

Reservoir simulations and feasibility study for seismic monitoring at CaMI.FRS

Marie Macquet and Donald C. Lawton



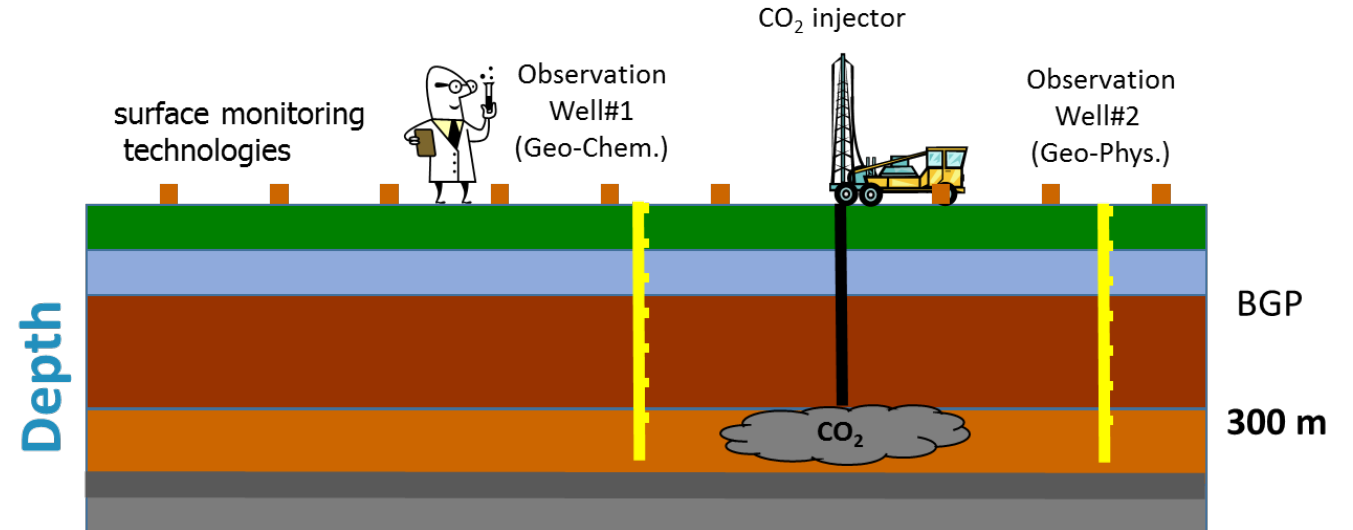
CREWES Annual Meeting, December 1st 2017, Banff, AB

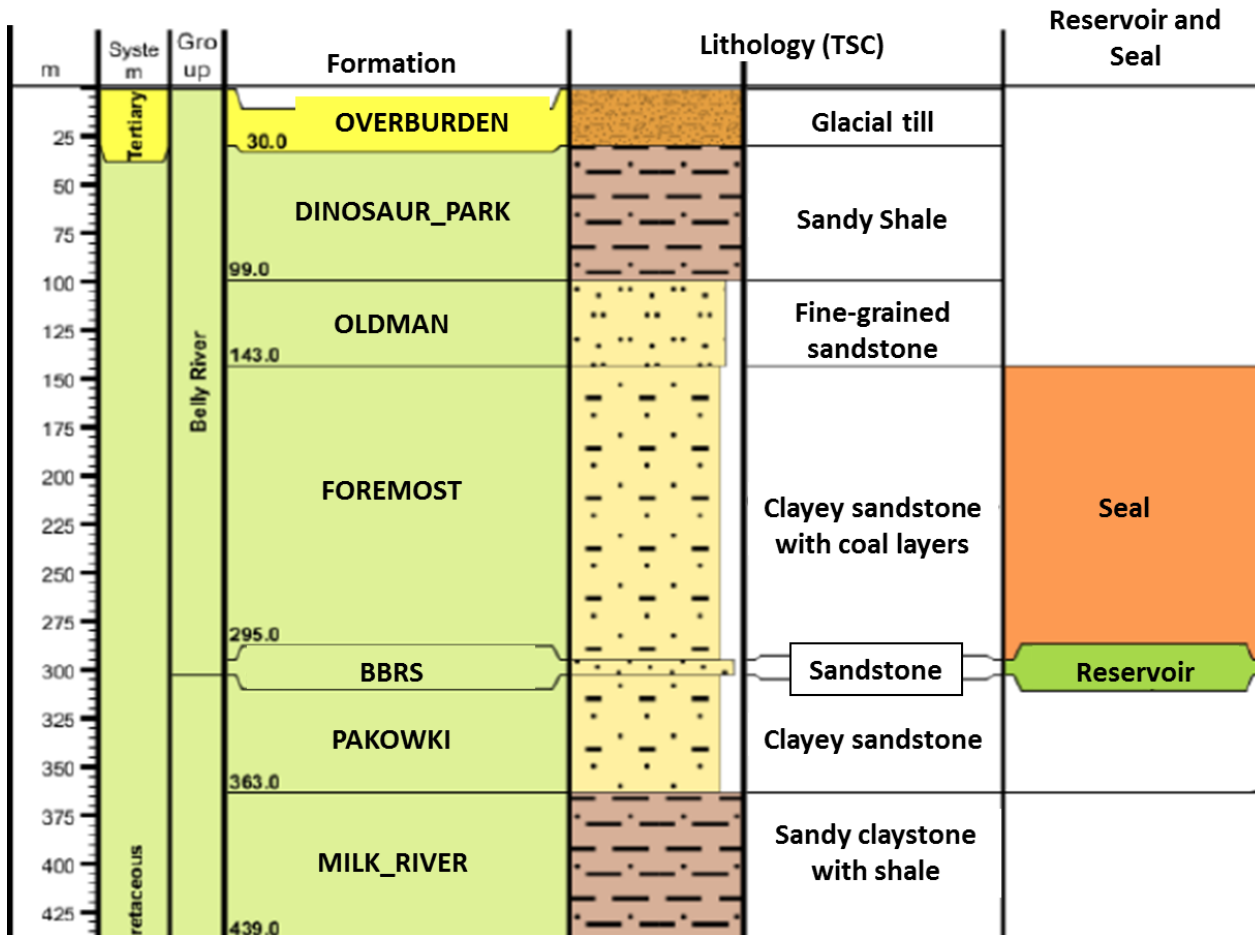


Purposes of CaMI.FRS :

- Develop improved monitoring technologies for early leakage detection ;
- Determine CO₂ detection thresholds.

=> Injection of a small amount of CO₂ (<1000/tons per year) at shallow depth (300m)





Reservoir target :

Basal Belly River Sandstone (BBRS) :

- 7m thickness (from 295 to 302m depth)
- Sandstone



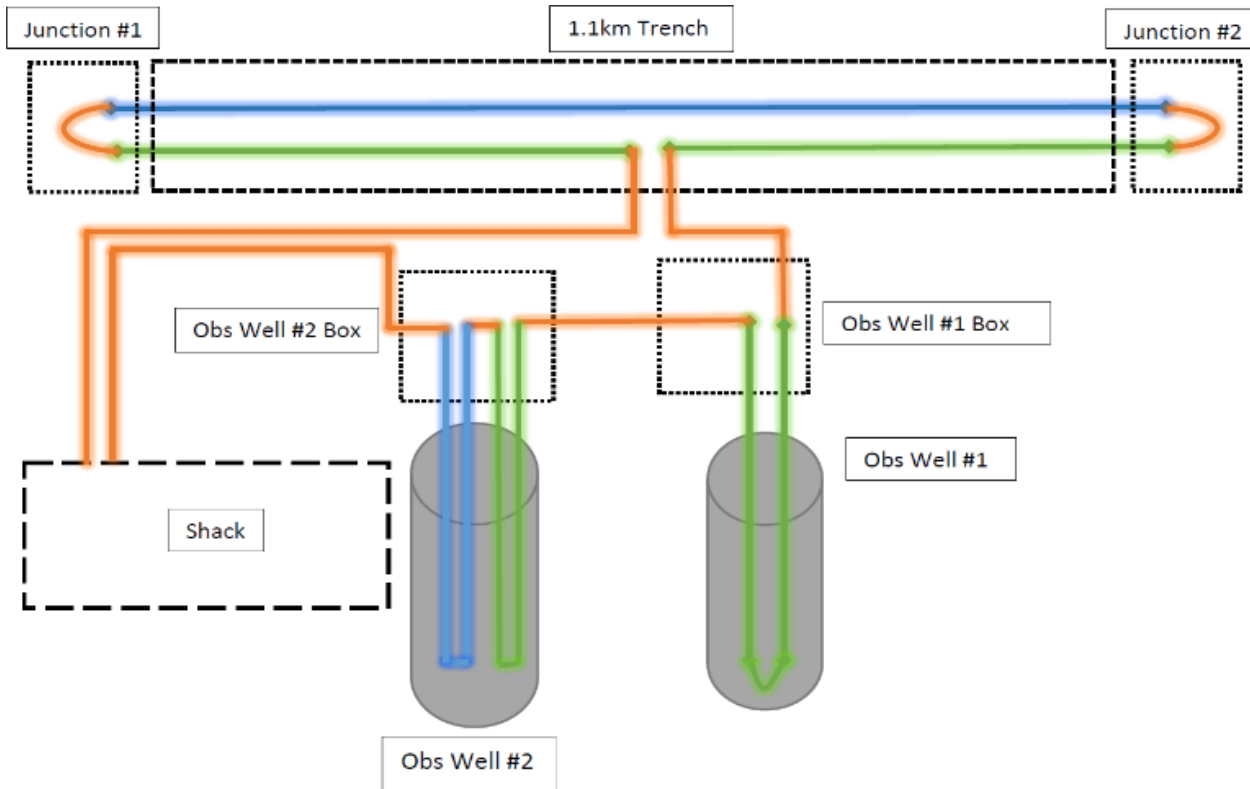
Seal :

Foremost formation

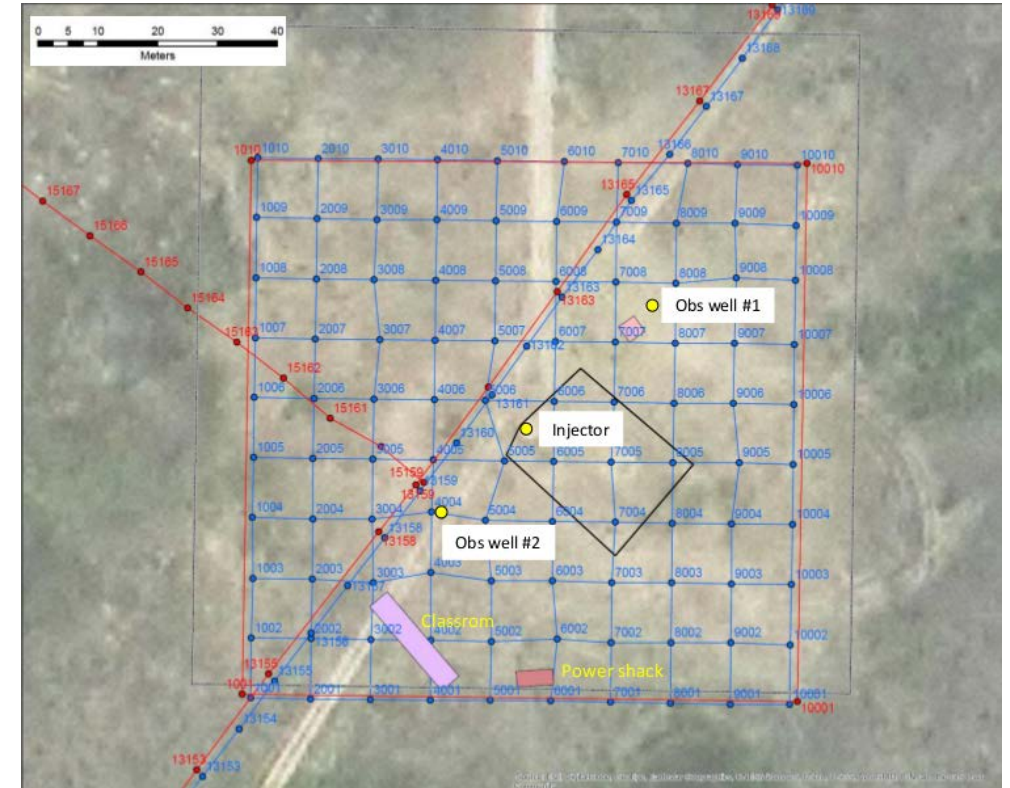
- 152m thickness (from 143 to 295m depth)
- Clayey sandstone with coal layers

CaMI.FRS – Geophysical installations

DAS (Harderman, Lawtown, Hall, Gordon presentations)



10x10 geophones array and continuous sources (Spackman presentation)



⇒ Feasibility study for seismic monitoring using surface seismic reflection

Feasibility study of seismic monitoring - Steps

1) Geomodelling

2) Fluid flow simulation

3) Fluid substitution

4) Seismic response simulation

HOW ?

Combining well logs
and 3D seismic,
interpolating

Running injection
simulations

Gassmann fluid substitution

3D final difference
modeling

WHY ?

To get 3D models of
the porosity
and permeability

To get CO₂ saturation and
the pressure response

To get 3D models of the
elastic parameters after
CO₂ injection

To see if we can detect
the CO₂ plume

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HOW ?

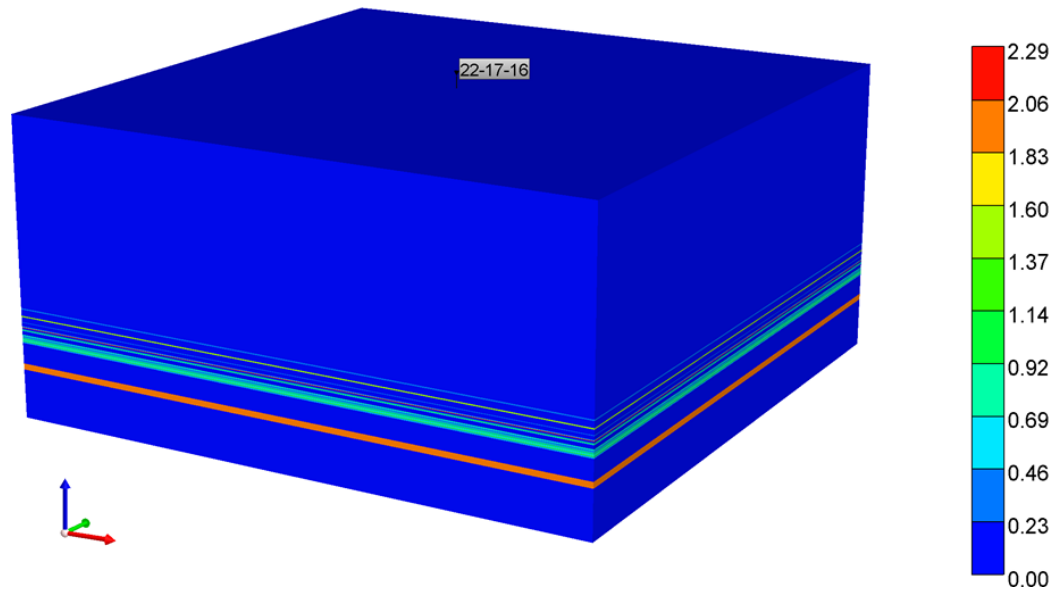
WHY ?

I - Geostatic models – J. Dongas and J. Barazza

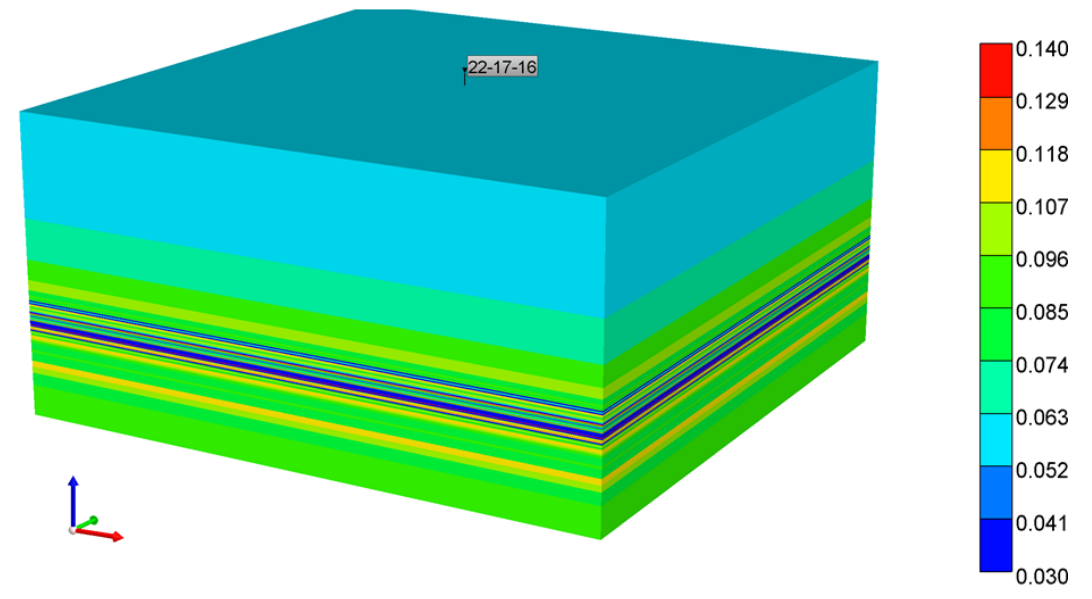
- Layer-cake model
- 1000m*1000m*250m
- built using wells logs and 3D seismic data

