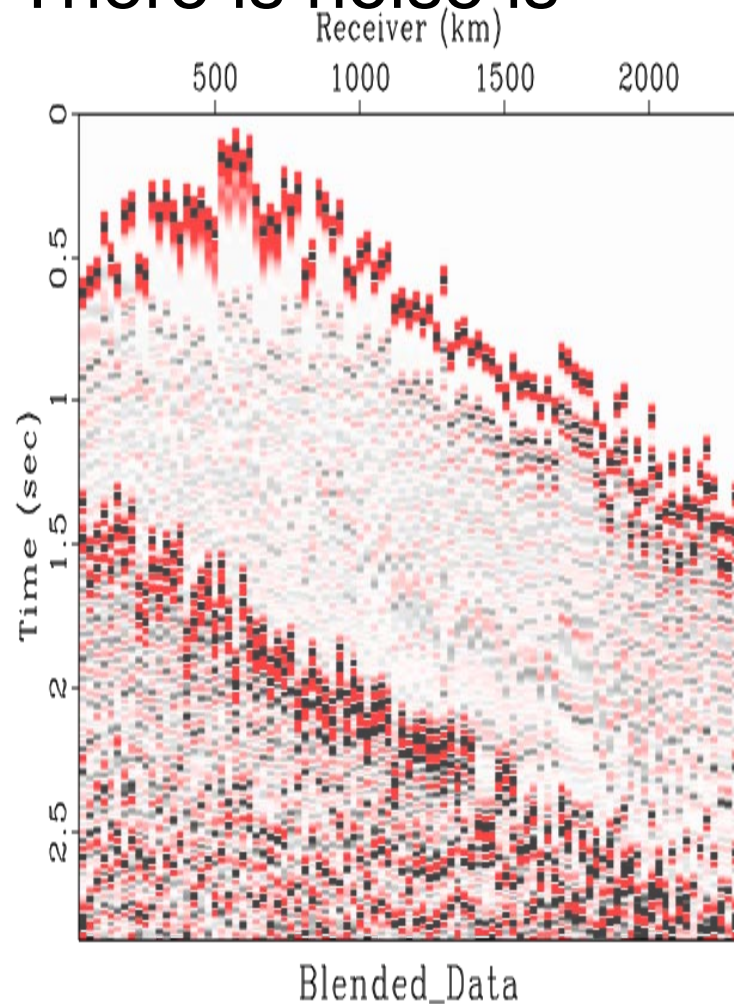


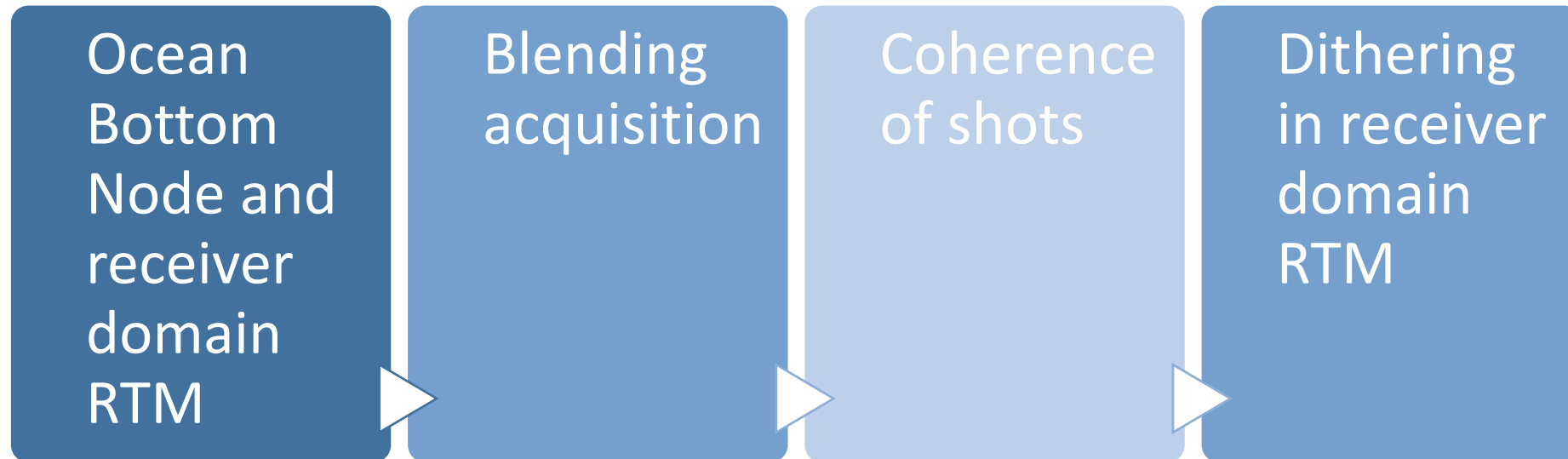
Blending acquisition

Extending and shifting/dithering:

