



Constraining model parameters in full waveform inversion

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Full waveform inversion

- FWI: match data by minimizing ϕ with respect to m
- Use first and second derivatives of ϕ to find a descent direction d
- Calculate step-length α which minimizes ϕ in that direction

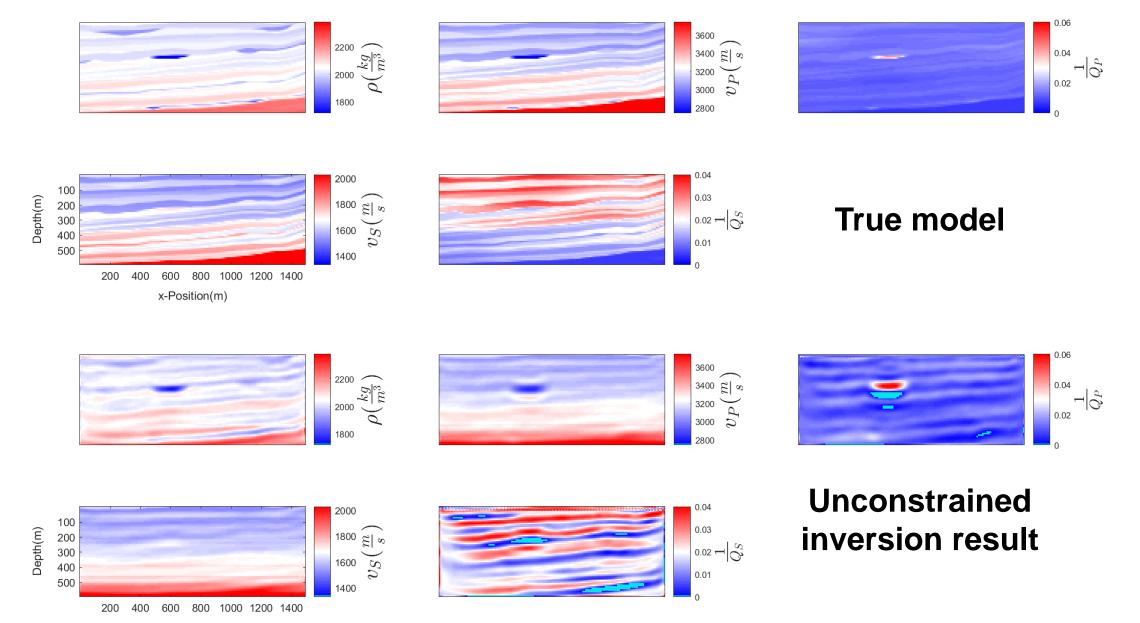
$$m_{k+1} = m_k + \alpha d(\phi, m_k)$$



- Properties like Q, V_P and porosity have physical constraints
- A naïve inversion will not always satisfy these constraints

How can we make our inversion satisfy our constraints?

Unconstrained inversion



Strategies for constraining optimization

We consider five broad approaches to constraining the inversion:

- 1. Step-length restriction
- 2. Projection of updates / update directions
- 3. Variable transforms
- 4. Hard penalty terms
- 5. Soft penalty terms

$$m_{k+1} = m_k + \alpha d(\phi, m_k)$$

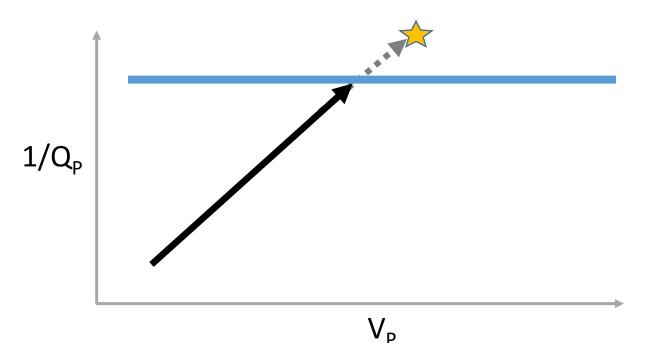
Cap step-lengths to prevent constraint violation

Advantages:

- Very simple to implement
- Exactly enforces constraint

Disadvantages:

• Often leads to cripplingly slow convergence or stalling



$$m_{k+1} = m_k + \frac{\alpha}{\alpha}d(\phi, m_k)$$

6

Cap step-lengths to prevent constraint violation

Advantages:

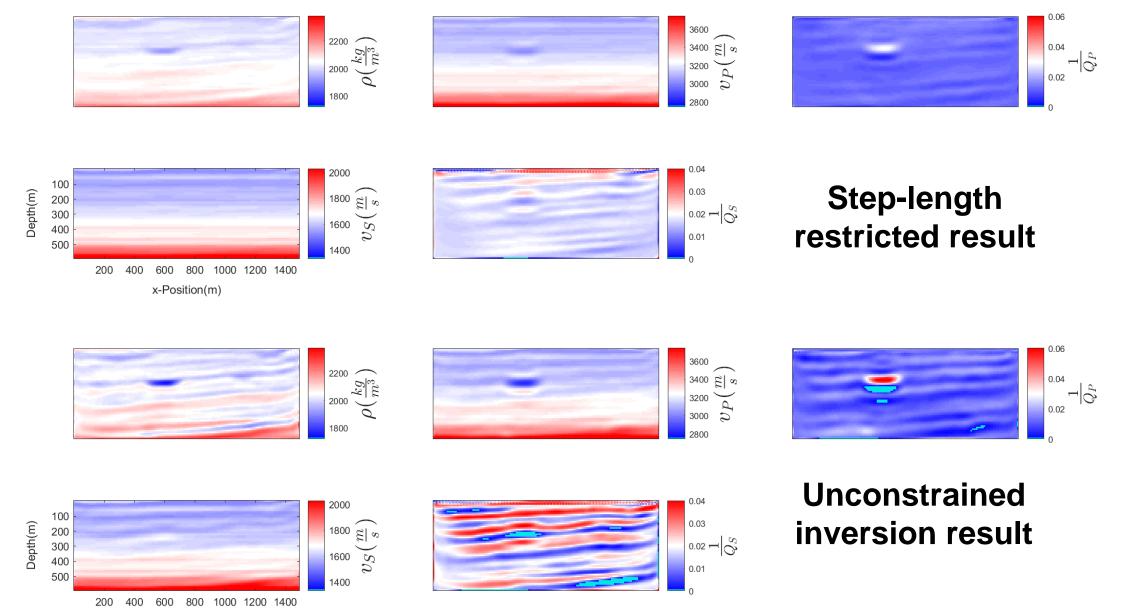
- Very simple to implement
- Exactly enforces constraint

 V_{P}

Disadvantages:

• Often leads to cripplingly slow convergence or stalling

Step-length restriction



x-Position(m)

Projection of updates

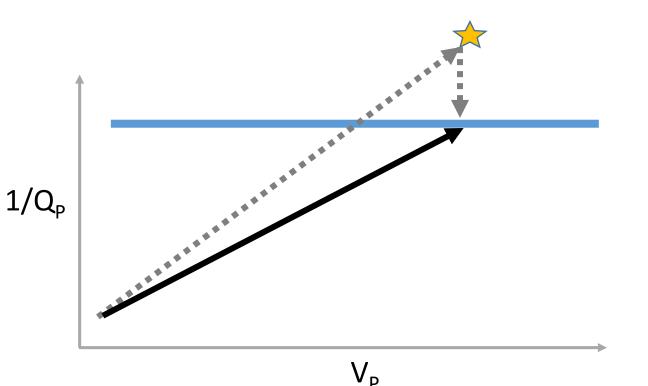
Line-search past constraint, project back to allowed region

Advantages:

- Very simple to implement
- Exactly enforces constraint
- Avoids very small or zero length steps