- $K_v/K_h = 0.1$
- Reservoir porosity ~ 0.1
- Reservoir permeability ~ 0.8 mD

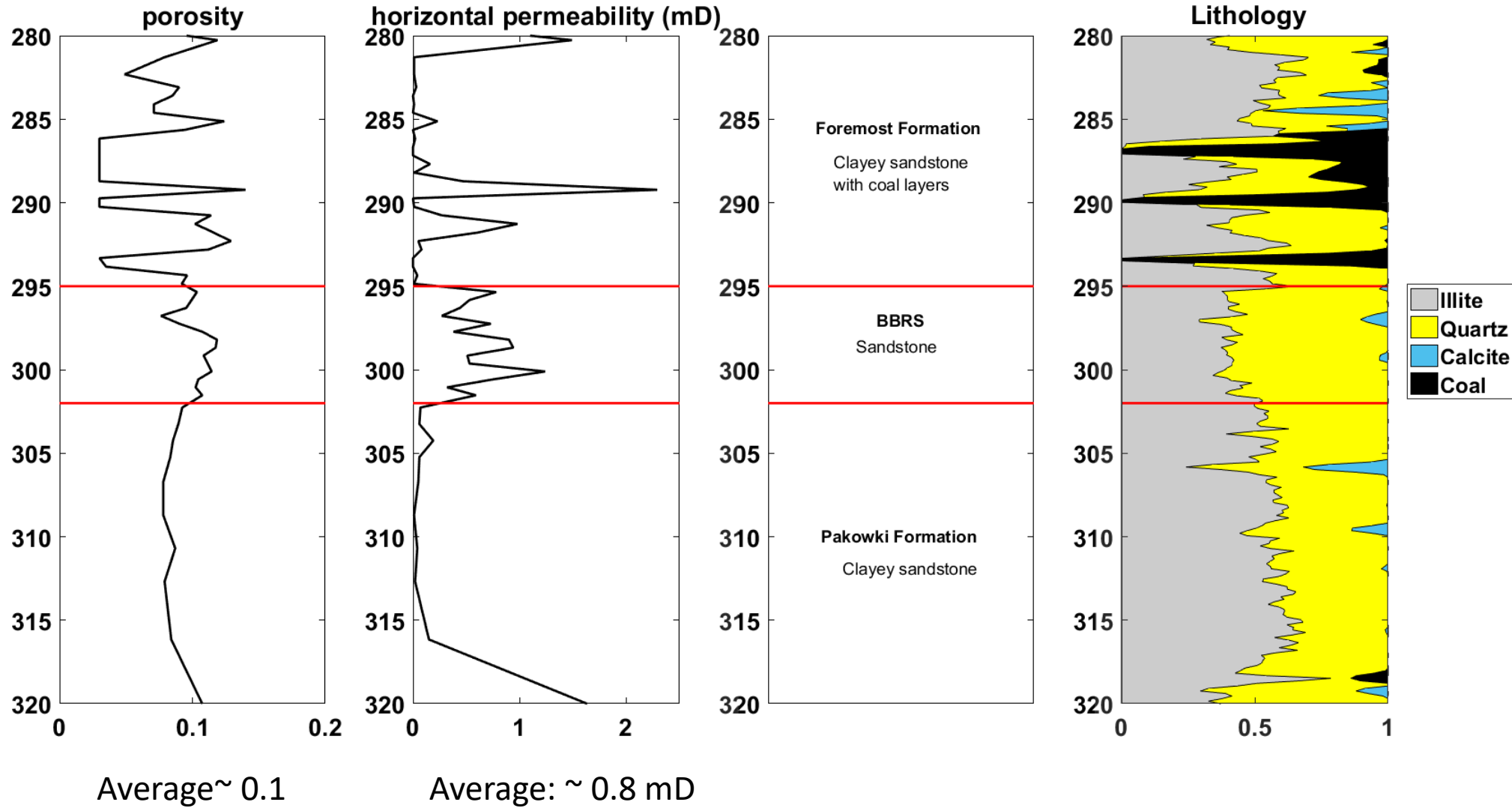
Permeability (mD)



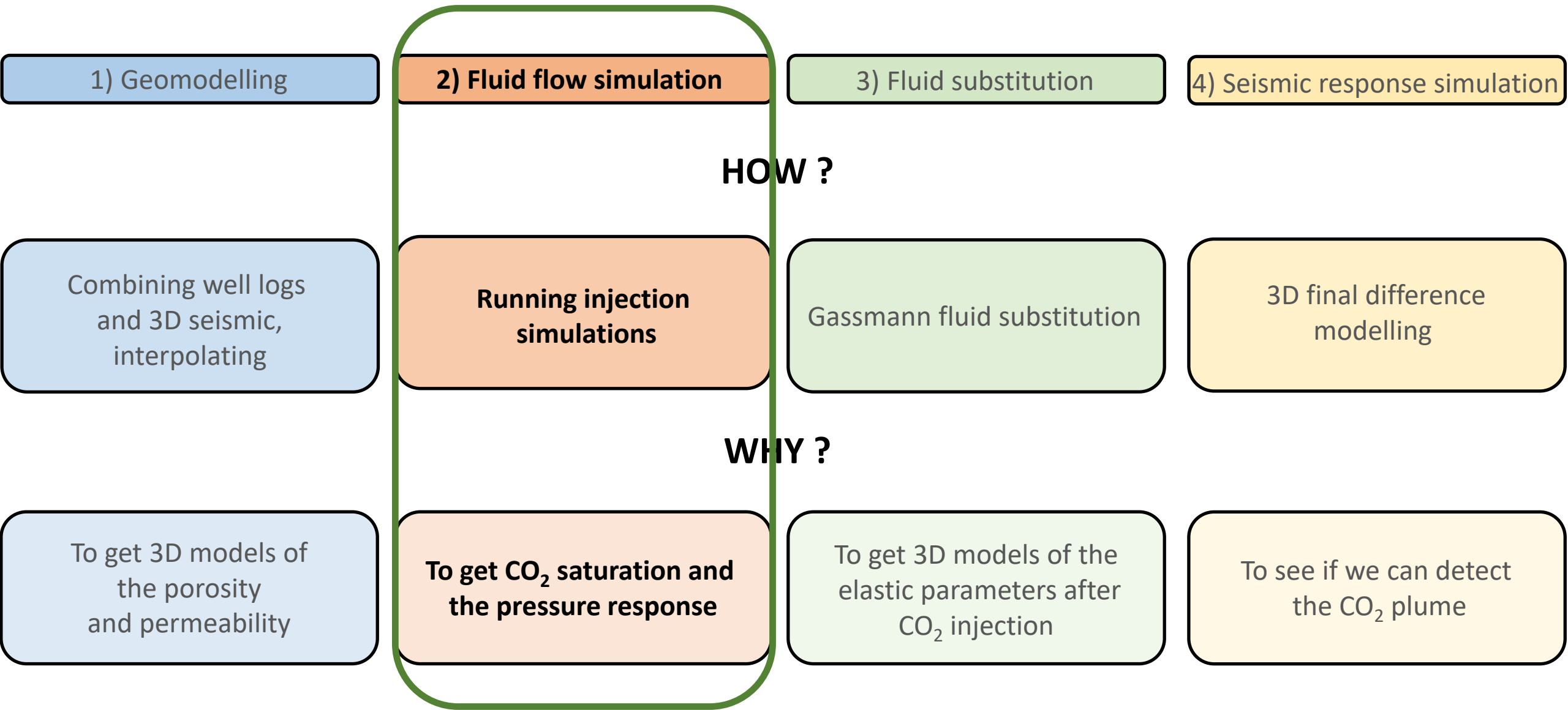
Porosity



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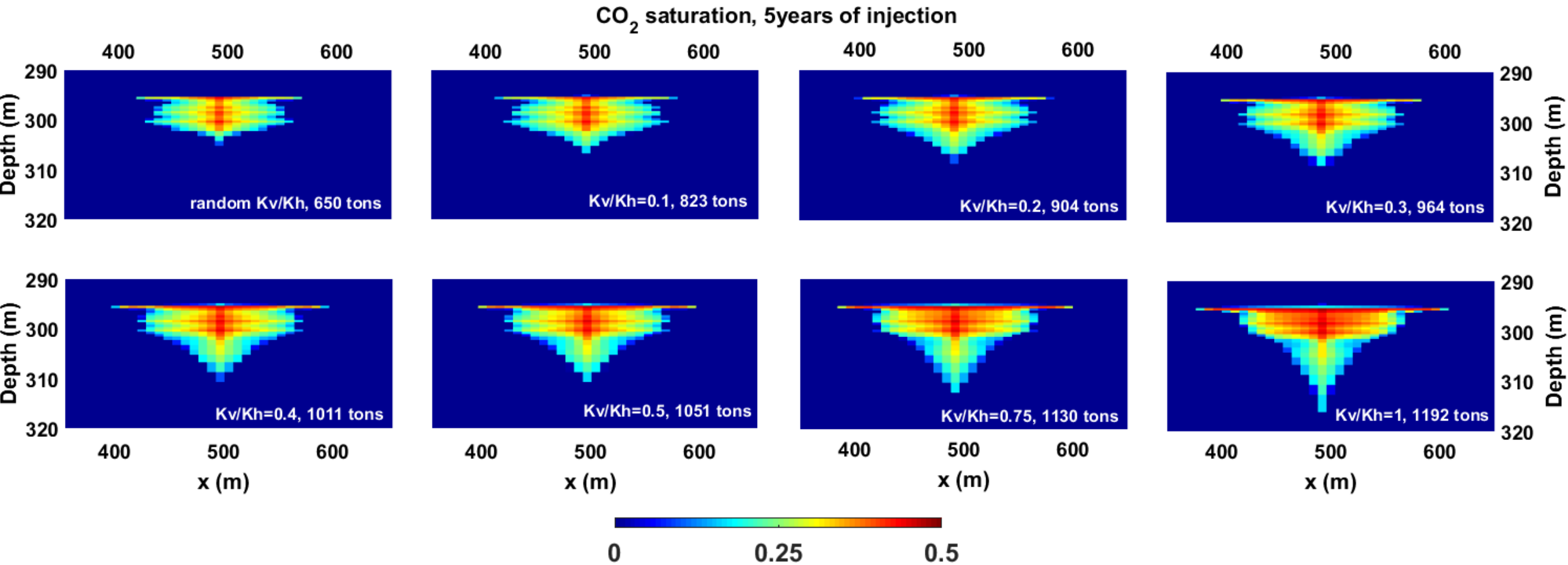


Feasibility study of seismic monitoring - Steps



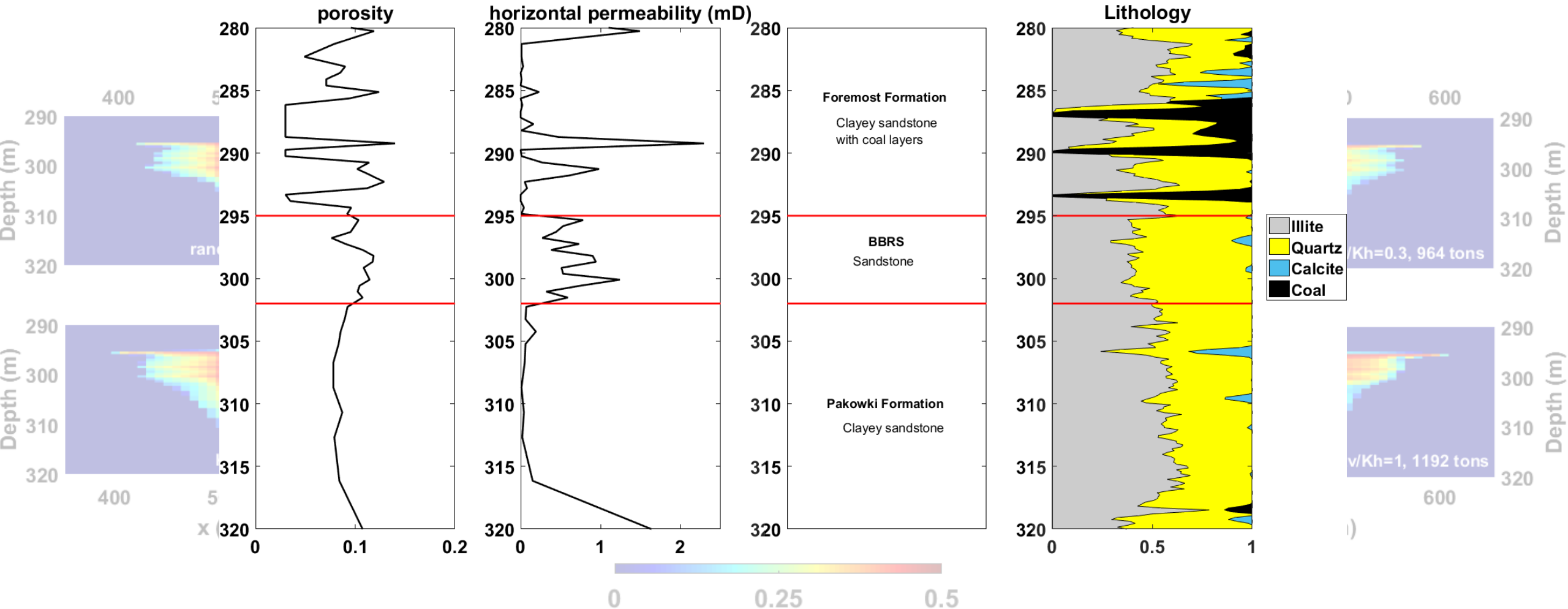
II - Injection simulations – Vertical permeability