Target shot is coherent and unwanted shots are incoherent

There is noise is







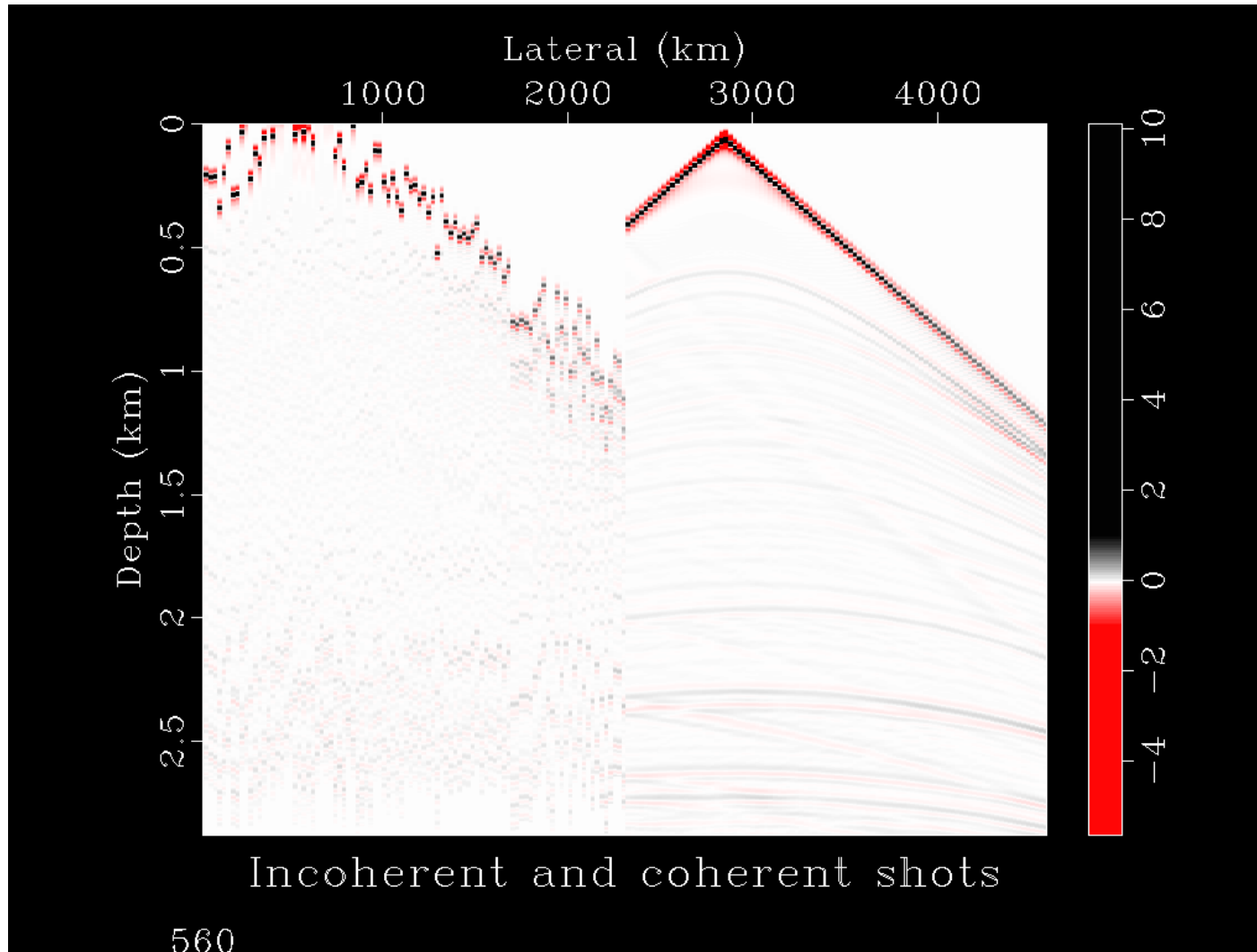
In blended receiver domain RTM, target shot is coherent and unwanted shots are incoherent.

RTM imaging condition amplifies coherent shots while cancels incoherent shots

Therefore blended RTM could remove the noise of blending.