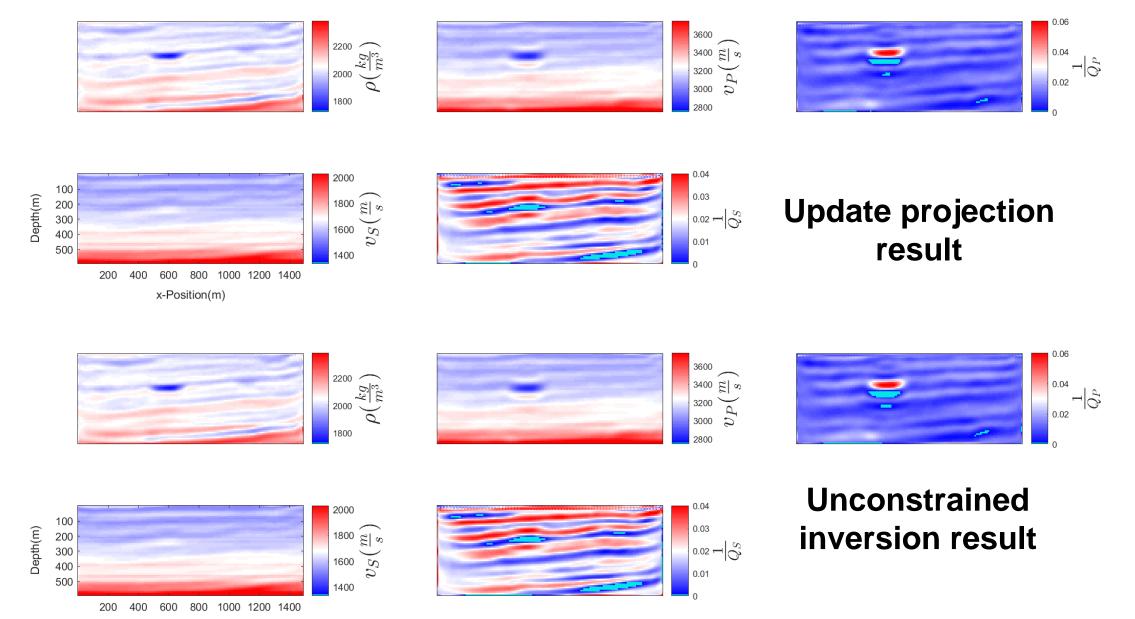


- Doesn't always decrease objective function
- Blind to barrier



$$m_{k+1} = m_k + \alpha d(\phi, m_k)$$

Projection of updates



x-Position(m)



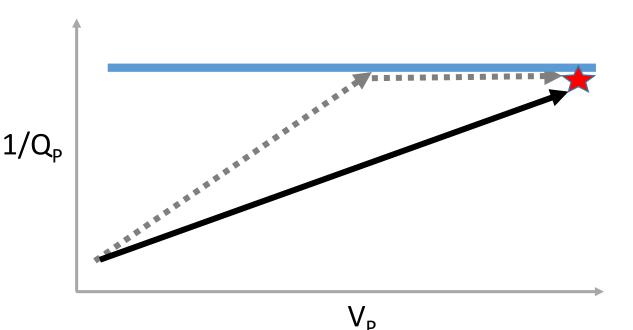
Project search direction onto constraints reached

Advantages:

- Exactly enforces constraint
- Avoids very small or zero length steps
- Only considers valid models in linesearch

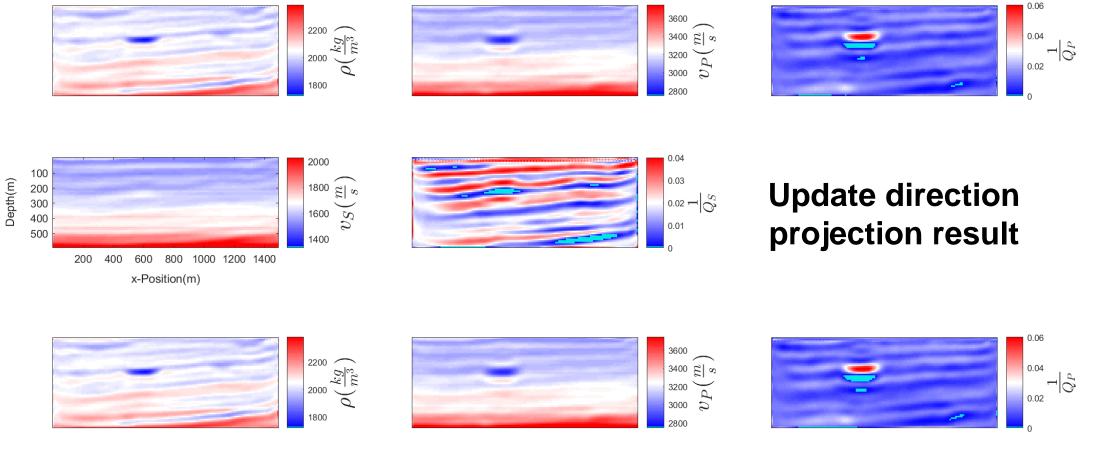
Disadvantages:

- Hugs, but ignores, the boundary
- Makes second-derivative information misleading



$$m_{k+1} = m_k + \alpha d(\phi, m_k)$$

Projection of update directions

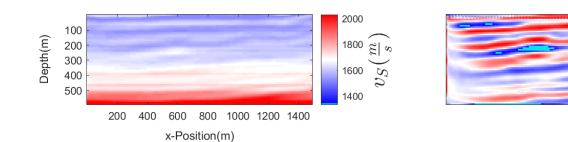


0.04

0.03

0.01

0.02 - O





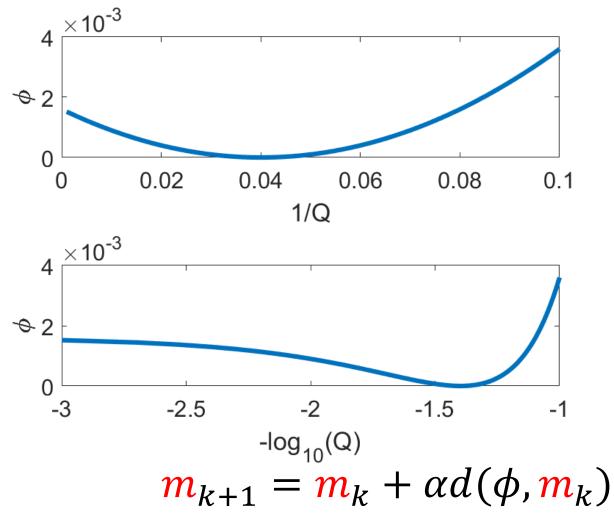
Choose variables which cannot violate constraints

Advantages:

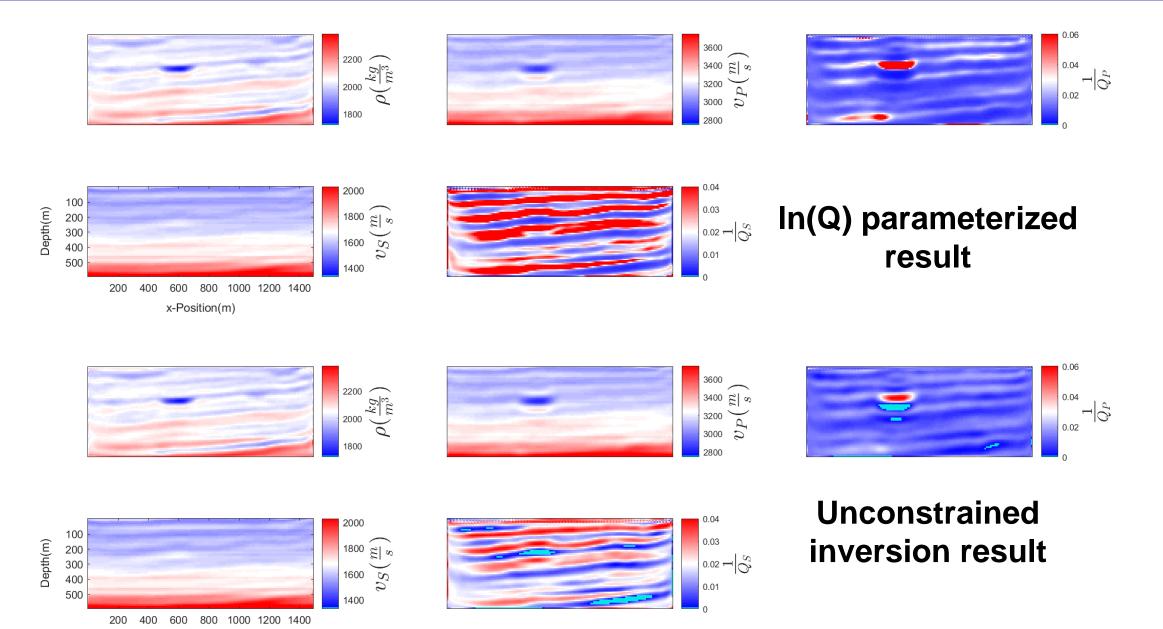
- Exactly enforces constraint
- Optimization approach can recognize constraint