Vertical permeability describes how the CO₂ can migrate vertically

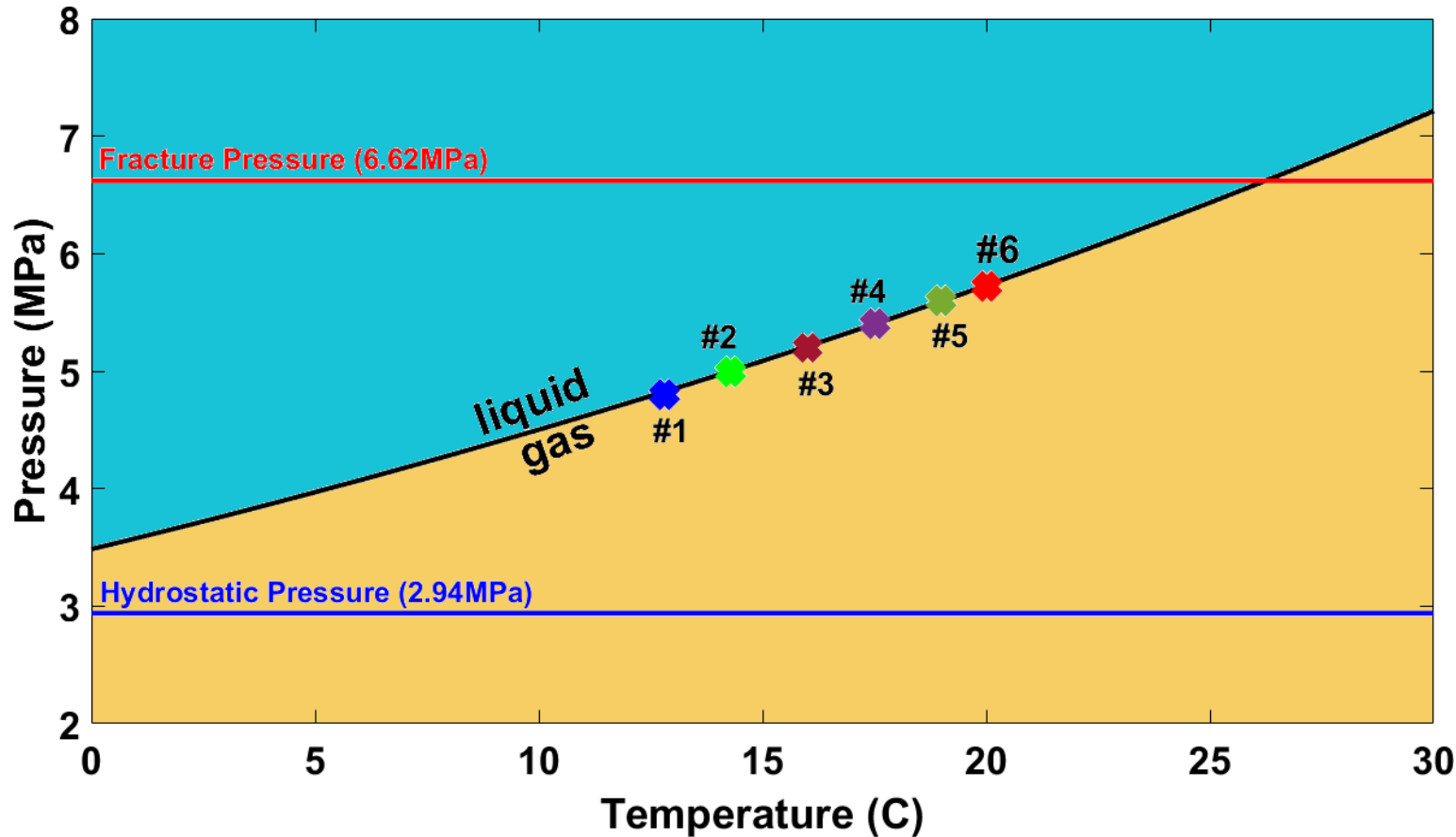


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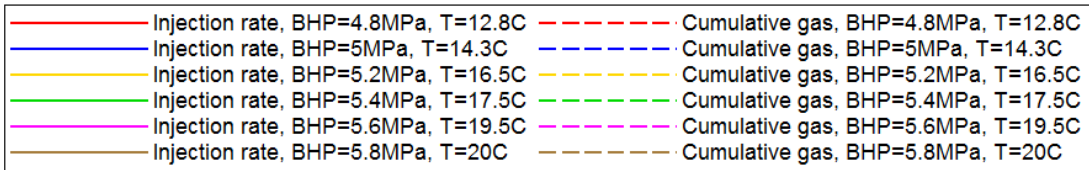
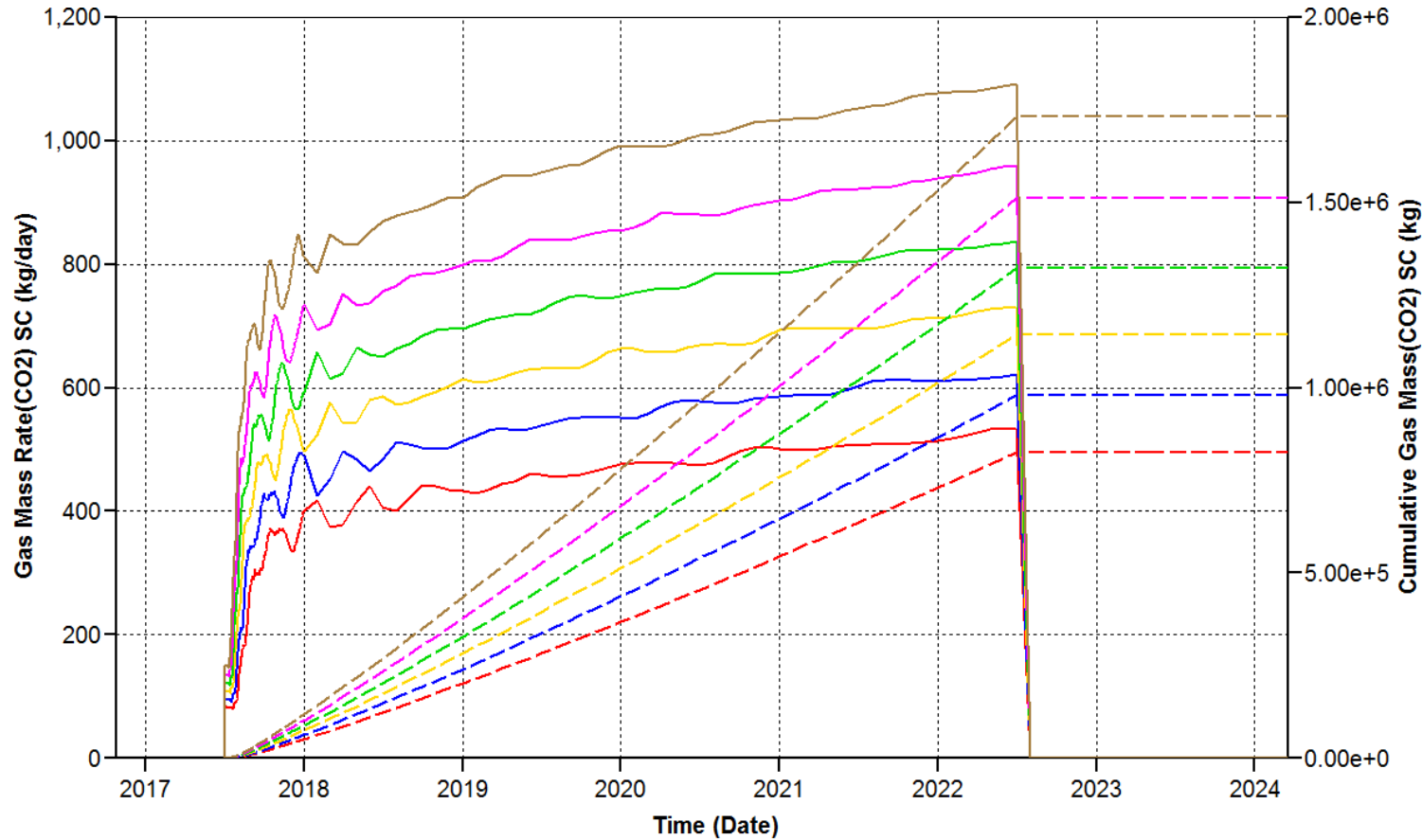
II - Injection simulations – Maximum Bottom-hole pressure



Constrains :

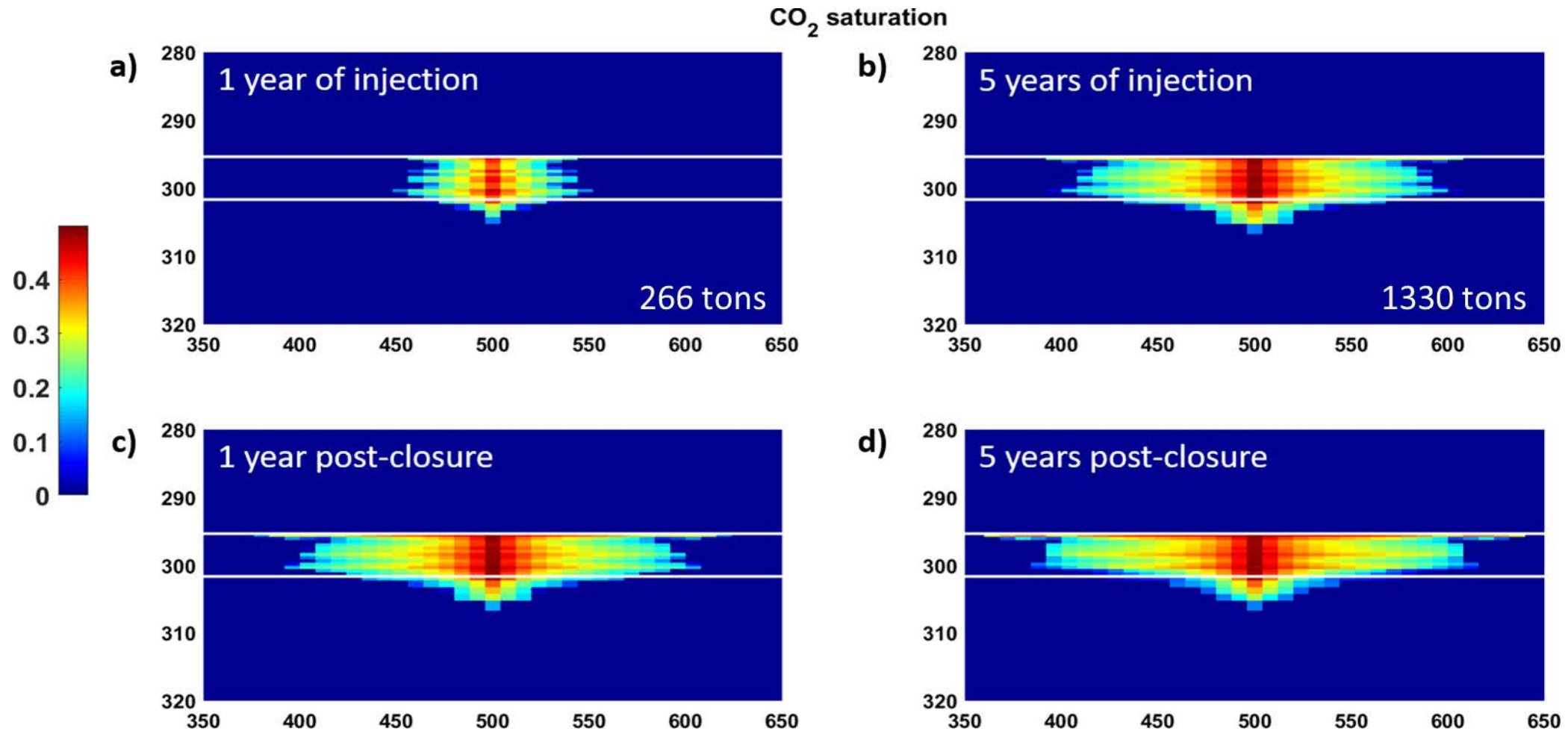
- (1) CO₂ in gaseous phase
- (2) Reservoir temperature = 12.8°C
- (3) Fracture pressure is 6.62 MPa

II - Injection simulations – Maximum Bottom-hole pressure



	Average rate (kg/day)	Total injected (tons)
4.8MPa	450	825
5.0MPa	535	980
5.2MPa	630	1145
5.4MPa	725	1320
5.6MPa	835	1520
5.8MPa	950	1730

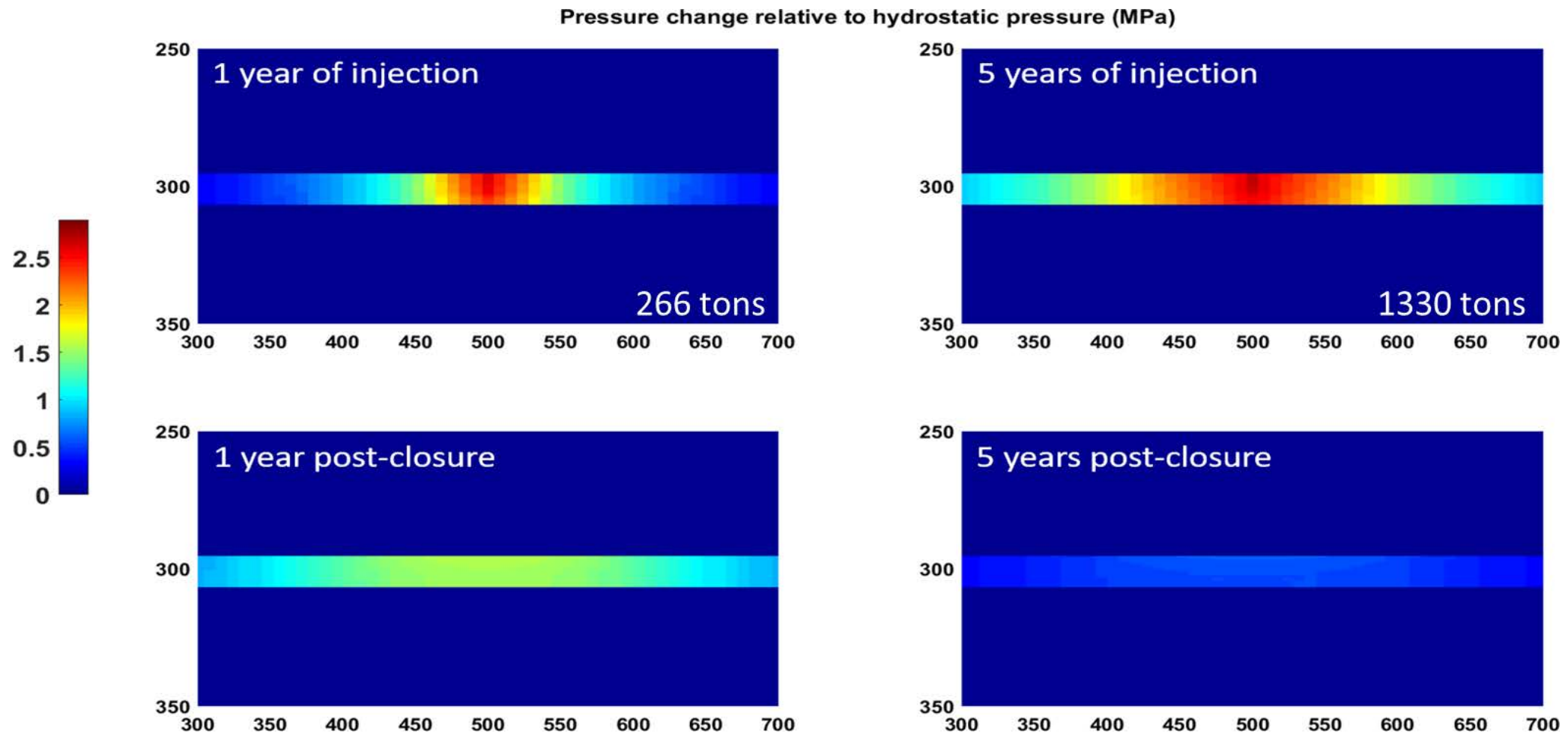
II - Injection simulation used – CO₂ saturation, BHP = 5.8MPa



Estimated irreducible water saturation = 0.5

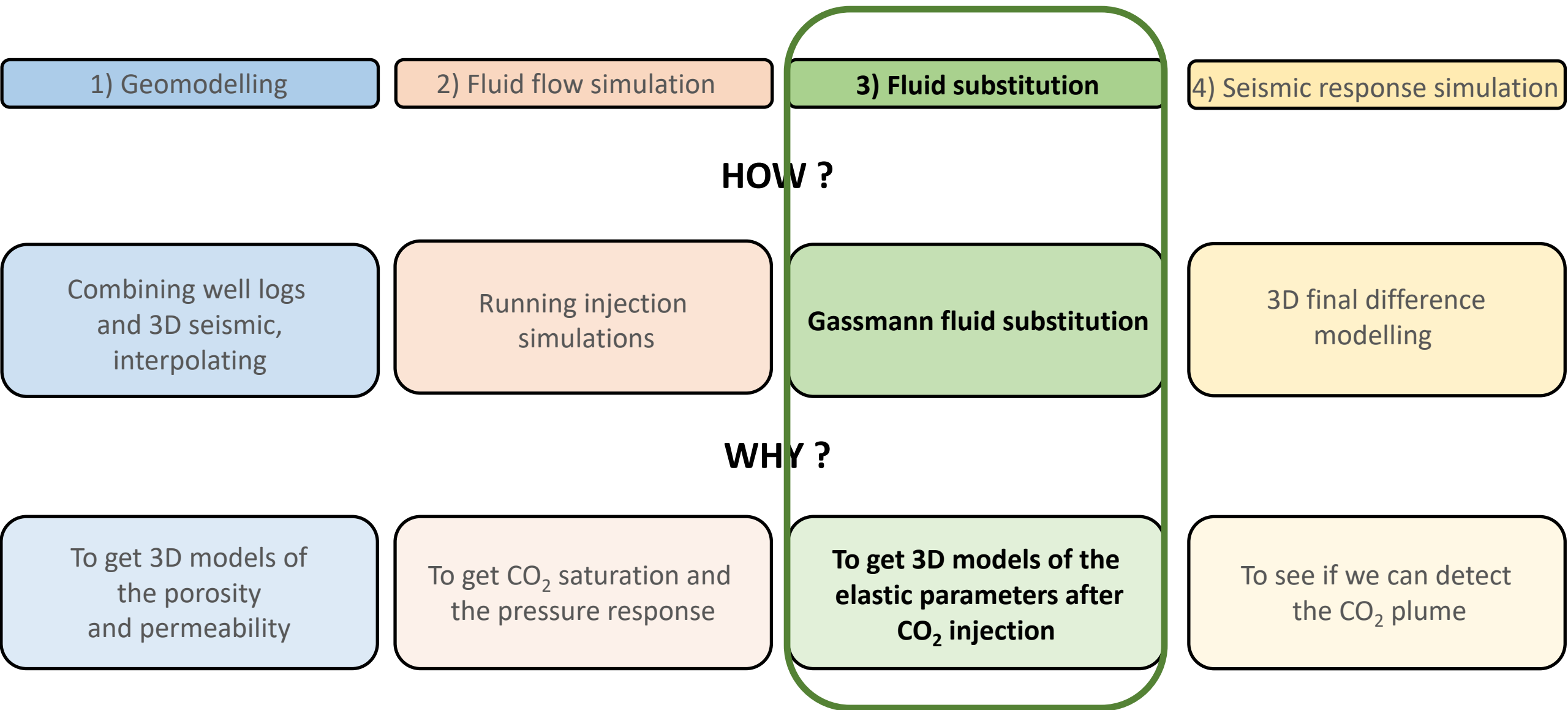
Gas and water permeability calculated using the Brooks-Corey model

II - Injection simulation used – Pressure



Hydrostatic pressure at 300m: 2.94MPa

Feasibility study of seismic monitoring - Steps



III - Fluid substitution – Modelling the elastic parameters variation

$$V_{P(new)} = \sqrt{\frac{K_{sat(new)} + \frac{4}{3} \mu_{sat}}{\rho(new)}}$$

Gassmann's equation links the bulk modulus of a rock to its pore, frame and fluid properties (Gassmann, 1951)

$$K_{sat} = K^* + \frac{[1 - \left(\frac{K^*}{K_0}\right)]^2}{\frac{\phi}{K_{fl}} + \frac{(1 - \phi)}{K_0} - \frac{K^*}{K_0^2}}$$

$$K_{sat(new)} = \frac{K_0}{\left[\frac{K_{sat(init)}}{K_0 - K_{sat(init)}} - \frac{K_{fluid(init)}}{\phi(K_0 - K_{fluid(init)})} + \frac{K_{fluid(new)}}{\phi(K_0 - K_{fluid(new)})} \right]^{-1} + 1}$$

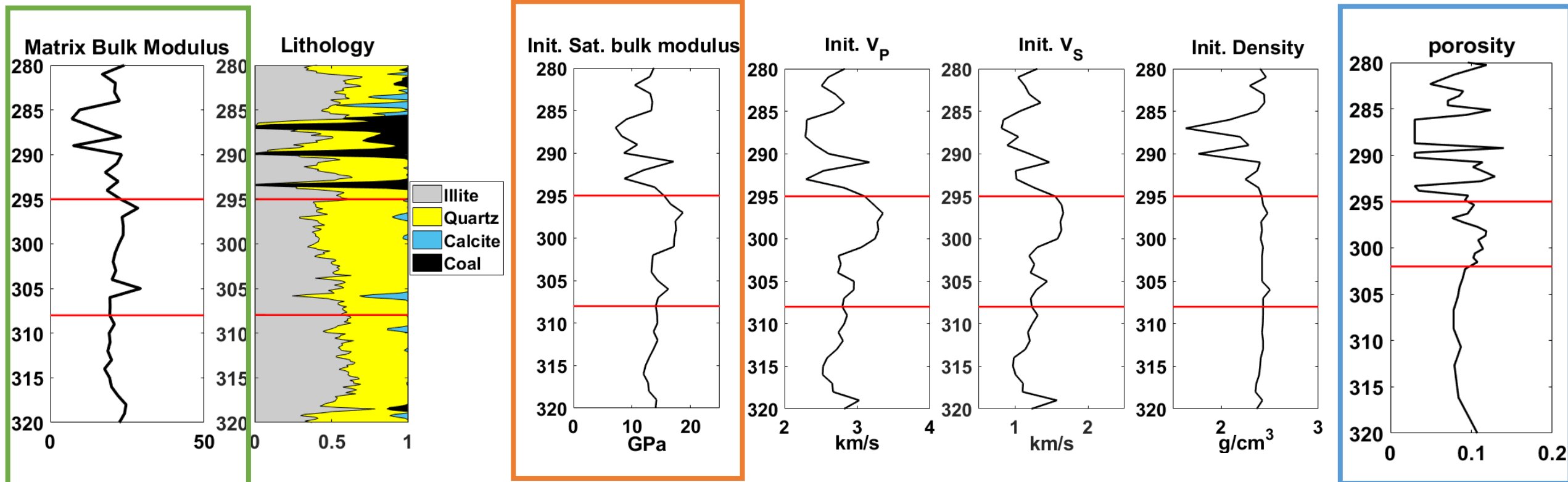
III - Fluid substitution – Input parameters

$$K_{sat(new)} = \frac{K_0}{\left[\frac{K_{sat(init)}}{K_0 - K_{sat(init)}} - \phi \frac{K_{fluid(init)}}{K_0 - K_{fluid(init)}} + \phi \frac{K_{fluid(new)}}{K_0 - K_{fluid(new)}} \right]^{-1} + 1}$$