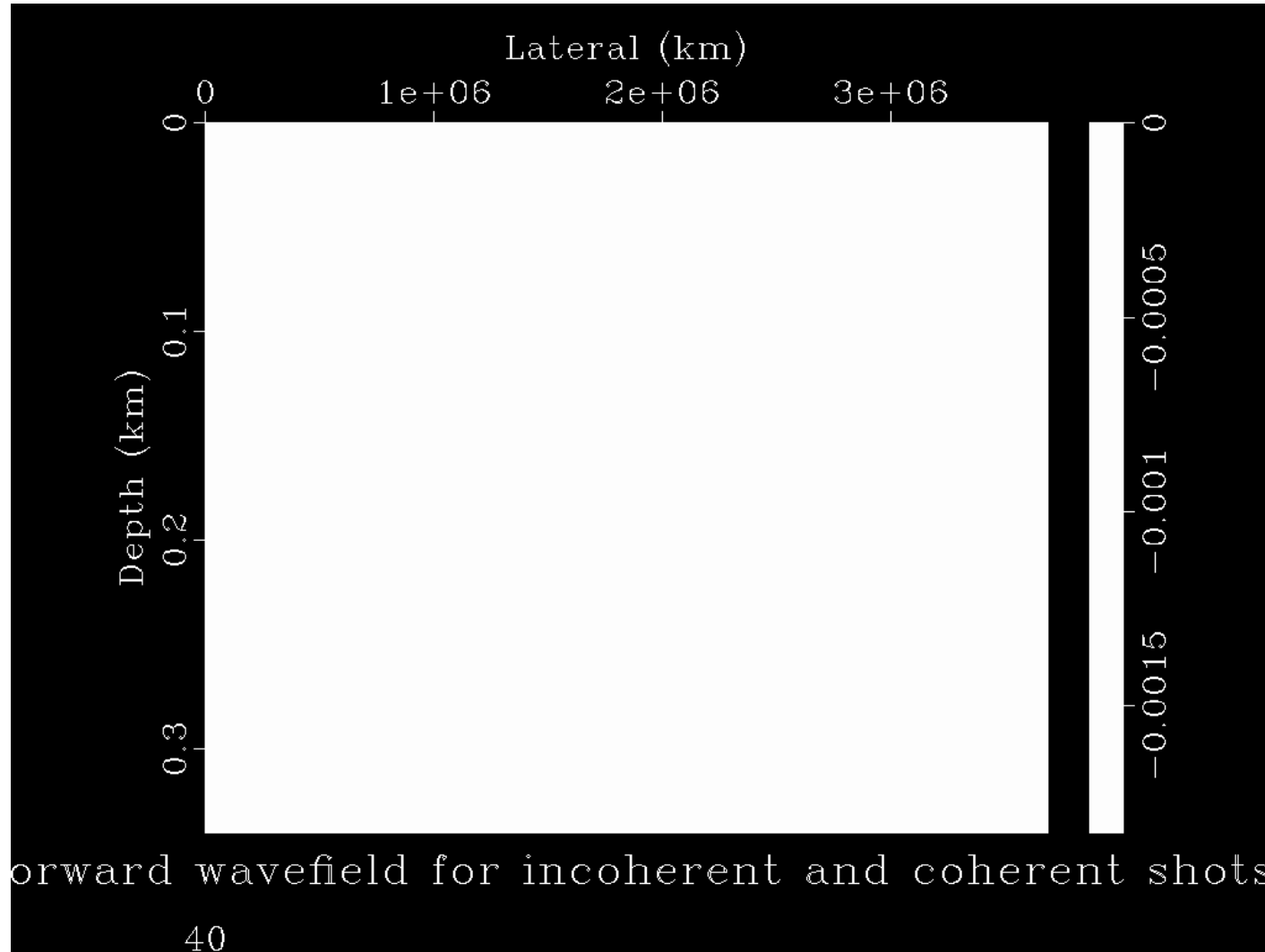


Coherency effects in RTM,



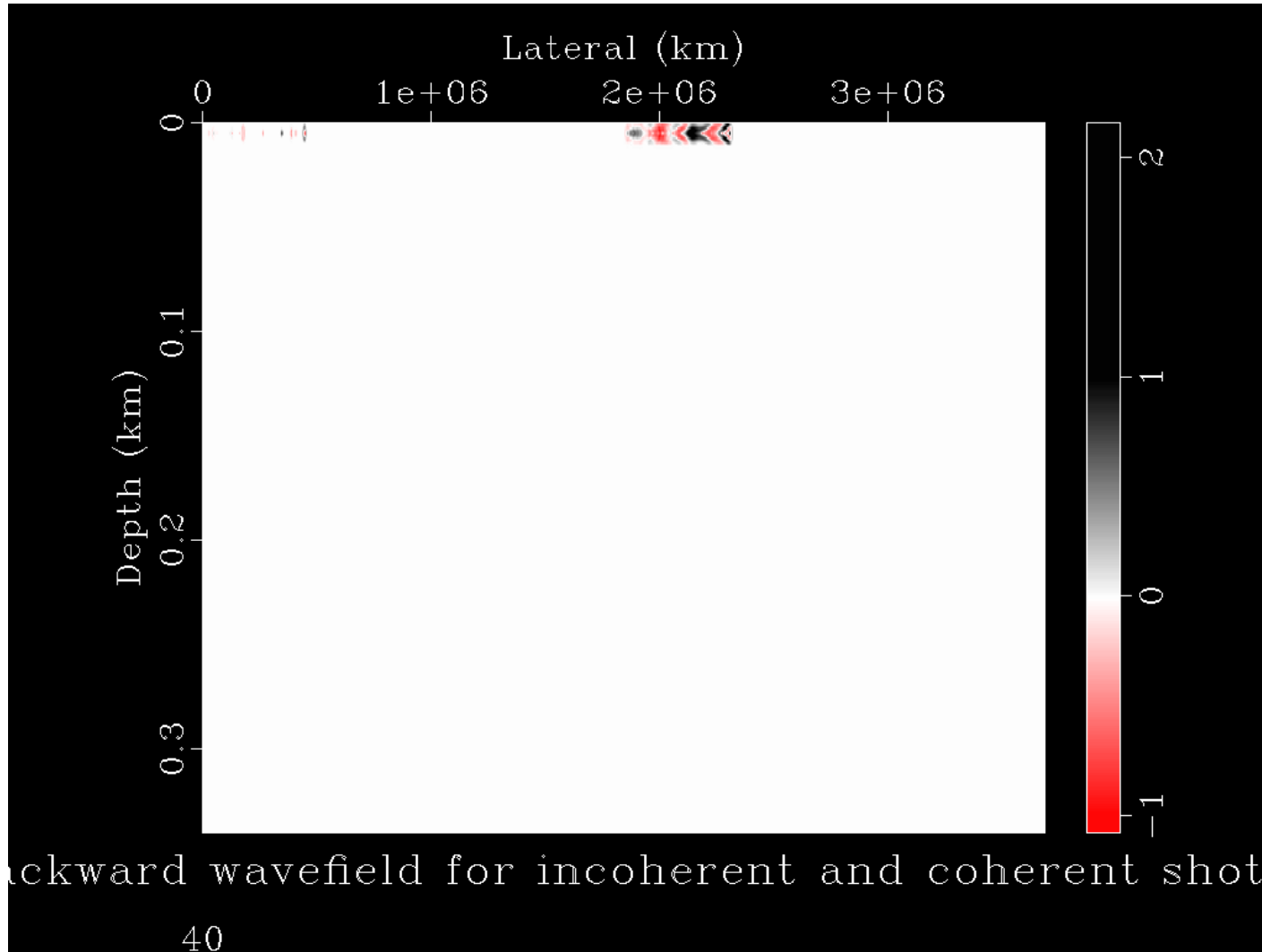


Coherency effects in RTM





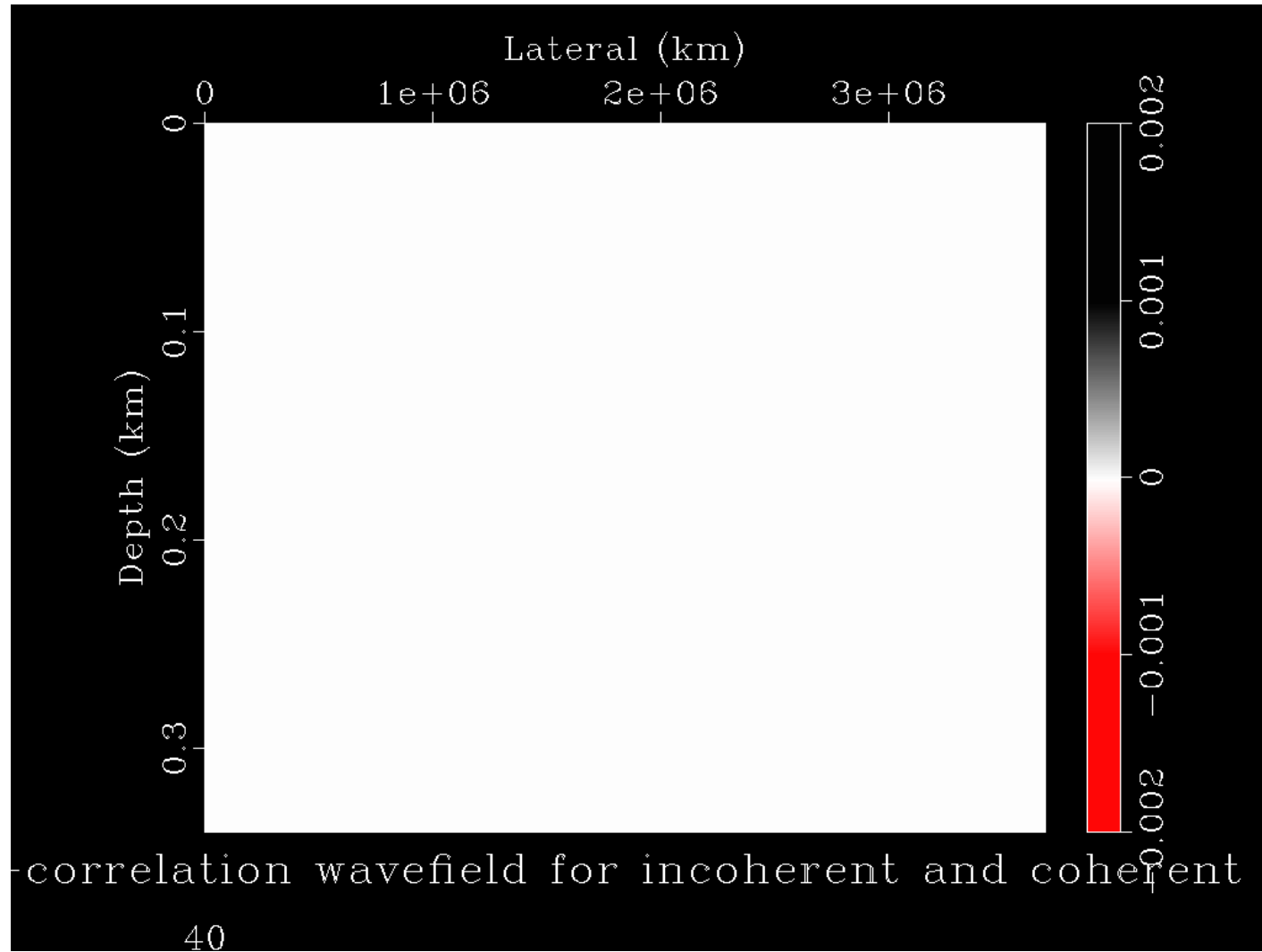