Disadvantages:

• If original problem was close to linear, transformed version will be very nonlinear



Variable transformations



x-Position(m)



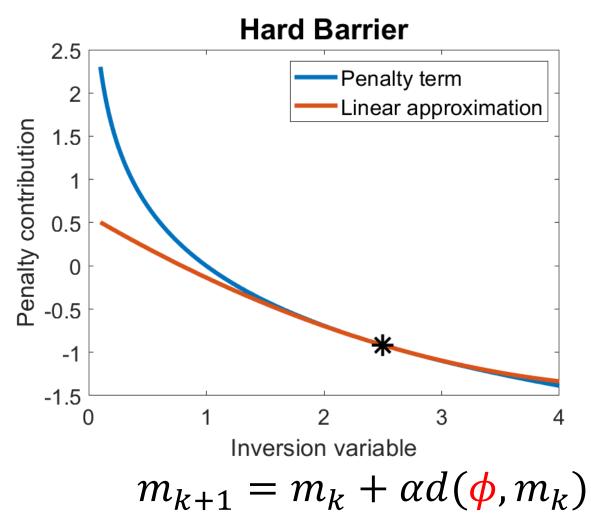
Infinite penalty at constraint

Advantages:

- Exactly enforces constraint
- Optimization approach can
 recognize constraint

Disadvantages:

 Barriers can be traps - easy to approach, difficult to get away from





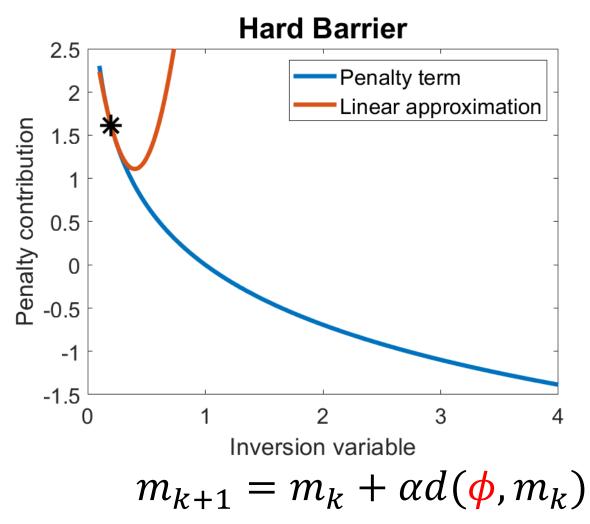
Infinite penalty at constraint

Advantages:

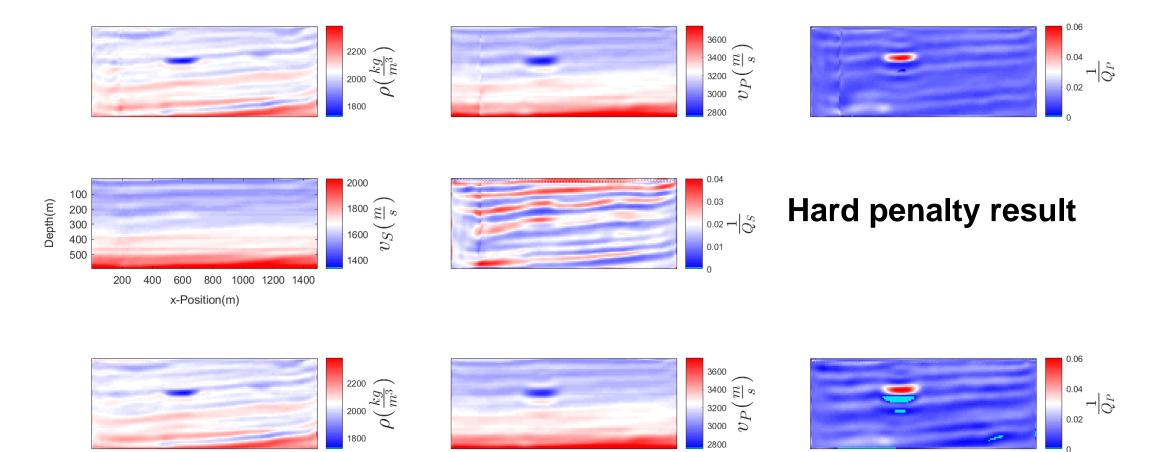
- Exactly enforces constraint
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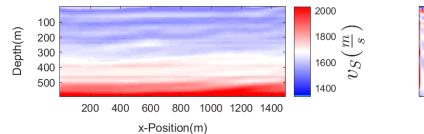
Disadvantages:

 Barriers can be traps - easy to approach, difficult to get away from



Hard penalty terms





Unconstrained inversion result



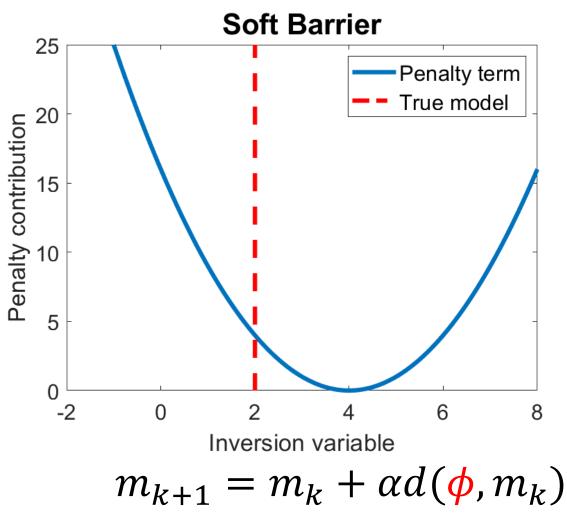
Finite linear penalty

Advantages:

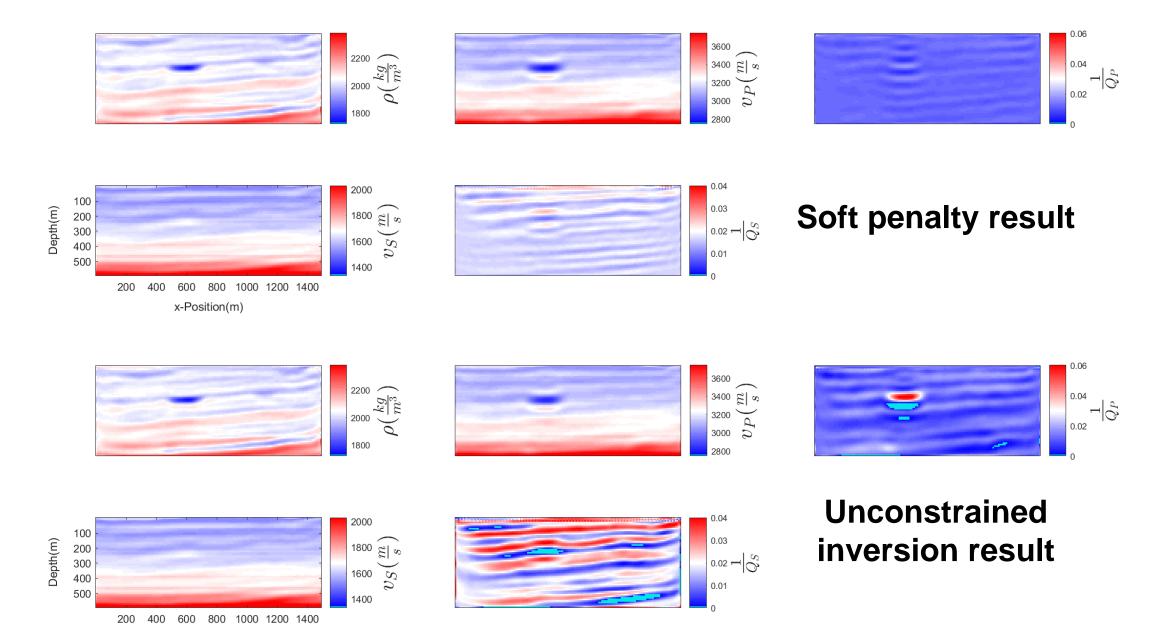
• Optimization approach anticipates penalty everywhere