K_0 is the matrix bulk modulus

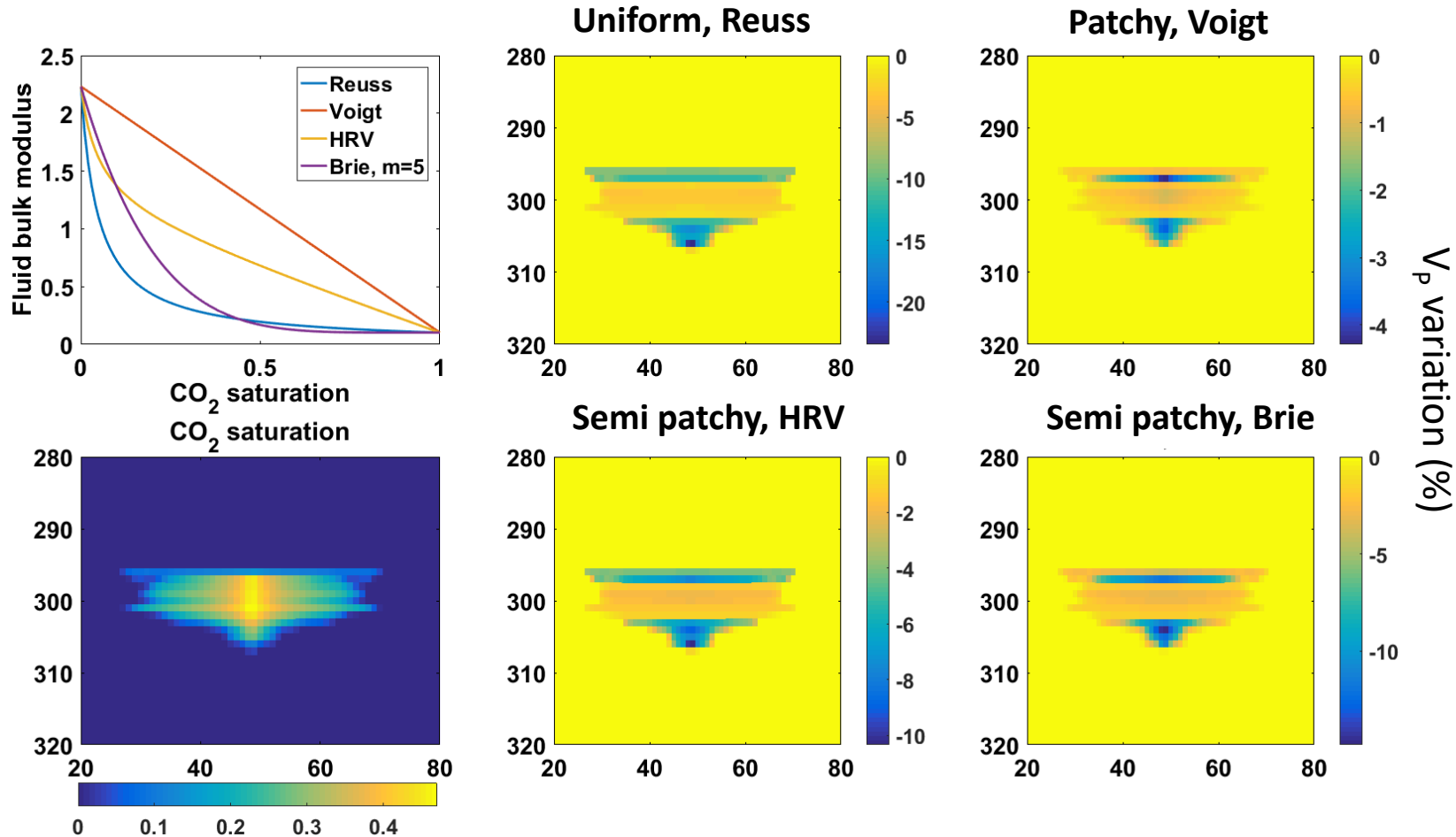
$K_{sat(init)}$ is the initial saturated bulk modulus

ϕ is the porosity



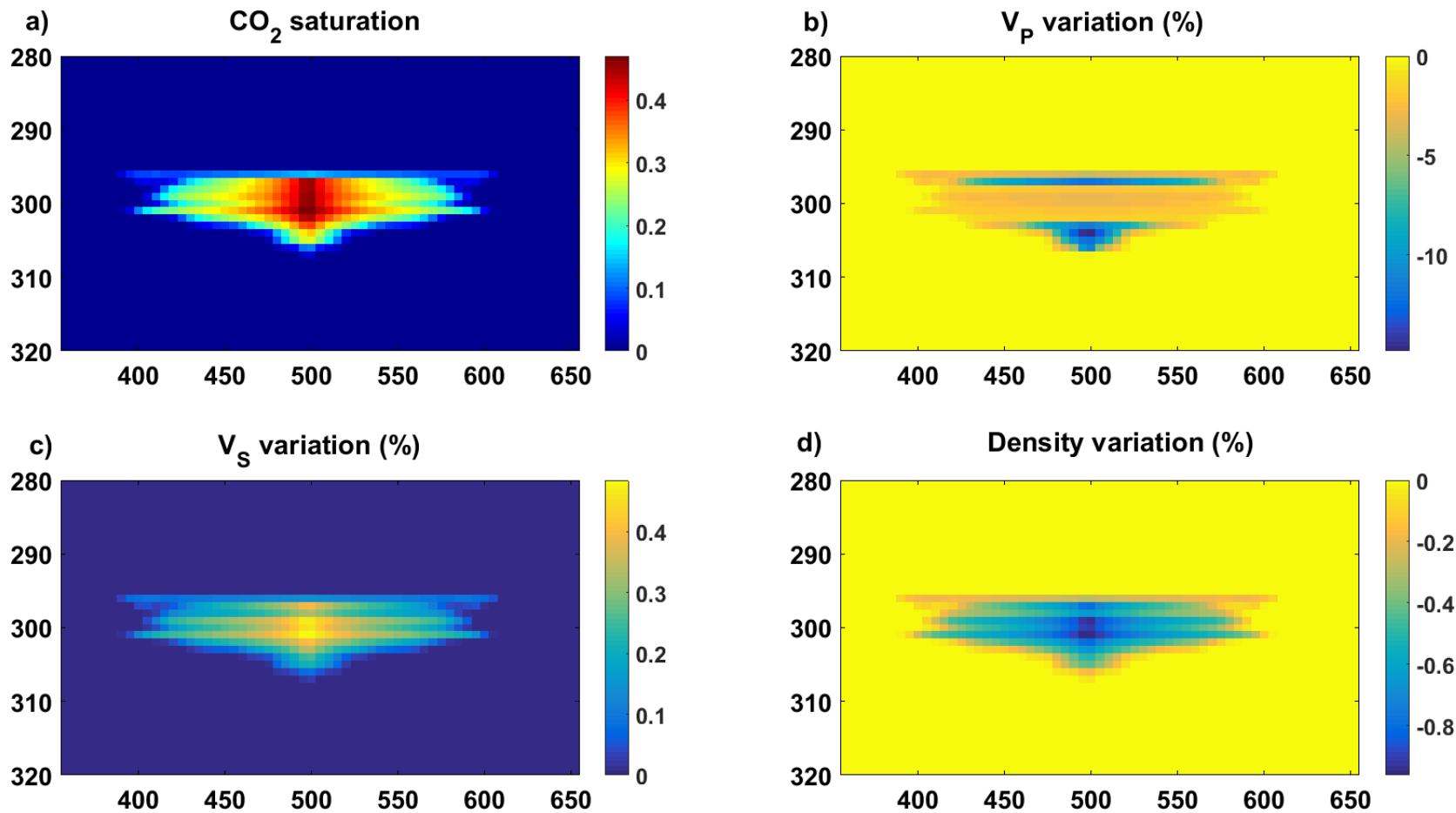
III - Fluid substitution – K_{fluid} - Which saturation behavior ?

$$K_{sat(new)} = \frac{K_0}{\left[\frac{K_{sat(init)}}{K_0 - K_{sat(init)}} - \frac{K_{fluid(init)}}{\phi(K_0 - K_{fluid(init)})} + \frac{K_{fluid(new)}}{\phi(K_0 - K_{fluid(new)})} \right]^{-1} + 1}$$



III - Fluid substitution – Final results

2D sections of elastic parameters variation, 5 years of injection



Average elastic parameters variation

	1 year of injection	5 years of injection
V_p	-1.82%	-2.42%
V_s	0.12%	0.15%
ρ	-0.23%	-0.3%

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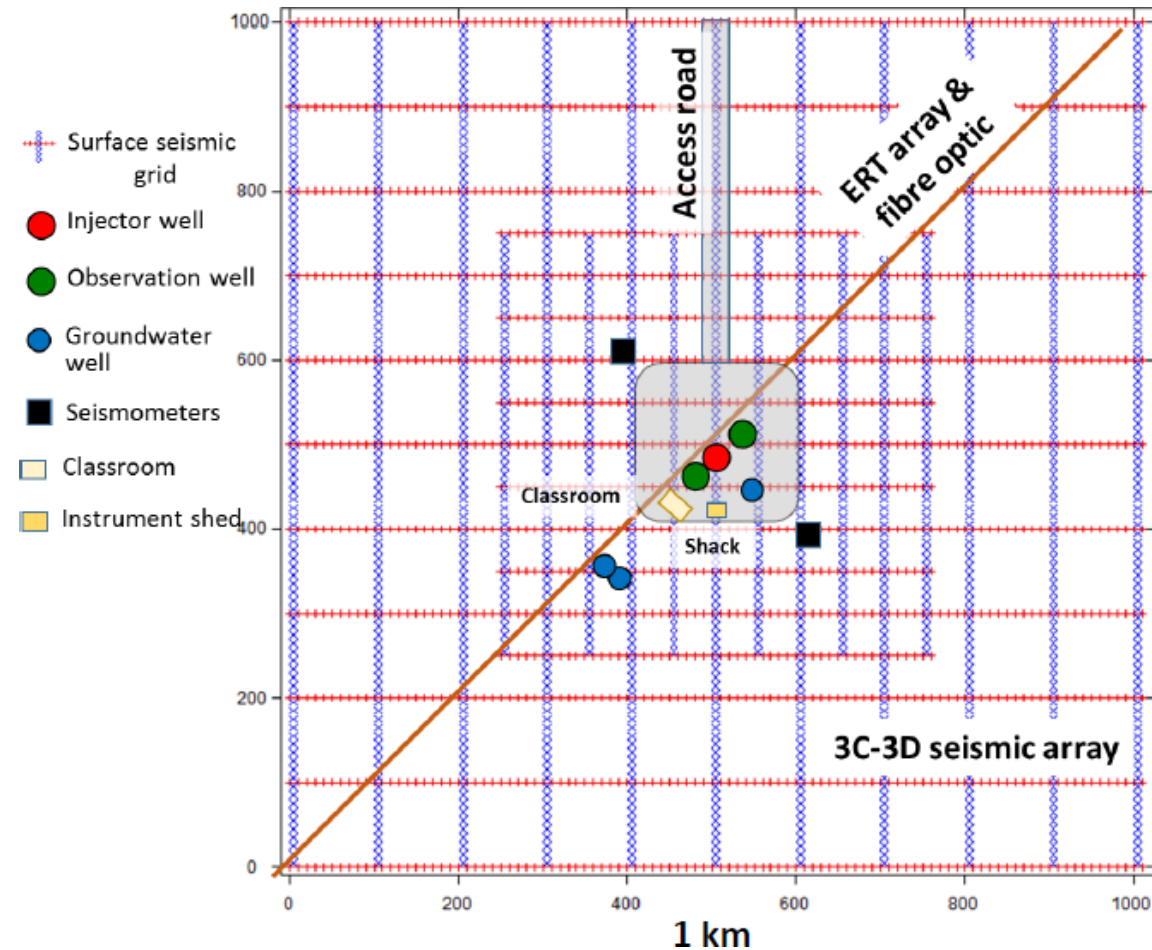
To get CO₂ saturation and the pressure response

To get 3D models of the elastic parameters after CO₂ injection

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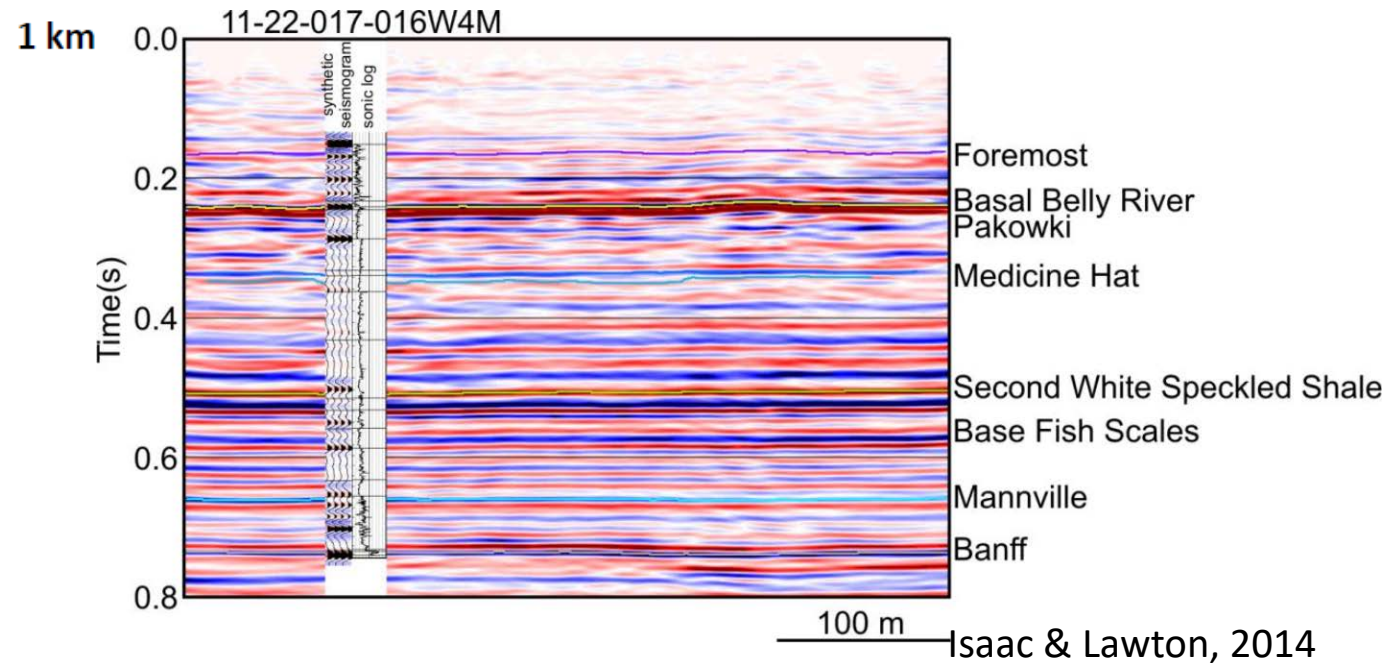
IV - Seismic simulation

2014 baseline acquisition



- 1400 receivers (blue)
- 1434 shots (red)

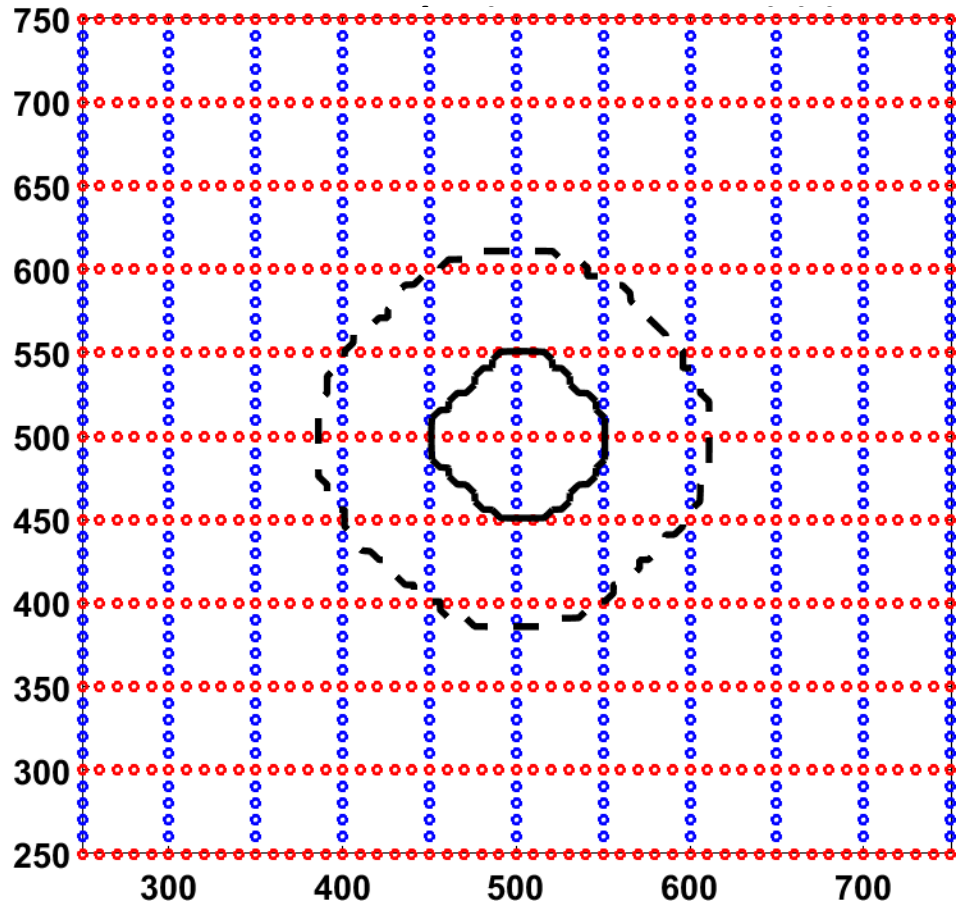
Bin size : 5m x 5m



Isaac & Lawton, 2014

IV - Seismic simulation

Data simulation with Tiger, a 3D anisotropic finite-difference modelling software (SINTEF)



- 561 receivers (blue)
- 561 sources (red)