Coherency effects in RTM



Backward wavefield for incoherent and coherent shots



Coherency effects in RTM

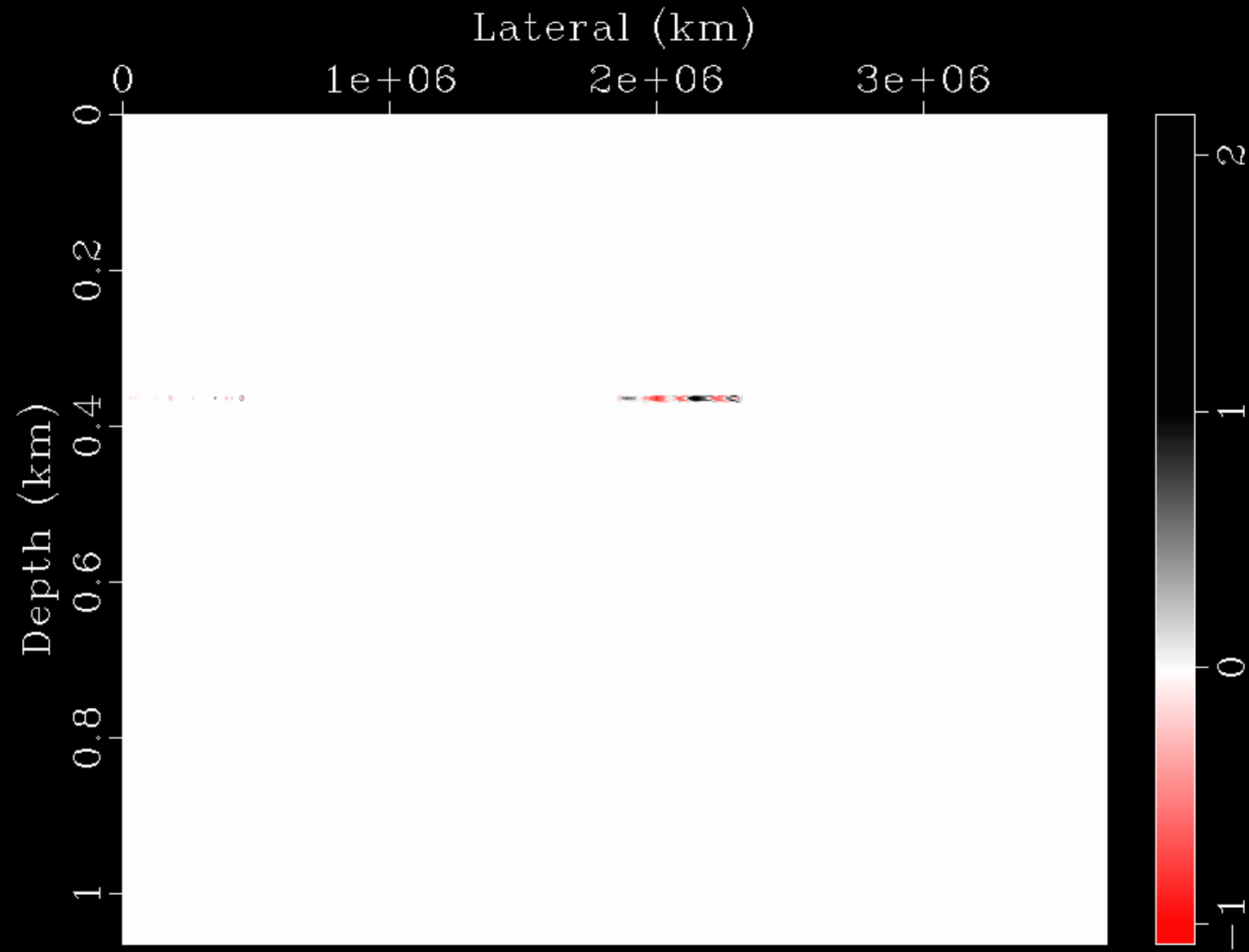


correlation wavefield for incoherent and coherent shots

