

Double-wavelet double-difference time-lapse waveform inversion

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- □ Time-lapse inversion strategies
- Double-wavelet double-difference
 - time-lapse waveform inversion
 - (DWDDWI)
- Conclusions

Waveform inversion

1) Data residuals $\delta d = d_0 - d_m$

2) Reflectivity residual $\delta R = Stk[Mig(\delta d)]$

3) Gradient $g = Imp(\delta R)$

4) Velocity perturbation $\delta m = \lambda g$

5) Velocity update

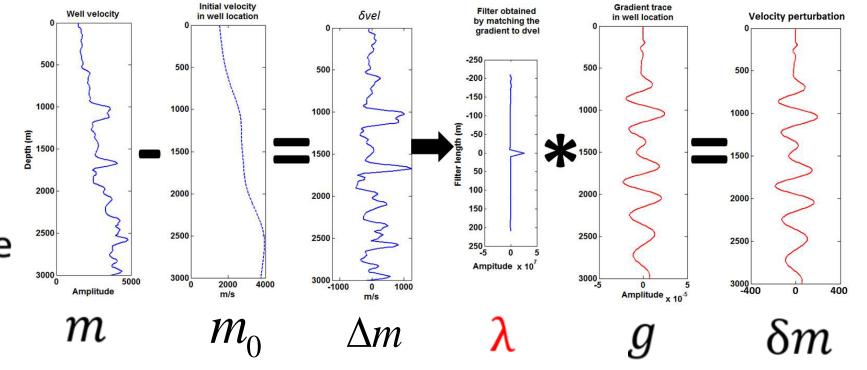
 $m_{k+1} = m_k + \delta m$

(Margrave et al., 2010; Romahn, 2019)

Log validation

 $\delta m = \lambda g$

- Log calibration
- Minimize difference between the gradient & δvel in the well



(Romahn and Innanen, 2016)