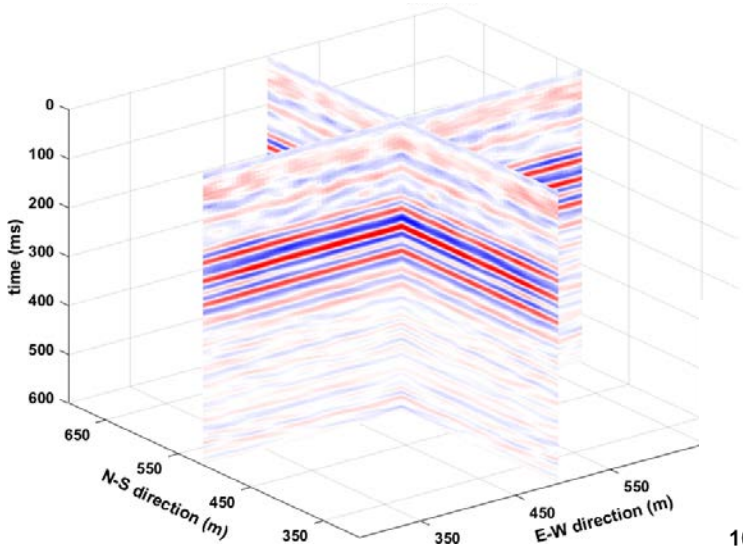
Standard processing with Vista

- Deconvolution
- NMO
- CMP stack
- Post-stack time migration

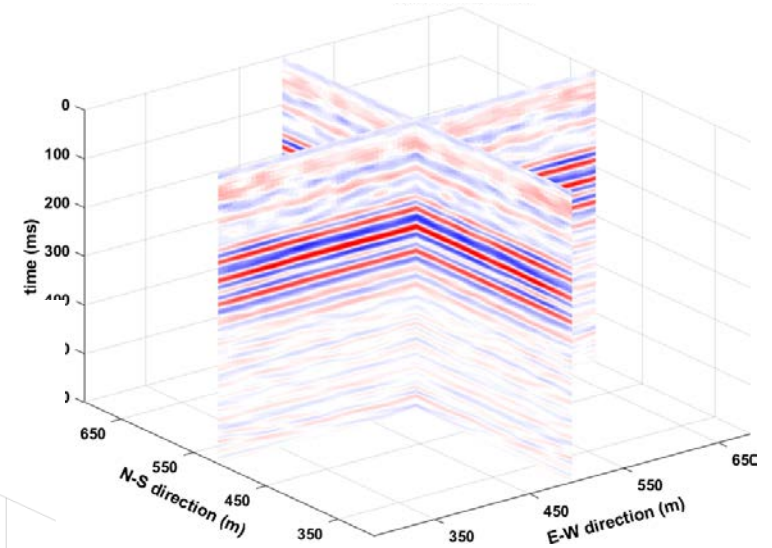
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IV - Seismic simulation

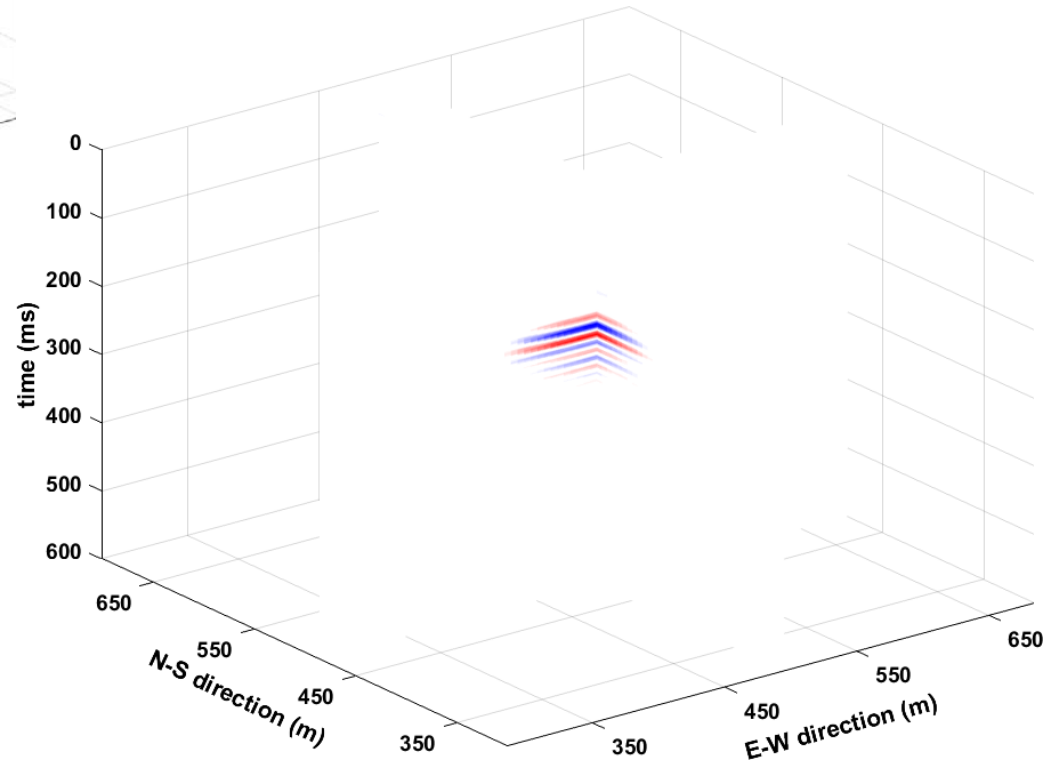
BASELINE



1 YEAR OF INJECTION



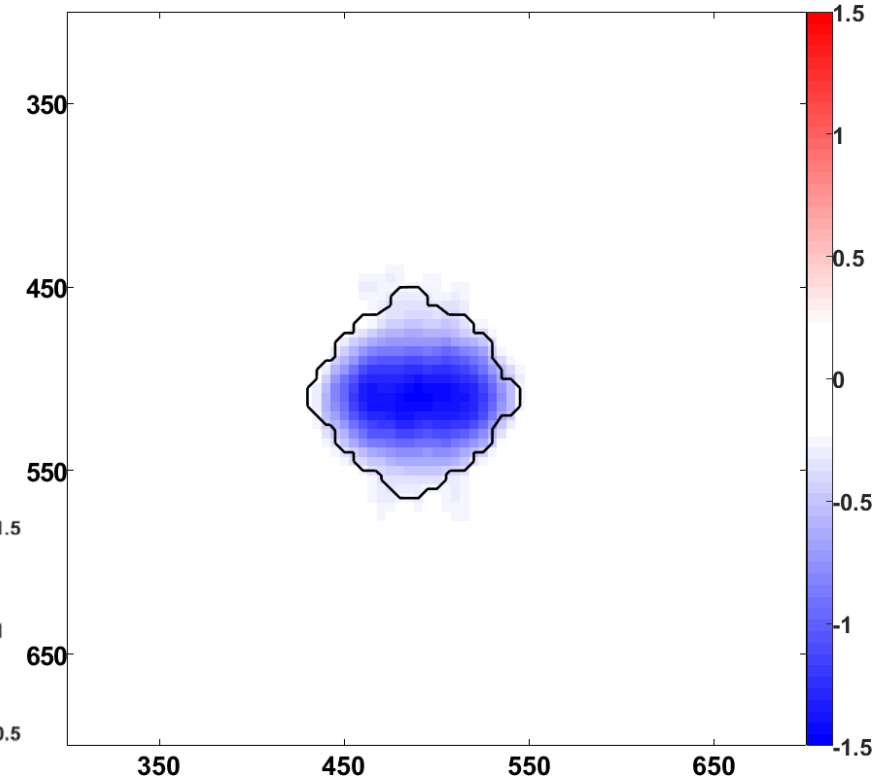
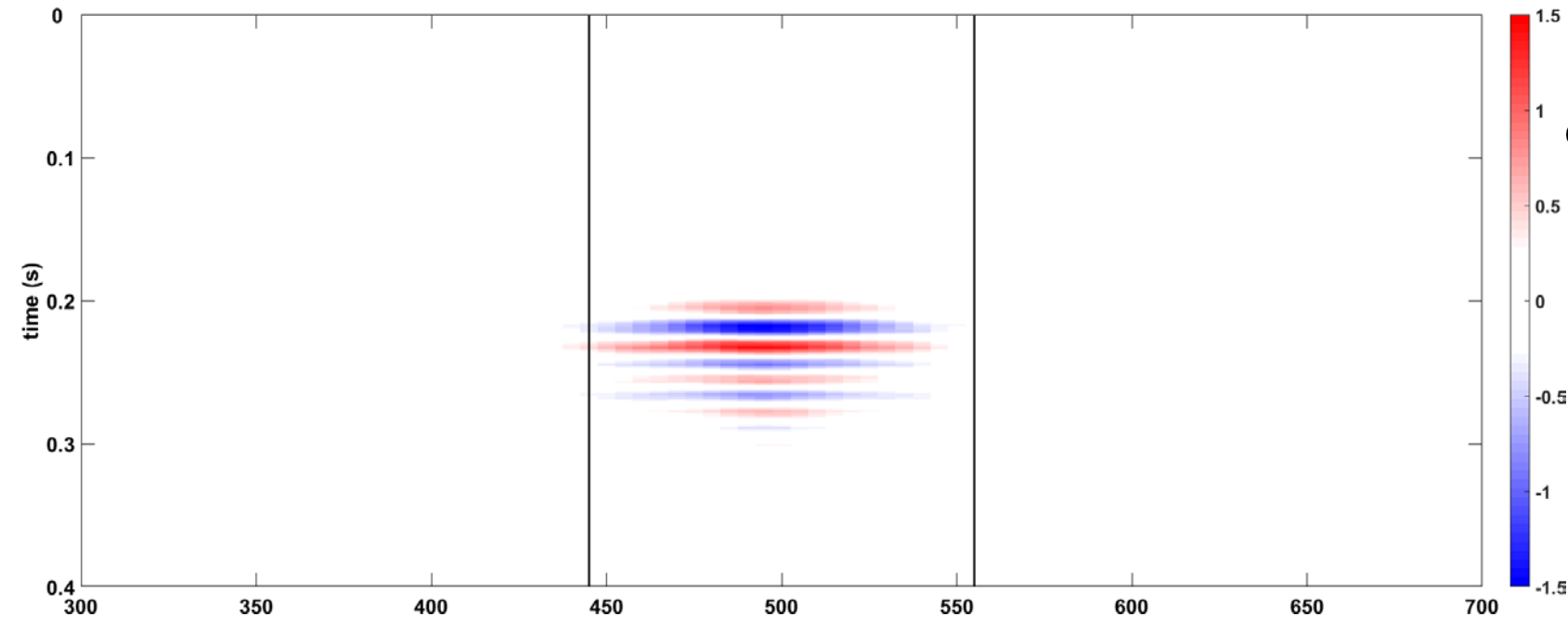
DIFFERENCE



IV - Difference between 1 year of injection and the baseline

1 year of injection (266 tons), no noise added

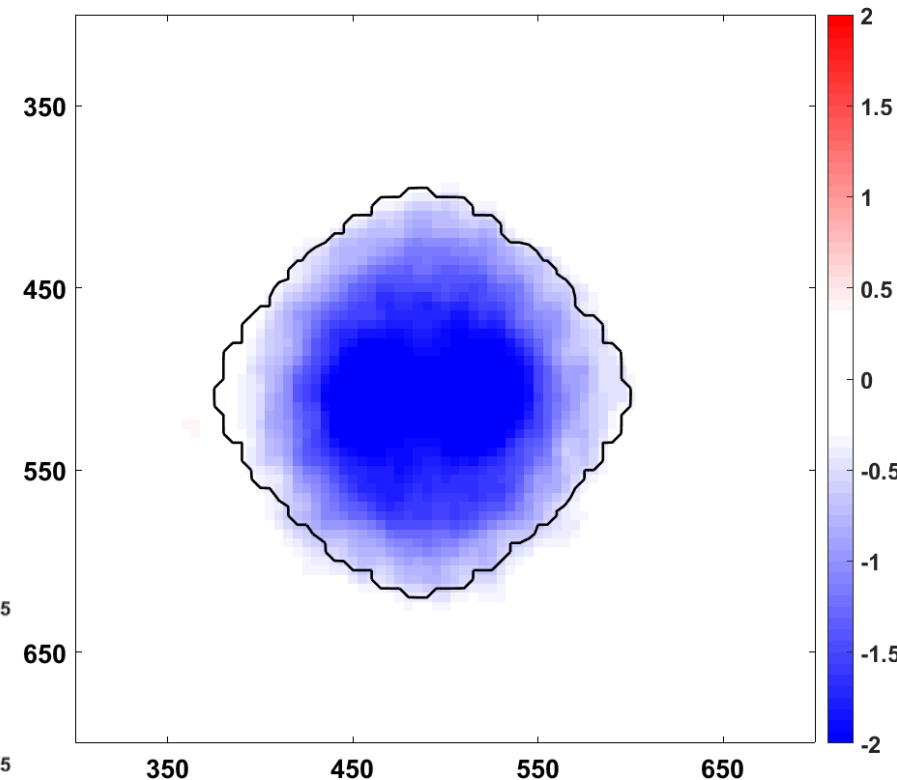
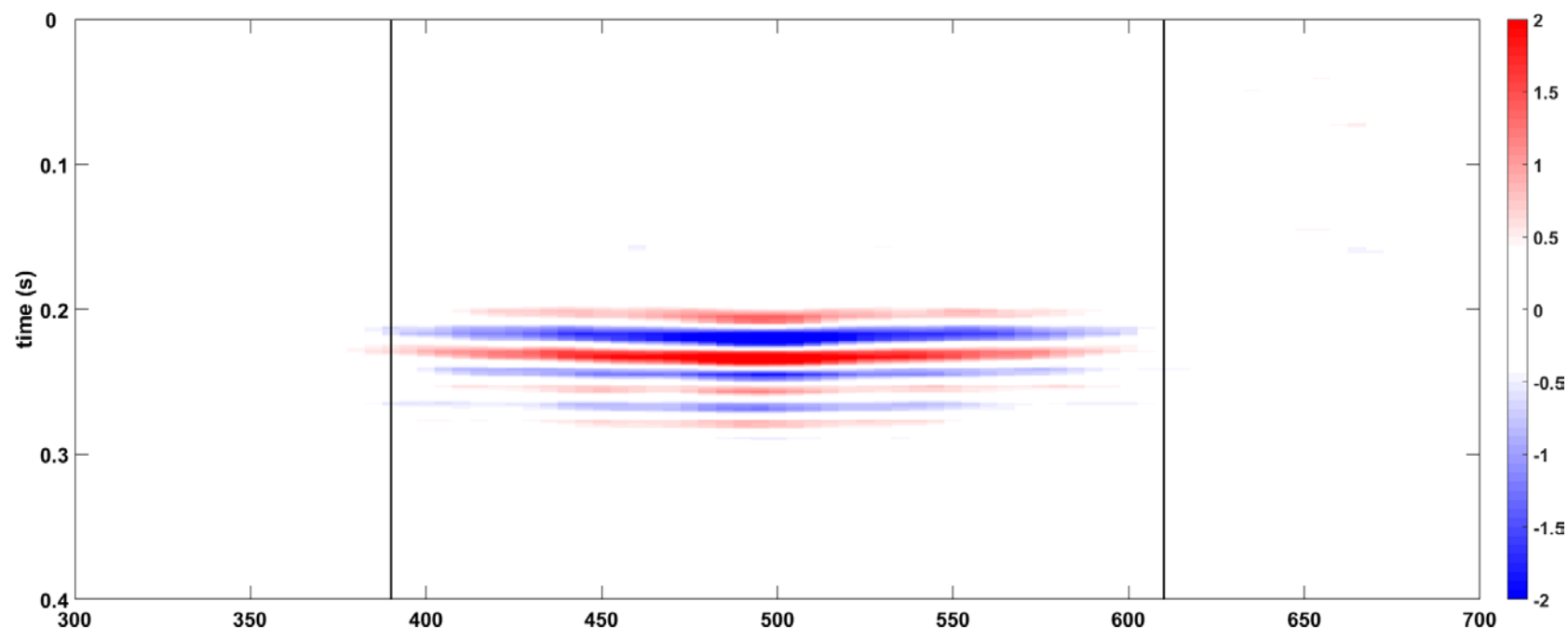
➡ perfect but impossible case



