Locating microseismic events and traveltime mapping using locally spherical wavefronts

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Traveltime grids



Traveltimes on raypaths to grids

Well fraccing

CO₂ injection





The main point

- Given three receiver locations (2D)
- <u>Traveltimes</u> of an event at those receiver locations

- 1. Locate the source and time of the event
- 2. Compute another traveltime at a nearby location

• Later, four receivers for 3D

Vidale's method (still plane waves)

$$\left(\frac{dt}{dx}\right)^2 + \left(\frac{dt}{dx}\right)^2 = \frac{1}{v^2}$$

$$t_4 = t_1 + \sqrt{\frac{2h^2}{v^2} - (t_3 - t_2)^2}$$

$$(t_4 - t_1)^2 + (t_3 - t_2)^2 = \frac{2h^2}{v^2}$$



Fast, OK accuracy, industry standard

Curved wavefront assumption

- 1. Locally constant velocity
- 2. Estimate center of curvature
- 3. Apparent source location (x_0, z_0)
- 4. Source time t_0
- 5. From apparent source
 - get time t₄



Difference between traveltimes $(t_2 - t_1)$ and $(t_3 - t_1)$



Loran C navigation system

Error in estimating t₄



Vidale's solution

Iterative solution

Location of source (x) and recording points (+)















1. This circle is tangent to the other three circles.

- 2. Its center is the source location (x_0, z_0) .
- 3. Its radius is vt₀



Our problem now becomes one of finding this circle that is tangent to three other circles.

Go to the internet and look up...

- A circle tangent to three other circles
- 1,610,000 responses



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Apollonius 262 BC to 190 BC

The Great Geometer

Introduced terms: parabola ellipse hyperbola



Wolfram MathW@rld

the web's most extensive mathematics resource

The three-circle problem was solved by Viète (Boyer 1968), and the solutions are called Apollonius circles. There are eight total solutions. The simplest solution is obtained by solving the three simultaneous quadratic equations

$$(x - x_1)^2 + (y - y_1)^2 - (r \pm r_1)^2 = 0$$
⁽¹⁾

$$(x - x_2)^2 + (y - y_2)^2 - (r \pm r_2)^2 = 0$$
(2)

$$(x - x_3)^2 + (y - y_3)^2 - (r \pm r_3)^2 = 0$$
(3)

in the three unknowns x, y, r for the eight triplets of signs (Courant and Robbins 1996). Expanding the equations gives

$$(x^{2} + y^{2} - r^{2}) - 2x x_{i} - 2y y_{i} \mp 2r r_{i} + (x_{i}^{2} + y_{i}^{2} - r_{i}^{2}) = 0$$
(4)

for i = 1, 2, 3. Since the first term is the same for each equation, taking (2) - (1) and (3) - (1) gives

$$\begin{array}{l} ax + b \ y + cr = d \\ a'x + b' \ v + c'r = d'. \end{array}$$
(5)

where

$$\alpha = 2(x_1 - x_2) \tag{7}$$

$$b = 2(y_1 - y_2)$$
 (8)

$$c = \pm 2(r_1 - r_2)$$
(9)

$$d = (x^2 + y^2 - r^2) - (x^2 + y^2 - r^2)$$
(10)

 $d = (x_1^2 + y_1^2 - r_1^2) - (x_2^2 + y_2^2 - r_2^2)$ (10)

and similarly for a', b', c' and d' (where the 2 subscripts are replaced by 3s). Solving these two simultaneous linear equations gives

$$b'd - bd' - b'cr + bc'r$$

$$x = \frac{ab' - ba'}{-a'd + ad' + a'cr - ac'r}$$
(11)

$$y = \frac{-a \, a + a \, c \, r - a \, c \, r}{a \, b' - a' \, b}, \tag{12}$$

which can then be plugged back into the quadratic equation (1) and solved using the quadratic formula.

It turns out...

• In general there are 8 possible solutions

• But <u>our case</u> is limited by the problem to only 2 solutions.



3D solution

- Use the identical form as for the 2D solution
- Requires <u>four</u> receivers and their clock times
- Find one sphere tangent to <u>four spheres</u>
- Only <u>two</u> solutions

Comments on the clock time

• The clock times can be very large relative to the Δ times. (Difference of large numbers)

- Subtract the minimum clock time from all other clock times:
 - simpler solutions
 - 2D: two circles and one point
 - 3D: three spheres and one point
 - $-t_0$ will be negative

Final words

- Receivers at <u>any location</u>
- <u>Circular</u> or spherical wavefronts
- Source time and location is computed
- Assumes <u>locally</u> constant velocities
- Many types of solutions for Apollonius' problem
- Illustrated with 2D data, solved for <u>3D data</u>
- Applications for:
 - Microseismic events, fraccing, CO2 sequestration
 - Monitoring of hazardous geological sites (Frank slide), volcanoes, ...
 - Computing gridded traveltimes
 - Converting ray traveltimes to gridded traveltimes