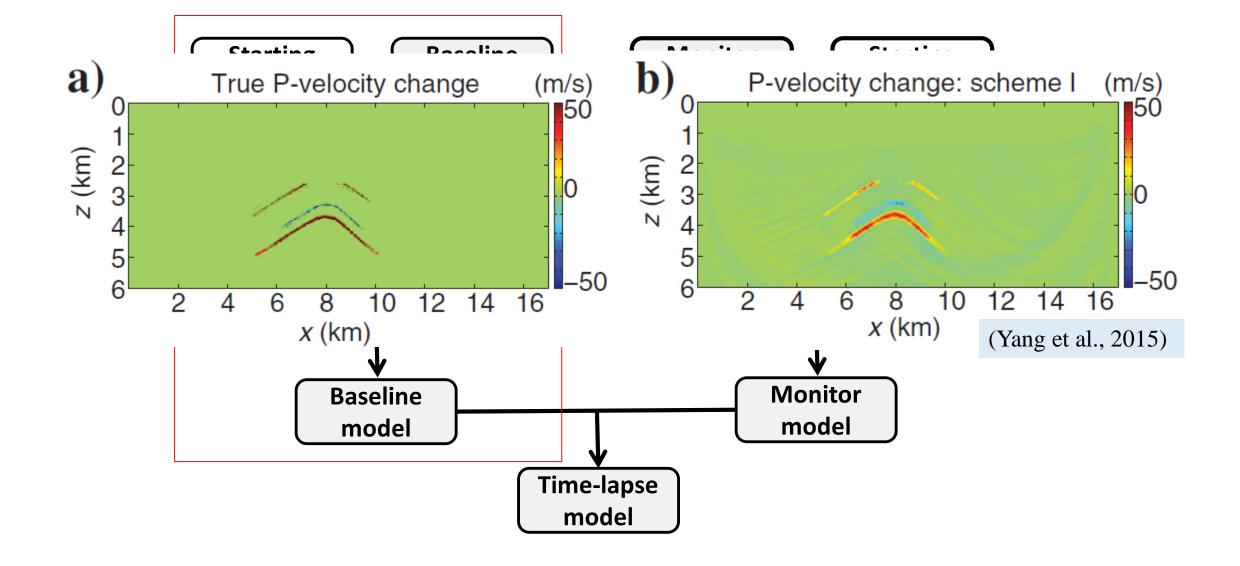
□ Time-lapse inversion strategies

Double-wavelet double-difference

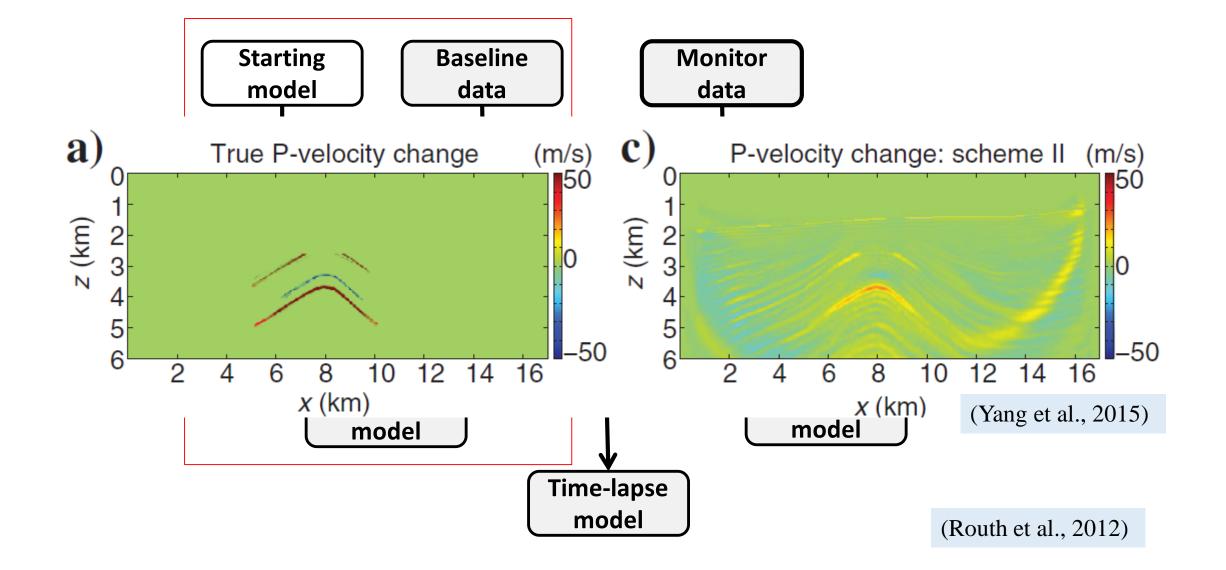
time-lapse waveform inversion

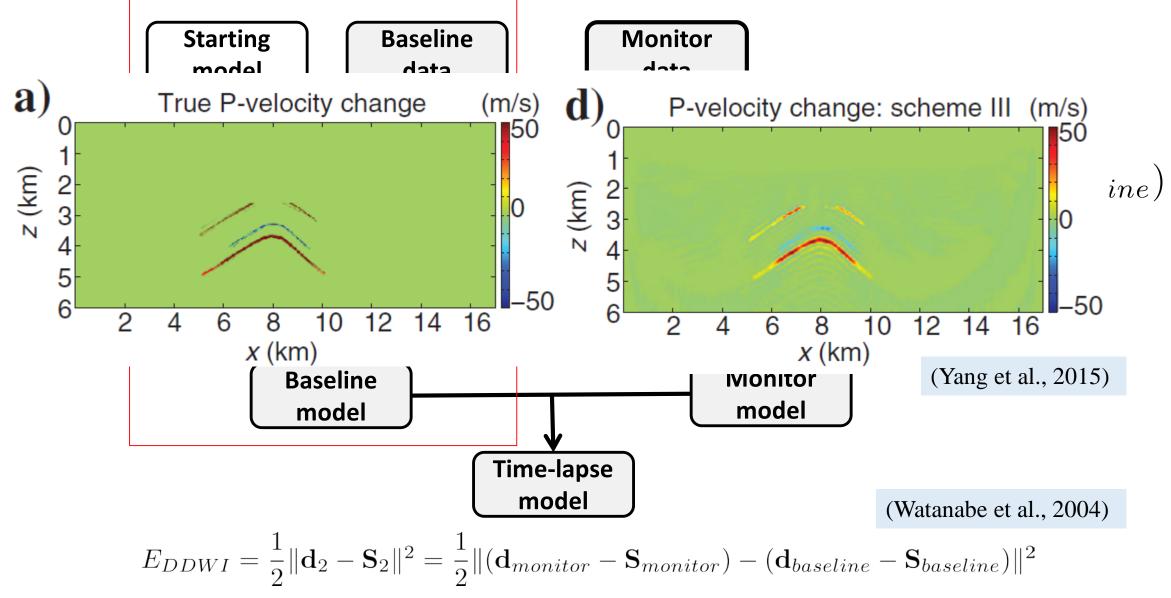
(DWDDWI)