IV - Difference between 5 years of injection and the baseline

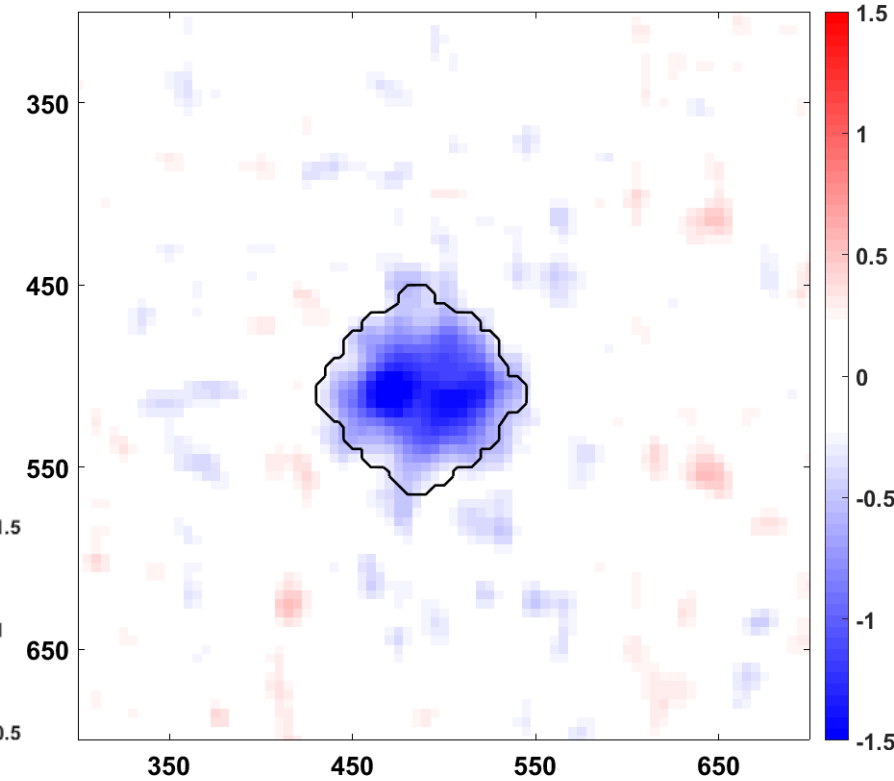
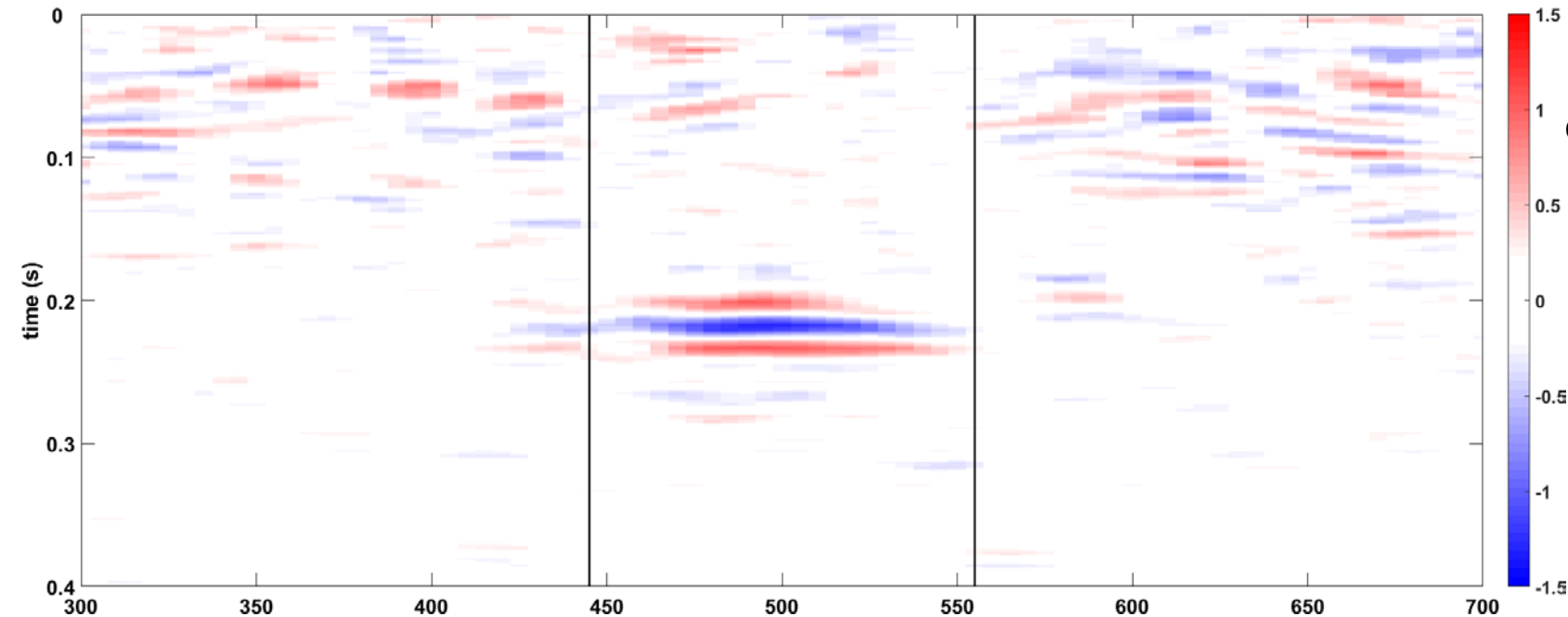
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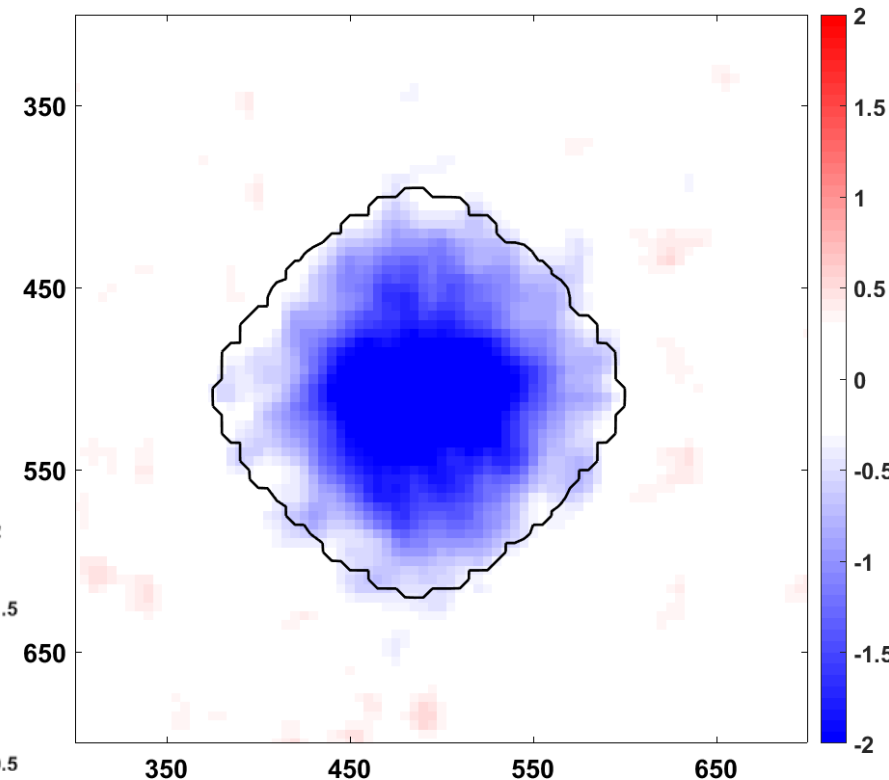
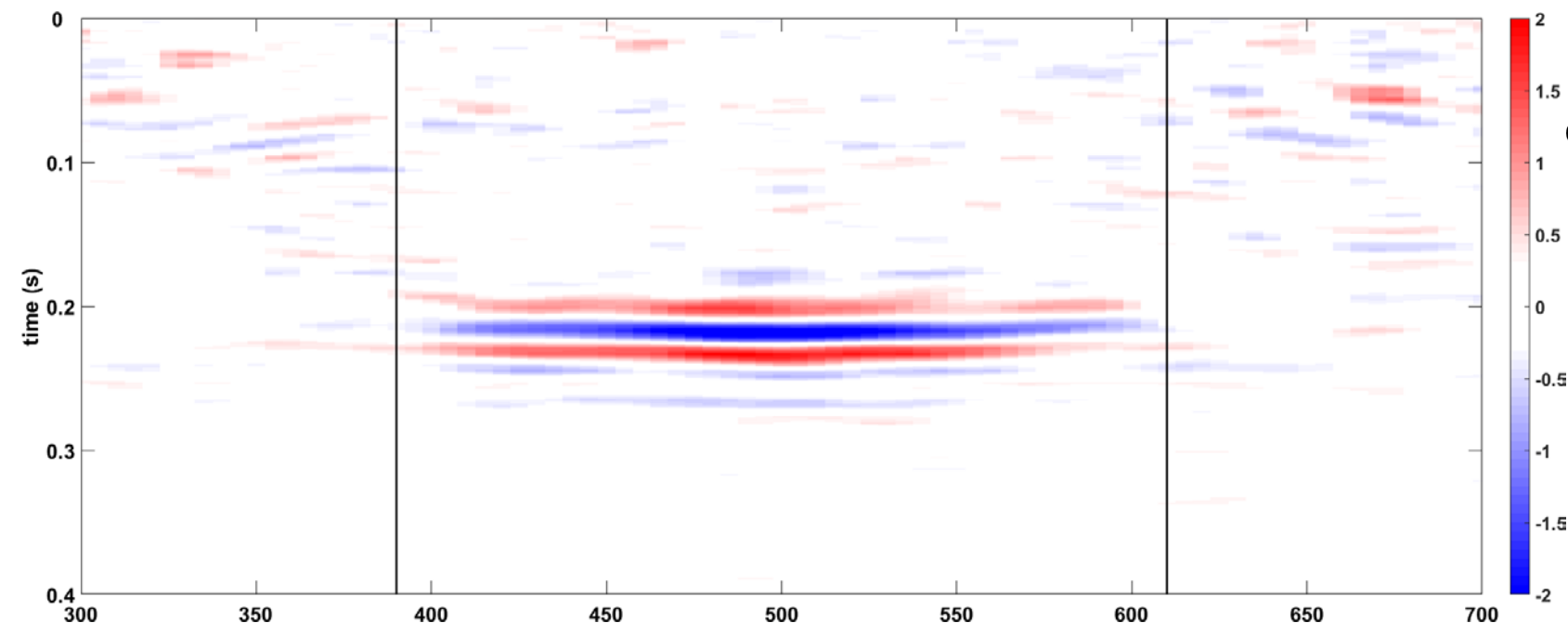
1 year of injection (266 tons), SNR = 20
➔ realistic case, based on real data



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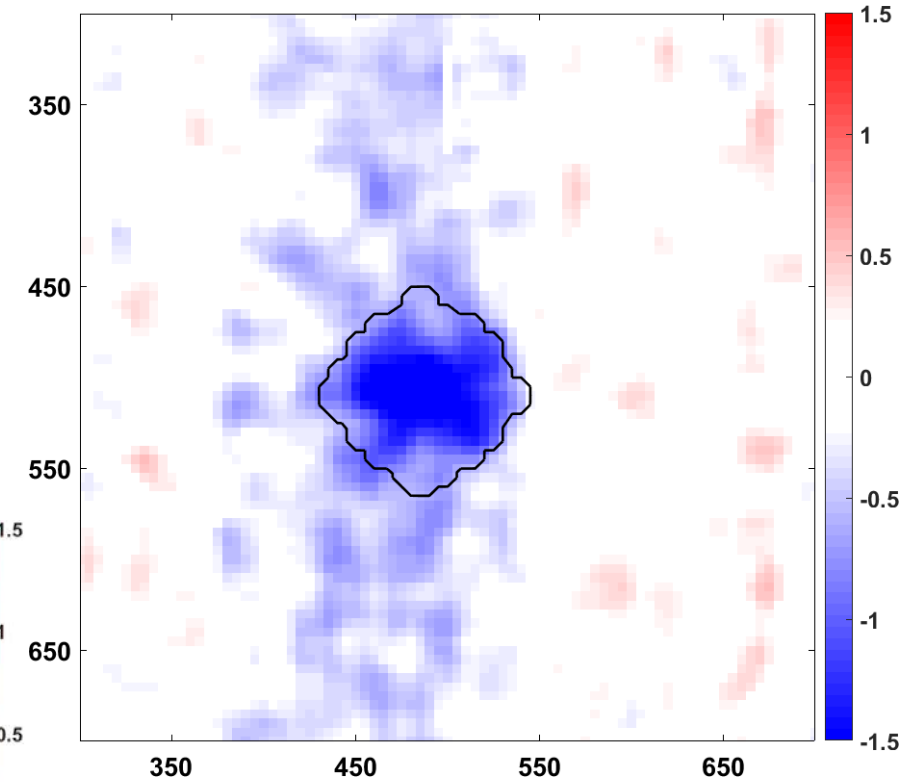
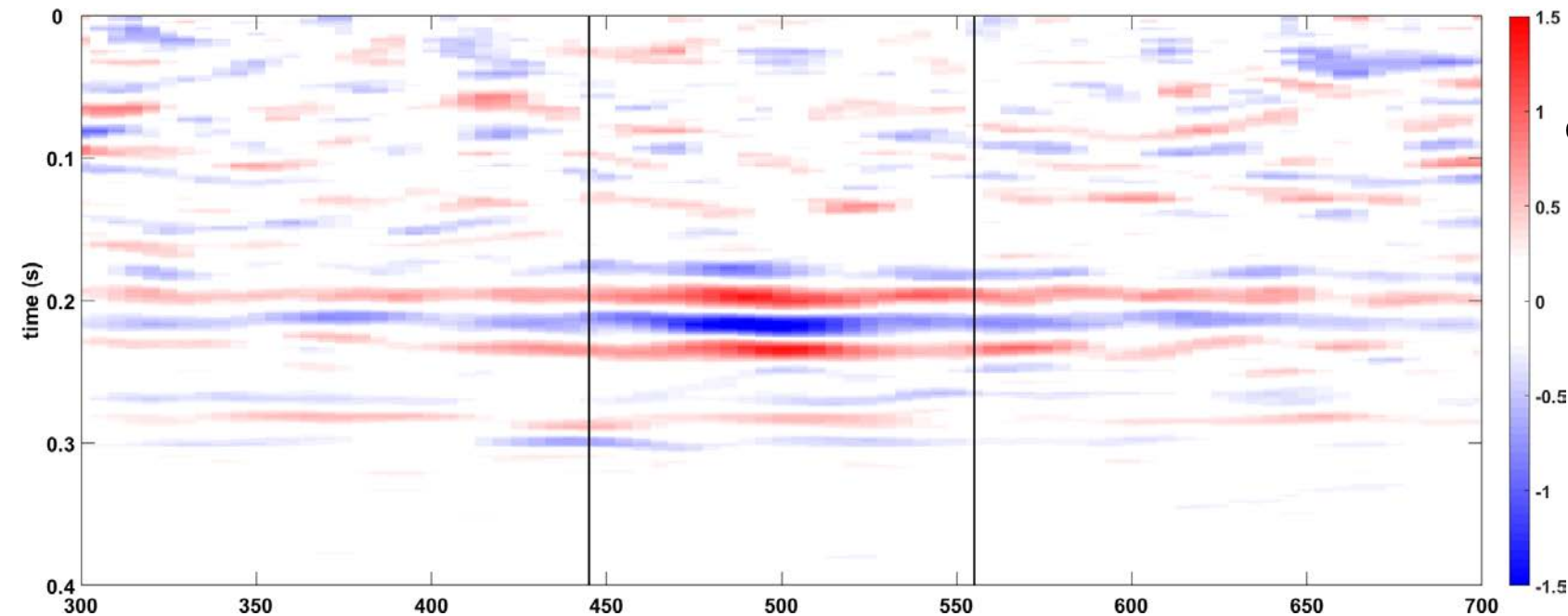
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IV - Difference between 1 year of injection and the baseline

1 year of injection (266 tons), SNR = 10

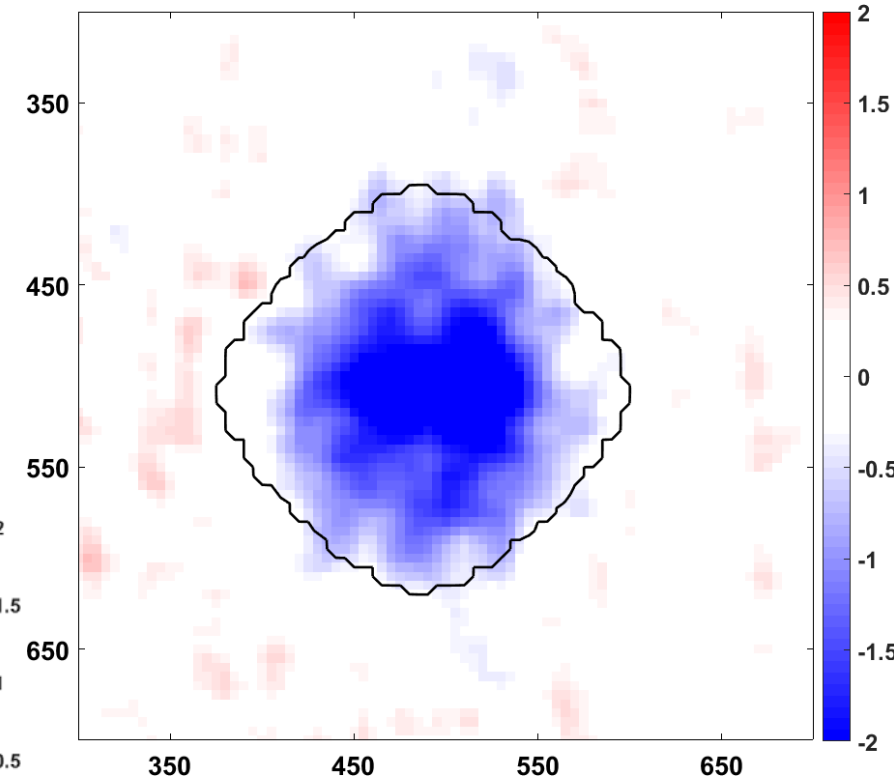
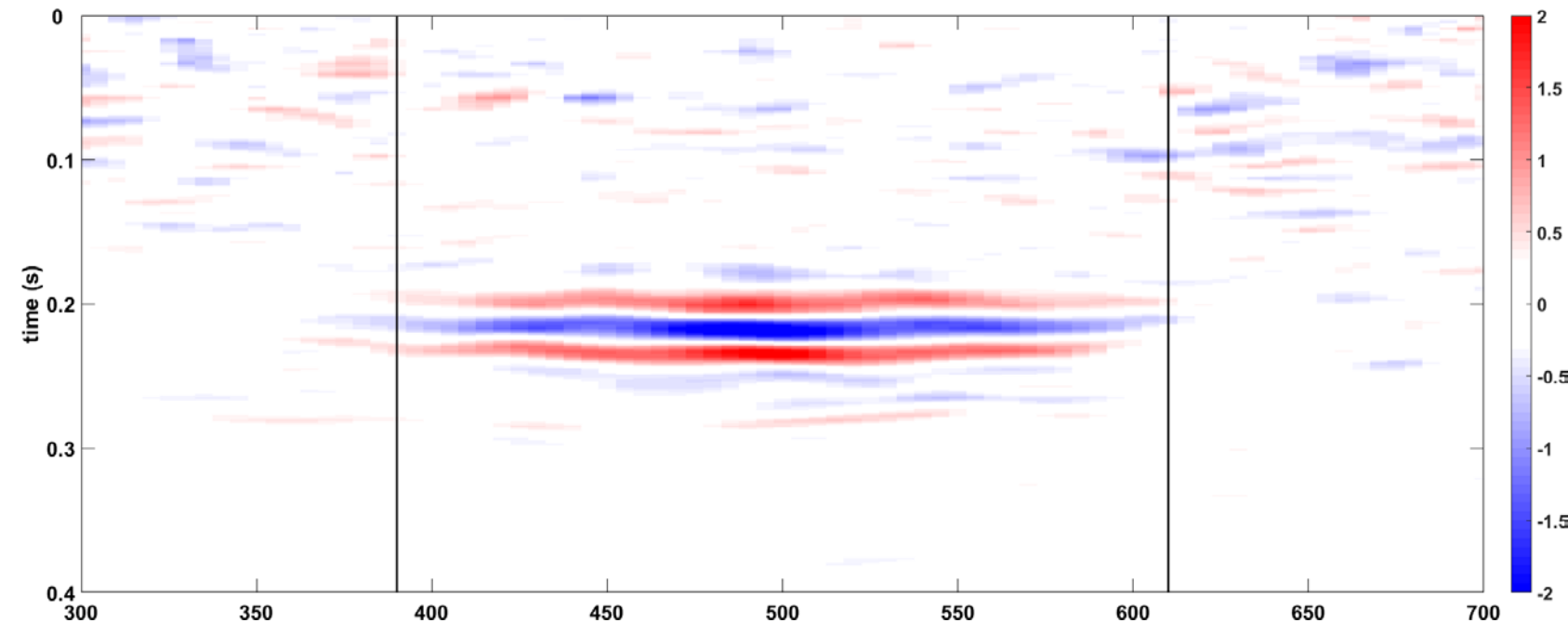
 pessimistic case