Disadvantages:

- Doesn't exactly enforce constraint
- Linear penalty terms push strongly on models even far from constraint



Soft penalty terms



x-Position(m)

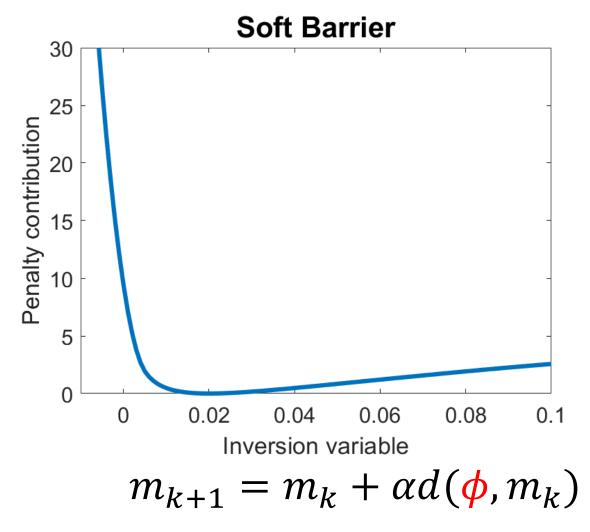
Linear-penalty to mild-penalty transition

Advantages:

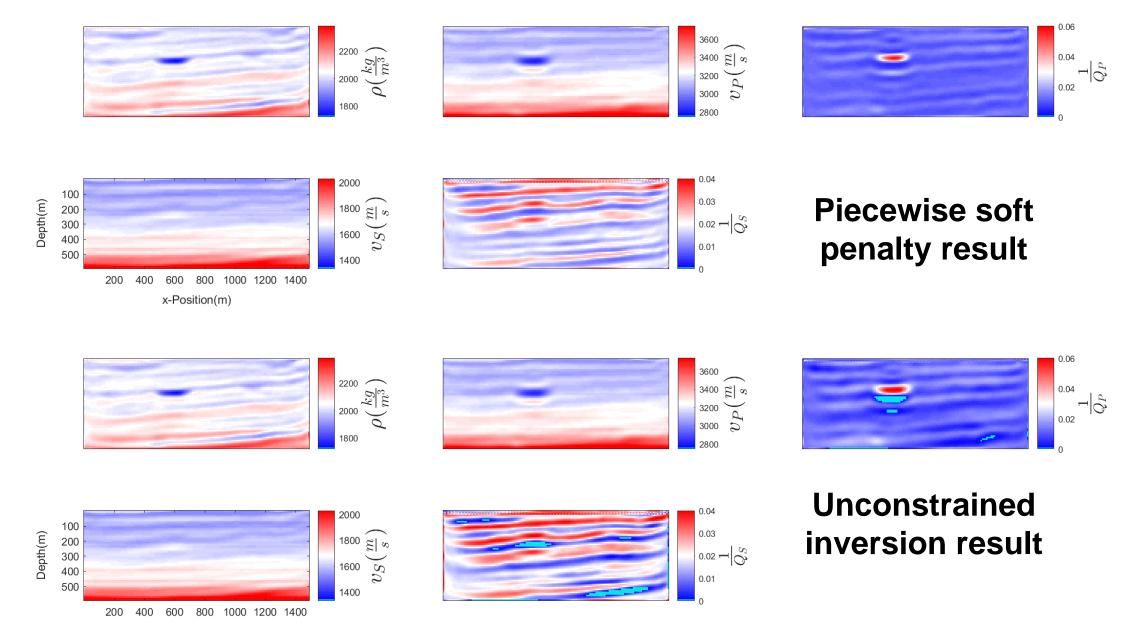
- Anticipates penalty close to constraint
- Little to no forcing away from constraint

Disadvantages:

- Doesn't exactly enforce constraint
- Struggles to anticipate penalty away from constraint



Piecewise soft penalty terms



x-Position(m)



- There are many ways to impose constraints in the FWI problem
- Hard constraints introduce substantial nonlinearity, which is problematic from an optimization standpoint
- Soft penalty terms may be more effective in constraining the inversion
- Piecewise penalty terms can create escapable barriers without overly biasing results



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