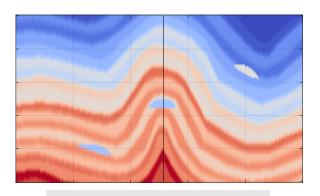
Conclusions



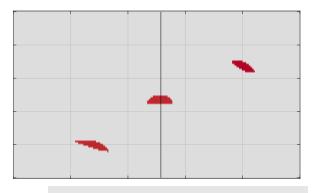
Sequential difference strategy



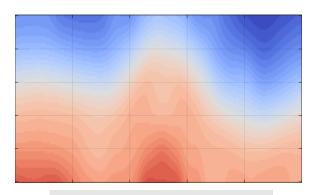




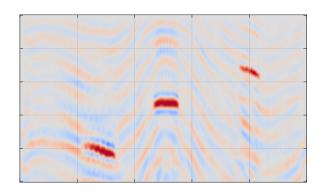
Baseline model



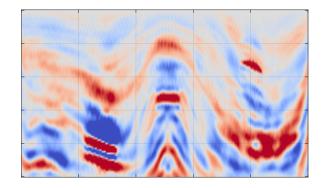
Time-lapse model



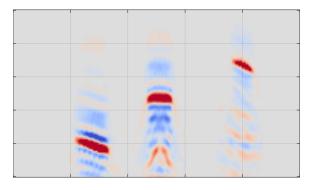
Starting model

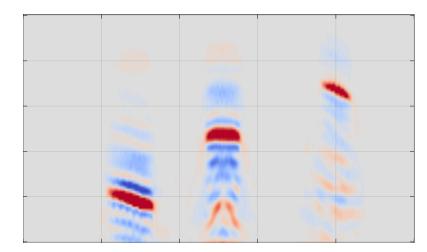


Parallel

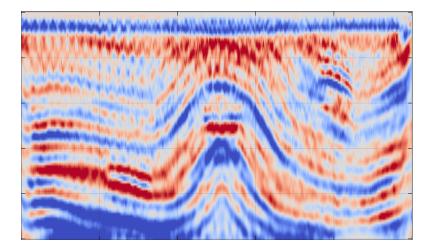


sequential





DDWI Wavelets for baseline and monitor data are the same

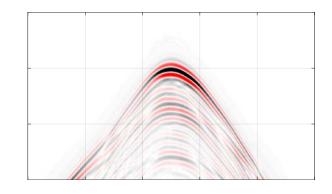


DDWI Wavelets for baseline and monitor data are different Double-difference strategy (DDWI)