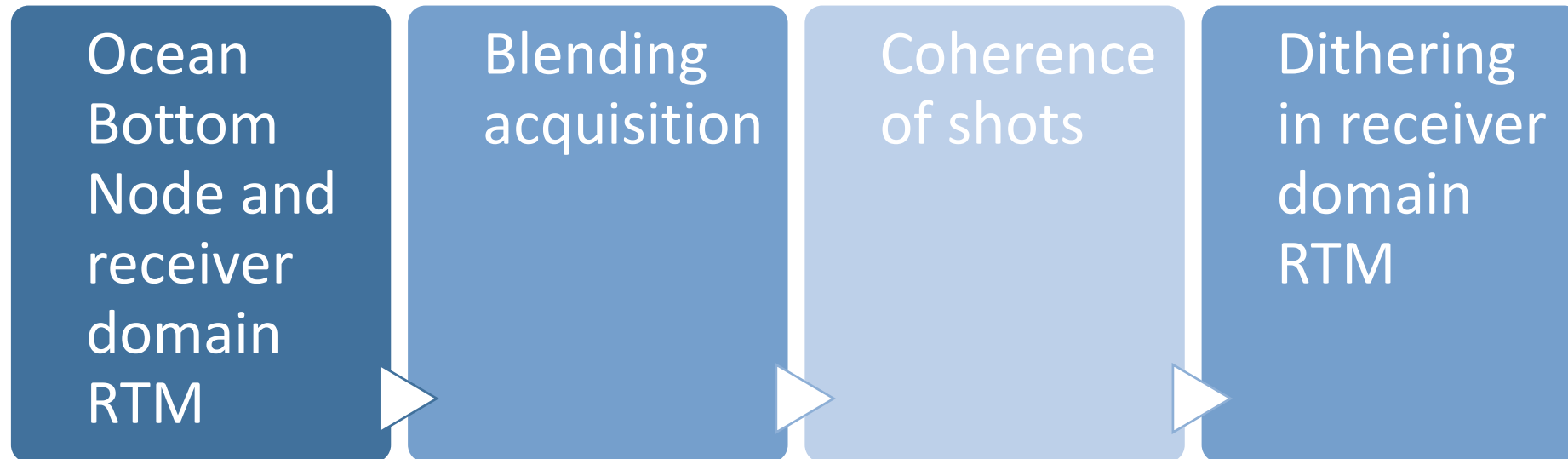


Coherence of shots

Cohe



Incoherent and coherent shots





Dithering in receiver domain RTM

There are many ways to apply the delay time into RTM:

Time delay to insert source in forward wavefield

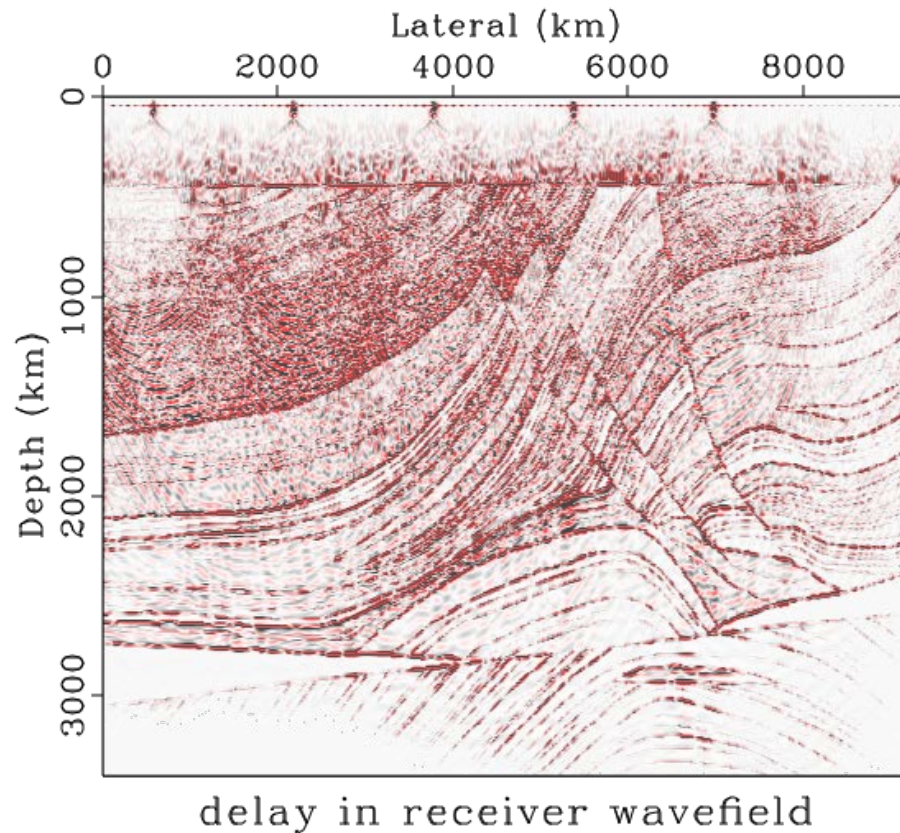
Time delay to insert data in backward wavefield