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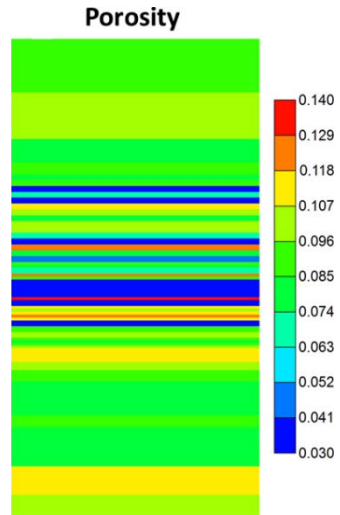
5 years of injection, SNR = 10

 pessimistic case

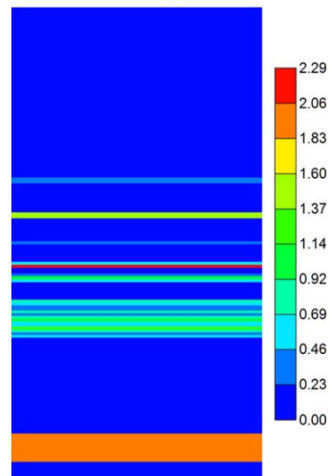


Summary

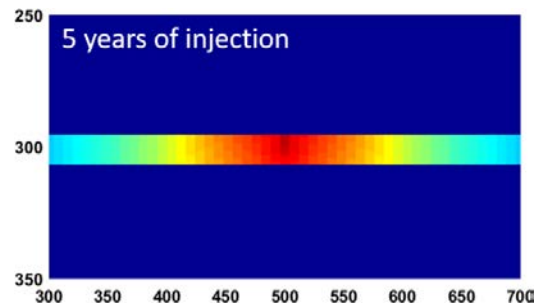
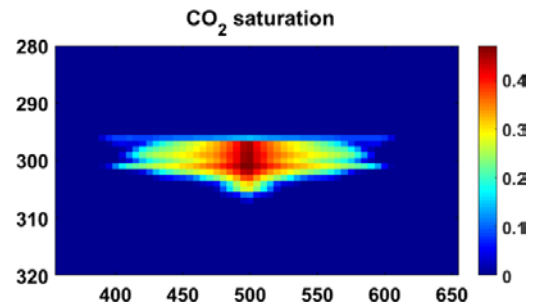
1) Geomodelling



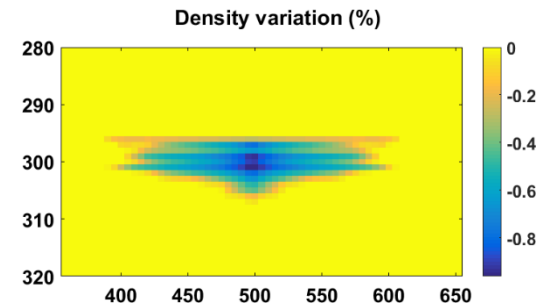
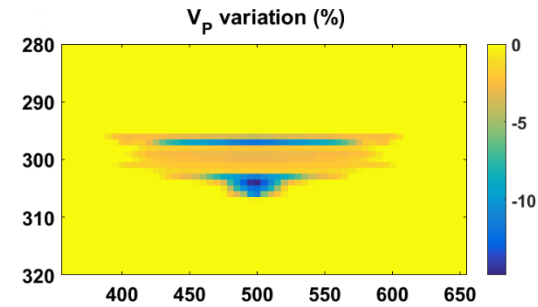
Permeability (mD)



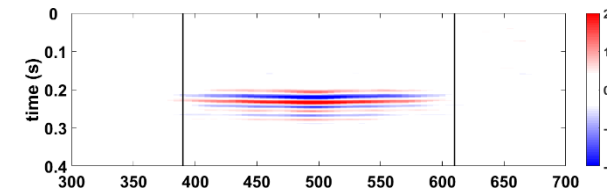
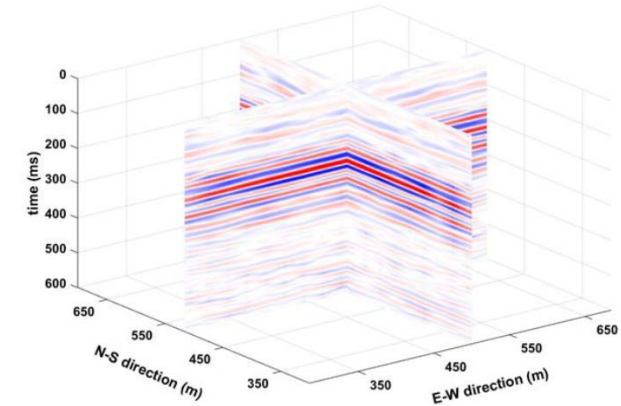
2) Fluid flow simulations



3) Fluid substitution



4) Seismic response simulation



Conclusions & Future work

1) Geomodelling

2) Fluid flow simulation

3) Fluid substitution

4) Seismic response simulation

ASSUMPTIONS

Assumption on vertical permeability

Assumption on the maximum bottom-hole pressure

Assumption on the Saturation behavior

Assumption on perfect survey repeatability

WHAT WE CAN DO

History match and updating geostatic models

Better estimation with pressure data from injection on field

Lab tests to better understand saturation behavior

Estimate non-repeatability using 2 datasets acquired on field

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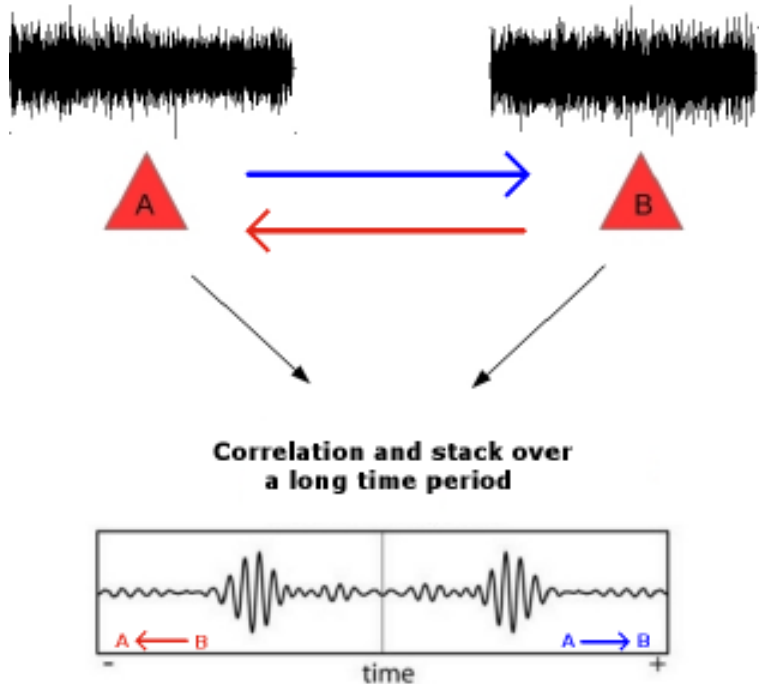
- CREWES sponsors
- CMC – CaMI sponsors
- NSERC - grant CRDPJ 461179-13
- CREWES staff and students,
- SINTEF for Tiger modelling software,
- Schlumberger for Vista processing software,
- CMG for the reservoir simulation software.

Thank you

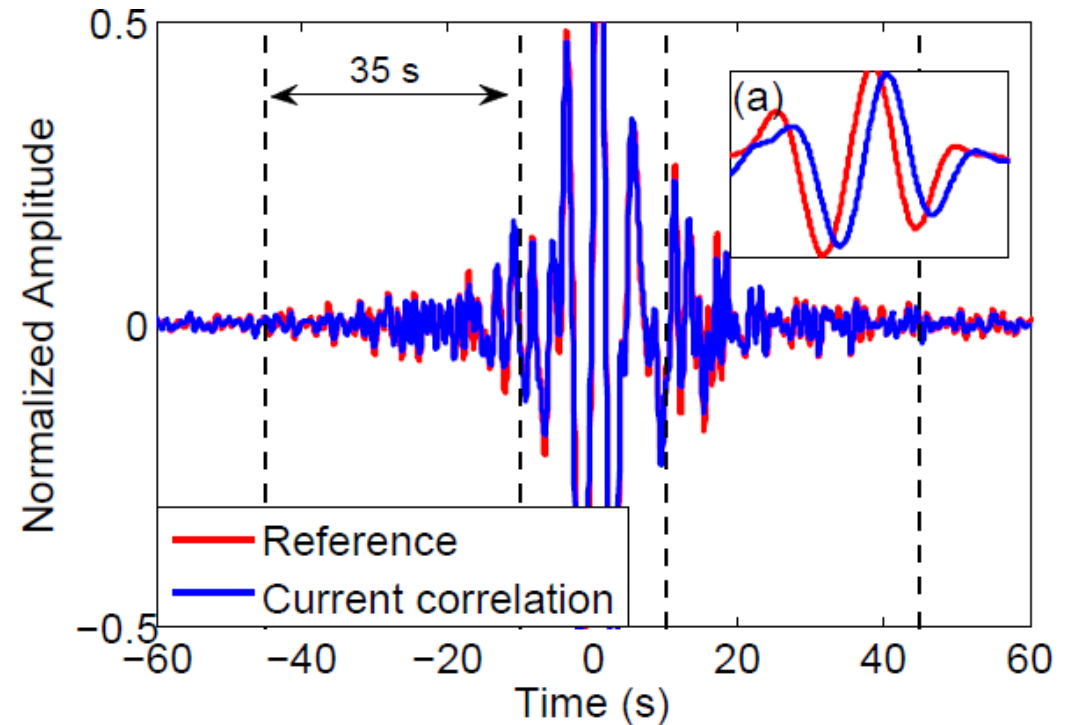


Future work – Use Ambient Noise Correlation

Principle: Correlating the noise registered at two stations approximate the Green function between those two stations



If you change the medium between the two stations, the results of the correlation will change

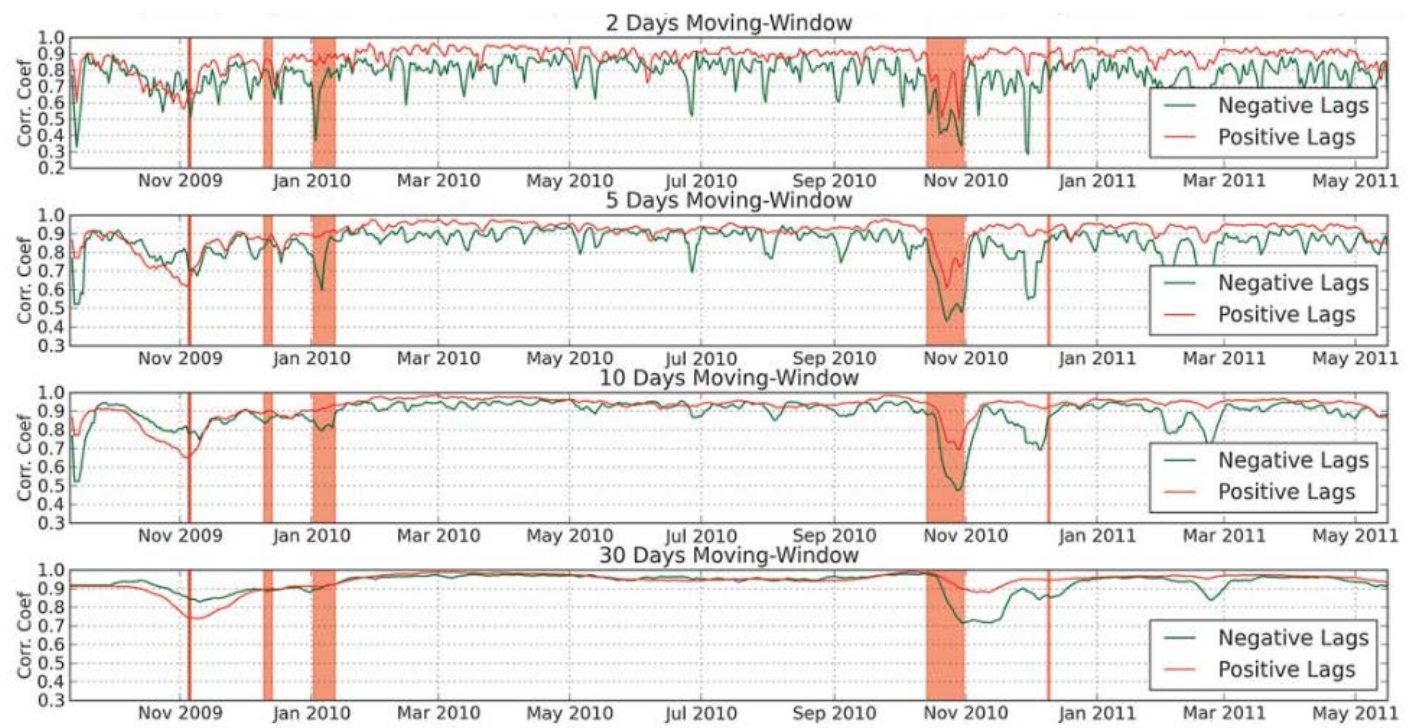


From Obermann et al., 2013

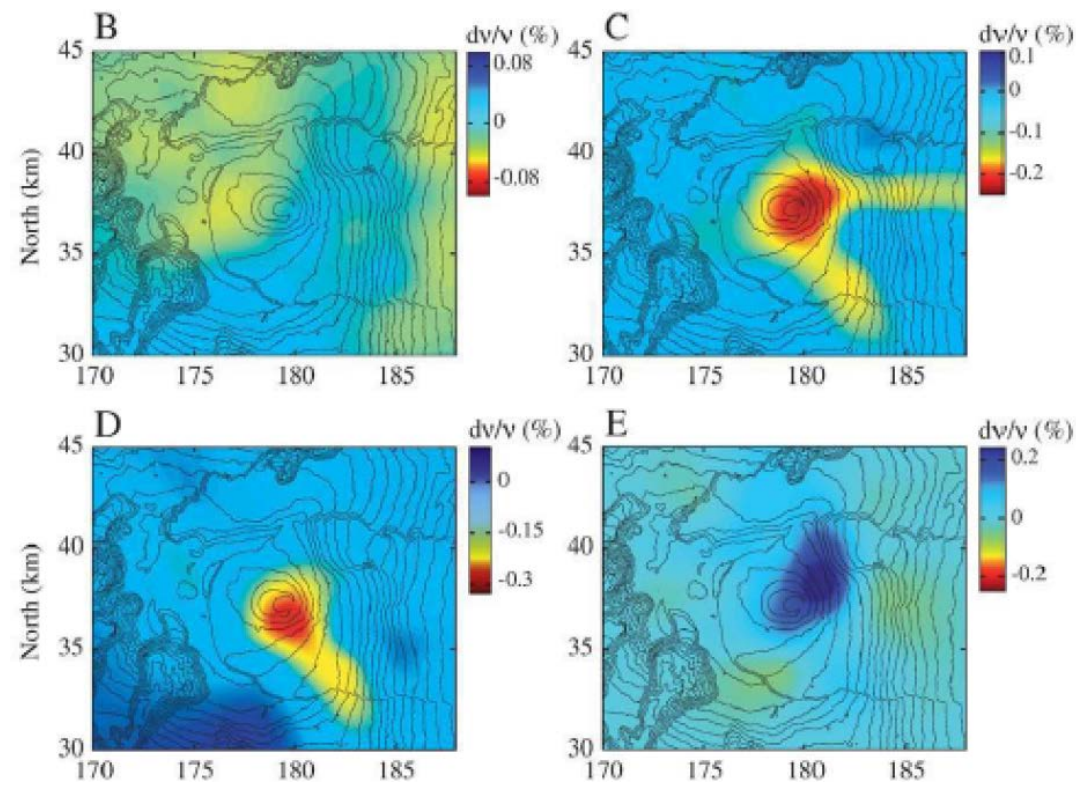
So far application of monitoring on volcanoes, on geothermal sites, on oil production field...