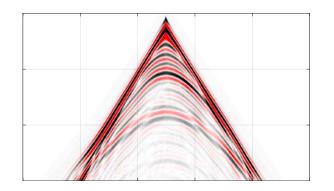
$$\begin{aligned} \textbf{DDWI} \quad & \mathbf{d}_2 = \mathbf{S}_{baseline} + (\mathbf{d}_{monitor} - \mathbf{d}_{baseline}) \\ & = \mathbf{S}_{baseline} + \left(\mathbf{W}_{monitor} * \mathbf{G}_{monitor} - \mathbf{W}_{baseline} * \mathbf{G}_{baseline} \right) \end{aligned}$$

when
$$\mathbf{W}_{monitor} = \mathbf{W}_{baseline} = \mathbf{W}$$

 $\mathbf{d}_2 = \mathbf{S}_{baseline} + \mathbf{W} * (\mathbf{G}_{monitor} - \mathbf{G}_{baseline})$



 $\mathbf{W}_{monitor} = \mathbf{W}_{baseline}$



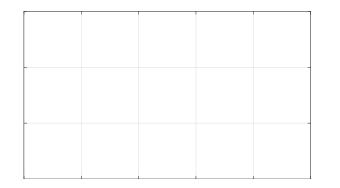
$$\mathbf{W}_{monitor}
eq \mathbf{W}_{baseline}$$



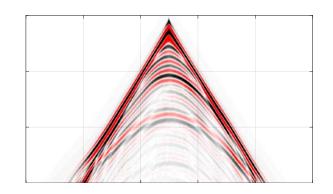
□ Time-lapse inversion strategies Double-wavelet double-difference time-lapse waveform inversion (DWDDWI)

Conclusions

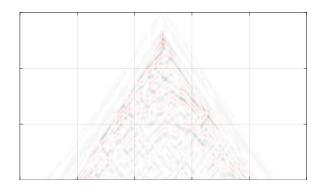
Double-wavelet double-difference time-lapse waveform inversion (DWDDWI) **DDWI** $\mathbf{d}_2 = \mathbf{S}_{baseline} + (\mathbf{d}_{monitor} - \mathbf{d}_{baseline})$ $= \mathbf{S}_{baseline} + (\mathbf{W}_{monitor} * \mathbf{G}_{monitor} - \mathbf{W}_{baseline} * \mathbf{G}_{baseline})$ New method: New monitor data New baseline data **DWDDWI** $\mathbf{d}_{2}' = \mathbf{S}_{baseline}' + \left(\mathbf{W}_{baseline} * \mathbf{d}_{monitor} - \mathbf{W}_{monitor} * \mathbf{d}_{baseline} \right)$ $= \mathbf{S}_{baseline}' + \left(\mathbf{W}_{baseline} * \mathbf{W}_{monitor} * \mathbf{G}_{monitor} - \mathbf{W}_{monitor} * \mathbf{W}_{baseline} * \mathbf{G}_{baseline} \right)$ $= \mathbf{S}_{baseline}' + \mathbf{W} * (\mathbf{G}_{monitor} - \mathbf{G}_{baseline})$ where $\mathbf{W}_{baseline} * \mathbf{W}_{monitor} = \mathbf{W}_{monitor} * \mathbf{W}_{baseline} = \mathbf{W}$ 13



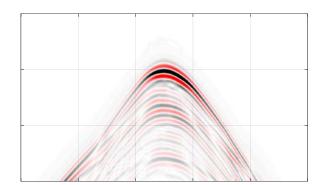
 $\mathbf{d}_{baseline}(10Hz) - \mathbf{d}_{baseline}(10Hz)$



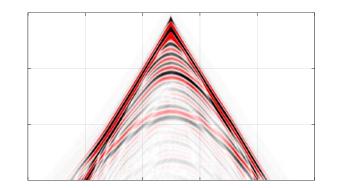
 $\mathbf{d}_{baseline}(10Hz) - \mathbf{d}_{baseline}(8Hz)$



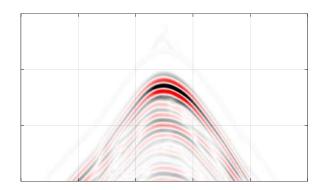
 $\mathbf{w}(8Hz) * \mathbf{d}_{baseline}(10Hz) \\ - \mathbf{w}(10Hz) * \mathbf{d}_{baseline}(8Hz)$