Dithering in receiver domain RTM

Time delay to insert source in forward wavefield: No

Time delay to insert data in backward wavefield: Yes

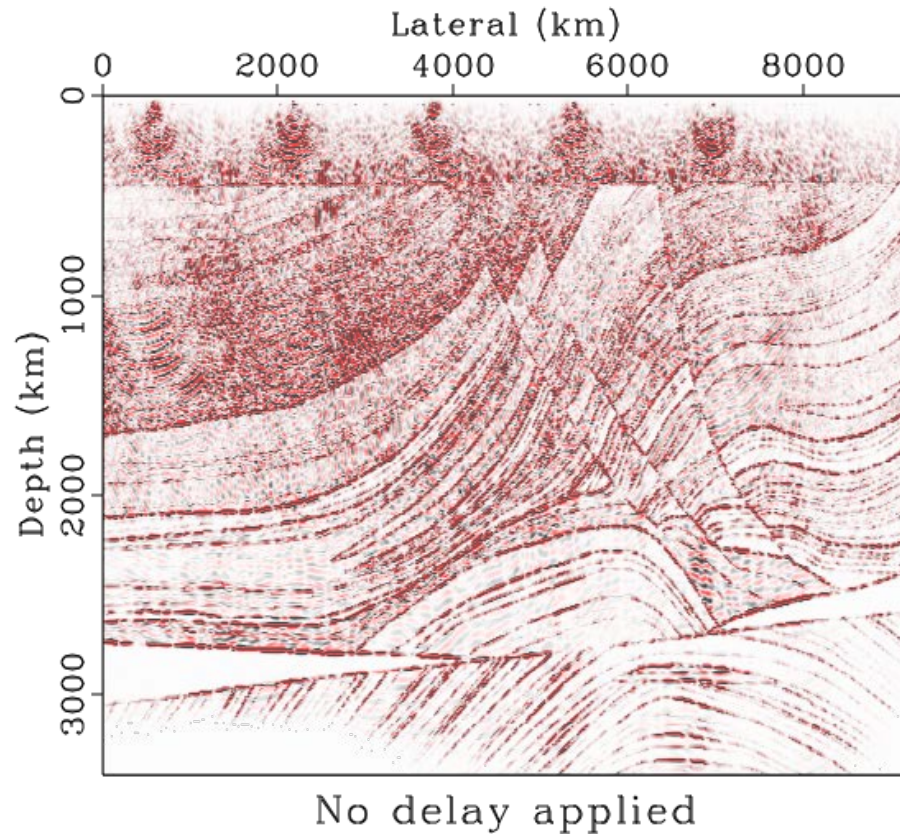




Dithering in receiver domain RTM

Time delay to insert source in forward wavefield: No

Time delay to insert data in backward wavefield: No

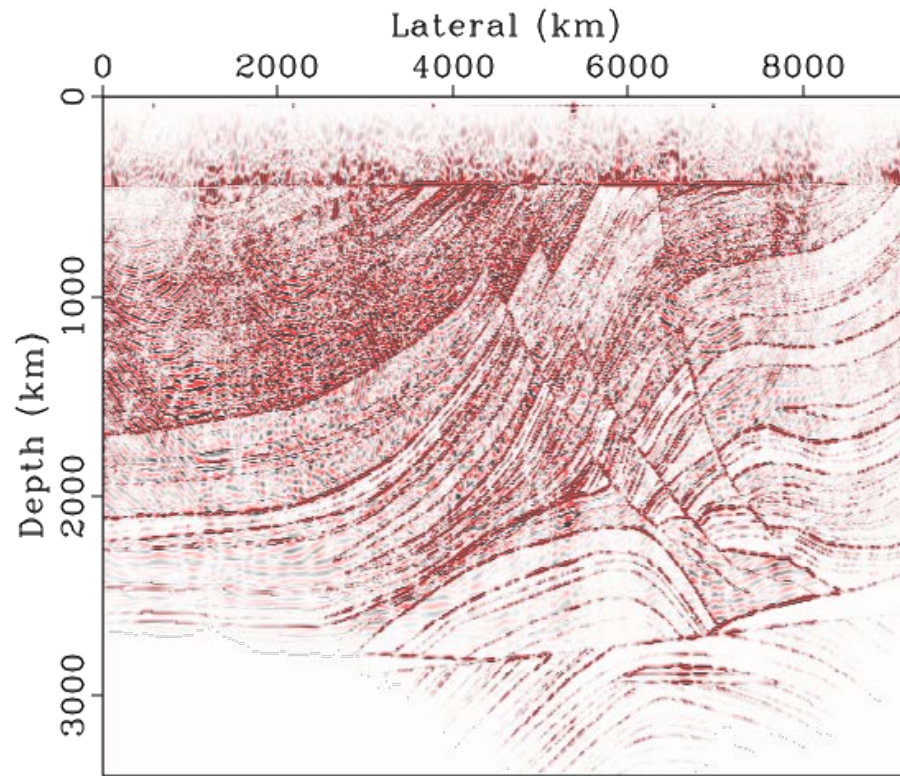




Dithering in receiver domain RTM

Time delay to insert source in forward wavefield: Yes

Time delay to insert data in backward wavefield: Yes



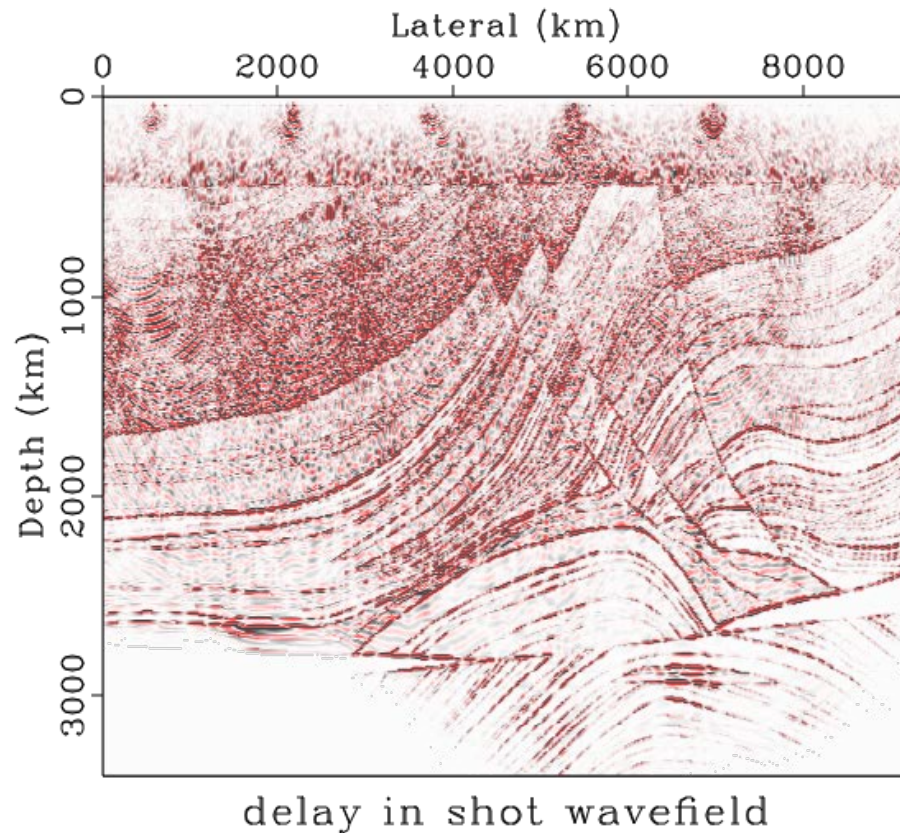
delay in shot and rcvr wavefield



Dithering in receiver domain RTM

Time delay to insert source in forward wavefield: Yes

Time delay to insert data in backward wavefield: No





Receiver domain RTM saves computation for OBN.

Blended acquisition saves acquisition time and cost.