Future work – Use Ambient Noise Correlation

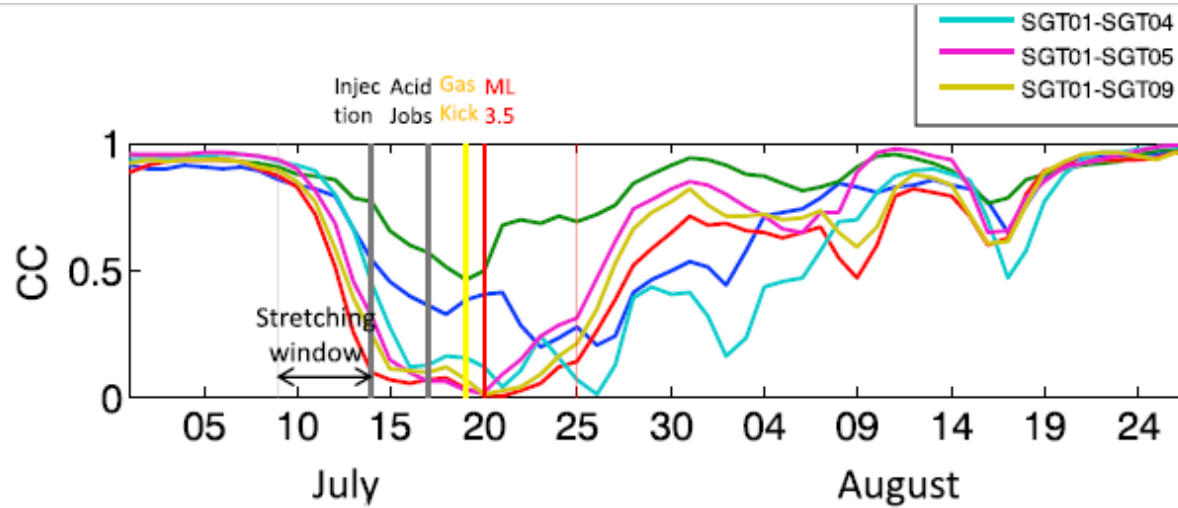
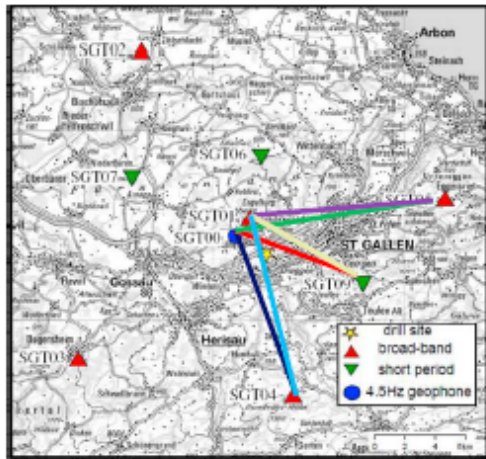
Computing the correlation function between a reference correlation and the current correlation (from Lecocq et al., 2014)



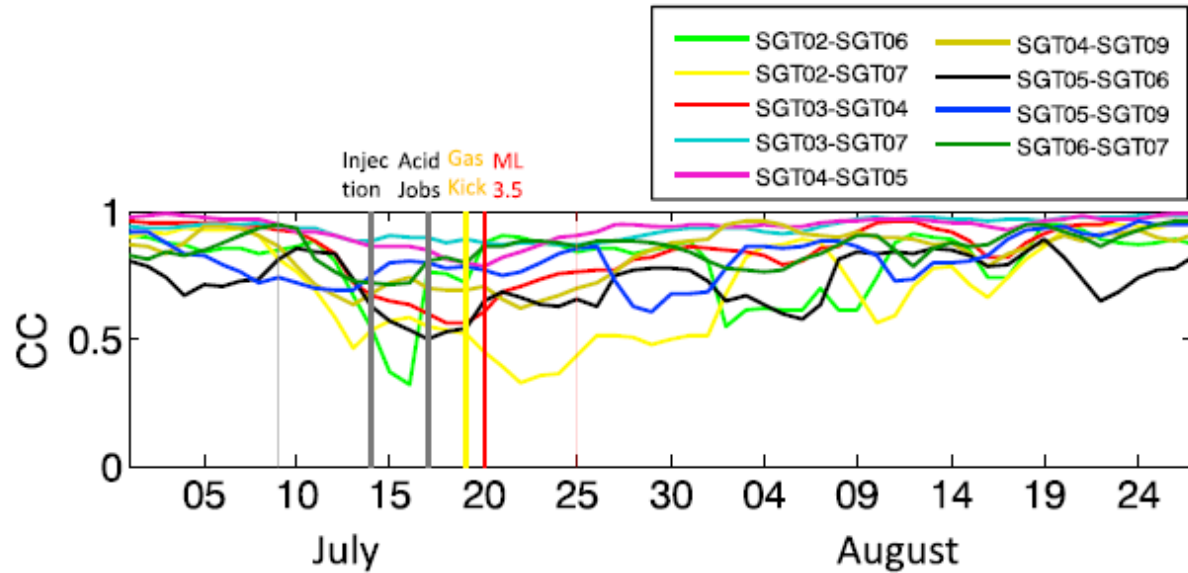
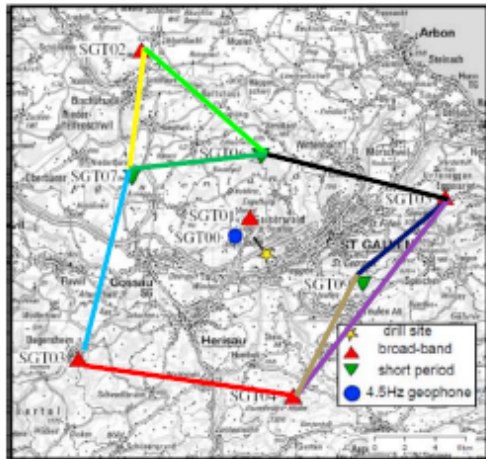
Regionalization of temporal changes (From Duputel et al., 2009)



Future work – Use Ambient Noise Correlation



(b)



Obermann et al., 2015

Future work – Use Ambient Noise Correlation

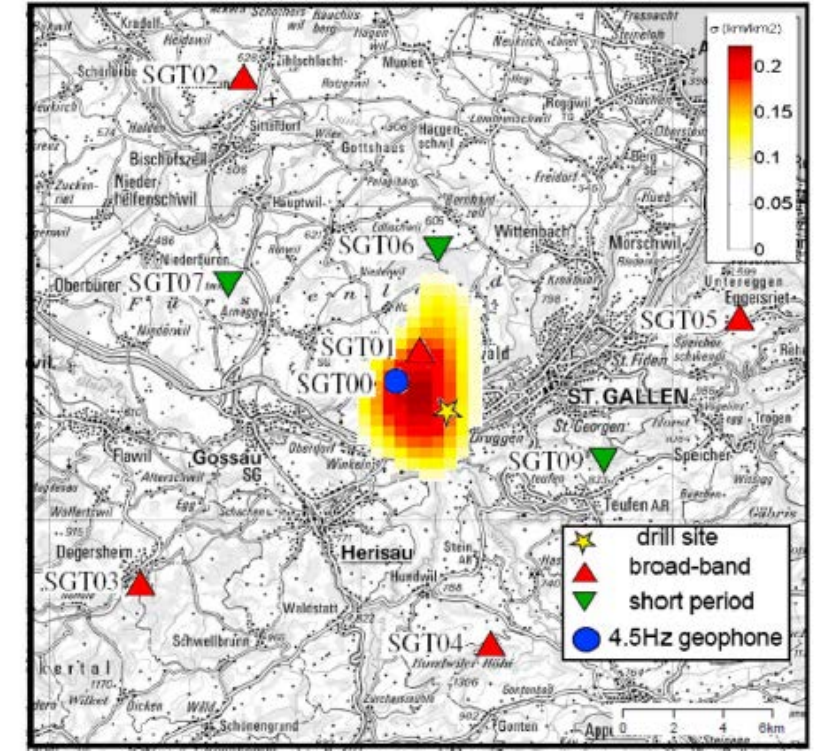
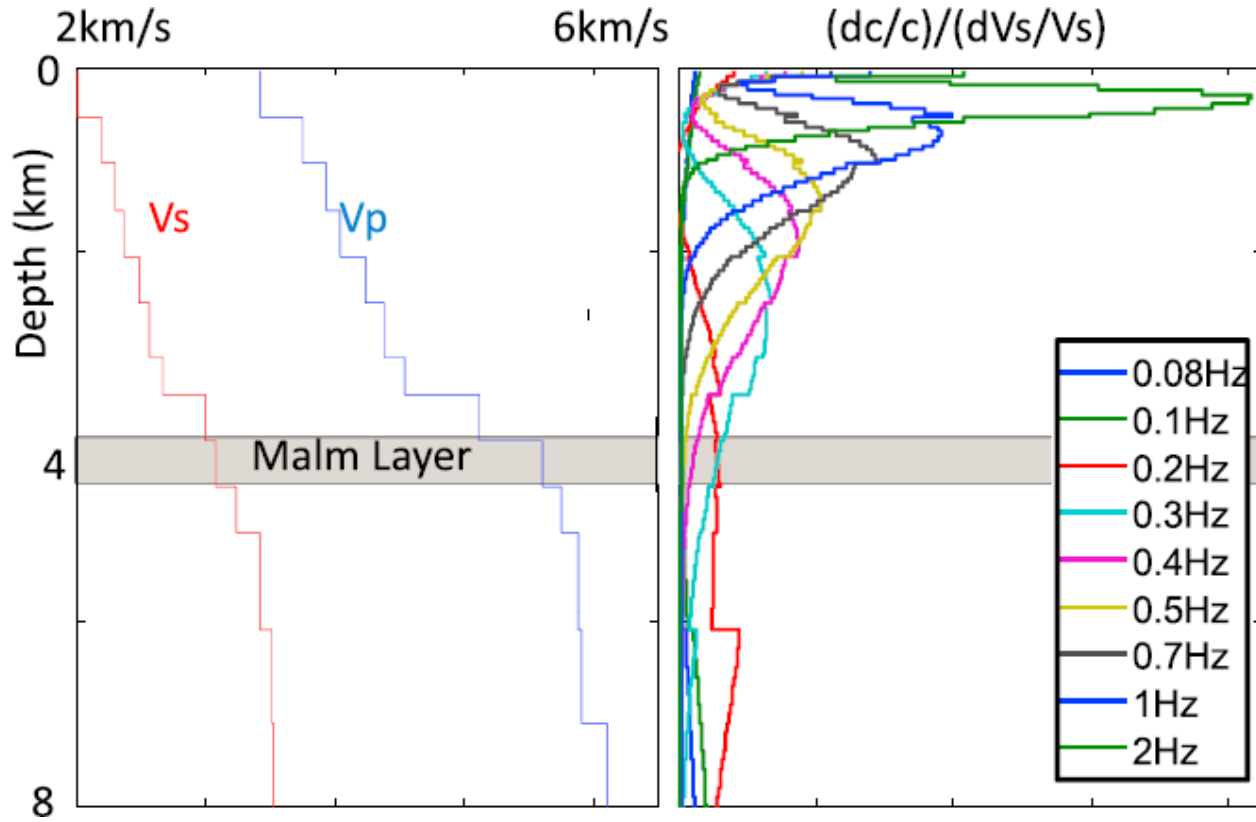


Figure 9. Scattering cross-section density changes derived by least squares inversion averaged over July 2013. The observed changes are around the injection well, indicating a causal relationship with the activities at the well.

Obermann et al., 2015

Future work – Use Ambient Noise Correlation

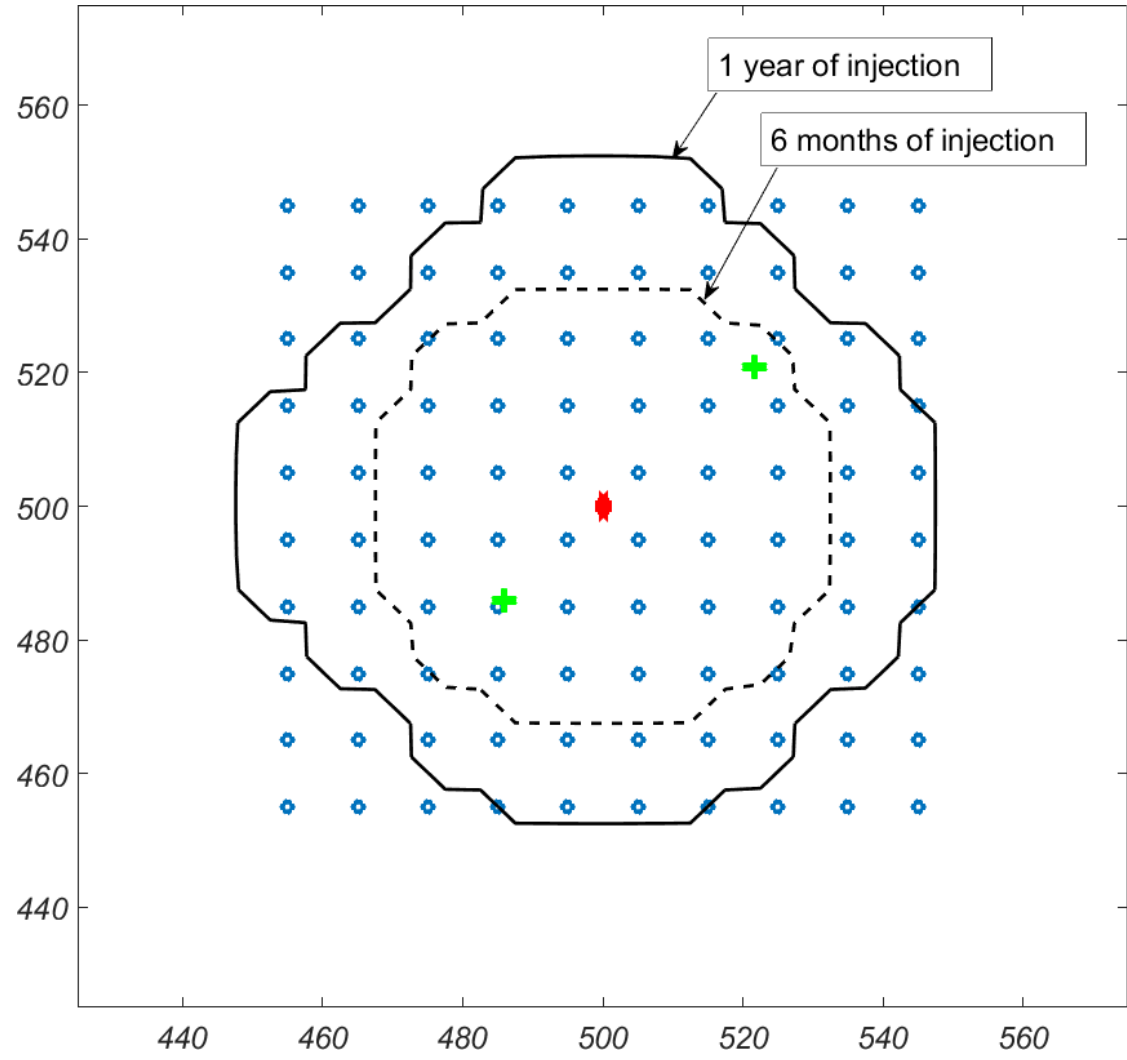


Fig. 14 CRR

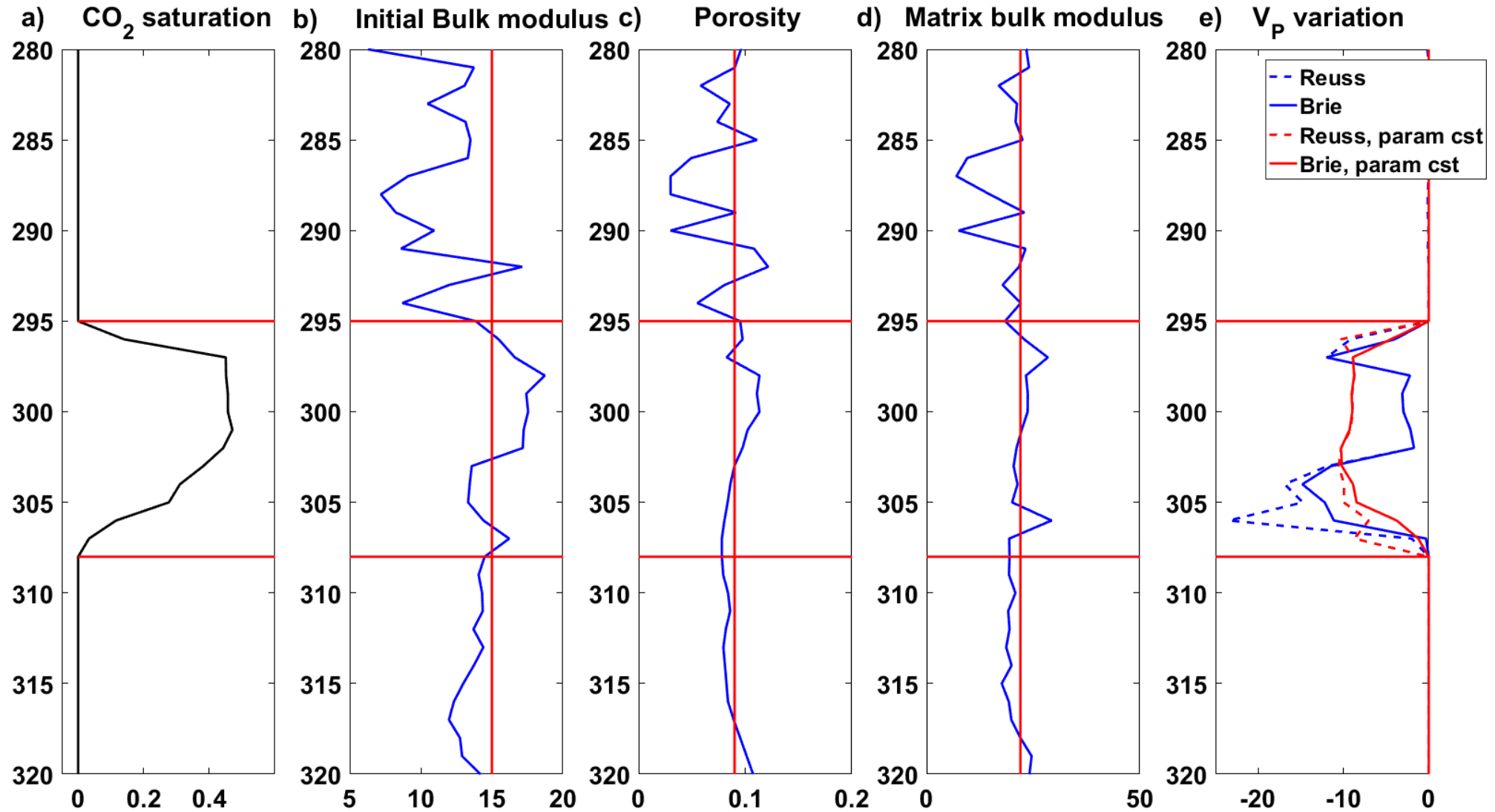


Fig. 15 CRR