 $\mathbf{d}_{monitor}(10Hz) - \mathbf{d}_{baseline}(10Hz)$

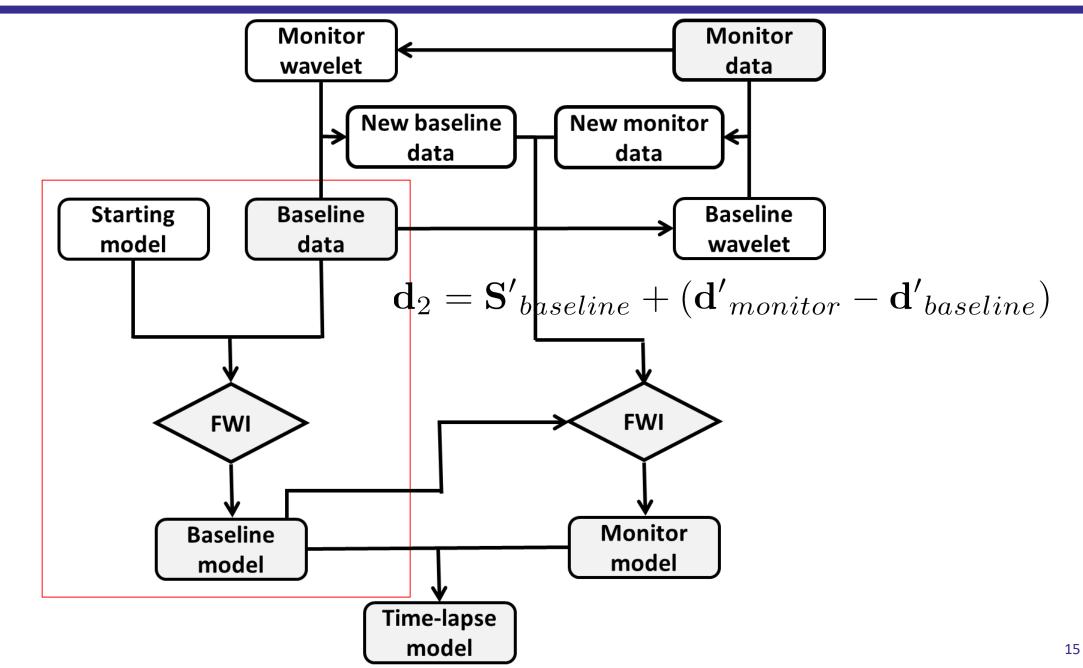


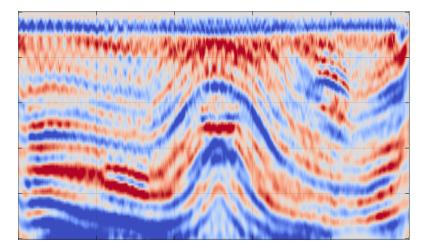
 $\mathbf{d}_{monitor}(10Hz) - \mathbf{d}_{baseline}(8Hz)$



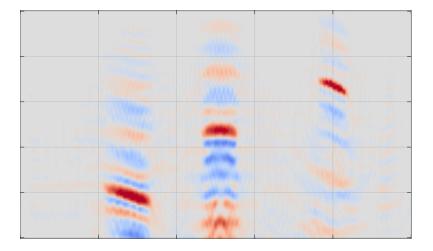
 $\mathbf{w}(8Hz) * \mathbf{d}_{monitor}(10Hz)$ $- \mathbf{w}(10Hz) * \mathbf{d}_{baseline}(8Hz)$

Double-wavelet double-difference strategy (DWDDWI)





DDWI Wavelets for baseline and monitor data are different



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- ✓ DDWI is not easy to be affected by the different convergences of baseline and monitor inversions
- ✓ DDWI demands an almost perfect repeatability between the two surveys (Yang et al., 2015)
- DWDDWI can handle well with the situation of wavelets for the two datasets are different
- ✓ DWDDWI works because the data difference caused by the wavelet difference is eliminated.
- \checkmark The premise is that the two wavelets are known



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