RTM attenuates incoherent shots

Dithering in blended receiver domain RTM is effective in deblending



Apply LS in Blended RTM in receiver domain

Connection between dithering and datum

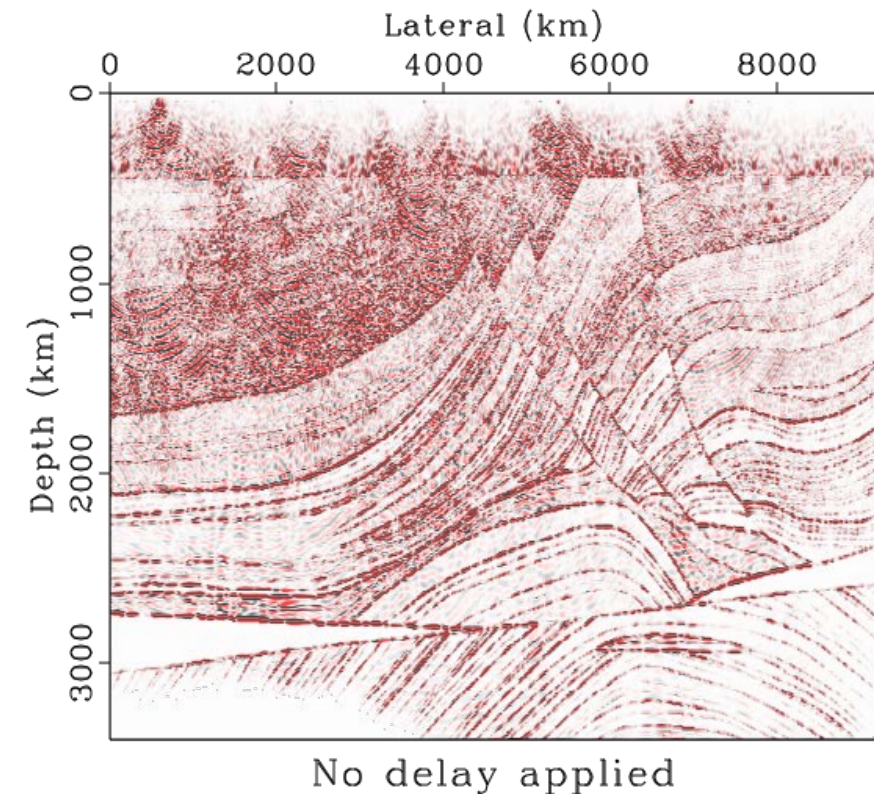
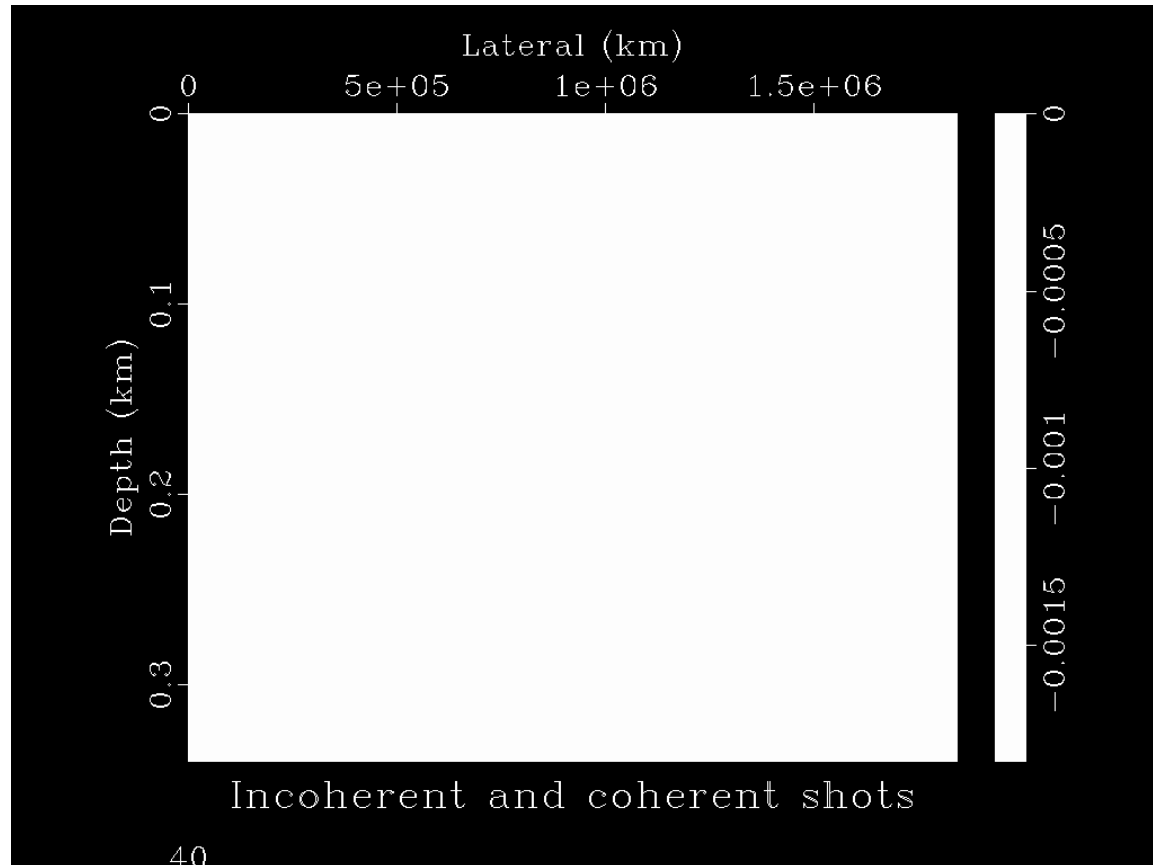
Deblending RTM in Common Receiver Gather utilizing dithering

->Deblending RTM in Common Offset Gather

->Deblending RTM in Common Angle Gather



In blended receiver domain RTM, apply multiple sources in the forward wavefield.





Questions?